

1. Causal Strategic Learning (CSL)

Example of causal strategic learning (CSL):

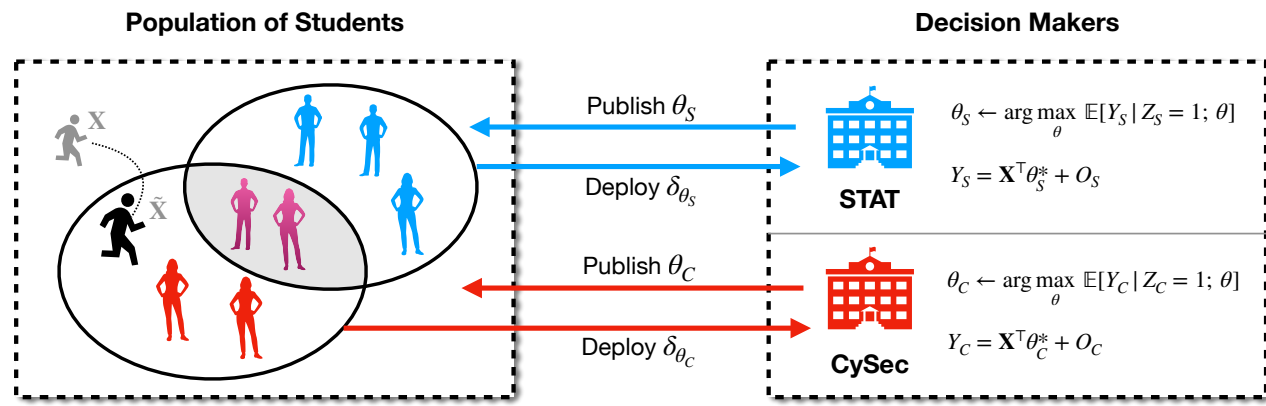
$$\text{College GPA} := \begin{bmatrix} \text{HS GPA} \\ \text{SAT} \end{bmatrix}^\top \begin{bmatrix} 0.9 \\ 0 \end{bmatrix} + \text{Noise}$$

$$\text{Predicted GPA} := \begin{bmatrix} \text{HS GPA} \\ \text{SAT} \end{bmatrix}^\top \begin{bmatrix} 0.7 \\ 0.001 \end{bmatrix}$$

- **Gaming:** Changing SAT affects the prediction but not the true outcome,
- **Genuine Improvement:** Changing HS GPA also affects the true outcome.

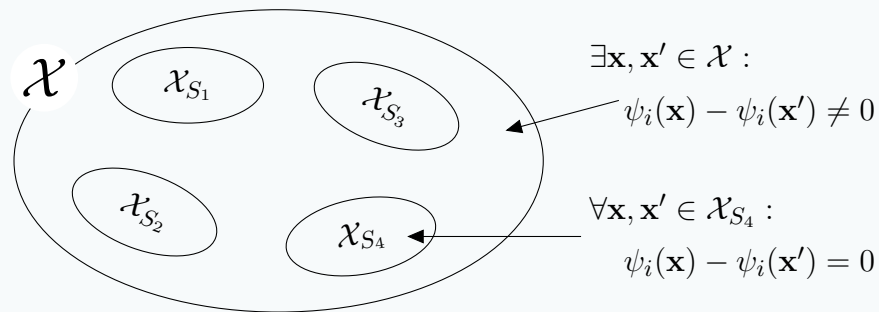
→ Learning the true causal mechanism for better decision making, (and there are complex interactions between decision makers and strategic agents).

2. CSL under Competitive Selection (An Example)



- 2 departments select from the same pool of students,
- They deploy their own selection rules δ_S and δ_C , parameterised by θ_S and θ_C ,
- Each wants to maximise the future GPA of their **own** students,
- Students modify \mathbf{X} to $\tilde{\mathbf{X}}$ to maximise admission chance.

5. Inferring Causal Parameters



$$Y_{it} = \mathbf{X}_t^\top \theta_i^* + \psi_i(\mathbf{X}_t) \Rightarrow \frac{dY_{it}}{d\mathbf{X}_t} = \theta_i^* + \frac{d(\psi_i(\mathbf{X}_t))}{d\mathbf{X}_t} \quad \text{✗} \quad (1)$$

$$\exists \mathcal{X}_S : \Delta Y_{it} = (\Delta \mathbf{X}_t)^\top \theta_i^* + \underbrace{\Delta \psi_i(\mathbf{X}_t)}_{=0} \Rightarrow \frac{d(\Delta Y_{it})}{d(\Delta \mathbf{X}_t)} = \theta_i^* \quad \text{✓} \quad (2)$$

A cooperative protocol for all decision makers to partition $\mathbf{X}_t \mid Z_t$ correctly!

All variables here are conditioned on Z_t , but not shown here for the sake of simplicity.

3. Impact of Competitive Selection

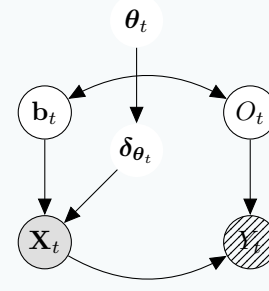


Figure 1: Prior work

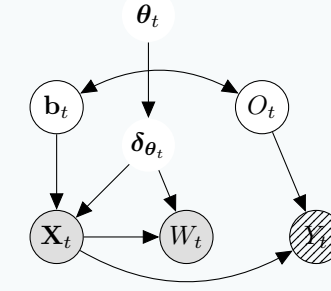


Figure 2: Ours with Selection

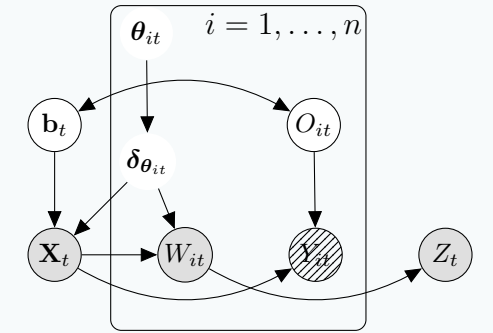


Figure 3: Ours with Competitive Selection

- In Fig. (2),
- cond. dependencies, $\theta_t \not\perp \{b_t, O_t\} \mid W_t \rightarrow$ harder to solve $\max_{\theta_t} \mathbb{E}[Y_t \mid W_t = 1; \theta_t]$;
 - biased data, $\{\theta_t, \mathbf{x}_t, \{y_t \mid w_t = 1\}\}_{t=1}^T \rightarrow$ harder to infer causation.

- In Fig. (3), $p(Y_{jt} \mid Z_t = j)$ depends on $p(Z_t = j \mid \mathbf{X}_t)$ which depends on $\{p(W_{it} \mid \mathbf{X}_t)\}_{i=1}^n \rightarrow$ interference from rival decision makers.

4. An Optimal Solution

Table 1: Our assumptions on agents' behaviour.

	base covariates	strategic response	preference factors	compliance model
is included	✓	✓	✓	✓
is heterogeneous	✓	✗	✗	✗

- We provide:
- the optimal solution for the case where interactions result in a linear function of θ_{it} ,
 - conditions that can be imposed by the government to safeguard social welfare.

$$\begin{aligned} \arg \max_{\theta_{it}} \mathbb{E}[Y_{it} \mid Z_t = i; \theta^{\text{all}}] &= \arg \max_{\theta_{it}} \left\{ \mathbb{E}[\text{Base} \mid Z_t = i; \theta^{\text{all}}] + \mathbb{E}[\text{Improvement} \mid Z_t = i; \theta^{\text{all}}] \right\} \\ &= \arg \max_{\theta_{it}} \left\{ \left(A_i^\top \theta_{it} + B_i + h_i(\theta_t^{\text{all} \setminus i}) \right) + \left(\theta_{it}^\top \gamma_{it} \mathcal{E} \mathcal{E}^\top \theta_i^* + C_i \right) \right\} \\ &= \frac{A_i + \gamma_{it} \mathcal{E} \mathcal{E}^\top \theta_i^*}{\|A_i + \gamma_{it} \mathcal{E} \mathcal{E}^\top \theta_i^*\|} \end{aligned}$$

- Ideally,
- $A_i = k \times \mathcal{E} \mathcal{E}^\top \theta_i^*$ for some $k > 0$,
 - and more...

6. Simulation

