Shanghai Bus Analysis

Load Required Libraries

```
library(ggplot2)
library(knitr)
library(dplyr)
library(reticulate)
library(formatR)
library(sf)
library(raster)
library(ggpubr)
library(jpeg)
library(maps)
library(rnaturalearth)
library(classInt)
library(ggmap)
```

Loading Bus Route Data

Extracting Bus Route Information

```
route1 <- bus_routes %>% filter(Id == 0)
route2 <- bus_routes %>% filter(Id == 1)

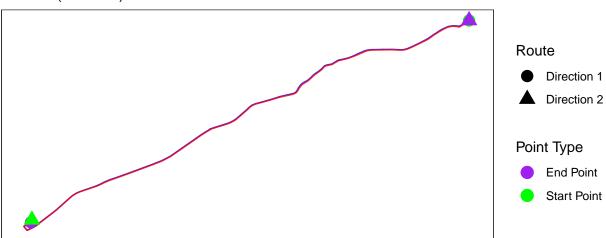
route1_coords <- st_coordinates(route1)[, 1:2]
route2_coords <- st_coordinates(route2)[, 1:2]

route1_start <- route1_coords[1, ] %>% as.numeric()
```

Bus Route Map Visualization

Bus Route 71 - Shanghai

Blue: 71.(.....–.....) Red: 71.(.....–.....)



This map visualization shows the geographic layout of Bus Route 71 in Shanghai, with two different directions shown in blue and red. The route follows a predominantly east-west axis across the city, with start and end points clearly marked.

Route Information Summary

Table 1: Bus Route 71 Information

Direction	Name			Length_km	Num_Points
1	71 (-)	17.56 [km]	180
2	71 (-)	$17.96 [\mathrm{km}]$	234

Loading GPS Bus Data

6

```
busgps_df <- read.csv("busgps.csv", header = FALSE, stringsAsFactors = FALSE)</pre>
colnames(busgps_df) <- c('GPSDateTime', 'LineId', 'LineName', 'NextLevel', 'PrevLevel',</pre>
                         'Strlatlon', 'ToDir', 'VehicleId', 'VehicleNo', 'unknow')
busgps_df$GPSDateTime <- as.POSIXct(busgps_df$GPSDateTime)</pre>
head(busgps df)
##
             GPSDateTime LineId LineName NextLevel PrevLevel
                                                                        Strlatlon
## 1 2019-01-16 23:59:59
                           7100
                                      71
                                               2
                                                          1 121.335413,31.173188
## 2 2019-01-17 00:00:00
                           7100
                                                2
                                                          1 121.334616,31.172271
                                      71
## 3 2019-01-17 00:00:00
                          7100
                                      71
                                               24
                                                          23 121.339955,31.173025
## 4 2019-01-17 00:00:01
                                                         13 121.409491,31.20433
                           7100
                                      71
                                                14
## 5 2019-01-17 00:00:03
                          7100
                                      71
                                                15
                                                        14 121.398615,31.200253
                                                          1 121.334853,31.171997
## 6 2019-01-17 00:00:04
                          7100
                                      71
                                                2
    ToDir VehicleId VehicleNo unknow
        1 D-R7103 Z5A-0021
## 1
## 2
        1 D-R1273
                    Z5A-0002
## 3
        0 D-R5257
                    Z5A-0020
        0 D-R5192
                    Z5A-0013
## 4
## 5
        0 D-T0951
                    Z5A-0022
                                  1
```

Updating Chinese Route Names to English

Z5A-0001

1

1 D-R6089

```
route_info <- data.frame(
    direction = c(direction1_name, direction2_name),
    start_station = c(" ", " "),
    end_station = c(" ", " "),
    route_id = c(0, 1))

knitr::kable(route_info, caption = "Original Chinese Station and Direction Names")</pre>
```

Table 2: Original Chinese Station and Direction Names

direction	start_station	end_station	route_id
71 (-)			0
71 (-)			1

Table 3: Updated English Station and Direction Names

direction	start_station	end_station	route_id	direction_en
71 (-)	Yanan Road Station	Shenkun Station	0	Yanan Road-Shenkun
71 (-)	Shenkun Station	Yanan Road Station	1	Shenkun-Yanan Road

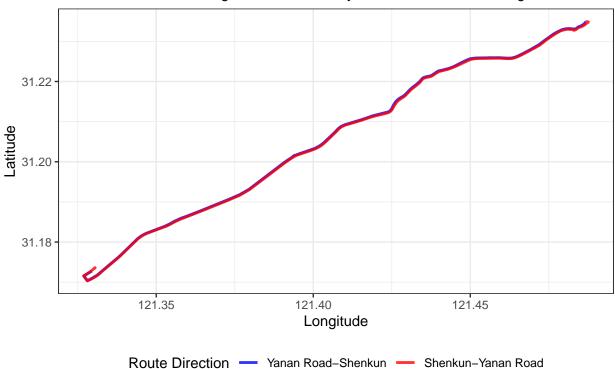
```
direction1_name_en <- route_info$direction_en[1]
direction2_name_en <- route_info$direction_en[2]</pre>
```

Comparison of Inbound and Outbound Routes

```
route1_df <- data.frame(st_coordinates(route1)[, 1:2]) %>%
  mutate(route = "Direction 1", point_id = 1:n())
route2_df <- data.frame(st_coordinates(route2)[, 1:2]) %>%
  mutate(route = "Direction 2", point_id = 1:n())
combined_routes <- bind_rows(route1_df, route2_df)</pre>
ggplot(combined_routes, aes(x = X, y = Y, color = route)) +
  geom_path(size = 1, alpha = 0.8) +
  theme bw() +
  scale_color_manual(values = c("Direction 1" = "blue", "Direction 2" = "red"),
                    labels = c(direction1_name_en, direction2_name_en)) +
  labs(title = "Bus Route 71 - Comparison of Inbound and Outbound Routes",
    subtitle = "Areas where routes diverge indicate one-way streets or different routing",
           x = "Longitude",
           y = "Latitude",
       color = "Route Direction") +
  theme(legend.position = "bottom")
```

```
## Warning: Using `size` aesthetic for lines was deprecated in ggplot2 3.4.0.
## i Please use `linewidth` instead.
## This warning is displayed once every 8 hours.
## Call `lifecycle::last_lifecycle_warnings()` to see where this warning was
## generated.
```

Bus Route 71 – Comparison of Inbound and Outbound Routes Areas where routes diverge indicate one–way streets or different routing



This visualization compares the inbound and outbound routes of Bus 71, highlighting areas where the two directions diverge. The report indicates this comparison helps identify one-way streets and routing differences between the Yanan Road-Shenkun and Shenkun-Yanan Road directions.

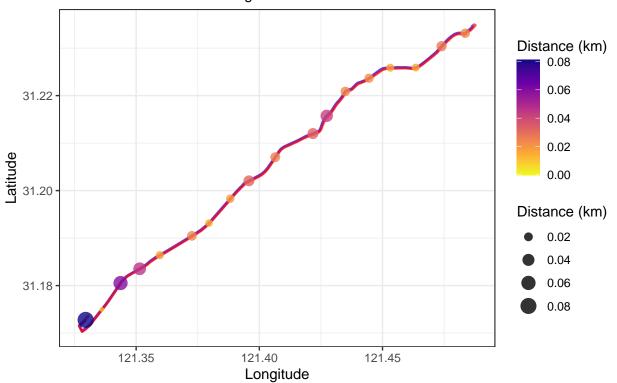
Route Divergence Analysis

Route Segment Divergence Visualization

```
ggplot() +
  geom_path(data = route1_df, aes(x = X, y = Y), color = "blue", size = 1, alpha = 0.7) +
  geom_path(data = route2_df, aes(x = X, y = Y), color = "red", size = 1, alpha = 0.7) +
  geom_point(data = route1_closest,
             aes(x = X, y = Y, color = dist_km, size = dist_km),
             alpha = 0.8) +
  scale_color_viridis_c("Distance (km)",
                       option = "plasma",
                       direction = -1,
                       limits = c(0, max(route1_closest$dist_km))) +
  scale_size_continuous("Distance (km)",
                       range = c(1, 5)) +
  theme bw() +
  labs(title = "Bus Route 71 - Route Segment Divergence",
    subtitle = paste("Points show how far each segment of the", direction1_name_en, "route is from the"
           x = "Longitude",
           y = "Latitude") +
  guides(color = guide_colorbar(title.position = "top"),
          size = guide_legend(title.position = "top"))
```

Bus Route 71 - Route Segment Divergence

Points show how far each segment of the Yanan Road-Shenkun route is from the Shen

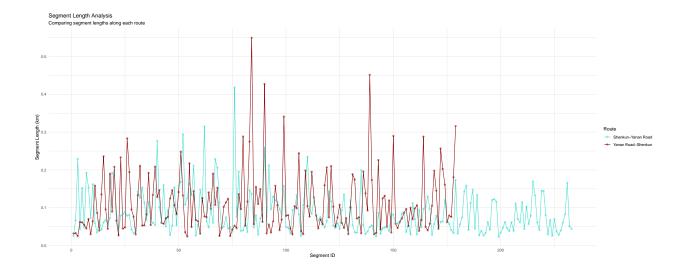


This visualization in Figure 17 of the report analyzes the divergence of Bus Route 71 from the Yanan Road path, with larger and darker points indicating greater distances from the reference

path. Most significant divergences are in the southwestern part of the route, while points become smaller and lighter as the route continues northeast.

Segment Length Analysis

```
calculate segment properties <- function(route df) {</pre>
  segments <- route_df %>%
    mutate(
      next_X = lead(X),
      next_Y = lead(Y),
      segment_length = sqrt((next_X - X)^2 + (next_Y - Y)^2) * 111.32,
      segment_direction = atan2(next_Y - Y, next_X - X) * 180/pi,
      segment_direction = ifelse(segment_direction < 0, segment_direction + 360, segment_direction)</pre>
    ) %>%
    filter(!is.na(segment_length))
  return(segments)}
route1_segments <- calculate_segment_properties(route1_df) %>%
  mutate(route = direction1_name_en,
         segment_id = row_number(),
         cumulative_distance = cumsum(segment_length))
route2_segments <- calculate_segment_properties(route2_df) %>%
  mutate(route = direction2_name_en,
         segment_id = row_number(),
         cumulative_distance = cumsum(segment_length))
all_segments <- bind_rows(route1_segments, route2_segments)</pre>
ggplot(all_segments, aes(x = segment_id, y = segment_length, color = route)) +
  geom_line() +
  geom_point(alpha = 0.5) +
  scale_color_manual(values = c("turquoise", "darkred")) +
  theme_minimal() +
  labs(
    title = "Segment Length Analysis",
    subtitle = "Comparing segment lengths along each route",
    x = "Segment ID",
    y = "Segment Length (km)",
    color = "Route"
```



This graph shown in Figure 18 compares segment lengths between the Shenkun-Yanan Road and Yanan Road-Shenkun routes. The report notes that segment lengths vary significantly and asymmetrically between directions, with the Yanan Road-Shenkun route (brown line) showing greater variability and higher peaks, while the Shenkun-Yanan Road route (cyan line) has shorter, more consistent segments.

Turn Analysis by Route

```
direction_changes <- all_segments %>%
  group by(route) %>%
  mutate(
    prev_direction = lag(segment_direction),
    turn_angle = abs(((segment_direction - prev_direction + 180) %% 360) - 180),
    significant_turn = turn_angle > 25
  ) %>%
  filter(!is.na(turn_angle))
turn_summary <- direction_changes %>%
  group_by(route) %>%
  summarize(
    total_turns = n(),
    significant_turns = sum(significant_turn),
    avg_turn_angle = mean(turn_angle),
    max_turn_angle = max(turn_angle)
  )
knitr::kable(turn_summary, caption = "Turn Analysis by Route")
```

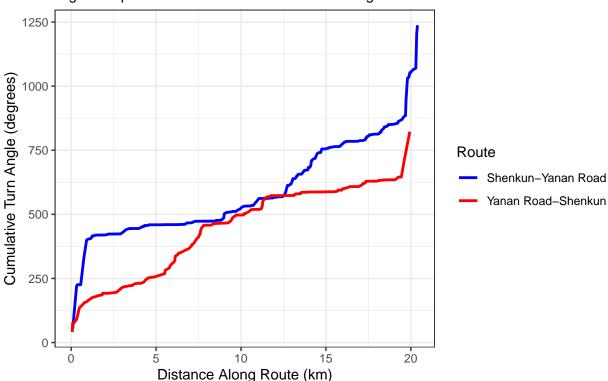
Table 4: Turn Analysis by Route

route	total_turns	significant_turns	avg_turn_angle	max_turn_angle
Shenkun-Yanan Road	232	8	5.334342	166.1686
Yanan Road-Shenkun	178	4	4.620225	108.7062

Cumulative Turn Analysis

Cumulative Turn Analysis

Higher slopes indicate sections with more turning



According to Figure 19(a) in the report, this analysis shows that the Shenkun-Yanan Road direction has a higher cumulative turn angle (exceeding 1200°) compared to the Yanan-Shenkun direction (under 850°). This suggests that the Shenkun-Yanan route has more frequent and sharper turns, potentially leading to slower travel times.

Travel Time Estimation Model

```
estimate_segment_speeds <- function(segments_df) {</pre>
  segments_df %>%
    group_by(route) %>%
    mutate(
      prev_direction = lag(segment_direction),
      turn_angle = if_else(is.na(prev_direction), 0,
                          abs(((segment_direction - prev_direction + 180) %% 360) - 180)),
      segment speed kmh = case when(
        turn_angle > 45 ~ 10,
        turn_angle > 30 ~ 15,
        turn_angle > 15 ~ 20,
        TRUE ~ 25
      ),
      segment_time_min = (segment_length / segment_speed_kmh) * 60,
      cumulative_time_min = cumsum(segment_time_min)
    ) %>%
    ungroup()
}
route1_timed <- estimate_segment_speeds(route1_segments)</pre>
route2_timed <- estimate_segment_speeds(route2_segments)</pre>
all_timed_segments <- bind_rows(route1_timed, route2_timed)</pre>
```

Estimated Travel Time Visualization

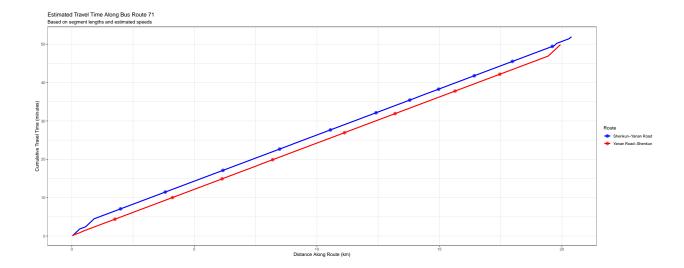
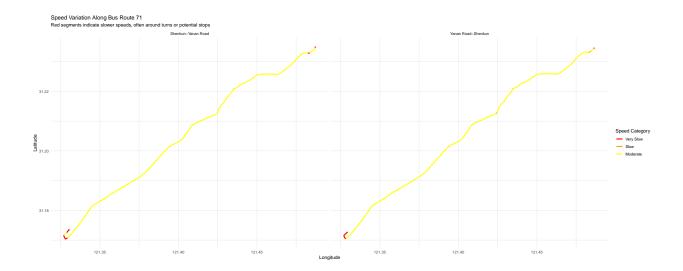


Figure 19(b) shows the estimated travel time along both directions. The report indicates that the Shenkun-Yanan Road direction has a longer estimated travel time (over 52 minutes) compared to the Yanan-Shenkun direction (around 51 minutes). While the absolute difference is small, it's consistent throughout the route, suggesting that route geometry and turns impact service time.

Speed Variation Map

```
slow_threshold <- 20</pre>
segment_map_data <- all_timed_segments %>%
  dplyr::select(X, Y, next_X, next_Y, segment_speed_kmh, route) %>%
  mutate(speed_category = cut(segment_speed_kmh,
                             breaks = c(0, 15, 20, 25, Inf),
                             labels = c("Very Slow", "Slow", "Moderate", "Normal")))
ggplot() +
  geom_segment(data = segment_map_data,
               aes(x = X, y = Y, xend = next_X, yend = next_Y,
                   color = speed_category),
               size = 1.2) +
  scale_color_manual(values = c("Very Slow" = "red", "Slow" = "orange",
                               "Moderate" = "yellow", "Normal" = "green")) +
  facet_wrap(~ route) +
  theme minimal() +
  labs(
   title = "Speed Variation Along Bus Route 71",
   subtitle = "Red segments indicate slower speeds, often around turns or potential stops",
   x = "Longitude",
   y = "Latitude",
   color = "Speed Category"
```



Key Points Analysis

```
sample_interval_km <- 1</pre>
extract_key_points <- function(route_df, interval_km = 1) {</pre>
  route_df$cum_dist <- c(0, cumsum(sqrt(diff(route_df$X)^2 + diff(route_df$Y)^2))) * 111.32
 max_dist <- max(route_df$cum_dist)</pre>
 target_dists <- seq(0, max_dist, by = interval_km)</pre>
  key_points <- data.frame(</pre>
    target_dist_km = target_dists,
    point_idx = numeric(length(target_dists)),
    stringsAsFactors = FALSE)
  for(i in 1:length(target_dists)) {
    key_points$point_idx[i] <- which.min(abs(route_df$cum_dist - target_dists[i]))</pre>
  }
 result <- route_df[key_points$point_idx, ] %>%
    mutate(key point id = row number(),
           key_point_label = paste0(round(cum_dist), " km"))
  return(result)
}
route1_key_points <- extract_key_points(route1_df, sample_interval_km)</pre>
route2_key_points <- extract_key_points(route2_df, sample_interval_km)</pre>
ggplot() +
  geom_path(data = route1_df, aes(x = X, y = Y), color = "blue", alpha = 0.5) +
  geom_path(data = route2_df, aes(x = X, y = Y), color = "darkred", alpha = 0.5) +
  geom_point(data = route1_key_points, aes(x = X, y = Y), color = "blue", size = 3) +
  geom_text(data = route1_key_points, aes(x = X, y = Y, label = key_point_label),
            color = "darkblue", vjust = -1.5, size = 3) +
```

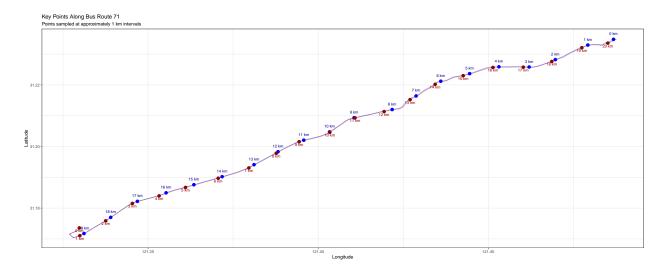


Figure 20 in the report shows key points along Bus Route 71 spaced at 1 km intervals. This visualization helps identify deviations, overlaps, and directional symmetry in the route, which is useful for transport planning and optimization.

Distance Matrix Calculation

```
calculate_distance_matrix <- function(points_df) {</pre>
  n <- nrow(points_df)</pre>
  dist_matrix <- matrix(0, nrow = n, ncol = n)</pre>
  for(i in 1:n) {
    for(j in 1:n) {
      if(i != j) {
         dist_matrix[i, j] <- sqrt(</pre>
           (points_df\$X[i] - points_df\$X[j])^2 +
           (points_df\(^Y[i] - points_df\(^Y[j])^2\)
         ) * 111.32
      }
    }
  }
  rownames(dist_matrix) <- points_df$key_point_label</pre>
  colnames(dist_matrix) <- points_df$key_point_label</pre>
  return(dist_matrix)
}
```

```
route1_dist_matrix <- calculate_distance_matrix(route1_key_points)
route2_dist_matrix <- calculate_distance_matrix(route2_key_points)

route1_dist_long <- as.data.frame(as.table(route1_dist_matrix)) %>%
    rename(from = Var1, to = Var2, distance_km = Freq)
```

Distance Matrix Visualization

Distance Matrix Between Key Points – Yanan Road–Shenkun Colors indicate the distance (km) between any two points along the route

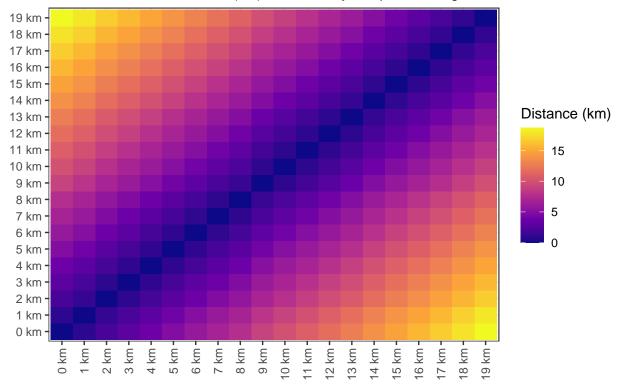


Figure 21 displays a distance matrix between key points along Bus Route 71. The matrix shows pairwise distances between points spaced every 1 km along the route. This visualization helps identify patterns of linearity and irregularity in the route, useful for understanding its spatial structure and finding opportunities for optimization.

Speed Analysis Along Route

```
ggplot(all_timed_segments, aes(x = cumulative_distance, y = segment_speed_kmh, color = route)) +
    geom_line() +
    geom_point(alpha = 0.5) +
    scale_color_manual(values = c("blue", "red")) +
    theme_bw() +
    labs(
        title = "Estimated Speeds Along Bus Route 71",
        subtitle = "Showing how speed varies based on segment characteristics",
        x = "Distance Along Route (km)",
        y = "Speed (km/h)",
        color = "Route")
```

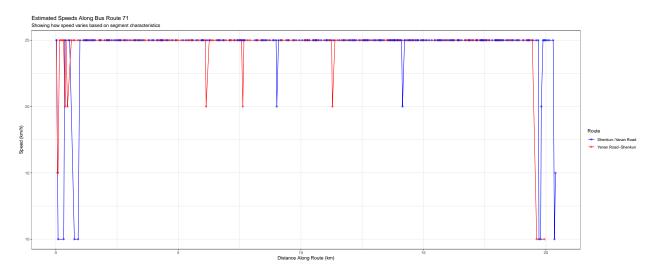


Figure 22 shows estimated speeds along both directions of Bus Route 71. Most segments operate near the maximum speed (25 km/h), but some drop to 10-15 km/h, particularly near the route ends. This suggests areas with signal delays, congestion, or complex intersections.

Travel Time Summary and Route with Time Markers

```
segments_df %>%
      group_by(route) %>%
      mutate(
        prev_direction = lag(segment_direction),
        turn_angle = if_else(is.na(prev_direction), 0,
                           abs(((segment_direction - prev_direction + 180) %% 360) - 180)),
        segment speed kmh = case when(
          turn_angle > 45 ~ 10,
          turn_angle > 30 ~ 15,
          turn_angle > 15 ~ 20,
          TRUE ~ 25
        ),
        segment_time_min = (segment_length / segment_speed_kmh) * 60,
        cumulative_time_min = cumsum(segment_time_min)) %>%
      ungroup()
  all_timed_segments <- estimate_segment_speeds(all_segments)</pre>
route_time_summary <- all_timed_segments %>%
  group_by(route) %>%
  summarize(total distance km = max(cumulative distance),
               total_time_min = max(cumulative_time_min),
                avg_speed_kmh = total_distance_km / (total_time_min / 60),
            min_segment_speed = min(segment_speed_kmh),
            max_segment_speed = max(segment_speed_kmh))
knitr::kable(route_time_summary, caption = "Estimated Travel Time Summary", digits = 2)
```

Table 5: Estimated Travel Time Summary

distancekmtotal	$$ time $_$ minavg $_$	_speedkm m in_	_segment_speemalax_s	segment_speed
20.39	51.91	23.57	10	25
19.94	49.88	23.98	10	25
	20.39	20.39 51.91	20.39 51.91 23.57	

```
find_time_markers <- function(route_data) {
  target_times <- seq(5, max(route_data$cumulative_time_min), by = 5)

result <- data.frame()

for(target_time in target_times) {
  idx <- which.min(abs(route_data$cumulative_time_min - target_time))

marker <- route_data[idx, ] %>%
  mutate(time_marker = paste0(round(cumulative_time_min), " min"))

result <- bind_rows(result, marker)</pre>
```

```
}
 return(result)
}
time_markers <- all_timed_segments %>%
  split(.$route) %>%
  lapply(find_time_markers) %>%
  bind_rows()
ggplot() +
  geom_path(data = route1_df, aes(x = X, y = Y), color = "blue", alpha = 0.5, size = 0.8) +
  geom_path(data = route2_df, aes(x = X, y = Y), color = "red", alpha = 0.5, size = 0.8) +
  geom_point(data = time_markers, aes(x = X, y = Y, color = route), size = 3) +
  geom_text(data = time_markers, aes(x = X, y = Y, label = time_marker, color = route),
            vjust = -1.5, size = 3) +
  scale_color_manual(values = c("blue", "red")) +
  theme_minimal() +
  labs(
   title = "Bus Route 71 with Time Markers",
    subtitle = "Estimated travel time markers at 5-minute intervals",
   x = "Longitude",
   y = "Latitude",
    color = "Route"
```

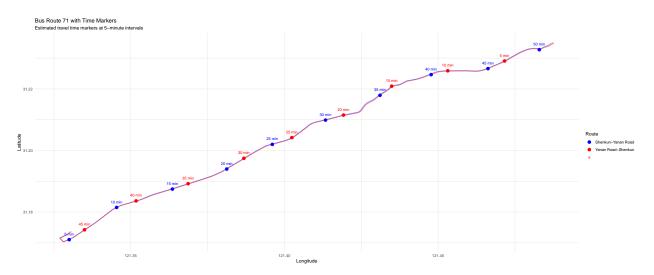


Figure 23 shows estimated travel times mapped along both directions of Route 71, with time markers at 5-minute intervals. The report notes that both directions follow similar paths, but time markers indicate non-uniform travel times across segments, highlighting directional inefficiencies that could be targets for optimization.

Segment Length Distribution by Route

```
ggplot(all_segments, aes(x = route, y = segment_length, fill = route)) +
  geom_boxplot() +
  scale_fill_manual(values = c("turquoise", "yellow")) +
  theme_bw() +
  labs(
    title = "Distribution of Segment Lengths by Route",
    subtitle = "Comparing segment length characteristics between routes",
    x = "Route",
    y = "Segment Length (km)",
    fill = "Route"
  ) +
  theme(legend.position = "none")
```

Distribution of Segment Lengths by Route Comparing segment length characteristics between routes

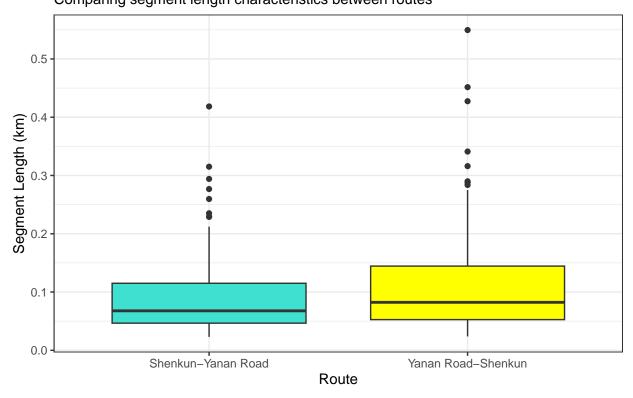


Figure 24 compares the distribution of segment lengths for both directions. The Shenkun-Yanan Road direction (turquoise) shows more uniform segment lengths with a lower median, while the Yanan-Shenkun Road direction (yellow) has greater variability and a higher median segment length. This asymmetry suggests differences in operational segmentation.

Speed Category Distribution by Route

```
ggplot(segment_map_data, aes(x = route, fill = speed_category)) +
geom_bar(position = "fill") +
```

Proportion of Speed Categories by Route

Comparing the distribution of speed segments between routes

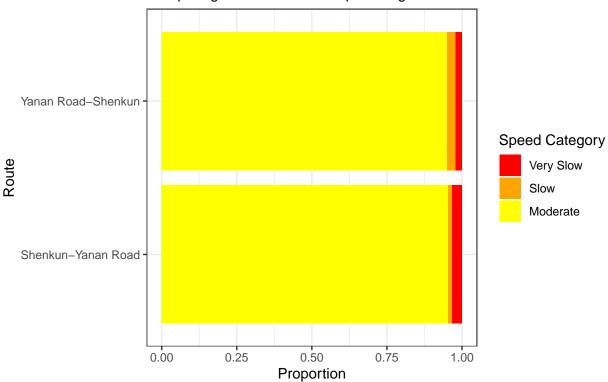


Figure 25 shows the proportion of speed categories along both directions. Moderate speeds (yellow) dominate both directions, but the Yanan-Shenkun direction has slightly more segments in the Slow and Very Slow categories, suggesting occasional congestion or operational issues like passenger boarding delays.

Vehicle ID Mapping

```
busgps_df <- busgps_df %>%
  mutate(jp_vehicleID = VehicleId) %>%
  group_by(VehicleId) %>%
  mutate(temp_id = cur_group_id()) %>%
  ungroup() %>%
  mutate(VehicleId = paste0("Vehicle_", temp_id)) %>%
```

```
subset(select = -temp_id)

vehicle_id_cols <- c("VehicleId", "jp_vehicleID")
vehicle_id_mapping <- unique(busgps_df[, vehicle_id_cols])
vehicle_id_mapping <- vehicle_id_mapping[order(vehicle_id_mapping$VehicleId), ]

knitr::kable(vehicle_id_mapping, caption = "Vehicle ID Mapping Reference")</pre>
```

Table 6: Vehicle ID Mapping Reference

VehicleId	jp_vehicleID
Vehicle_1	D-98307
$Vehicle_10$	D-R2773
$Vehicle_11$	D-R3531
$Vehicle_12$	D-R3571
$Vehicle_13$	D-R5192
$Vehicle_14$	D-R5257
$Vehicle_15$	D-R5627
$Vehicle_16$	D-R6025
$Vehicle_17$	D-R6051
$Vehicle_18$	D-R6079
$Vehicle_19$	D-R6089
$Vehicle_2$	D-R0725
$Vehicle_20$	D-R6573
$Vehicle_21$	D-R6679
$Vehicle_22$	D-R7103
$Vehicle_23$	D-R7162
$Vehicle_24$	D-R7165
$Vehicle_25$	D-R7265
$Vehicle_26$	D-R7506
$Vehicle_27$	D-R7537
$Vehicle_28$	D-R7622
$Vehicle_29$	D-R7667
$Vehicle_3$	D-R0937
$Vehicle_30$	D-R7673
$Vehicle_31$	D-R7689
$Vehicle_32$	D-R7715
$Vehicle_33$	D-R7920
$Vehicle_34$	D-R8357
$Vehicle_35$	D-S3726
$Vehicle_36$	D-S8053
$Vehicle_37$	D-T0951
$Vehicle_38$	D-T0971
$Vehicle_39$	D-T7031
$Vehicle_4$	D-R1137
$Vehicle_40$	D-T7051
$Vehicle_41$	D-T9651
$Vehicle_5$	D-R1273
$Vehicle_6$	D-R1530
$Vehicle_7$	D-R2192
$Vehicle_8$	D-R2311

VehicleId	jp_vehicleID
Vehicle_9	D-R2313

Vehicle Activity Distribution

```
busgps_df <- busgps_df %>%
  mutate(
    coordinates = strsplit(as.character(Strlatlon), ","),
    latitude = as.numeric(sapply(coordinates, function(x) x[1])),
    longitude = as.numeric(sapply(coordinates, function(x) x[2])))
vehicle_activity <- busgps_df %>%
  count(VehicleId) %>%
  arrange(desc(n))
ggplot(vehicle_activity, aes(x = reorder(VehicleId, -n), y = n)) +
  geom_bar(stat = "identity", fill = "steelblue") +
  theme_bw() +
  theme(axis.text.x = element_text(angle = 90, hjust = 1)) +
  labs(
    title = "Vehicle Activity Distribution",
    subtitle = "Number of GPS records per vehicle",
    x = "Vehicle ID",
    y = "Number of GPS Records"
```

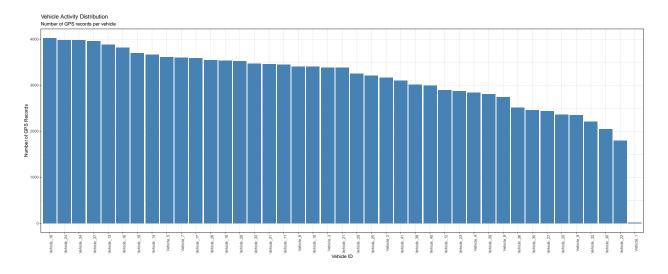


Figure 26 shows the distribution of GPS records across vehicles. Most vehicles show high activity levels (3,000-4,000 records), with a few showing significantly lower counts. This helps identify consistently active vehicles versus those that may have malfunctioning GPS devices or limited service periods.

Vehicle Activity by Hour of Day

```
busgps_df <- busgps_df %>%
  mutate(hour_of_day = as.numeric(format(GPSDateTime, "%H")))
hourly_activity <- busgps_df %>%
  count(VehicleId, hour_of_day) %>%
  filter(VehicleId %in% head(vehicle_activity$VehicleId, 10))

ggplot(hourly_activity, aes(x = hour_of_day, y = VehicleId, fill = n)) +
  geom_tile() +
  scale_fill_viridis_c("Number of Records", option = "plasma") +
  theme_bw() +
  labs(
    title = "Vehicle Activity by Hour of Day",
    subtitle = "Shows when each vehicle is most active",
    x = "Hour of Day (24-hour format)",
    y = "Vehicle ID") +
  scale_x_continuous(breaks = 0:23)
```

Vehicle Activity by Hour of Day Shows when each vehicle is most active

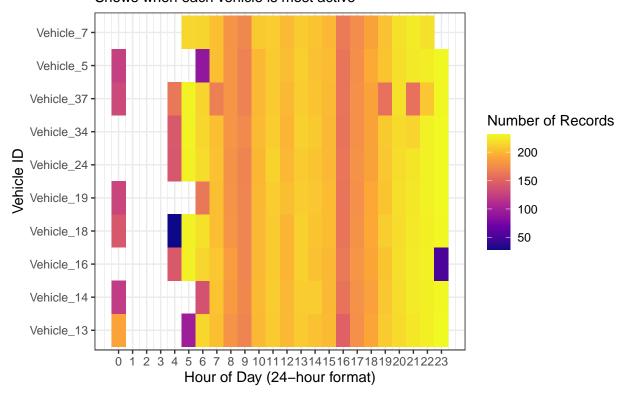


Figure 27 is a heatmap showing hourly activity for the ten most active vehicles. Peak activity occurs between 6-10 AM and during late afternoon hours. Most vehicles show minimal activity from midnight to 5 AM, matching the expected service patterns with morning and evening rush hours being the busiest periods.

Vehicle Speed Analysis

```
vehicle_speed <- busgps_df %>%
  arrange(VehicleId, GPSDateTime) %>%
  group_by(VehicleId) %>%
  mutate(prev_lat = lag(latitude),
         prev_lon = lag(longitude),
        prev_time = lag(GPSDateTime),
   dist_km = ifelse(!is.na(prev_lat),
                    sqrt((longitude - prev_lon)^2 + (latitude - prev_lat)^2) * 111.32,
                    NA).
   time_diff_hours = as.numeric(difftime(GPSDateTime, prev_time, units = "hours")),
   speed_kmh = ifelse(!is.na(time_diff_hours) & time_diff_hours > 0 & time_diff_hours < 0.1,</pre>
                      dist km / time diff hours, NA)) %>%
  filter(!is.na(speed_kmh) & speed_kmh < 100)</pre>
ggplot(vehicle_speed, aes(x = reorder(VehicleId, speed_kmh, FUN = median), y = speed_kmh)) +
  geom_boxplot(fill = "turquoise") +
  theme_bw() +
  theme(axis.text.x = element_text(angle = 90, hjust = 1)) +
  labs(
   title = "Distribution of Vehicle Speeds",
   subtitle = "Comparing operating speeds across different vehicles",
   x = "Vehicle ID",
   y = "Speed (km/h)") +
  coord_cartesian(ylim = c(0, 60))
```

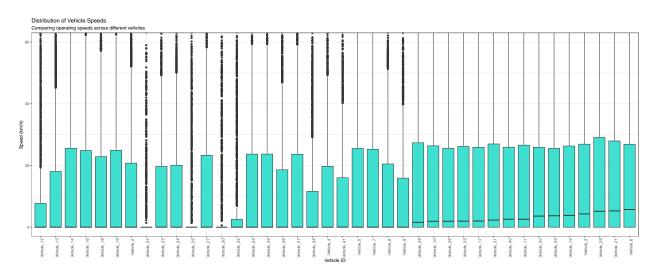


Figure 28 shows speed distributions for various vehicles. The report notes that some vehicles (like D-R2313 and D-R71745) have very low median speeds, while others (D-R1137, D-R2192, D-R6025) maintain higher, more consistent speeds. This helps identify potential mechanical issues or route-specific constraints affecting vehicle performance.

Direction Distribution by Vehicle

```
direction_by_vehicle <- busgps_df %>%
    count(VehicleId, ToDir) %>%
    group_by(VehicleId) %>%
    mutate(proportion = n / sum(n))

ggplot(direction_by_vehicle, aes(x = VehicleId, y = proportion, fill = factor(ToDir))) +
    geom_bar(stat = "identity") +
    scale_fill_brewer(palette = "Set1", name = "Direction") +
    theme_bw() +
    theme(axis.text.x = element_text(angle = 90, hjust = 1)) +
    labs(
        title = "Direction Distribution by Vehicle",
        subtitle = "Shows whether vehicles serve specific directions or both",
        x = "Vehicle ID",
        y = "Proportion of Records"
    )
```

Direction Distribution by Vehicle

Shows whether vehicles serve specific directions or both

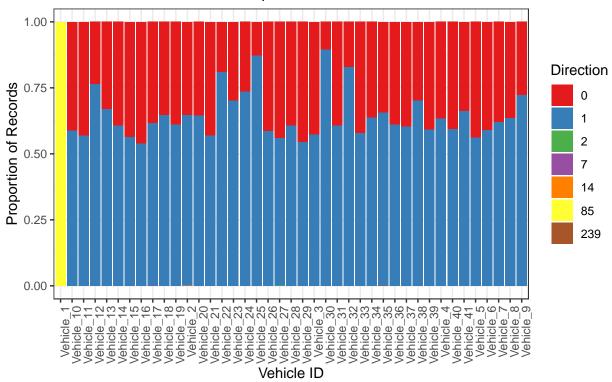


Figure 29 shows how vehicles are distributed across route directions. Most vehicles serve two main directions (0 and 1), likely representing inbound and outbound routes. Some vehicles are evenly split between directions, while others are predominantly assigned to one direction. The graph also reveals some anomalous direction codes that may indicate data issues.

Vehicle Dwell Time Analysis

```
dwell_analysis <- vehicle_speed %>%
 mutate(
   is_stationary = speed_kmh < 3 & !is.na(speed_kmh),</pre>
   dwell_group = cumsum(c(1, diff(as.numeric(is_stationary)) != 0))
 filter(is_stationary) %>%
  group_by(VehicleId, dwell_group) %>%
  summarize(
   dwell_time_min = as.numeric(difftime(max(GPSDateTime), min(GPSDateTime), units = "mins")),
   avg_latitude = mean(latitude),
   avg_longitude = mean(longitude),
    .groups = "drop"
 ) %>%
 filter(dwell_time_min > 1)
ggplot(dwell_analysis, aes(x = reorder(VehicleId, dwell_time_min, FUN = median), y = dwell_time_min)) +
  geom_boxplot(fill = "lightgreen") +
  theme_bw() +
  theme(axis.text.x = element_text(angle = 90, hjust = 1)) +
 labs(
   title = "Vehicle Dwell Time Analysis",
   subtitle = "Time spent stopped at locations (potential bus stops or traffic)",
   x = "Vehicle ID",
   y = "Dwell Time (minutes)"
  coord_cartesian(ylim = c(0, 15))
```

Vehicle Dwell Time Analysis

Time spent stopped at locations (potential bus stops or traffic)

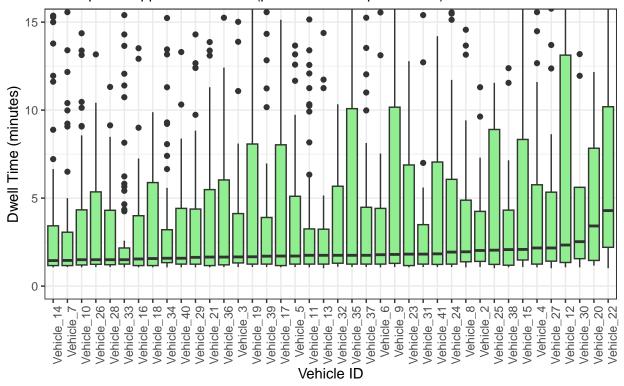


Figure 30 shows the dwell time distribution for each vehicle, revealing how long buses remain stationary at specific locations. The report indicates that longer dwell times may suggest high passenger activity or traffic congestion, while frequent extended stops could indicate high-demand areas that may need service adjustments.

Turn Analysis by Route

```
# Analyze the directional changes along the routes
# Calculate turn angles between segments
direction_changes <- all_segments %>%
  group_by(route) %>%
  mutate(
   prev_direction = lag(segment_direction),
   turn_angle = abs(((segment_direction - prev_direction + 180) %% 360) - 180),
    significant_turn = turn_angle > 25 # Define significant turns as >25 degrees
  ) %>%
  filter(!is.na(turn_angle))
# Count the number of significant turns on each route
turn_summary <- direction_changes %>%
  group_by(route) %>%
  summarize(
   total turns = n(),
    significant_turns = sum(significant_turn),
```

```
avg_turn_angle = mean(turn_angle),
    max_turn_angle = max(turn_angle)
)

# Display the turn summary
knitr::kable(turn_summary, caption = "Turn Analysis by Route")
```

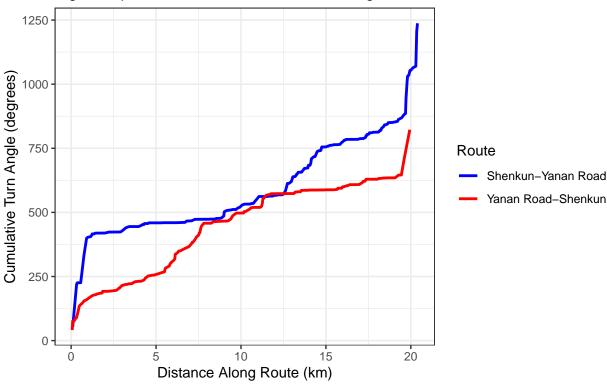
Table 7: Turn Analysis by Route

route	total_turns	significant_turns	avg_turn_angle	max_turn_angle
Shenkun-Yanan Road	232	8	5.334342	166.1686
Yanan Road-Shenkun	178	4	4.620225	108.7062

Cumulative Turn Analysis

Cumulative Turn Analysis

Higher slopes indicate sections with more turning



According to Figure 19(a) in the report, this analysis shows that the Shenkun-Yanan Road direction has a higher cumulative turn angle (exceeding 1200°) compared to the Yanan-Shenkun direction (under 850°). This suggests that the Shenkun-Yanan route has more frequent and sharper turns, potentially leading to slower travel times.

Travel Time Estimation Model

```
segment_speed_kmh = case_when(
        turn_angle > 45 ~ 10, # Very sharp turns: 10 km/h
        turn_angle > 30 ~ 15, # Sharp turns: 15 km/h
        turn_angle > 15 ~ 20, # Moderate turns: 20 km/h
        TRUE ~ 25
                               # Straight segments: 25 km/h
      ),
      # Calculate time for each segment (in minutes)
      segment_time_min = (segment_length / segment_speed_kmh) * 60,
      # Calculate cumulative time
      cumulative_time_min = cumsum(segment_time_min)
    ) %>%
    ungroup()
}
# Apply the speed model to both routes
route1_timed <- estimate_segment_speeds(route1_segments)</pre>
route2_timed <- estimate_segment_speeds(route2_segments)</pre>
# Combine the timed routes
all_timed_segments <- bind_rows(route1_timed, route2_timed)</pre>
```

Estimated Travel Time Visualization

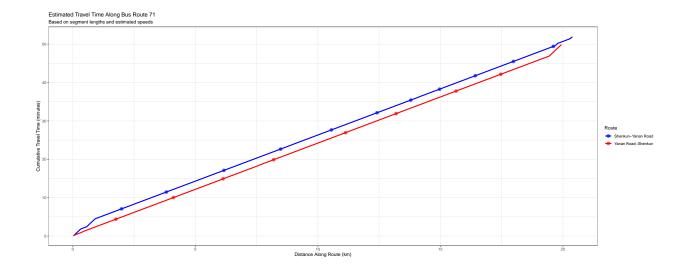
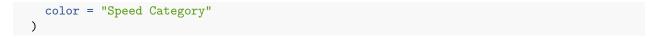
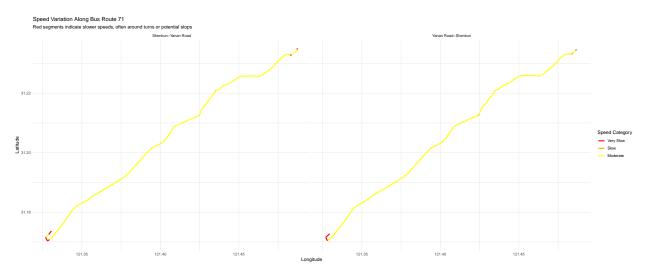


Figure 19(b) shows the estimated travel time along both directions. The report indicates that the Shenkun-Yanan Road direction has a longer estimated travel time (over 52 minutes) compared to the Yanan-Shenkun direction (around 51 minutes). While the absolute difference is small, it's consistent throughout the route, suggesting that route geometry and turns impact service time.

Speed Variation Map

```
slow_threshold <- 20 # km/h</pre>
# Create segment mapping dataset
segment_map_data <- all_timed_segments %>%
  dplyr::select(X, Y, next_X, next_Y, segment_speed_kmh, route) %>%
  mutate(speed_category = cut(segment_speed_kmh,
                             breaks = c(0, 15, 20, 25, Inf),
                             labels = c("Very Slow", "Slow", "Moderate", "Normal")))
# Create map showing speed variation along the routes
ggplot() +
  # Draw segments colored by speed
  geom_segment(data = segment_map_data,
               aes(x = X, y = Y, xend = next_X, yend = next_Y,
                   color = speed_category),
               size = 1.2) +
  # Color scale for speeds
  scale_color_manual(values = c("Very Slow" = "red", "Slow" = "orange",
                               "Moderate" = "yellow", "Normal" = "green")) +
  # Facet by route
  facet_wrap(~ route) +
  theme minimal() +
  labs(
   title = "Speed Variation Along Bus Route 71",
   subtitle = "Red segments indicate slower speeds, often around turns or potential stops",
   x = "Longitude",
   y = "Latitude",
```





Key Points Analysis

```
#### sample_interval_km can be user input in shiny
# Distance Matrix Analysis
# Identify key points along the route (e.g., every 1km)
# and calculate distances between them
# Create a set of key points along each route
sample_interval_km <- 1 # Sample points approximately every 1km</pre>
# Function to extract key points at regular distance intervals
extract key points <- function(route df, interval km = 1) {</pre>
  # Calculate cumulative distance
 route_df$cum_dist <- c(0, cumsum(sqrt(diff(route_df$X)^2 + diff(route_df$Y)^2))) * 111.32
  # Define target distances
 max_dist <- max(route_df$cum_dist)</pre>
  target_dists <- seq(0, max_dist, by = interval_km)</pre>
  # For each target distance, find the closest point
  key_points <- data.frame(</pre>
    target_dist_km = target_dists,
    point_idx = numeric(length(target_dists)),
    stringsAsFactors = FALSE)
  for(i in 1:length(target_dists)) {
    key_points$point_idx[i] <- which.min(abs(route_df$cum_dist - target_dists[i]))</pre>
  # Extract the key points
```

```
result <- route_df[key_points$point_idx, ] %>%
    mutate(key_point_id = row_number(),
           key_point_label = paste0(round(cum_dist), " km"))
  return(result)
# Extract key points from both routes
route1_key_points <- extract_key_points(route1_df, sample_interval_km)</pre>
route2_key_points <- extract_key_points(route2_df, sample_interval_km)</pre>
# Visualize the key points on the map
ggplot() +
  # Base routes
  geom_path(data = route1_df, aes(x = X, y = Y), color = "blue", alpha = 0.5) +
  geom_path(data = route2_df, aes(x = X, y = Y), color = "darkred", alpha = 0.5) +
  # Key points
  geom_point(data = route1_key_points, aes(x = X, y = Y), color = "blue", size = 3) +
  geom_text(data = route1_key_points, aes(x = X, y = Y, label = key_point_label),
            color = "darkblue", vjust = -1.5, size = 3) +
  geom_point(data = route2_key_points, aes(x = X, y = Y), color = "darkred", size = 3) +
  geom_text(data = route2_key_points, aes(x = X, y = Y, label = key_point_label),
            color = "darkred", vjust = 1.5, size = 3) +
  theme_bw() +
  labs(title = "Key Points Along Bus Route 71", subtitle = paste("Points sampled at approximately", sam
   x = "Longitude",
   y = "Latitude")
```

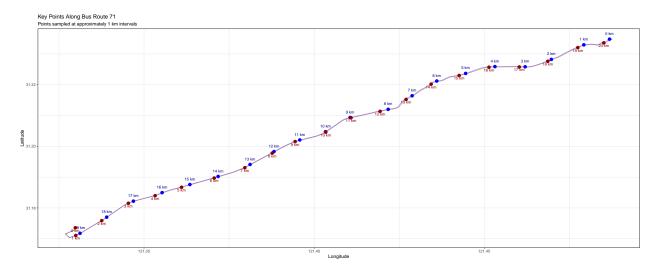


Figure 20 in the report shows key points along Bus Route 71 spaced at 1 km intervals. This visualization helps identify deviations, overlaps, and directional symmetry in the route, which is useful for transport planning and optimization.

Distance Matrix Calculation

```
# Now, calculate the distance matrix
# Function to calculate distance matrix between points
calculate_distance_matrix <- function(points_df) {</pre>
  n <- nrow(points df)</pre>
  dist_matrix <- matrix(0, nrow = n, ncol = n)</pre>
  for(i in 1:n) {
    for(j in 1:n) {
      if(i != j) {
        # Calculate Euclidean distance in km
        dist_matrix[i, j] <- sqrt(</pre>
           (points_df\$X[i] - points_df\$X[j])^2 +
           (points_df\frac{$Y[i] - points_df\frac{$Y[j]}^2}
        ) * 111.32
      }
    }
  }
  rownames(dist_matrix) <- points_df$key_point_label</pre>
  colnames(dist_matrix) <- points_df$key_point_label</pre>
  return(dist_matrix)
}
# Calculate distance matrices
route1_dist_matrix <- calculate_distance_matrix(route1_key_points)</pre>
route2_dist_matrix <- calculate_distance_matrix(route2_key_points)</pre>
# Convert distance matrix to long format for visualization
route1_dist_long <- as.data.frame(as.table(route1_dist_matrix)) %>%
  rename(from = Var1, to = Var2, distance_km = Freq)
```

Distance Matrix Visualization

Distance Matrix Between Key Points – Yanan Road–Shenkun Colors indicate the distance (km) between any two points along the route

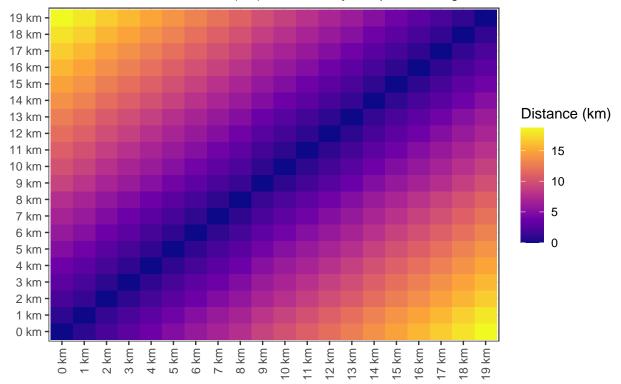


Figure 21 displays a distance matrix between key points along Bus Route 71. The matrix shows pairwise distances between points spaced every 1 km along the route. This visualization helps identify patterns of linearity and irregularity in the route, useful for understanding its spatial structure and finding opportunities for optimization.

Speed Analysis Along Route

```
ggplot(all_timed_segments, aes(x = cumulative_distance, y = segment_speed_kmh, color = route)) +
  geom_line() +
  geom_point(alpha = 0.5) +
  scale_color_manual(values = c("blue", "red")) +
  theme_bw() +
  labs(
    title = "Estimated Speeds Along Bus Route 71",
    subtitle = "Showing how speed varies based on segment characteristics",
    x = "Distance Along Route (km)",
    y = "Speed (km/h)",
    color = "Route")
```

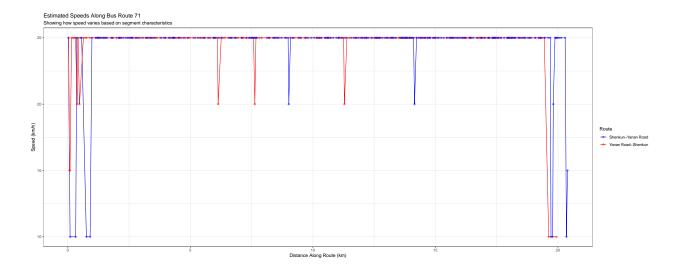


Figure 22 shows estimated speeds along both directions of Bus Route 71. Most segments operate near the maximum speed (25 km/h), but some drop to 10-15 km/h, particularly near the route ends. This suggests areas with signal delays, congestion, or complex intersections.

Travel Time Summary and Route with Time Markers

```
# First, make sure all_timed_segments exists and has the necessary columns
if(!exists("all_timed_segments")) {
  # If not, recreate the route segments with time estimates
  route1_segments <- calculate_segment_properties(route1_df) %>%
   mutate(route = direction1_name_en,
           segment_id = row_number(),
           cumulative_distance = cumsum(segment_length))
  route2_segments <- calculate_segment_properties(route2_df) %>%
   mutate(route = direction2_name_en,
           segment id = row number(),
           cumulative_distance = cumsum(segment_length))
  # Combine segments
  all_segments <- bind_rows(route1_segments, route2_segments)</pre>
  # Assign speeds based on segment properties
  estimate_segment_speeds <- function(segments_df) {</pre>
    segments_df %>%
      group_by(route) %>%
      mutate(
        # Calculate turn sharpness from previous segment
        prev_direction = lag(segment_direction),
        turn_angle = if_else(is.na(prev_direction), 0,
                           abs(((segment_direction - prev_direction + 180) %% 360) - 180)),
        # Assign speeds based on segment characteristics
        segment speed kmh = case when(
          turn_angle > 45 ~ 10, # Very sharp turns: 10 km/h
```

```
turn_angle > 30 ~ 15, # Sharp turns: 15 km/h
          turn_angle > 15 ~ 20, # Moderate turns: 20 km/h
          TRUE ~ 25
                                 # Straight segments: 25 km/h
        ),
        # Calculate time for each segment (in minutes)
        segment_time_min = (segment_length / segment_speed_kmh) * 60,
        # Calculate cumulative time
        cumulative_time_min = cumsum(segment_time_min)) %>%
      ungroup()
   }
  # Apply the speed model to all segments
  all_timed_segments <- estimate_segment_speeds(all_segments)</pre>
# Calculate route summary statistics
route_time_summary <- all_timed_segments %>%
  group_by(route) %>%
  summarize(total_distance_km = max(cumulative_distance),
               total_time_min = max(cumulative_time_min),
                avg_speed_kmh = total_distance_km / (total_time_min / 60),
            min_segment_speed = min(segment_speed_kmh),
            max_segment_speed = max(segment_speed_kmh))
# Display the summary
knitr::kable(route_time_summary, caption = "Estimated Travel Time Summary", digits = 2)
```

Table 8: Estimated Travel Time Summary

route	total_distance_kmtot	al_time_minav	g_speed_km h in_	_segment_speemalax_	_segment_speed
Shenkun-Yanan	20.39	51.91	23.57	10	25
Road Yanan	19.94	49.88	23.98	10	25
Road-Shenkun					

```
# Create time-distance markers every 5 minutes - rewritten without do()
# First create a function to find markers for one route
find_time_markers <- function(route_data) {
   target_times <- seq(5, max(route_data$cumulative_time_min), by = 5)

# Initialize results dataframe
   result <- data.frame()

for(target_time in target_times) {
    # Find the closest point to the target time
   idx <- which.min(abs(route_data$cumulative_time_min - target_time))

# Add this point to our results
   marker <- route_data[idx, ] %>%
    mutate(time_marker = paste0(round(cumulative_time_min), " min"))
```

```
result <- bind_rows(result, marker)</pre>
  }
  return(result)
}
# Apply the function to each route
time_markers <- all_timed_segments %>%
  split(.$route) %>%
  lapply(find_time_markers) %>%
  bind_rows()
# Plot route map with time markers
ggplot() +
  # Base routes
  geom_path(data = route1_df, aes(x = X, y = Y), color = "blue", alpha = 0.5, size = 0.8) +
  geom_path(data = route2_df, aes(x = X, y = Y), color = "red", alpha = 0.5, size = 0.8) +
  # Time markers
  geom_point(data = time_markers, aes(x = X, y = Y, color = route), size = 3) +
  geom_text(data = time_markers, aes(x = X, y = Y, label = time_marker, color = route),
            vjust = -1.5, size = 3) +
  scale_color_manual(values = c("blue", "red")) +
  theme minimal() +
  labs(
    title = "Bus Route 71 with Time Markers",
    subtitle = "Estimated travel time markers at 5-minute intervals",
    x = "Longitude",
    y = "Latitude",
    color = "Route"
```

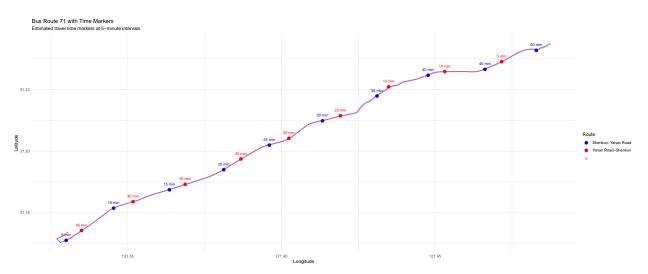


Figure 23 shows estimated travel times mapped along both directions of Route 71, with time markers at 5-minute intervals. The report notes that both directions follow similar paths, but time markers indicate non-uniform travel times across segments, highlighting directional inefficiencies that could be targets for optimization.

Segment Length Distribution by Route

```
# 1. Boxplot comparing segment lengths between routes
ggplot(all_segments, aes(x = route, y = segment_length, fill = route)) +
    geom_boxplot() +
    scale_fill_manual(values = c("turquoise", "yellow")) +
    theme_bw() +
    labs(
        title = "Distribution of Segment Lengths by Route",
        subtitle = "Comparing segment length characteristics between routes",
        x = "Route",
        y = "Segment Length (km)",
        fill = "Route"
    ) +
    theme(legend.position = "none")
```

Distribution of Segment Lengths by Route

Comparing segment length characteristics between routes

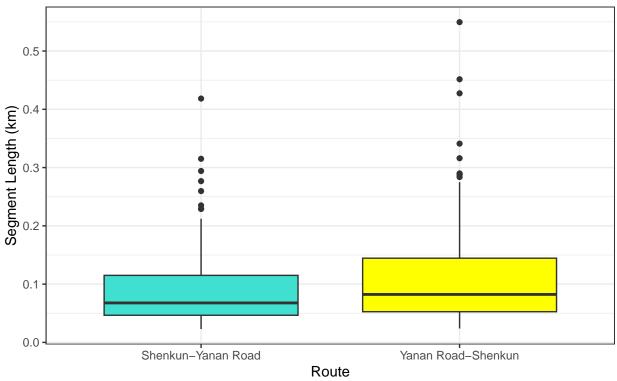


Figure 24 compares the distribution of segment lengths for both directions. The Shenkun-Yanan Road direction (turquoise) shows more uniform segment lengths with a lower median, while the Yanan-Shenkun Road direction (yellow) has greater variability and a higher median segment length. This asymmetry suggests differences in operational segmentation.

Speed Category Distribution by Route

Proportion of Speed Categories by Route Comparing the distribution of speed segments between routes

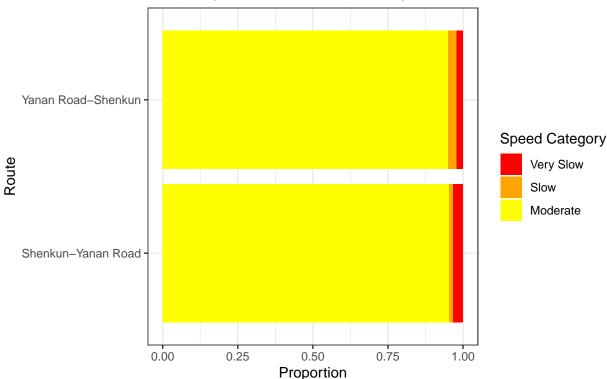


Figure 25 shows the proportion of speed categories along both directions. Moderate speeds (yellow) dominate both directions, but the Yanan-Shenkun direction has slightly more segments in the Slow and Very Slow categories, suggesting occasional congestion or operational issues like passenger boarding delays.

Vehicle ID Mapping

```
# Creating a copy of the original VehicleId and creating simplified labels
busgps_df <- busgps_df %>%
    # First we store the original IDs
    mutate(jp_vehicleID = VehicleId) %>%
    group_by(VehicleId) %>% # A mapping of unique VehicleIDs to simplified labels
    mutate(temp_id = cur_group_id()) %>%
    ungroup() %>%
    mutate(VehicleId = pasteO("Vehicle_", temp_id)) %>% # Simplified VehicleId labels
    # Removing the temporary ID column without using select()
    subset(select = -temp_id)

vehicle_id_mapping <- unique(busgps_df[, vehicle_id_cols])
vehicle_id_mapping <- vehicle_id_mapping[order(vehicle_id_mapping$VehicleId), ]

knitr::kable(vehicle_id_mapping, caption = "Vehicle ID Mapping Reference")</pre>
```

Table 9: Vehicle ID Mapping Reference

VehicleId	jp_vehicleID
$Vehicle_1$	$Vehicle_1$
$Vehicle_10$	$Vehicle_18$
$Vehicle_11$	$Vehicle_19$
$Vehicle_12$	$Vehicle_2$
$Vehicle_13$	$Vehicle_20$
$Vehicle_14$	$Vehicle_21$
$Vehicle_15$	$Vehicle_22$
$Vehicle_16$	$Vehicle_23$
$Vehicle_17$	$Vehicle_24$
$Vehicle_18$	$Vehicle_25$
$Vehicle_19$	$Vehicle_26$
$Vehicle_2$	$Vehicle_10$
$Vehicle_20$	$Vehicle_27$
$Vehicle_21$	$Vehicle_28$
$Vehicle_22$	$Vehicle_29$
$Vehicle_23$	$Vehicle_3$
$Vehicle_24$	$Vehicle_30$
$Vehicle_25$	$Vehicle_31$
$Vehicle_26$	$Vehicle_32$
$Vehicle_27$	$Vehicle_33$
$Vehicle_28$	$Vehicle_34$
$Vehicle_29$	$Vehicle_35$
$Vehicle_3$	$Vehicle_11$
$Vehicle_30$	$Vehicle_36$
$Vehicle_31$	$Vehicle_37$
$Vehicle_32$	$Vehicle_38$
$Vehicle_33$	$Vehicle_39$
$Vehicle_34$	$Vehicle_4$
$Vehicle_35$	$Vehicle_40$
$Vehicle_36$	$Vehicle_41$
$Vehicle_37$	$Vehicle_5$

VehicleId	jp_vehicleID		
Vehicle_38	Vehicle_6		
$Vehicle_39$	Vehicle_7		
$Vehicle_4$	$Vehicle_12$		
$Vehicle_40$	Vehicle_8		
$Vehicle_41$	Vehicle_9		
$Vehicle_5$	$Vehicle_13$		
Vehicle_6	$Vehicle_14$		
Vehicle_7	$Vehicle_15$		
Vehicle_8	$Vehicle_16$		
$Vehicle_9$	$Vehicle_17$		

Vehicle Activity Distribution

```
# First, let's extract coordinates from Strlatlon
busgps_df <- busgps_df %>%
 mutate(
    # Extract coordinates from Strlatlon column (assuming format "lat,lon")
   coordinates = strsplit(as.character(Strlatlon), ","),
   latitude = as.numeric(sapply(coordinates, function(x) x[1])),
   longitude = as.numeric(sapply(coordinates, function(x) x[2])))
# 1. Vehicle activity distribution - number of GPS points per vehicle
vehicle_activity <- busgps_df %>%
  count(VehicleId) %>%
  arrange(desc(n))
# Plot the distribution
ggplot(vehicle_activity, aes(x = reorder(VehicleId, -n), y = n)) +
 geom_bar(stat = "identity", fill = "steelblue") +
 theme bw() +
 theme(axis.text.x = element_text(angle = 90, hjust = 1)) +
 labs(
   title = "Vehicle Activity Distribution",
   subtitle = "Number of GPS records per vehicle",
   x = "Vehicle ID",
   y = "Number of GPS Records"
 )
```

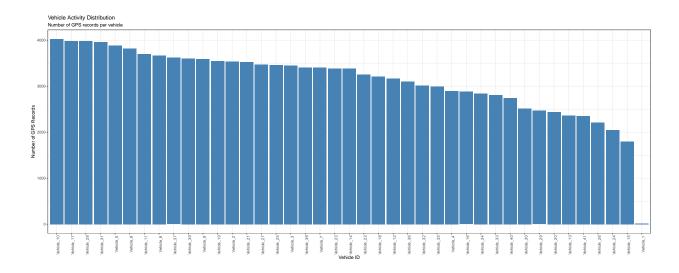


Figure 26 shows the distribution of GPS records across vehicles. Most vehicles show high activity levels (3,000-4,000 records), with a few showing significantly lower counts. This helps identify consistently active vehicles versus those that may have malfunctioning GPS devices or limited service periods.

Vehicle Activity by Hour of Day

```
# Extract hour from timestamp
busgps_df <- busgps_df %>%
  mutate(hour_of_day = as.numeric(format(GPSDateTime, "%H")))
# Analyze vehicle activity by hour of day
hourly_activity <- busgps_df %>%
  count(VehicleId, hour_of_day) %>%
  # Get the top 10 most active vehicles
  filter(VehicleId %in% head(vehicle_activity$VehicleId, 10))
# Create a heatmap of vehicle activity by hour
ggplot(hourly_activity, aes(x = hour_of_day, y = VehicleId, fill = n)) +
  geom_tile() +
  scale_fill_viridis_c("Number of Records", option = "plasma") +
  theme_bw() +
  labs(
    title = "Vehicle Activity by Hour of Day",
    subtitle = "Shows when each vehicle is most active",
    x = "Hour of Day (24-hour format)",
    y = "Vehicle ID") +
  scale_x_continuous(breaks = 0:23)
```

Vehicle Activity by Hour of Day

Shows when each vehicle is most active

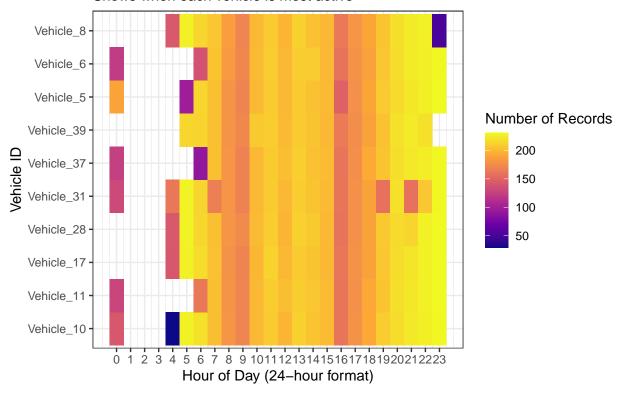


Figure 27 is a heatmap showing hourly activity for the ten most active vehicles. Peak activity occurs between 6-10 AM and during late afternoon hours. Most vehicles show minimal activity from midnight to 5 AM, matching the expected service patterns with morning and evening rush hours being the busiest periods.

Vehicle Speed Analysis

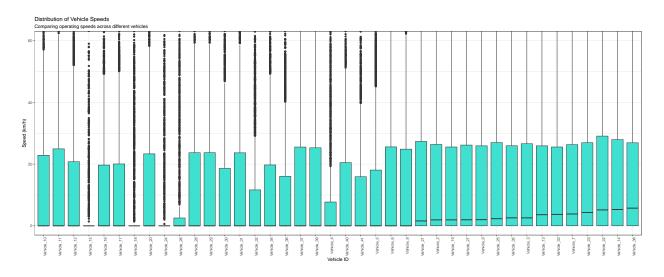


Figure 28 shows speed distributions for various vehicles. The report notes that some vehicles (like D-R2313 and D-R71745) have very low median speeds, while others (D-R1137, D-R2192, D-R6025) maintain higher, more consistent speeds. This helps identify potential mechanical issues or route-specific constraints affecting vehicle performance.

Direction Distribution by Vehicle

```
# Analyze which direction each vehicle typically serves
direction_by_vehicle <- busgps_df %>%
    count(VehicleId, ToDir) %>%
    group_by(VehicleId) %>%
    mutate(proportion = n / sum(n))

# Plot the proportion of directions by vehicle
ggplot(direction_by_vehicle, aes(x = VehicleId, y = proportion, fill = factor(ToDir))) +
    geom_bar(stat = "identity") +
    scale_fill_brewer(palette = "Set1", name = "Direction") +
    theme_bw() +
```

```
theme(axis.text.x = element_text(angle = 90, hjust = 1)) +
labs(
   title = "Direction Distribution by Vehicle",
   subtitle = "Shows whether vehicles serve specific directions or both",
   x = "Vehicle ID",
   y = "Proportion of Records"
)
```

Direction Distribution by Vehicle

Shows whether vehicles serve specific directions or both

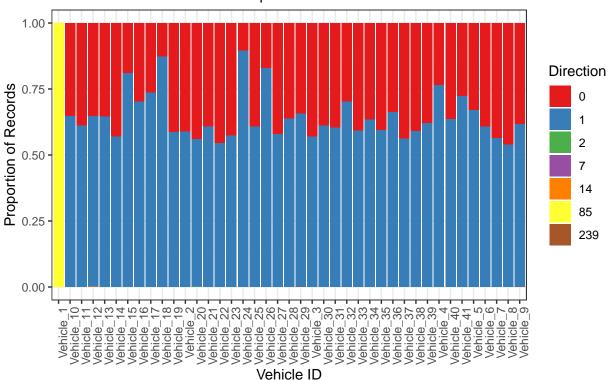


Figure 29 shows how vehicles are distributed across route directions. Most vehicles serve two main directions (0 and 1), likely representing inbound and outbound routes. Some vehicles are evenly split between directions, while others are predominantly assigned to one direction. The graph also reveals some anomalous direction codes that may indicate data issues.

Vehicle Dwell Time Analysis

```
# Calculate dwell time (time spent at one location) by looking for consecutive GPS points
# that are very close to each other
dwell_analysis <- vehicle_speed %>%
   mutate(
    is_stationary = speed_kmh < 3 & !is.na(speed_kmh),
    dwell_group = cumsum(c(1, diff(as.numeric(is_stationary))) != 0))
) %>%
filter(is_stationary) %>%
```

```
group_by(VehicleId, dwell_group) %>%
  summarize(
   dwell_time_min = as.numeric(difftime(max(GPSDateTime), min(GPSDateTime), units = "mins")),
   avg_latitude = mean(latitude),
   avg_longitude = mean(longitude),
    .groups = "drop"
  ) %>%
  filter(dwell_time_min > 1) # Focus on stops longer than 1 minute
# Boxplot of dwell times by vehicle
ggplot(dwell_analysis, aes(x = reorder(VehicleId, dwell_time_min, FUN = median), y = dwell_time_min)) +
  geom_boxplot(fill = "lightgreen") +
  theme_bw() +
  theme(axis.text.x = element_text(angle = 90, hjust = 1)) +
  labs(
   title = "Vehicle Dwell Time Analysis",
    subtitle = "Time spent stopped at locations (potential bus stops or traffic)",
   x = "Vehicle ID",
   y = "Dwell Time (minutes)"
  ) +
  coord_cartesian(ylim = c(0, 15))
```

Vehicle Dwell Time Analysis

Time spent stopped at locations (potential bus stops or traffic)

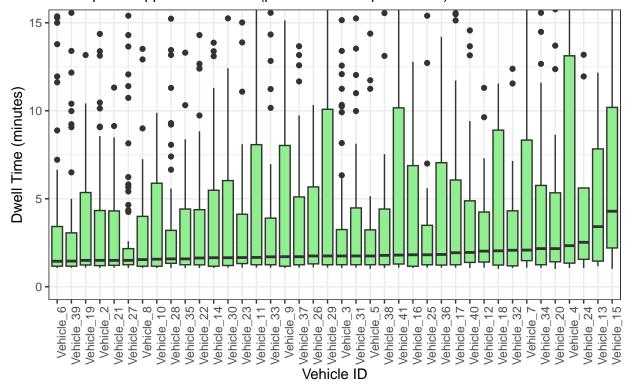


Figure 30 shows the dwell time distribution for each vehicle, revealing how long buses remain stationary at specific locations. The report indicates that longer dwell times may suggest high passenger activity or traffic congestion, while frequent extended stops could indicate high-demand

areas that may need service adjustments.