

# The Role of Pseudorandomness in (Computational) Differential Privacy

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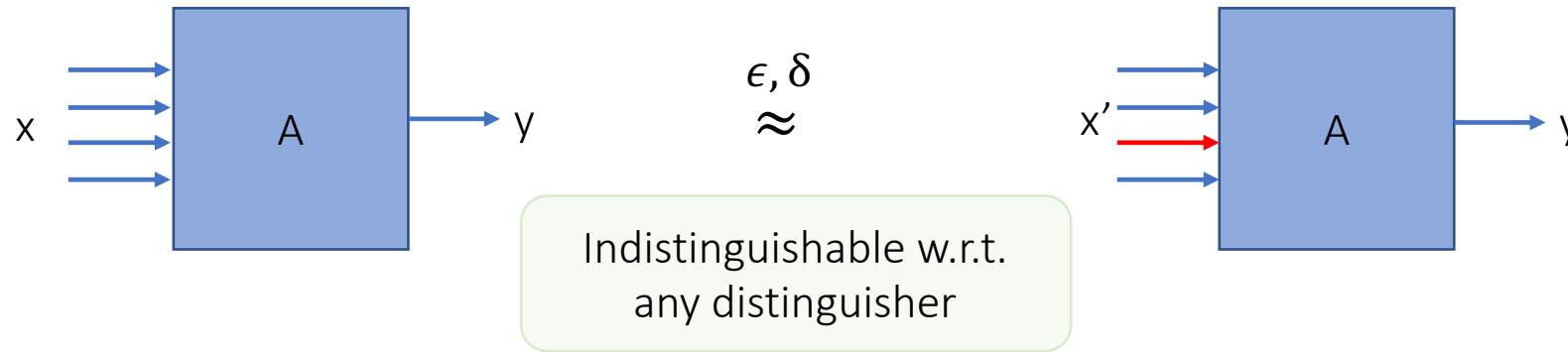
Boston University,

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# Plan of the talk

1. Overview of the papers
  1. Computational Differential Privacy
    1. Dense Model Theorem
  2. SV-sources for DP algorithms
  3. PRGs for Local DP algorithms
2. Proof of the equivalence result
  1. Simple Direction: hybrid argument
  2. Hard direction: dense model theorem
3. Possible extensions and future work

# Differential Privacy

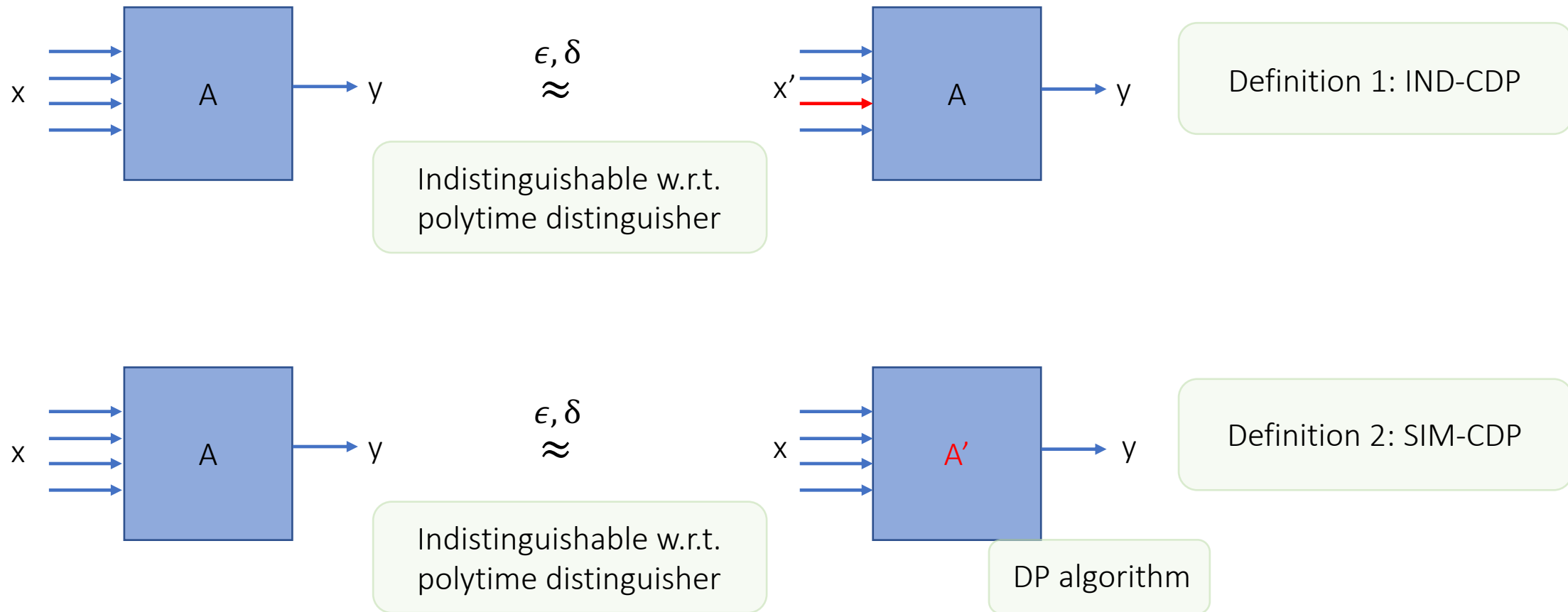


$A$  is  $(\epsilon, \delta)$ -differentially private if for every set of possible outputs  $O$ , and for every neighboring  $x, x'$ :

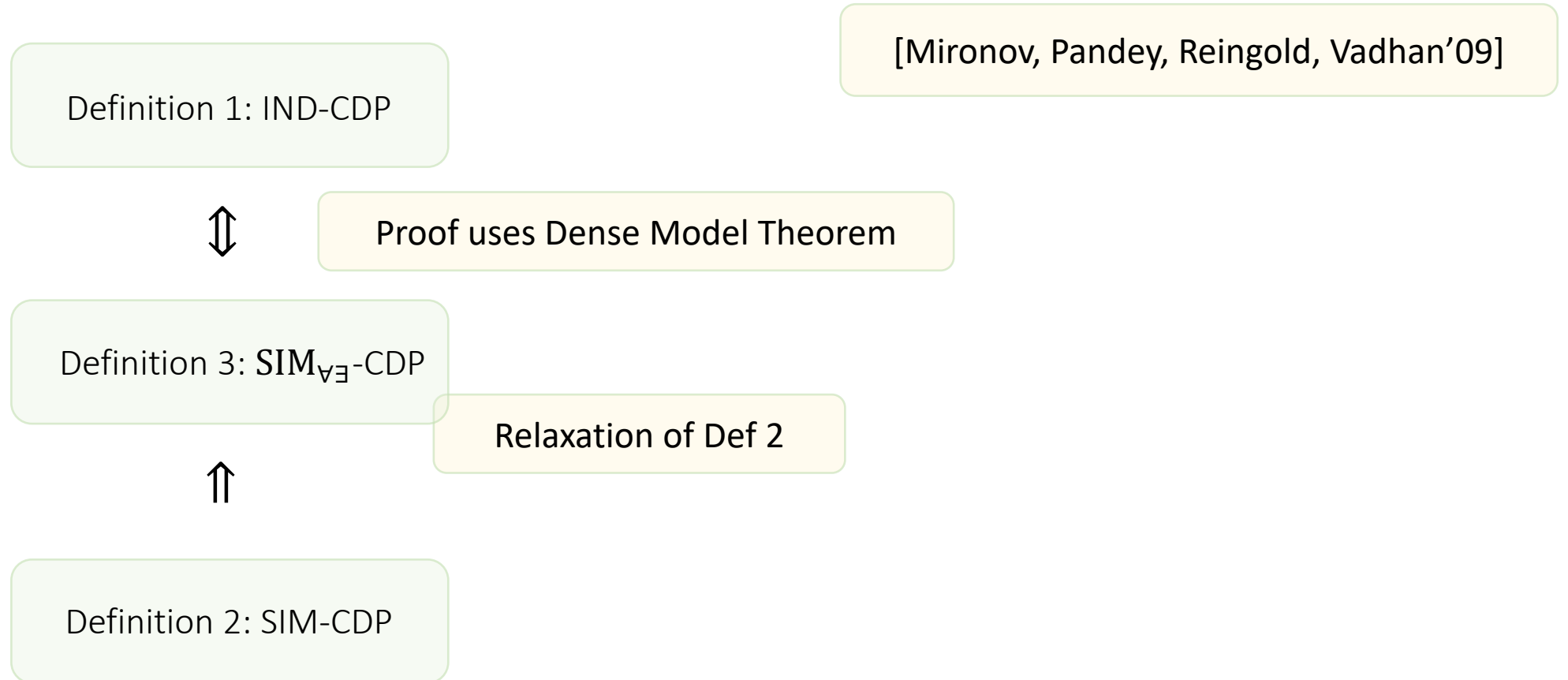
$$P[A(x) \in O] \leq e^\epsilon \cdot P[A(x') \in O] + \delta$$

# Computational Differential Privacy

If a real adversary is a polysize probabilistic circuit, can we relax the definition of Differential Privacy?



# Main Theorem of this talk



# Differential Privacy and Randomness Sources

All non-trivial DP algorithms should be randomized

- Standard algorithms sample from the uniform distribution



Can we use Santha-Vazirani random sources instead of the Uniform distribution?

- Every  $i$ -th bit in the gamma-SV sequence has bias gamma
- Obstacles:
  - SV sources are non-extractable
  - Cannot construct signatures and other basic “privacy” protocols out of it

# Differential Privacy with SV sources of Randomness

Can we build DP protocols that uses SV sources of randomness?

[Dodis, Lopez-Alt, Mironov, Vadhan'09]

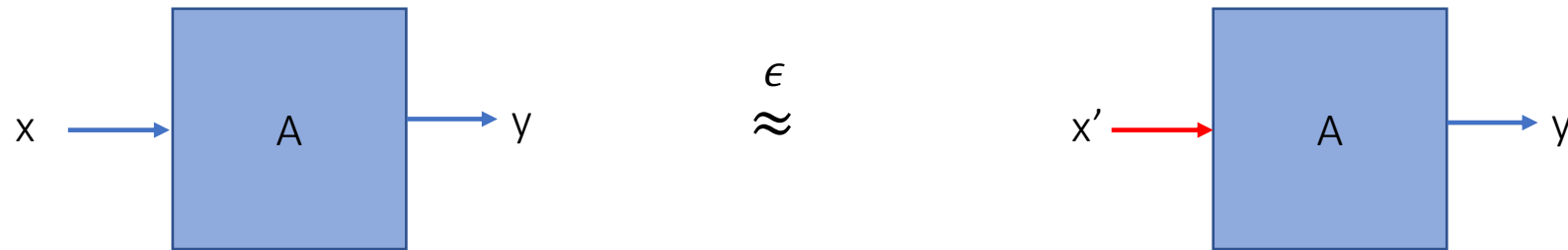


- No, if we use additive noise DP algorithms
  - $A(x) = f(x) + \text{random\_noise}$ , where  $f$  is a true, non-DP answer
- Yes, if we use additive noise DP algorithms with the discretization
  - The main intuition is that sets of probabilities of getting the same output values should be almost the same for all neighboring datasets

# Local Differential Privacy

Users may not trust a centralized database,

- Then, they can add noise to their data guarantee their privacy



For every user, for every pair of values  $x, x'$  that this user may have, for every possible output  $o$ :

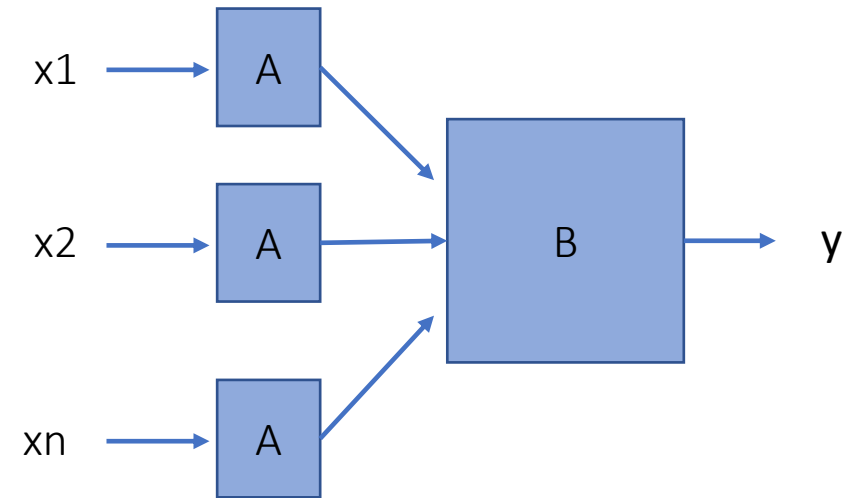
$$P[A(x) = o] \leq e^\epsilon \cdot P[A(x') = o]$$



# Local DP: communication overhead

Each user adds noise, encodes, sends their data to the centralized server

- Many users (millions in case of Google, Apple, Facebook) send their data
- Amount of information in each message is small due to noise
- If encoding is not efficient, then communication overhead is huge



What if result of each algorithm A could be encoded using an output of a PRG, so we would need to send only a seed of such PRG?

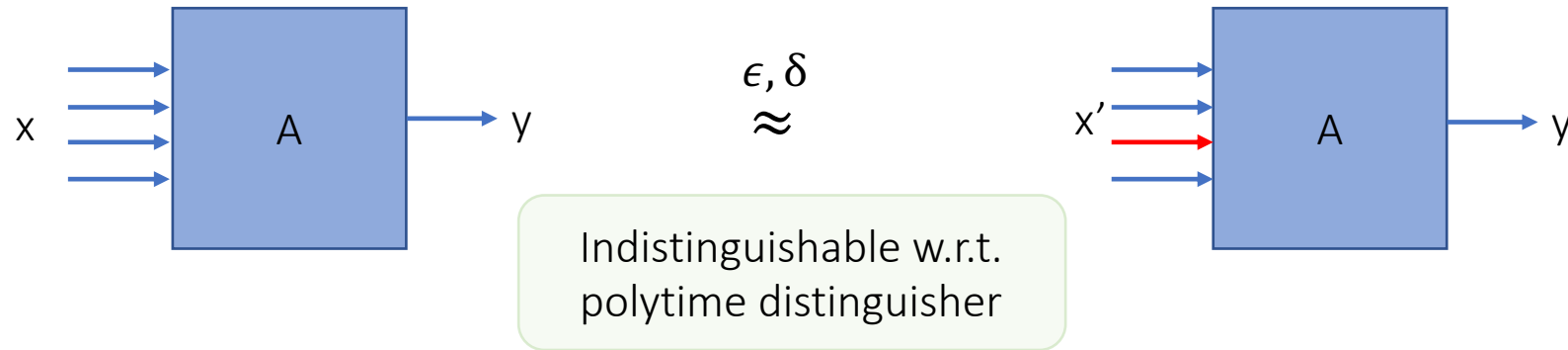
Can significantly decrease communication

- For element counting
- For mean estimation

[Feldman, Talwar'21]

Proof of  $\text{SIM}_{\forall \exists}$ -CDP  $\Leftrightarrow$  IND-CDP

# CDP: two definitions



## Definition $\text{SIM}_{\forall \exists}$ -CDP:

Distribution on outputs of  $A$  is indistinguishable by polysized circuits from a distribution on outputs of a family of DP algorithm

## Definition IND-CDP:

Distribution on outputs of  $A$  on different inputs is indistinguishable

# Equivalence result

## Theorem:

A mechanism  $B$  is IND-CDP if and only if  $B$  is  $\text{SIM}_{\forall\exists}$ -CDP

## Proof idea:

$\text{SIM}_{\forall\exists}$ -CDP  $\Rightarrow$  IND-CDP

Hybrid argument

$\text{SIM}_{\forall\exists}$ -CDP  $\Leftarrow$  IND-CDP

Dense Model Theorem

This talk

# Dense, Pseudodense, and Indist Distributions

Distribution  $X$  is  $e^\epsilon$ -dense in  $Y$  if

- $X, Y$  are distribution over the same set  $R$ ,
- $\forall x \in R \Pr[X = x] \leq e^\epsilon \cdot \Pr[Y = x]$ .

Distribution  $X$  is  $\delta$ -indistinguishable from  $Y$  w.r.t. a family of predicates  $\mathbf{A}: R \rightarrow \{0,1\}$  if

- $\forall A \in \mathbf{A} \quad | \Pr[A(X) = 1] - \Pr[A(Y) = 1] | \leq \delta$ .

Distribution  $X$  is  $(e^\epsilon, \delta)$ -pseudodense in  $Y$  w.r.t. a family of predicates  $\mathbf{A}: R \rightarrow \{0,1\}$  if

- $\forall A \in \mathbf{A} \quad \Pr[A(X) = 1] \leq e^\epsilon \cdot \Pr[A(Y) = 1] + \delta$ .

# DP Definitions via Pseudodensity

$f: \mathcal{D} \rightarrow R$  is  $\epsilon$ -DP if and only if for all neighboring  $D, D' \in \mathcal{D}$

- $f(D)$  is  $e^\epsilon$ -dense in  $f(D')$ .

$\{f_k\}: \mathcal{D} \rightarrow R$  is  $\epsilon_k$ -IND-CDP if and only if for all

- Exists  $s(k) = k^{\omega(1)}$
- For all neighboring  $D, D' \in \mathcal{D}$  of size  $\leq s(k)$   $f_k(D)$  is  $(e^\epsilon, \frac{1}{s(k)})$ -pseudodense in  $f_k(D')$ 
  - w.r.t. circuits of size  $\leq s(k)$

$\{f_k\}: \mathcal{D} \rightarrow R$  is  $\epsilon_k$ -SIM $_{\forall\exists}$ -CDP if and only if for all sequences of neighboring inputs  $\{(D_k, D_k')\}$

- Exists  $s(k) = k^{\omega(1)}$
- Exists  $\{F_k\}$ , such that every  $F_k$  is  $\epsilon_k$ -DP
- $f_k(D)$  is  $\frac{1}{s(k)}$ -indistinguishable from  $F_k(D)$ .
  - w.r.t. circuits of size  $\leq s(k)$

# Dense Model Theorem

Theorem:

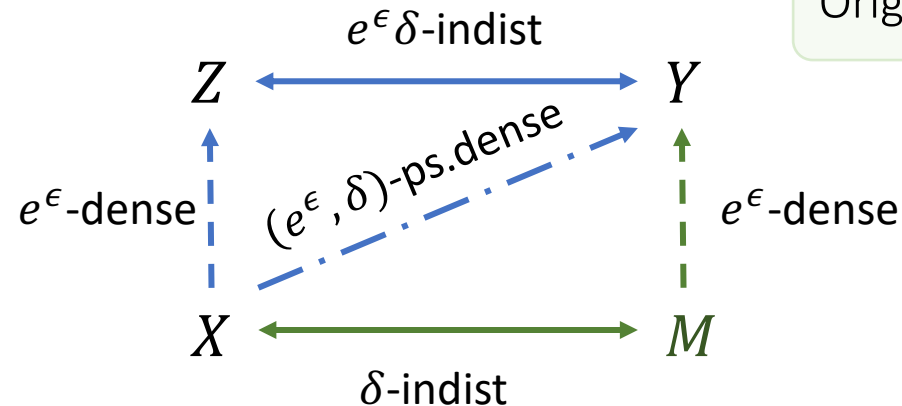
$X, Y$ , and  $Z$  are distributions over finite set  $R$

- $X$  is  $e^\epsilon$ -dense in  $Z$
- $A = \{a_i\}$  is a set of predicates  $a_i: R \rightarrow \{0,1\}$

If all distributions that are  $e^\epsilon$ -dense in  $Y$  are  $\delta$ -distinguishable from  $X$ ,

Then  $Z$  is  $\Omega(e^\epsilon \delta)$ -distinguishable from  $Y$ .

[Reingold, Trevisan, Tulsiani, Vadhan'08]



Original proof for  $Y = U_X$

# New Dense Model Theorem

Theorem:

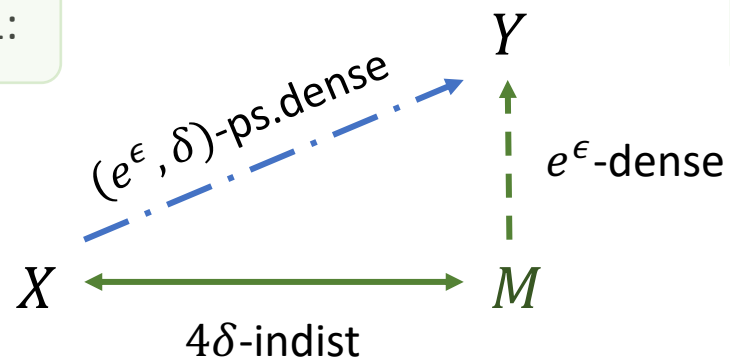
[Mironov, Pandey, Reingold, Vadhan'09]

$X, Y$  are distributions over finite set  $R$

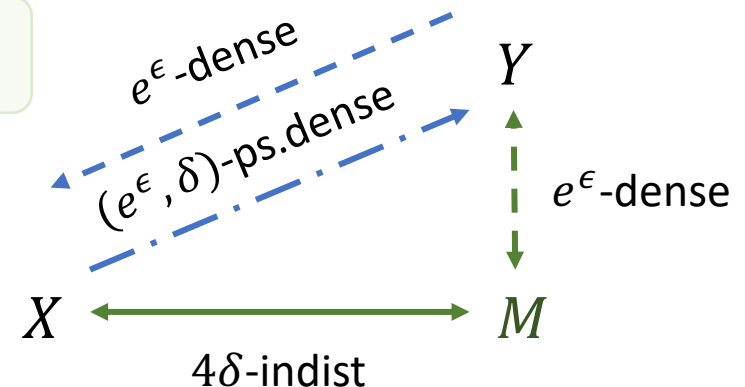
- $X$  is  $(e^\epsilon, \delta)$ -pseudodense in  $Y$
- $G(A)$  is a family of threshold predicates

1. Then there exists a distribution  $M$  that is  $e^\epsilon$ -dense in  $Y$  and  $4\delta$ -distinguishable from  $X$  with respect to family of predicates  $A$ ;
2. If  $Y$  is  $e^\epsilon$ -dense in  $X$ , then  $Y$  is  $e^\epsilon$ -dense in  $M$ .

Statement 1:



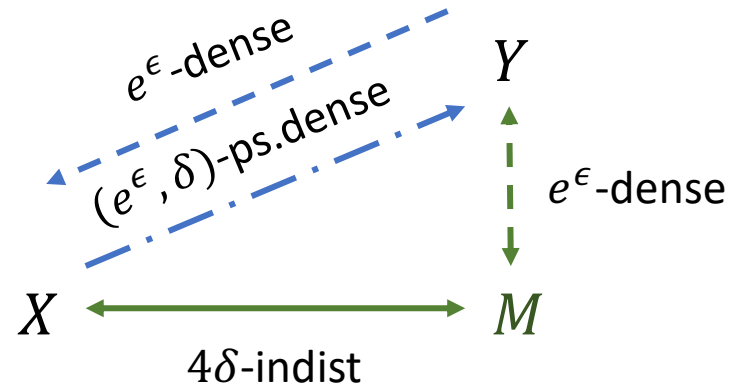
Statement 2:





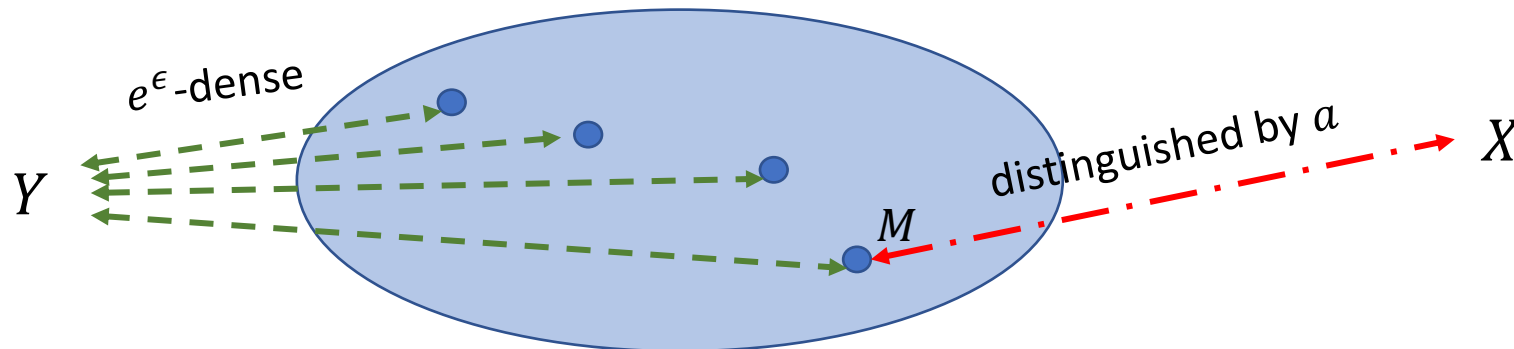
# Proof of New Dense Model Theorem

Theorem:



Proof by contradiction:

Assume for any  $M$  that is  $e^\epsilon$ -dense in  $Y$  exists  $a \in \mathbf{A}$  that distinguishes  $M$  from  $X$  w.p.  $\geq \mu = 4\delta$ .



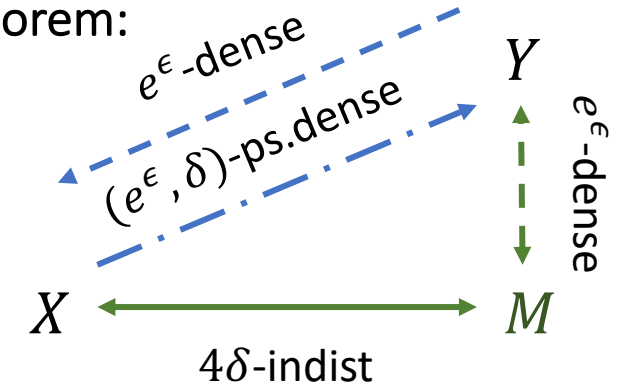
# Proof of NDMT

Set of all such  $M$  is convex

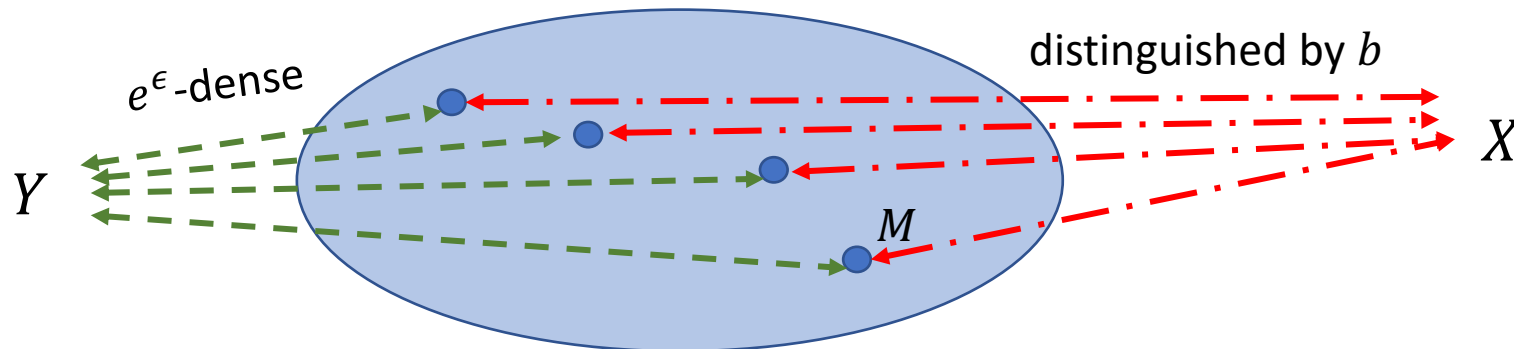
**Idea:** apply MinMax principle to get a new predicate  $b$  that distinguishes every  $M$  from  $X$  w.p.  $\geq \mu = 4\delta$

- Player A picks a predicate  $a$
- Player B picks a distribution  $D$
- The payoff is  $E[a(D)] - E[a(X)]$
- $\exists$  mixed strategy  $b: \forall M E[b(M)] - E[b(X)] \geq \gamma$
- $\exists$  mixed strategy  $M': \forall a E[a(M')] - E[a(X)] \leq \gamma$

Theorem:



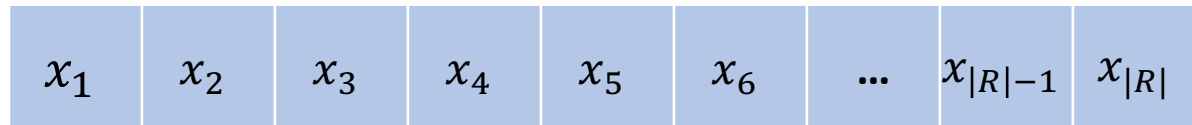
Distribution over dense distributions is a dense-distribution  $\Rightarrow \gamma \geq \mu$



# Proof of NDMT

Consider  $b: \forall M \mathbb{E}[b(M)] - \mathbb{E}[b(X)] \geq \mu$

Sort all elements  $x \in R$  in decreasing order of  $\Pr[b(x) = 1]$



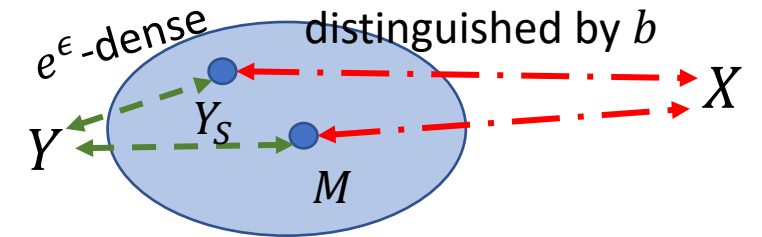
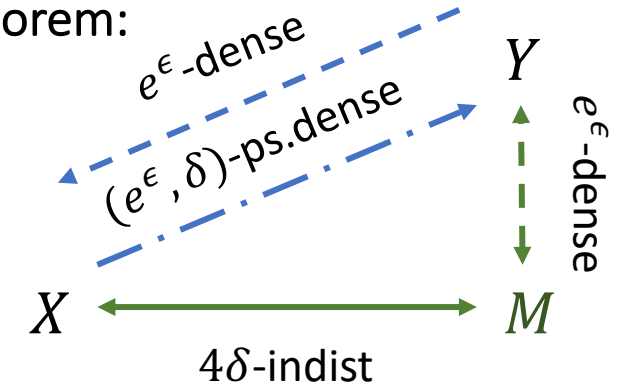
$$S: \Pr[Y \in S] = \frac{1}{1 + e^\epsilon}$$

Define a new distribution  $Y_S$ :

$$\Pr[Y_S = y] = \Pr[Y = y] \cdot \begin{cases} e^\epsilon, & \text{if } y \in S \\ e^{-\epsilon}, & \text{otherwise} \end{cases}$$

$Y_S$  and  $Y$  are  $e^\epsilon$ -dense  $\Rightarrow b$  distinguishes  $Y_S$  from  $X$

Theorem:



# Proof of NDMT

## Lemma:

$F: X \rightarrow [0,1]$

- $Z$  and  $W$  are distributions, such that  $E[F(Z)] \geq E[F(W)] + \mu$

Then exists  $t \in [\frac{\mu}{2}, 1]$ , such that

- $\Pr[F(Z) > t] \geq \Pr[F(W) \geq t - \frac{\mu}{2}] + \frac{\mu}{2}$

Applying this lemma for  $F(x) = \Pr[b(x) = 1]$ ,  $X$ , and  $Y_S$  we get:

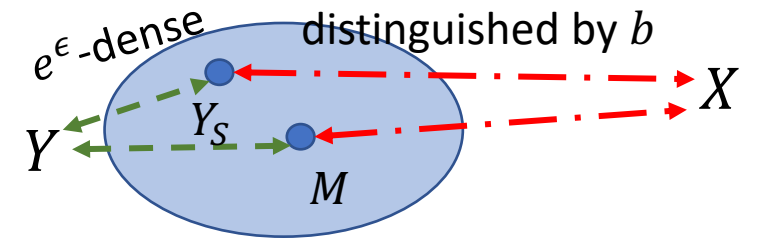
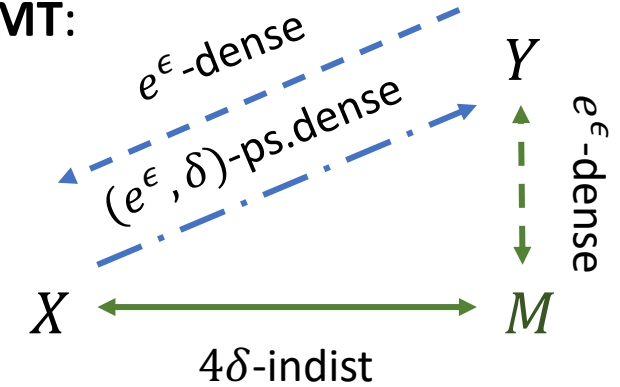
- $\Pr\left[\underbrace{\Pr[b(X) = 1]}_{\geq t + \frac{\mu}{2}} > t + \frac{\mu}{2}\right] \geq \Pr\left[\underbrace{\Pr[b(Y_S) = 1]}_{\geq t} \geq t\right] + \frac{\mu}{2}$

If  $\geq t + \frac{\mu}{2}$ :  $b'(x) = 1$   
 “looks like  $X$ ”

If  $< t$ :  $b'(x) = 0$   
 “looks like  $Y_S$ ”

new classifier, based on  
 the output probability of  $b$

NDMT:



# Proof of NDMT

$$* \Pr \left[ \underbrace{\Pr[b(X) = 1]}_{\text{If } \geq t + \frac{\mu}{2} : b'(x) = 1 \text{ "looks like X"}} > t + \frac{\mu}{2} \right] \geq \Pr \left[ \underbrace{\Pr[b(Y_S) = 1]}_{\text{If } < t : b'(x) = 0 \text{ "looks like } Y_S"}} \geq t \right] + \frac{\mu}{2}$$

If  $\geq t + \frac{\mu}{2} : b'(x) = 1$   
"looks like X"

If  $< t : b'(x) = 0$   
"looks like  $Y_S$ "

**Claim:**  $b'(y) = 0 \forall y \notin S$

**Proof** by contradiction:

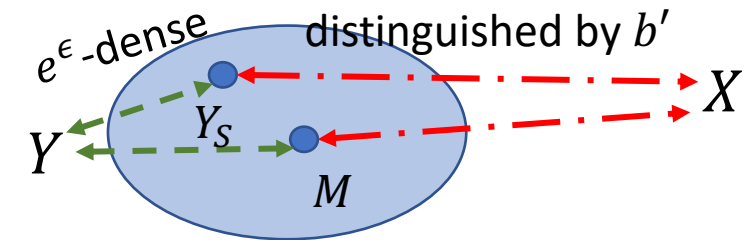
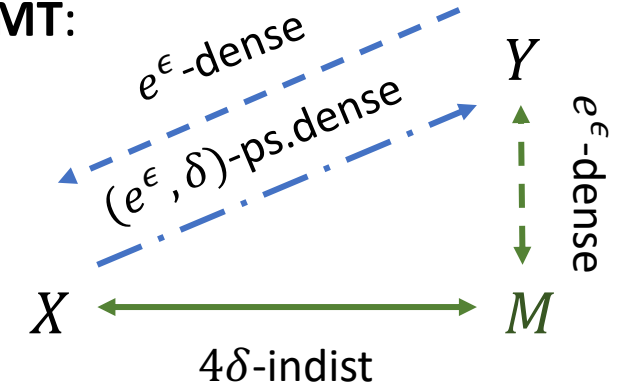
By construction  $b'(y) \neq 0 \forall y \in S$

$Y$  is dense in  $X \Rightarrow$  for all  $y \notin S$

$$\bullet \Pr[Y_S = y] = e^{-\epsilon} \cdot \Pr[Y = y] \leq e^{-\epsilon} e^{\epsilon} \cdot \Pr[X = y] = \Pr[X = y]$$

$$\Pr[b'(Y_S) = 0] = \sum_{\substack{y \notin S \\ b(y)=0}} \Pr[Y_S = y] \leq \sum_{\substack{y \notin S \\ b(y)=0}} \Pr[X = y] = \Pr[b'(X) = 0]$$

**NDMT:**



Contradiction with \*:

$$\begin{aligned} \Pr[b'(X) = 0] &\leq 1 - \Pr[b'(X) = 1] \\ &\leq 1 - \Pr[b'(Y) \neq 0] - \frac{\mu}{2} = \Pr[b'(Y) = 0] - \frac{\mu}{2} \end{aligned}$$

# Final part of the proof of NDMT

Using the fact that  $b'(y) = 0 \forall y \notin S$ :

- $\Pr[b'(Y) \neq 0] = e^{-\epsilon} \cdot \Pr[b'(Y_S) \neq 0] < e^{-\epsilon} (\Pr[b'(X) = 1] - \frac{\mu}{2})$
- $\Pr[b'(X) = 1] > e^{\epsilon} \cdot \Pr[b'(Y) \neq 0] + \frac{\mu}{2}$

This could be a contradiction with a pseudosensitivity of  $X$  in  $Y$  if  $b'$  was from the original family of predicates

## Lemma:

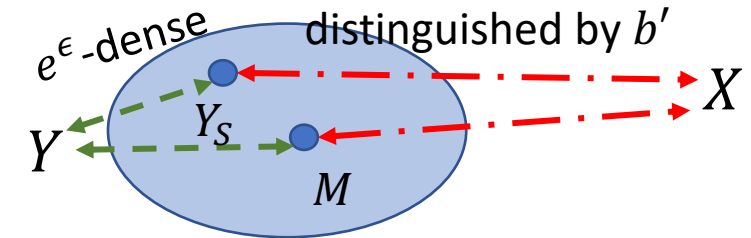
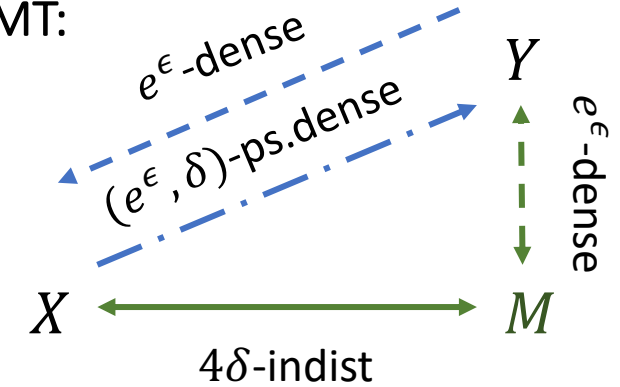
$F: R \rightarrow [0,1]$  is a convex combination of bounded functions from  $G$

- $Z_1, Z_2$  distributions of  $G$
- $\alpha, \beta > 0$

Then for  $k = O(\frac{1}{\alpha^2} \cdot \log \frac{1}{\beta})$  there are  $f_1, f_2, \dots, f_k \in G$  such that

- $\Pr \left[ \left| F(Z_i) - \frac{1}{k} \cdot (f_1(Z_i) + f_2(Z_i) + \dots + f_k(Z_i)) \right| > \alpha \right] \leq \beta, \text{ for } i = 1, 2$

NDMT:



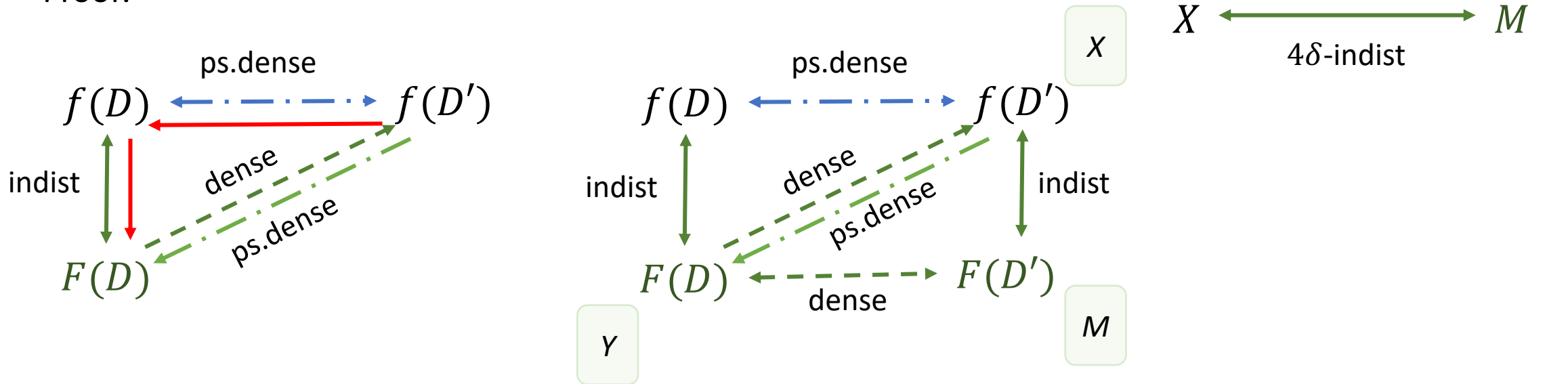
IND-CDP  $\Rightarrow$   $\text{SIM}_{\mathcal{A}}^{\text{E}}$ -CDP using NDMT

## Theorem:

If a family  $\{f_k\}: D \rightarrow R_k$  is  $\epsilon_k$ -IND-CDP,

Then it is also  $\epsilon_k$ -SIM<sub>Δ<sup>∃</sup></sub>-CDP.

**Proof:**



# Conclusion

- Pseudorandomness can help to construct new DP algorithms
  - Can use PRGs to reduce communication complexity for Local-DP algorithms
  - Can use SV-sources with imperfect randomness to construct DP algorithms
  - Can use PRGs and computational indistinguishability to construct various Computationally DP algorithms
- Technical result that we discussed today:
  - Proof of the New Dense Model Theorem
  - Its application to showing that  $\text{IND-CDP} \Rightarrow \text{SIM}_{\forall\exists}\text{-CDP}$



# Open Problems

- The separation between  $\text{SIM}_{\forall\exists}$ -CDP from SIM-CDP remains an open question
- How else, could we apply the new Dense Model Theorem?
- What other random sources (with imperfect randomness) could we use to build DP algorithms?
- Can we unconditionally compress communication in other Local-DP algorithms?

