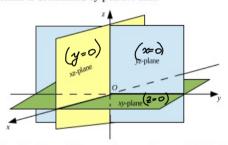
## Chapter 12. Vectors and the geometry of space Section 12.1 Three-dimensional coordinate system

## 3D Space.

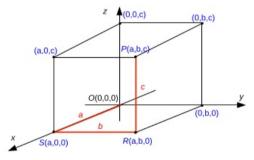
In order to represent points in space, we first choose a fixed point O (the origin) and tree directed lines through O that are perpendicular to each other, called the **coordinate axes** and labeled the x-axis, y-axis, and z-axis. Usually we think of the x and y-axes as being horizontal and z-axis as being vertical.

The direction of z-axis is determined by the **right-hand rule**: if your index finger points in the positive direction of the x-axis, middle finger points in the positive direction of the y-axis, then your thumb points in the positive direction of the z-axis.

The three coordinate axes determine the three **coordinate planes**. The xy-plane contains the x- and y-axes and its equation is z=0, the xz-plane contains the x- and z-axes and its equation is y=0, The yz-plane contains the y- and z-axes and its equation is x=0. These three coordinate planes divide space into eight parts called **octants**. The **first octant** is determined by positive axes.



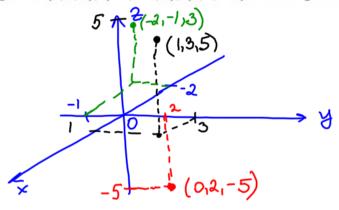
Take a point P in space, let a be directed distance from yz-plane to P, b be directed distance from xz-plane to P, and c be directed distance from xy-plane to P. We represent the point P by the ordered triple (a,b,c) of real numbers, and we call a, b, and c the **coordinates** of P. The point P(a,b,c) determine a rectangular box. If we drop a perpendicular from P to the xy-plane, we get a point Q(a,b,0) called the **projection** of P on the xy-plane. Similarly, R(0,b,c) and S(a,0,c) are the projections of P on the yz-plane and xz-plane, respectively.



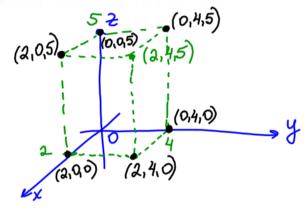
The Cartesian product  $\mathbb{R} \times \mathbb{R} \times \mathbb{R} = \mathbb{R}^3 = \{(x,y,z)|x,y,z \in \mathbb{R}\}$  is the set of all ordered triplets of real numbers. We have given a one-to-one correspondence between points P in space and ordered triplets (a,b,c) in  $\mathbb{R}^3$ . It is called a **tree-dimensional rectangular coordinate system**.

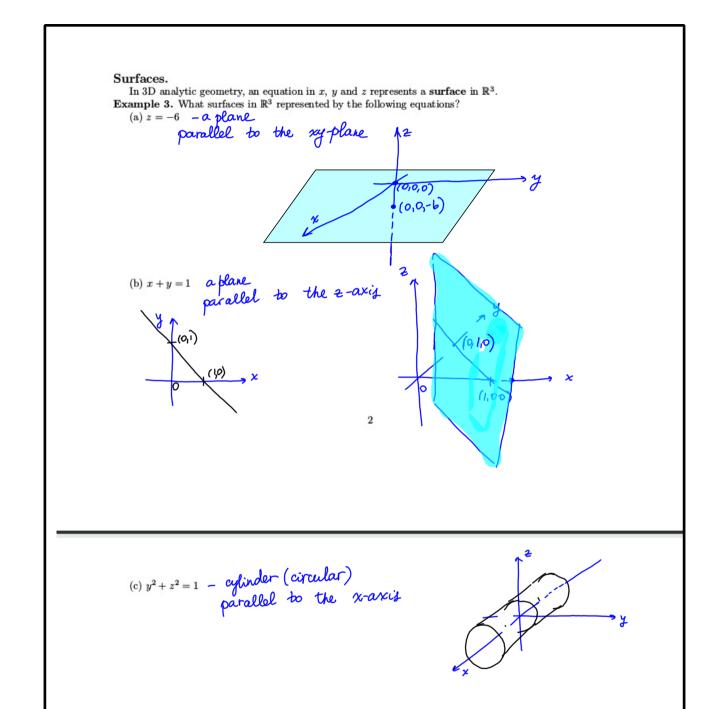


Example 1. Sketch the points (1,3,5), (-2,-1,3), (0,2,-5) on a single set of coordinate axes.



Example 2. Draw a rectangular box with the origin and (2, 4, 5) as opposite vertices and with its faces parallel to coordinate planes. Label all vertices of the box.





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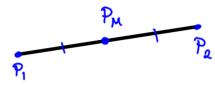
Distance and Spheres.

The distance formula in three dimensions. The distance  $|P_1P_2|$  between the points  $P_1(x_1, y_1, z_1)$  and  $P_2(x_2, y_2, z_2)$  is

$$|P_1P_2| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

The midpoint of the line segment from  $P_1(x_1, y_1, z_1)$  to  $P_2(x_2, y_2, z_2)$  is

$$\boxed{P_{M}\left(\frac{x_{1}+x_{2}}{2},\frac{y_{1}+y_{2}}{2},\frac{z_{1}+z_{2}}{2}\right)}$$



**Example 4.** Find the length of the sides and medians of a triangle with vertices A(2,-1,0), B(4,1,1), C(4,-5,4).

$$|AC| = \sqrt{(4-2)^2 + (-5-(-1))^2 + (4-0)^2} = \sqrt{4+16+16} = \sqrt{36} = 6$$

$$L \text{ is the midpoint of the segment AC.}$$

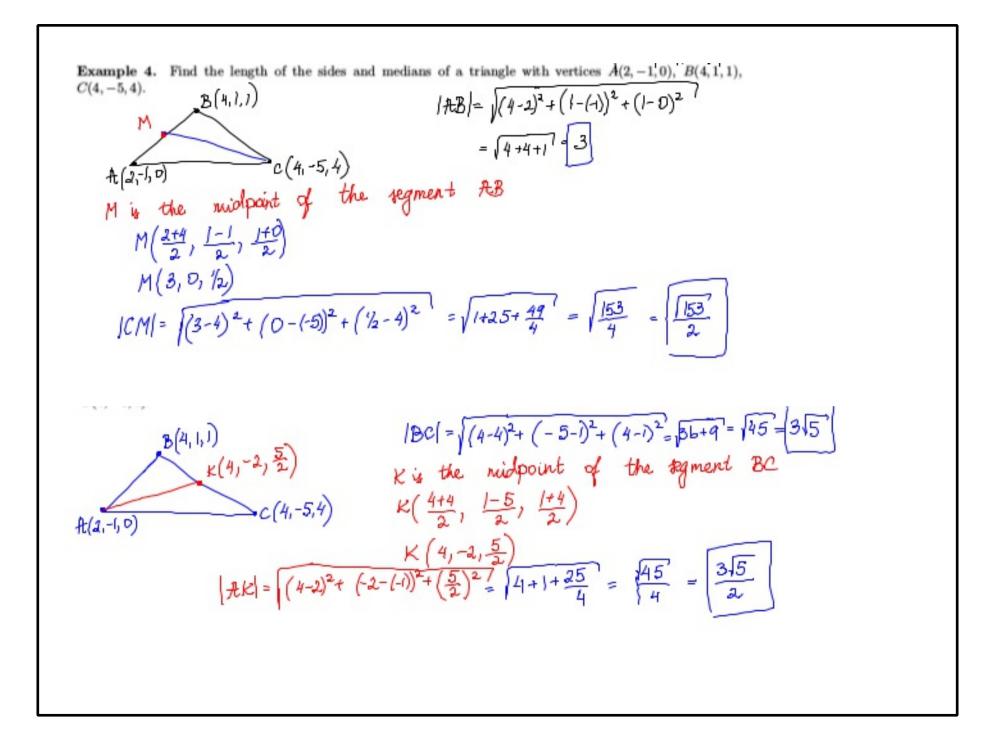
$$C(4,-5,4)$$

$$L\left(\frac{2+4}{2}, \frac{-1-5}{2}, \frac{4+0}{2}\right)$$

$$L(3,-3,2)$$

$$L(3,-3,2)$$

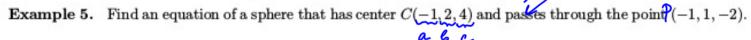
$$|BL| = \sqrt{3-4}^2 + (-3-1)^2 + (2-1)^2 = \sqrt{1+|b+1|} = \sqrt{18} = \boxed{3/2}$$



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Equation of a sphere of radius R and center C(a,b,c) is

$$(x-a)^2 + (y-b)^2 + (z-c)^2 = R^2$$



$$R^{2} |CP|^{2} = (-1 - (-1))^{2} + (1 - 2)^{2} + (-2 - 4)^{2} = 1 + 36 = 37$$

$$(x+1)^{2} + (y-2)^{2} + (2-4)^{2} = 37$$

Example 6. Show that the equation

$$x^2 + y^2 + z^2 + 8x - 6y + 2z + 17 = 0$$

represents a sphere. Find its center and radius.