

# The Theoretical Minimum

## Classical Mechanics - Solutions

L10E03

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**Exercise 1.** *Using the definition of PB's and the axioms, work out the PB's in Equations (19). Hint: In each expression, look for things in the parentheses that have non-zero Poisson Brackets with the coordinate  $x$ ,  $y$  or  $z$ . For example, in the first PB,  $x$  has a nonzero PB with  $p_x$ .*

Let's start by recalling Equations (19):

$$\begin{aligned}\{x, L_z\} &= \{x, (xp_y - yp_x)\} \\ \{y, L_z\} &= \{y, (xp_y - yp_x)\} \\ \{z, L_z\} &= \{z, (xp_y - yp_x)\}\end{aligned}$$

Then, let's make things a little clearer/regular by renaming our coordinate variables:

$$x = q_x; \quad y = q_y; \quad z = q_z$$

So, for  $k \in \{x, y, z\}$  (that's the set containing  $x$ ,  $y$  and  $z$ , not a weird Poisson bracket), then all the Poisson brackets to compute are of the form:

$$\{q_k, L_z\} = \{q_k, (q_x p_y - q_y p_x)\}$$

Let's reduce it from the axioms:

$$\begin{aligned}\{q_k, L_z\} &= \{q_k, (q_x p_y - q_y p_x)\} \\ &= -\{(q_x p_y - q_y p_x), q_k\} \quad (\text{anti-symmetry}) \\ &= -(\{q_x p_y, q_k\} - \{q_y p_x, q_k\}) \quad (\text{linearity}) \\ &= \{q_y p_x, q_k\} - \{q_x p_y, q_k\} \\ &= \left( q_y \underbrace{\{p_x, q_k\}}_{=0} + p_x \underbrace{\{q_y, q_k\}}_{=0} \right) - \left( q_x \underbrace{\{p_y, q_k\}}_{=0} + p_y \underbrace{\{q_x, q_k\}}_{=0} \right) \quad (\text{product rule}) \\ &= q_y \{p_x, q_k\} - q_x \{p_y, q_k\} \quad \{q_i, q_j\} = 0\end{aligned}$$

Now suffice for us to evaluate that last expression with each value of  $k$ , and simplify the result with  $\{q_i, p_j\} = \delta_i^j$ :

$$\begin{aligned}k = x &: \{q_x, L_z\} = q_y \{p_x, q_x\} - q_x \{p_y, q_x\} = q_y \\ k = y &: \{q_y, L_z\} = q_y \{p_x, q_y\} - q_x \{p_y, q_y\} = -q_x \\ k = z &: \{q_z, L_z\} = q_y \{p_x, q_z\} - q_x \{p_y, q_z\} = 0\end{aligned}$$

Or, with the original notations:

$\{x, L_z\}$	$=$	$y$
$\{y, L_z\}$	$=$	$-x$
$\{z, L_z\}$	$=$	$0$

**Remark 1.** *Our solution slightly differs from the one in the book, as the latter contains a small sign error: the infinitesimal rotation is said to be:*

$$\begin{aligned}\delta_x &= -\epsilon y \\ \delta_y &= \epsilon x\end{aligned}$$

*But earlier in the 7th lecture (p135), it was defined to be, small renaming aside:*

$$\begin{aligned}\delta_x &= \epsilon y \\ \delta_y &= -\epsilon x\end{aligned}$$