

The Theoretical Minimum

Classical Mechanics - Solutions

I03E01

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Exercise 1. Compute all first and second partial derivatives—including mixed derivatives—of the following functions.

$$\begin{aligned}x^2 + y^2 &= \sin(xy) \\ \frac{x}{y} e^{(x^2+y^2)} \\ e^x \cos y\end{aligned}$$

This is again a simple differentiation exercise. We're not going to go too much in details; you may want to refer to L02E01 if you need a more detailed treatment. The process is very mechanical: use linearity to isolate constants and propagate differentiation to individual terms, if there's a product of functions, use the product rule, and if you can represent an expression as a composition of functions, often by introducing intermediate functions, apply the chain rule.

Regarding partial differentiation, the key thing is to consider all arguments of a function to be constants but the one we're differentiating the function against.

$E(x, y) : x^2 + y^2 = \sin(xy)$

This looks more like an expression than a function; we'll interpret its differentiation to be the differentiation of each part of the equality.

$\frac{\partial}{\partial x} E(x, y) : 2x = y \cos(xy);$	$\frac{\partial}{\partial y} E(x, y) : 2y = x \cos(xy)$
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We may now compute second order derivatives:

$\frac{\partial^2}{\partial x^2} E(x, y) : 2 = -y^2 \sin(xy);$	$\frac{\partial^2}{\partial y^2} E(x, y) : 2 = -x^2 \sin(xy)$
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And assuming the symmetry of second derivatives:

$$\frac{\partial^2}{\partial x \partial y} E(x, y) = \frac{\partial^2}{\partial y \partial x} E(x, y) : \boxed{2 = \cos(xy) - xy \sin(xy)}$$

Remark 1. The fact that:

$$\frac{\partial^2}{\partial x \partial y} \varphi = \frac{\partial^2}{\partial y \partial x} \varphi$$

Isn't so obvious, mathematically speaking: the result is called *Clairaut's theorem*, or *Schwarz's theorem*¹. It requires φ to have **continuous second partial derivatives**. In the context of classical mechanics, almost always we'll be dealing with smooth² functions of time (positions/velocities/accelerations, so we'll always assume it to be true.

¹https://en.wikipedia.org/wiki/Symmetry_of_second_derivatives

²<https://en.wikipedia.org/wiki/Smoothness>

$$\varphi(x, y) = \frac{x}{y} e^{(x^2+y^2)}$$

First order derivatives; we can go a little slower here. Essentially, reserve the constant $(1/y)$, apply the product rule followed by a chain rule:

$$\begin{aligned} \frac{\partial}{\partial x} \varphi(x, y) &= \frac{1}{y} \frac{\partial}{\partial x} x e^{(x^2+y^2)} \\ &= \frac{1}{y} \left(\left(\frac{\partial}{\partial x} x \right) e^{(x^2+y^2)} + x \left(\frac{\partial}{\partial x} e^{(x^2+y^2)} \right) \right) \\ &= \frac{1}{y} \left(e^{(x^2+y^2)} + x \left(\frac{\partial}{\partial x} x^2 + y^2 \right) e^{(x^2+y^2)} \right) \\ &= \boxed{\frac{1}{y} (2x^2 + 1) e^{(x^2+y^2)}} \end{aligned}$$

Remark 2. As I don't think this has been encountered before, note that we'll use the following "identity":

$$x^{-n} = \frac{1}{x^n}$$

to help compute the derivatives of x^{-n} using the rule to derivate x^n :

$$\frac{d}{dx} \frac{1}{x^n} = \frac{d}{dx} x^{-n} = -n x^{-n-1} = -n \frac{1}{x^{n+1}}$$

And so for the other first order-derivative:

$$\begin{aligned} \frac{\partial}{\partial y} \varphi(x, y) &= x \frac{\partial}{\partial y} y^{-1} e^{(x^2+y^2)} \\ &= \boxed{x e^{(x^2+y^2)} \left(2 - \frac{1}{y^2} \right)} \end{aligned}$$

Then for the (non-mixed) second order derivatives:

$$\begin{aligned} \frac{\partial^2}{\partial x^2} \varphi(x, y) &= \frac{1}{y} \frac{\partial^2}{\partial x^2} (2x^2 + 1) e^{(x^2+y^2)}; & \frac{\partial^2}{\partial y^2} \varphi(x, y) &= x \frac{\partial^2}{\partial y^2} e^{(x^2+y^2)} (2 - y^{-2}) \\ &= \frac{1}{y} e^{(x^2+y^2)} (4x + (2x^2 + 1)2x); & &= x e^{(x^2+y^2)} ((2 - y^{-2})2y + 2y^{-3}) \\ &= \boxed{\frac{x}{y} (4x^2 + 6) e^{(x^2+y^2)}}; & &= \boxed{2x e^{(x^2+y^2)} \left(2y - \frac{1}{y} + \frac{1}{y^3} \right)} \end{aligned}$$

Finally, for the mixed second derivatives:

$$\frac{\partial^2}{\partial x \partial y} \varphi(x, y) = (2x^2 + 1) e^{(x^2+y^2)} (-y^{-2} + y^{-1}2y) = \boxed{(2x^2 + 1) e^{(x^2+y^2)} \left(2 - \frac{1}{y^2} \right)}$$

Remark 3. There's a common shortcut notation for partial derivatives that we will use from now on:

$$\frac{\partial}{\partial x} \varphi = \varphi_x; \quad \frac{\partial^2}{\partial x^2} \varphi = \varphi_{x,x}; \quad \frac{\partial^2}{\partial y \partial x} \varphi = \varphi_{x,y}$$

$$\phi(x, y) = e^x \cos y$$

$$\begin{aligned} \phi_x(x, y) &= \boxed{e^x \cos y}; & \phi_y(x, y) &= \boxed{-e^x \sin y} \\ \phi_{x,x}(x, y) &= \boxed{e^x \cos y}; & \phi_{y,y}(x, y) &= \boxed{-e^x \cos y} \\ \phi_{x,y}(x, y) &= \phi_{y,x}(x, y) = \boxed{-e^x \sin y} \end{aligned}$$