The Role of Pseudorandomness in (Computational) Differential Privacy

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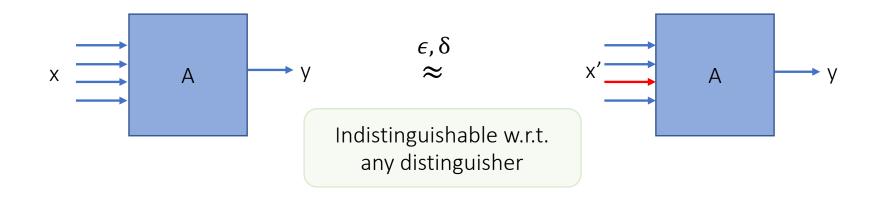
Sofya Raskhodnikova

Boston University, December 20, 2021

Plan of the talk

- 1. Overview of the papers
 - 1. Computational Differential Privacy
 - 1. Dense Model Theorem
 - 2. SV-sources for DP algorithms
 - 3. PRGs for Local DP algorithms
- 2. Proof of the equivalence result
 - 1. Simple Direction: hybrid argument
 - 2. Hard direction: dense model theorem
- 3. Possible extensions and future work

Differential Privacy

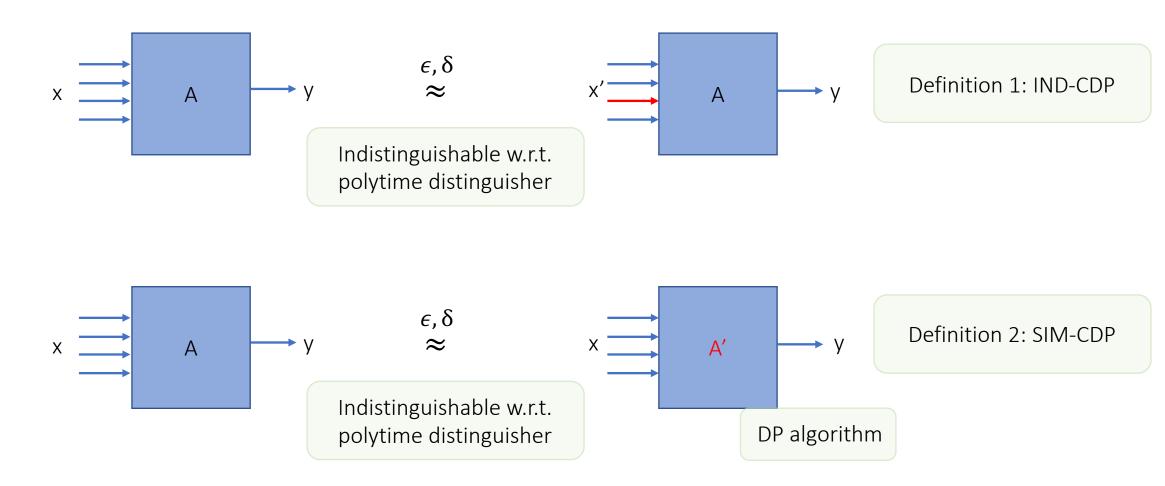


A is (ϵ, δ) -differentially private if for every set of possible outputs O, and for every neighboring x, x':

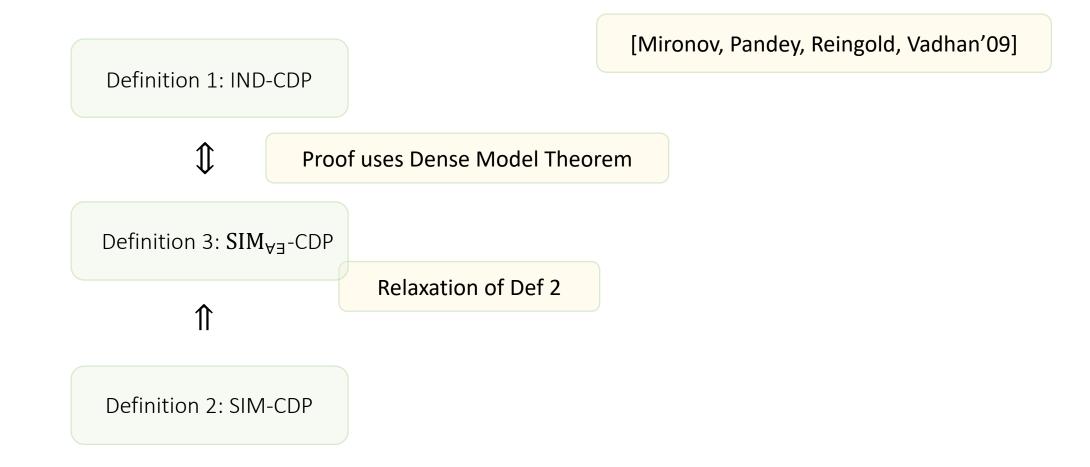
$$P[A(x) \in O] \le e^{\epsilon} \cdot P[A(x') \in O] + \delta$$

Computational Differential Privacy

If a real adversary is a polysize probabilistic circuit, can we relax the definition of Differential Privacy?



Main Theorem of this talk



Differential Privacy and Randomness Sources

All non-trivial DP algorithms should be randomized

• Standard algorithms sample from the uniform distribution



Can we use Santha-Vazirani random sources instead of the Uniform distribution?

- Every i-th bit in the gamma-SV sequence has bias gamma
- Obstacles:
 - SV sources are non-extractable
 - Cannot construct signatures and other basic "privacy" protocols out of it

Differential Privacy with SV sources of Randomness

Can we build DP protocols that uses SV sources of randomness?

[Dodis, Lopez-Alt, Mironov, Vadhan'09]



- No, if we use additive noise DP algorithms
 - A(x)=f(x)+random_noise, where f is a true, non-DP answer
- Yes, if we use additive noise DP algorithms with the discretization
 - The main intuition is that sets of probabilities of getting the same output values should be almost the same for all neighboring datasets

Local Differential Privacy

Users may not trust a centralized database,

Then, they can add noise to their data guarantee their privacy



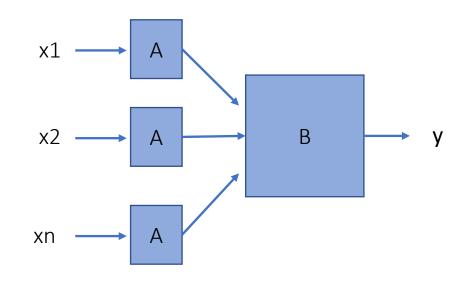
For every user, for every pair of values x, x' that this user may have, for every possible output o:

$$P[A(x) = o] \le e^{\epsilon} \cdot P[A(x') = o]$$

Local DP: communication overhead

Each user adds noise, encodes, sends their data to the centralized server

- Many users (millions in case of Google, Apple, Facebook) send their data
- Amount of information in each message is small due to noise
- If encoding is not efficient, then communication overhead is huge



What if result of each algorithm A could be encoded using an output of a PRG, so we would need to send only a seed of such PRG?

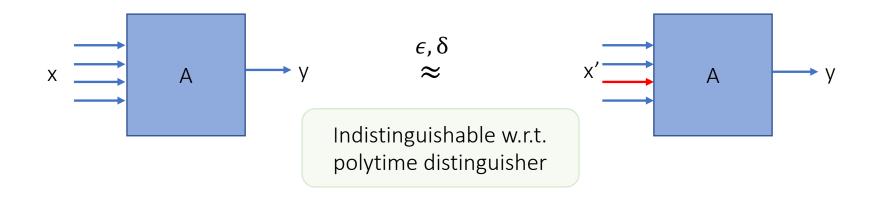
Can significantly decrease communication

- For element counting
- For mean estimation

[Feldman, Talwar'21]

Proof of $SIM_{\forall\exists}$ -CDP \Leftrightarrow IND-CDP

CDP: two definitions



Definition SIM $_{\forall\exists}$ -CDP:

Distribution on outputs of A is indistinguishable by polysized circuits from a distribution on outputs of a family of DP algorithm

Definition IND-CDP:

Distribution on outputs of A on different inputs is indistinguishable

Equivalence result

Theorem:

A mechanism B is IND-CDP if and only if B is $SIM_{\forall\exists}$ -CDP

Proof idea:

 $SIM_{\forall\exists}$ -CDP => IND-CDP

Hybrid argument

 $SIM_{\forall\exists}$ -CDP <= IND-CDP

Dense Model Theorem

This talk

Dense, Pseudodense, and Indist Distributions

Distribution X is e^{ϵ} -dense in Y if

- X, Y are distribution over the same set R,
- $\forall x \in R \Pr[X = x] \le e^{\epsilon} \cdot \Pr[Y = x].$

Distribution X is δ -indistinguishable from Y w.r.t. a family of predicates $A: R \to \{0,1\}$ if

• $\forall A \in A \mid \Pr[A(X) = 1] - \Pr[A(Y) = 1] \mid \leq \delta$.

Distribution X is (e^{ϵ}, δ) -pseudodense in Y w.r.t. a family of predicates $A: R \to \{0,1\}$ if

• $\forall A \in A \ \Pr[A(X) = 1] \le e^{\epsilon} \cdot \Pr[A(Y) = 1] + \delta$.

DP Definitions via Pseudodensity

 $f: \mathbf{D} \to R$ is ϵ -DP if and only if for all neighboring $D, D' \in \mathbf{D}$

• f(D) is e^{ϵ} -dense in f(D').

 $\{f_k\}: \mathbf{D} \to R \text{ is } \epsilon_k\text{-IND-CDP if and only if for all }$

- Exists $s(k) = k^{\omega(1)}$
- For all neighboring $D, D' \in \mathbf{D}$ of size $\leq s(k)$ $f_k(D)$ is $(e^{\epsilon}, \frac{1}{s(k)})$ -pseudodense in $f_k(D')$
 - w.r.t. circuits of size $\leq s(k)$

 $\{f_k\}: \mathbf{D} \to R \text{ is } \epsilon_k \text{- SIM}_{\forall\exists}\text{-CDP if and only if for all sequences pf neighboring inputs } \{(D_k, D_k')\}$

- Exists $s(k) = k^{\omega(1)}$
- Exists $\{F_k\}$, such that every F_k is ϵ_k -DP
- $f_k(D)$ is $\frac{1}{s(k)}$ -indistinguishable from $F_k(D)$.
 - w.r.t. circuits of size $\leq s(k)$

Dense Model Theorem

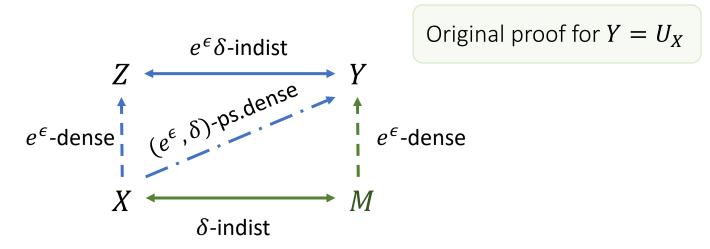
Theorem:

X, Y, and Z are distributions over finite set R

- X is e^{ϵ} -dense in Z
- $A = \{a_i\}$ is a set of predicates $a_i: R \to \{0,1\}$

If all distributions that are e^{ϵ} -dense in Y are δ -distinguishable from X,

Then Z is $\Omega(e^{\epsilon}\delta)$ -distinguishable from Y.



[Reingold, Trevisan, Tulsiani, Vadhan'08]

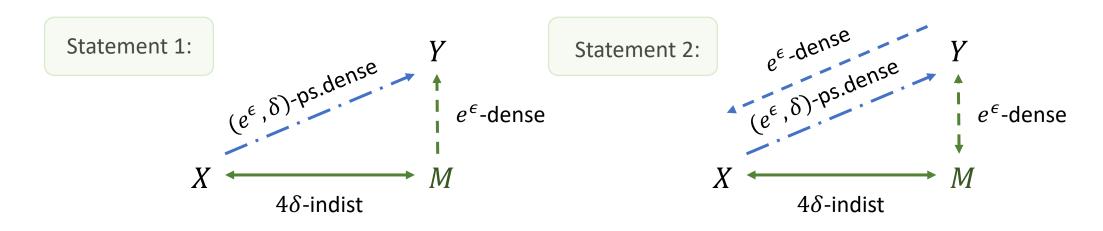
New Dense Model Theorem

Theorem:

[Mironov, Pandey, Reingold, Vadhan'09]

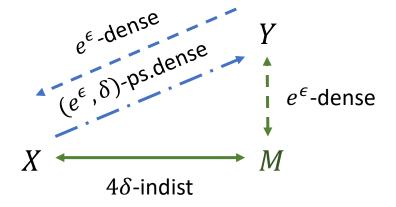
X, Y are distributions over finite set R

- X is (e^{ϵ}, δ) -pseudodense in Y
- G(A) is a family of threshold predicates
- 1. Then there exists a distribution M that is e^{ϵ} -dense in Y and 4δ -distinguishable from X with respect to family of predicates A;
- 2. If Y is e^{ϵ} -dense in X, then Y is e^{ϵ} -dense in M.



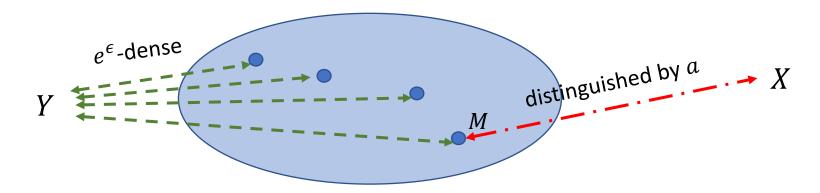
Proof of New Dense Model Theorem

Theorem:



Proof by contradiction:

Assume for any M that is e^{ϵ} -dense in Y exists $\alpha \in A$ that distinguishes M from X w.p. $\geq \mu = 4\delta$.



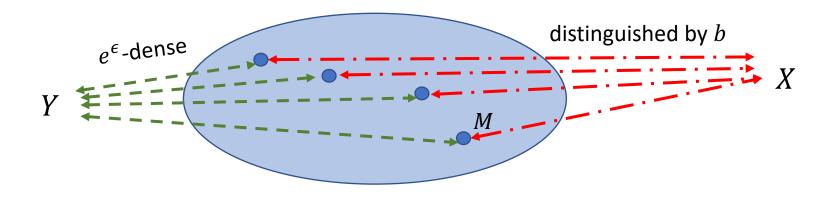
Set of all such *M* is convex

Idea: apply MinMax principle to get a new predicate b that distinguishes every M from X w.p. $\geq \mu = 4\delta$

- Player A picks a predicate *a*
- Player B picks a distribution D
- The payoff is E[a(D)] E[a(X)]
- \exists mixed strategy $b: \forall M \ \mathrm{E}[b(M)] \mathrm{E}[b(X)] \ge \gamma$
- \exists mixed strategy M': $\forall a \ \mathrm{E}[a(M')] \mathrm{E}[a(X)] \leq \gamma$

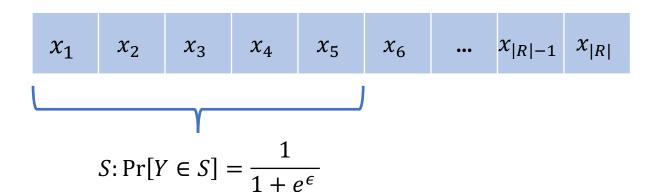
Theorem: $e^{\epsilon - de^{nse}} Y$ $(e^{\epsilon}, \delta) - ps. de^{nse}$ $X \longrightarrow M$ $4\delta - indist$

Distribution over dense distributions is a dense-distribution => $\gamma \ge \mu$



Consider $b: \forall M \ \mathrm{E}[b(M)] - \mathrm{E}[b(X)] \ge \mu$

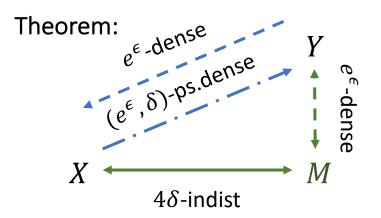
Sort all elements $x \in R$ in decreasing order of $\Pr[b(x) = 1]$

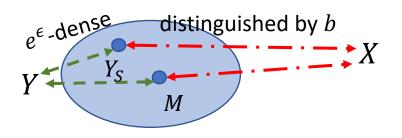


Define a new distribution Y_S :

$$\Pr[Y_S = y] = \Pr[Y = y] \cdot \begin{cases} e^{\epsilon}, & \text{if } y \in S \\ e^{-\epsilon}, & \text{otherwise} \end{cases}$$

 Y_S and Y are e^{ϵ} -dense => b distinguishes Y_S from X





Lemma:

 $F: X \rightarrow [0,1]$

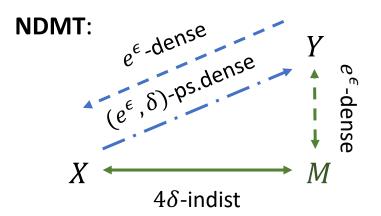
- Z and W are distributions, such that $\mathrm{E}[F(Z)] \geq \mathrm{E}[F(W)] + \mu$ Then exists $t \in [\frac{\mu}{2}, 1]$, such that
- $\Pr[F(Z) > t] \ge \Pr\left[F(W) \ge t \frac{\mu}{2}\right] + \frac{\mu}{2}$

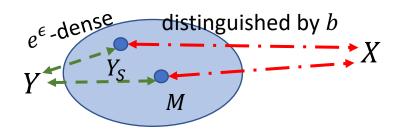
Applying this lemma for $F(x) = \Pr[b(x) = 1]$, X, and Y_S we get:

•
$$\Pr\left[\Pr[b(X) = 1] > t + \frac{\mu}{2}\right] \ge \Pr\left[\Pr[b(Y_S) = 1] \ge t\right] + \frac{\mu}{2}$$

If
$$\geq t + \frac{\mu}{2}$$
: $b'(x) = 1$ If $<$ t: $b'(x) = 0$ "looks like Y_S "

new classifier, based on the output probability of *b*





*
$$\Pr\left[\Pr[b(X) = 1] > t + \frac{\mu}{2}\right] \ge \Pr[\Pr[b(Y_S) = 1] \ge t] + \frac{\mu}{2}$$

If $\ge t + \frac{\mu}{2} : b'(x) = 1$

"looks like X"

If $< t: b'(x) = 0$
"looks like Y."

Claim: $b'(y) = 0 \ \forall y \notin S$

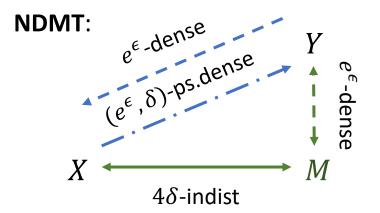
Proof by contradiction:

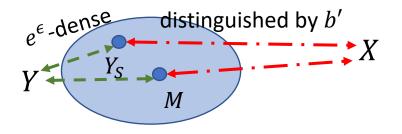
By construction $b'(y) \neq 0 \ \forall y \in S$

Y is dense in X = for all $y \notin S$

•
$$\Pr[Y_S = y] = e^{-\epsilon} \cdot \Pr[Y = y] \le e^{-\epsilon} e^{\epsilon} \cdot \Pr[X = y] = \Pr[X = y]$$

$$\Pr[b'(Y_S) = 0] = \sum_{\substack{y \notin S \\ b(y) = 0}} \Pr[Y_S = y] \le \sum_{\substack{y \notin S \\ b(y) = 0}} \Pr[X = y] = \Pr[b'(X) = 0]$$





$$\Pr[b'(X) = 0] \le 1 - \Pr[b'(X) = 1]$$

$$\le 1 - \Pr[b'(Y) \ne 0] - \frac{\mu}{2} = \Pr[b'(Y) = 0] - \frac{\mu}{2}$$

Final part of the proof of NDMT

Using the fact that $b'(y) = 0 \ \forall y \notin S$:

- $\Pr[b'(Y) \neq 0] = e^{-\epsilon} \cdot \Pr[b'(Y_S) \neq 0] < e^{-\epsilon} (\Pr[b'(X) = 1] \frac{\mu}{2})$
- $\Pr[b'(X) = 1] > e^{\epsilon} \cdot \Pr[b'(Y) \neq 0] + \frac{\mu}{2}$

This could a contradiction with a pseudosensity of X in Y if b' was from the original family of predicates

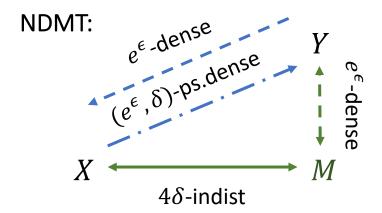
Lemma:

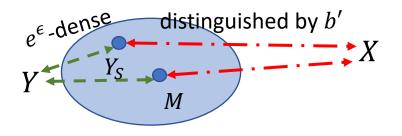
 $F: R \to [0,1]$ is a convex combination of bounded functions from G

- Z_1, Z_2 distributions of G
- $\alpha, \beta > 0$

Then for $k = O(\frac{1}{\alpha^2} \cdot \log \frac{1}{\beta})$ there are $f_1, f_2, ..., f_k \in G$ such that

•
$$\Pr\left[|F(Z_i) - \frac{1}{k} \cdot (f_1(Z_i) + f_2(Z_i) + \dots + f_k(Z_i)| > \alpha \right] \le \beta$$
, for $i = 1, 2$





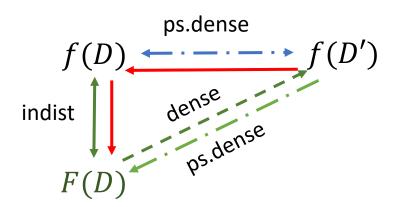
IND-CDP => $SIM_{\forall\exists}$ -CDP using NDMT

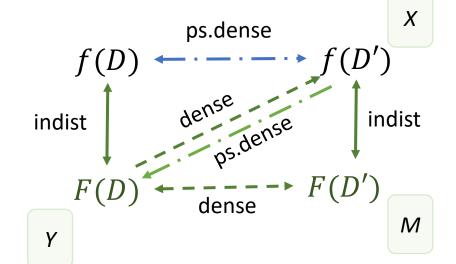
Theorem:

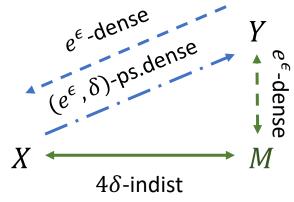
If a family $\{f_k\}: D \to R_k$ is ϵ_k -IND-CDP,

Then it is also ϵ_k - SIM $_{\forall \exists}$ -CDP.

Proof:







Conclusion

- Pseudorandomness can help to construct new DP algorithms
 - Can use PRGs to reduce communication complexity for Local-DP algorithms
 - Can use SV-sources with imperfect randomness to construct DP algorithms
 - Can use PRGs and computational indistinguishability to construct various Computationally DP algorithms
- Technical result that we discussed today:
 - Proof of the New Dense Model Theorem
 - Its application to showing that IND-CDP => $SIM_{\forall\exists}$ -CDP

Open Problems

- The separation between $SIM_{\forall\exists}$ -CDP from SIM-CDP remains an open question
- How else, could we apply the new Dense Model Theorem?
- What other random sources (with imperfect randomness) could we use to build DP algorithms?
- Can we unconditionally compress communication in other Local-DP algorithms?