# HD MAPS MOBILE MAPPING AND MODELLING

DR DEJAN VASIĆ





#### **AGENDA**

#### **ABOUT US**

- WHO WE ARE
- WHAT WE OFFER

## MOBILE MAPPING DATA POINT CLOUD DATA PROCESSING

- INITIAL DATA PROCESSING
- POINT CLOUD RUN
   MATCHING
- POINT CLOUD
   CLASSIFICATION
- FEATURE EXTRACTION

#### MOBILE MAPPING PROJECTS PRACTICAL APPLICATION

- TOPOGRAPHIC MAPS
- CLEARANCEMEASUREMENTS
- HD MAPS
- VISUALISATION





#### **SOMETHING ABOUT US**



WHO WE ARE

**OUR MISION** 

DataDEV is founded as a private-owned company located in Europe, Germany and Serbia. The company team is composed of experts from various technical and programming fields.

Our mission is to develop disruptive Artificial Intelligence (AI) mapping technology for (near) real-time HD-map generation. Our goal is to be regional technology leader.

#### WHAT WE OFFER

**MOBILE MAPPING** 

3D CAD AND BIM MODELS

HAD MAPS

**IMAGE BLURRING** 



#### **MOBILE MAPPING**

Mobile laser scanning is an emerging technology capable of capturing three dimensional data from surrounding objects. With state-of-the-art sensors, the achieved point clouds capture object details with good accuracy and precision.



#### HAD MAPS

DataDEV works on creation of the digital platforms for driving simulation using real time spatial information that have been made within Mobile Mapping System.



#### **3D CAD AND BIM MODELS**

Our highly skilled technicans have vast experience in the manipulation and conversion of a point cloud data into CAD or BIM products.



#### **IMAGE BLURRING**

DataDEV offers reliable methodology and fully automated procedures for blurring of faces and license plates.

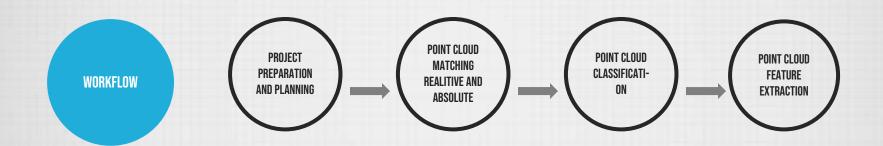
The blurring of faces and license plates is required in order to comply privacy laws.





#### **MOBILE MAPPING DATA PROCESSING**

#### **PROCEDURES**

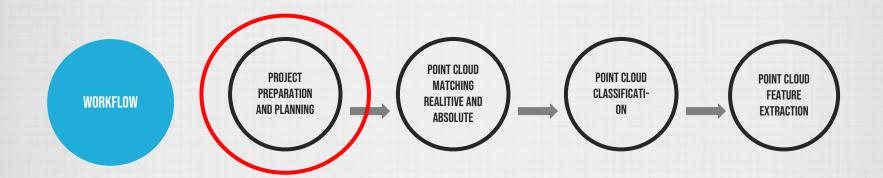






#### **MOBILE MAPPING DATA PROCESSING**

#### **PROCEDURES**







## **MOBILE MAPPING SYSTEMS**







RIEGL VMX 250

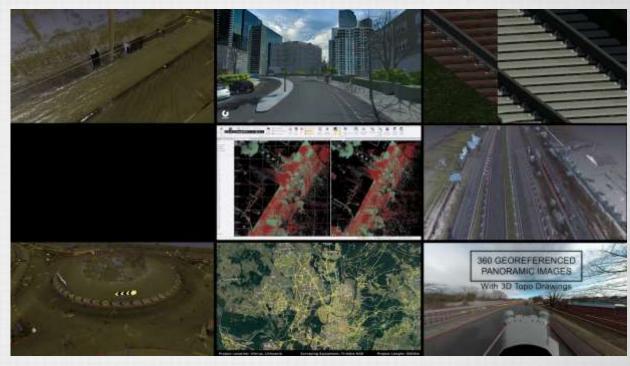






#### PROJECT PREPARATION AND PLANING

- POINT CLOUD INITIAL PROCESSING
  - GNSS CORECTION POSPAC
  - TRAJECTORY PROCESSING
  - POINT CLOUD COLOURISATION
  - POINT CLOUD EXPORT



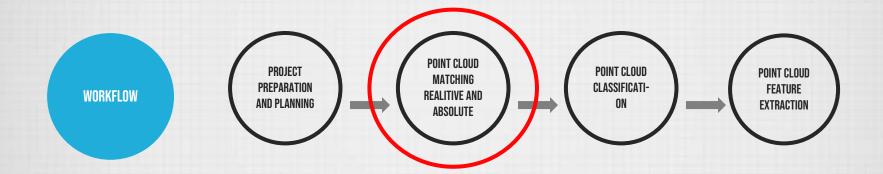




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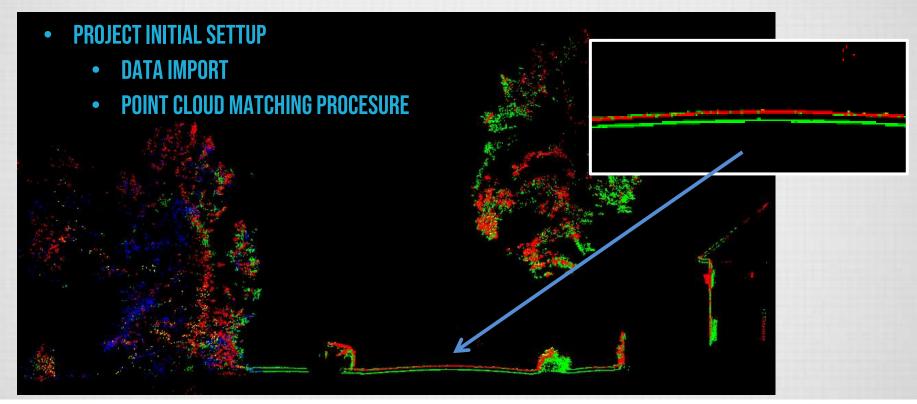
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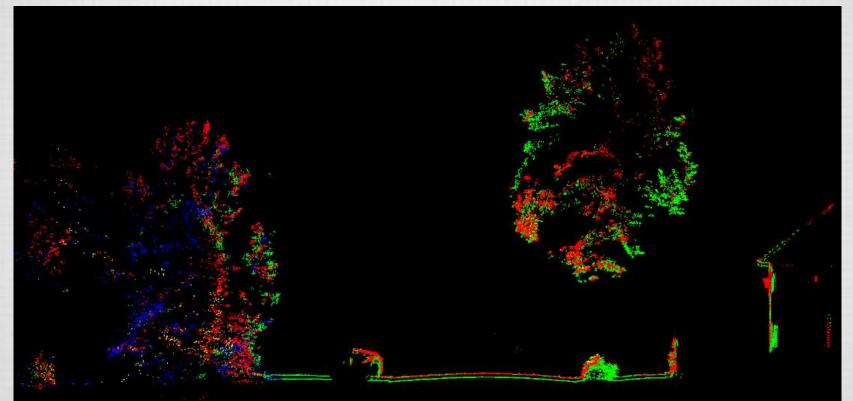






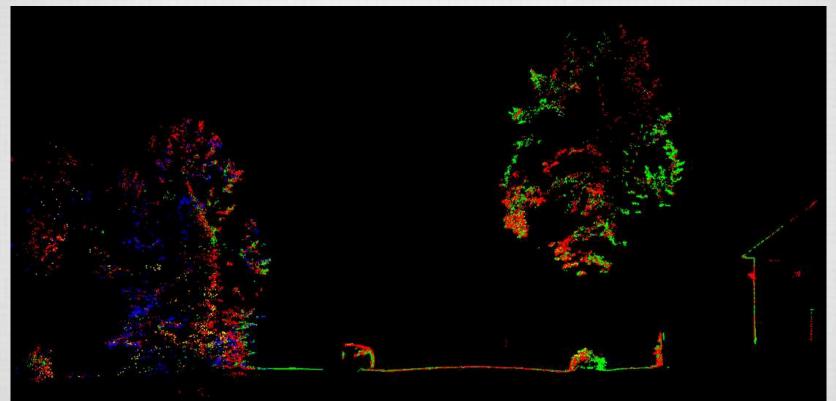








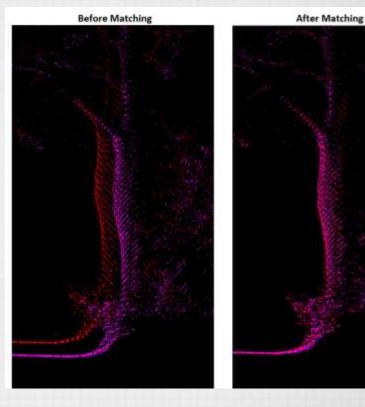








- POINT CLOUD AND IMAGERY MATCHING
- CONTROL POINTS
- KNOWN PROBLEMS
- COMERCIAL SOFTWARES
- MANUAL PROCEDURES
- AUTOMATIC PROCEDURES

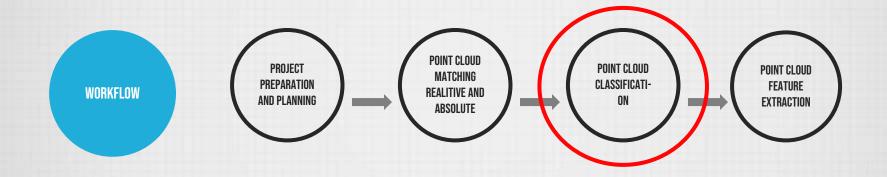






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#### **PROCEDURES**







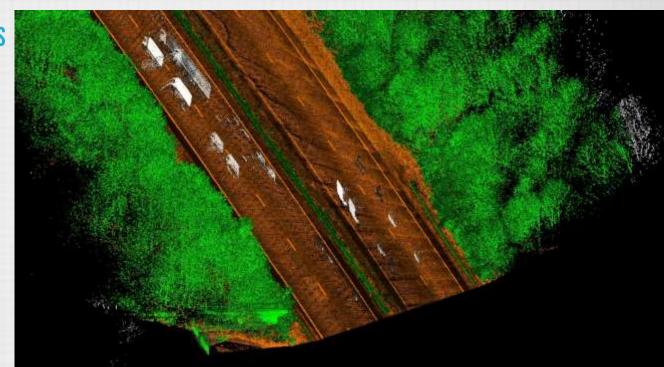
- POINT CLOUD CLASSIFICATION
  - DIFFERENT APPROACHES







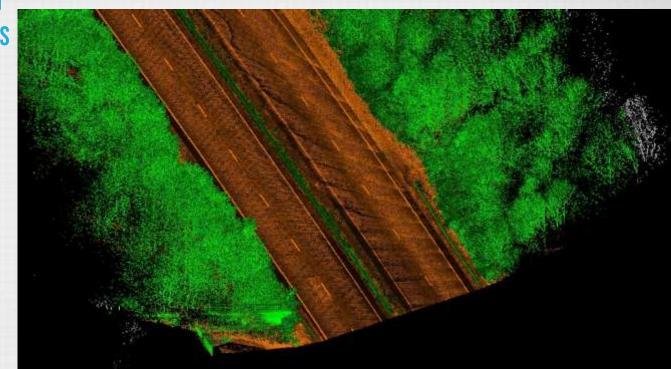
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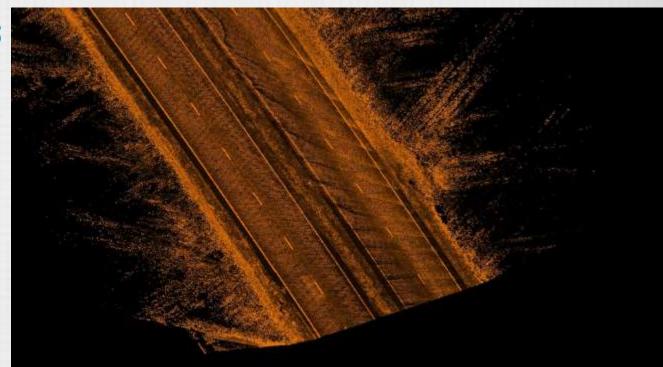
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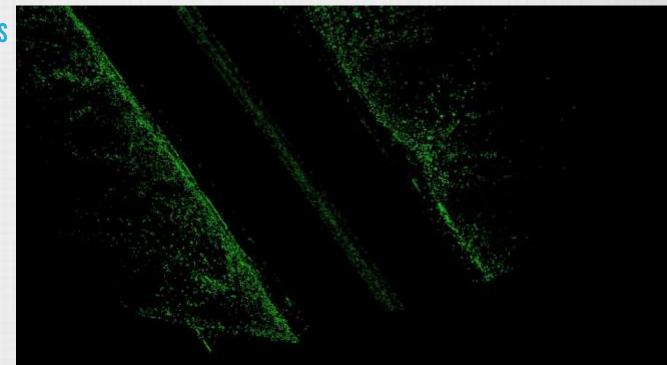
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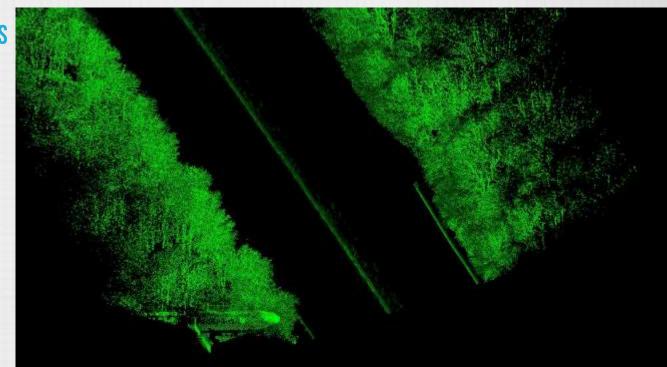
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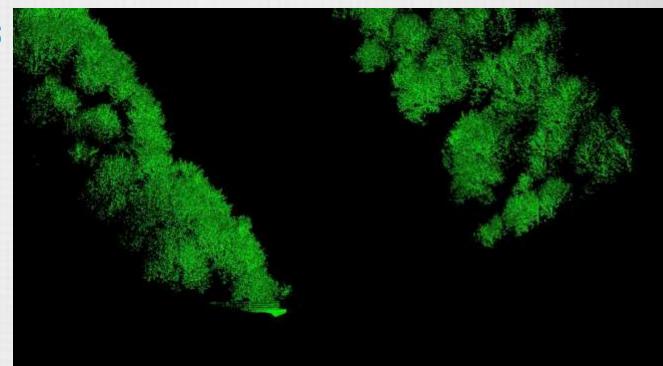
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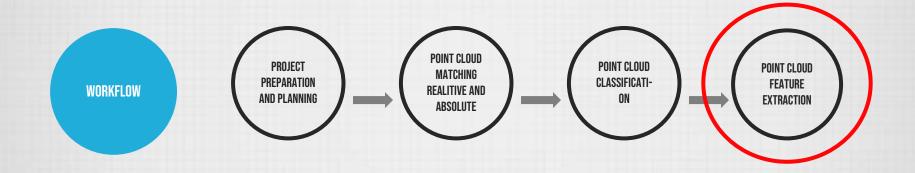




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#### **MOBILE MAPPING DATA PROCESSING**

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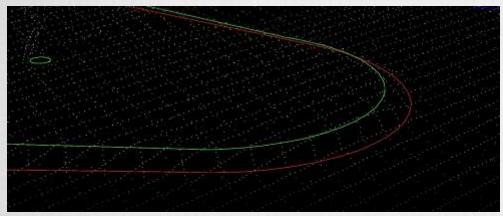
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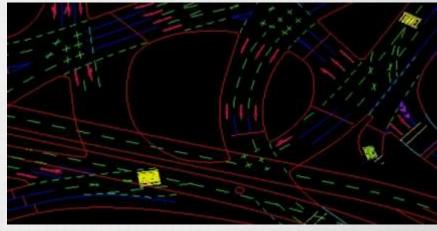






CURBS AND EDGE OF ROAD

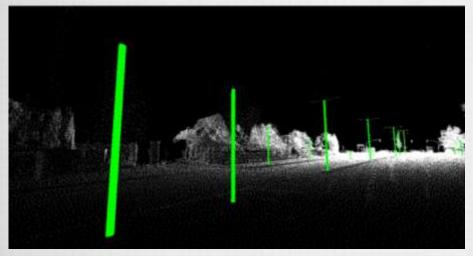


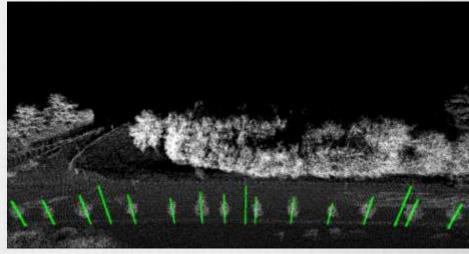






• STREET LIGHTINGS AND PILARS

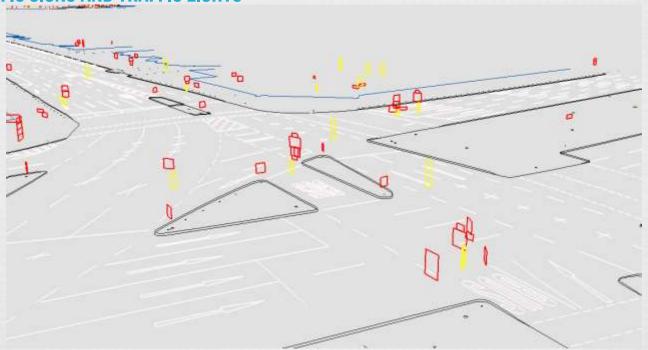








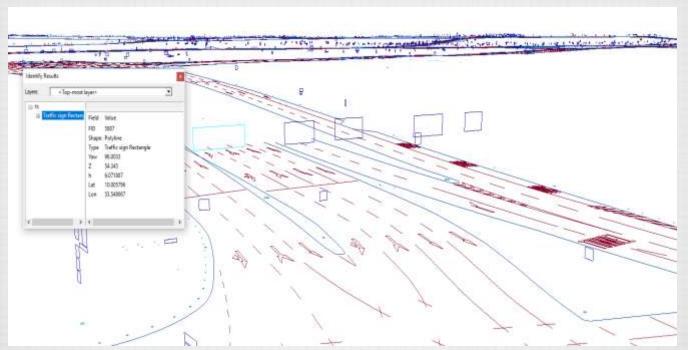
TRAFFIC SIGNS AND TRAFFIC LIGHTS







• TRAFFIC SIGNS AND TRAFFIC LIGHTS













- TOPOGRAPHIC MAPS
- CLEARANCE MEASUREMENT
- HD MAPS
- VISUALIZATION

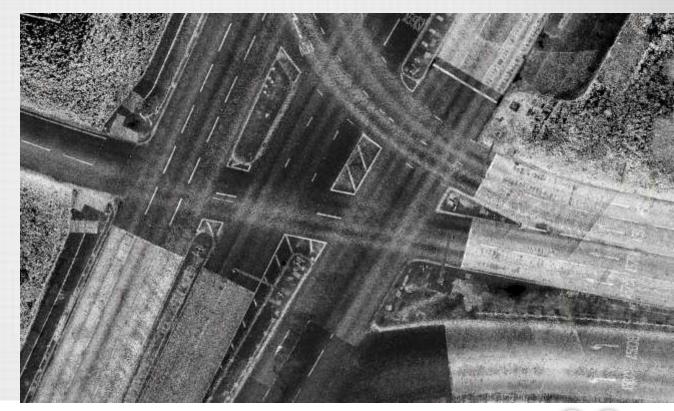




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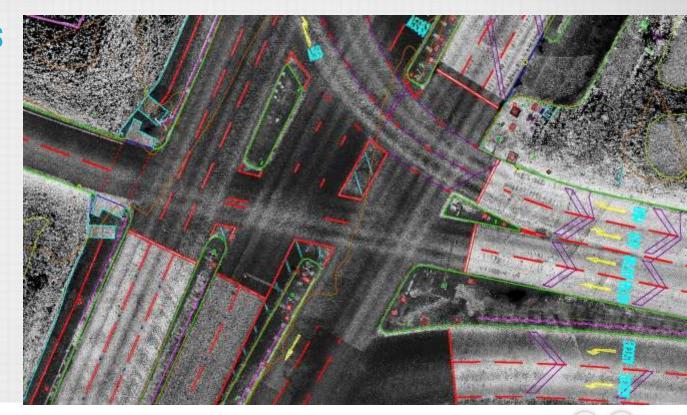






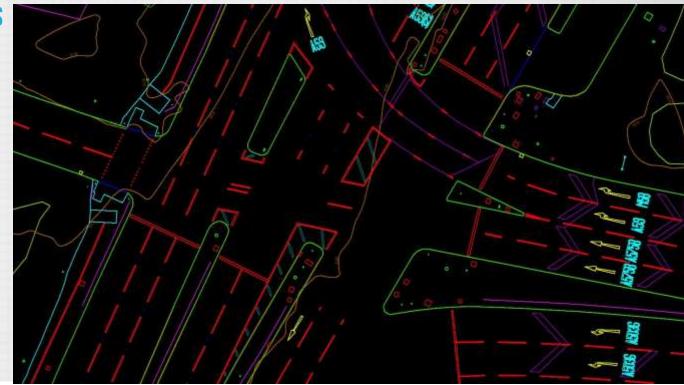












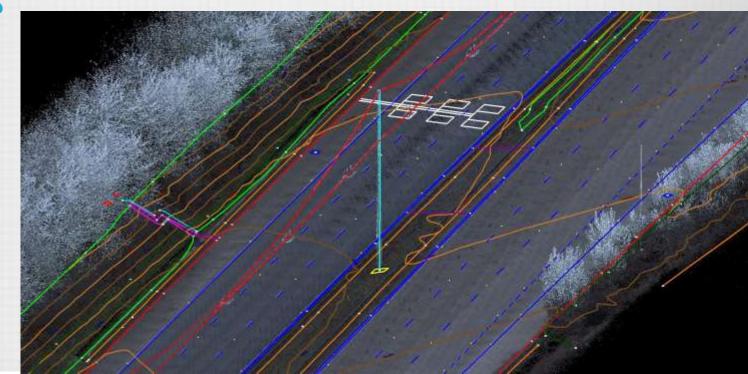






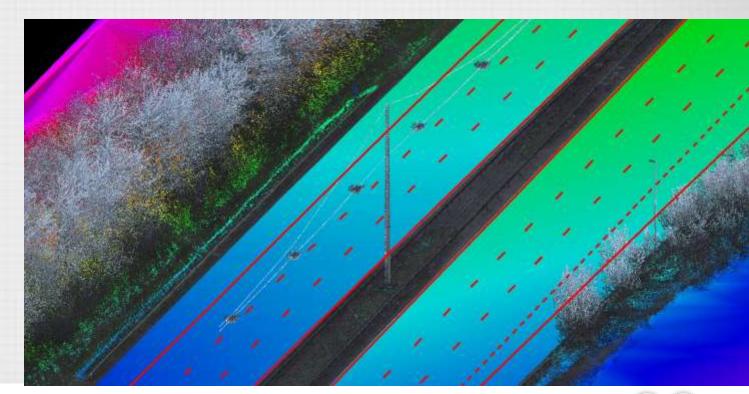
















- TOPOGRAPHIC MAPS
- CLEARANCE MEASUREMENT
- HD MAPS
- VISUALIZATION

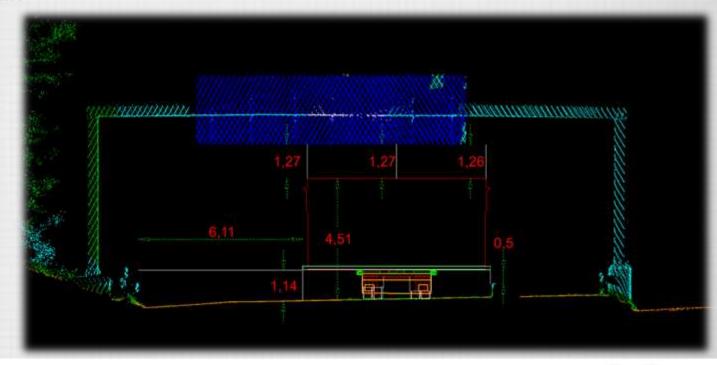




- CLEARANCE MEASUREMENT
  - RISK ASSESMENT IN THE TRANSPORT OF OBJECTS OF LARGE DIMENSIONS
  - DATA PROCESSING LABEL CLEARANCE TOOL POLYGON REPRESENTING EDGE OF ROAD SURFACE AUTOMATICAL DETECTION OF CRITICAL PLACES WHERE VEHICLE COINCIDENCES WITH TUNNEL OR OVERPASS POINTS TRANSFERED TO PREDEFINED COINCIDENCE CLASS

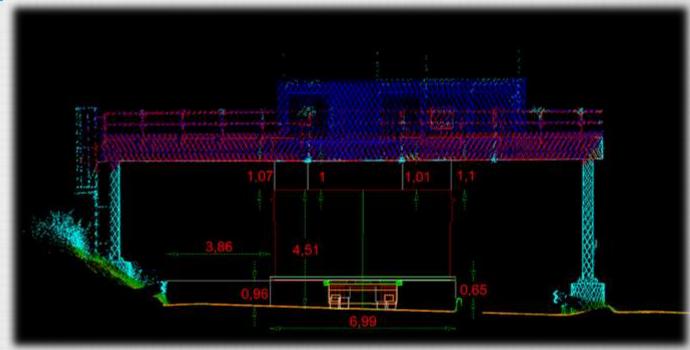






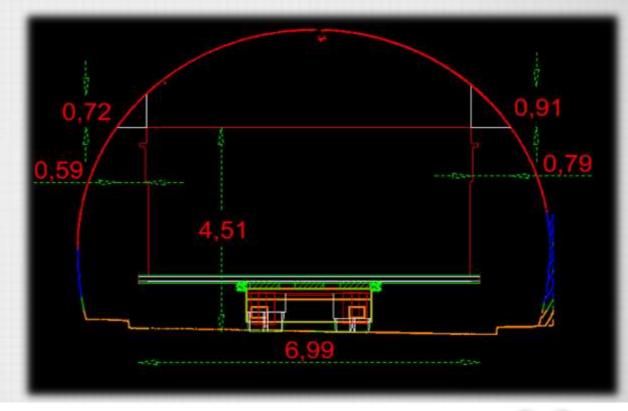




















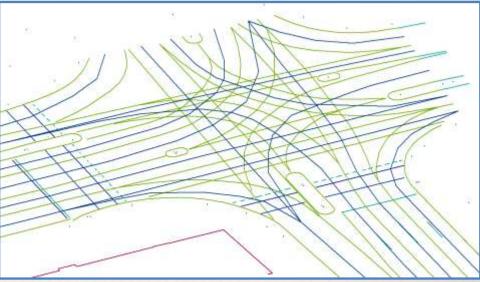


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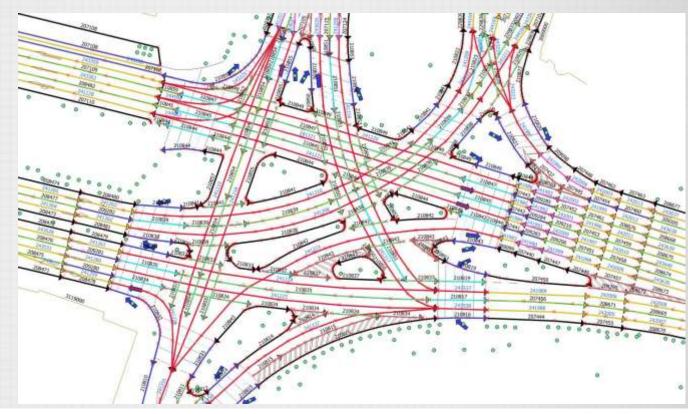






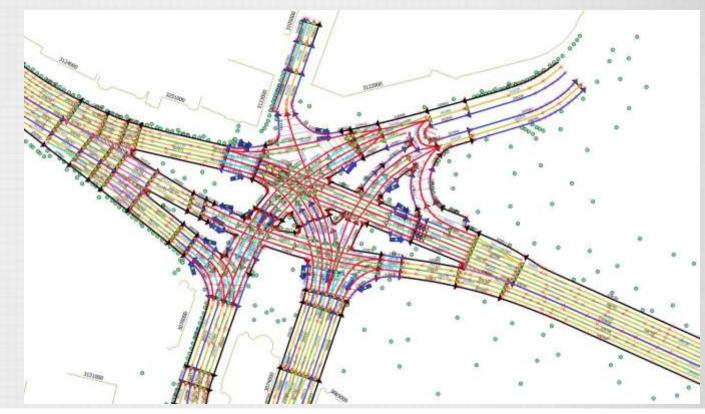






















- TOPOGRAPHIC MAPS
- CLEARANCE MEASUREMENT
- HD MAPS
- VISUALIZATION





VISUALISATION







#### **OUR CONTACT DETAILS**

Contact us and we will answer your request!



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# THANK YOU FOR YOUR TIME!

