

به نام خدا

آشنایی با زبان AVR C

انواع داده

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Why program the AVR in C?

- Compilers produce hex files
 - We download it into the Flash of μC
 - The size of hex file is one of main concerns
 - Because of the limited on-chip Flash
- The choice of programming language affects the compiled program size
 - Assembly language produce a hex file that is much **smaller** than C
 - Assembly language is often **tedious** and **time consuming**
 - C programming is less time consuming and much **easier** to write
 - But the size is much **larger**

Major reasons for programming in C instead of Assembly

- ✓ It is easier and less time consuming
- ✓ Easier to modify and update
- ✓ You can use code available in function libraries
- ✓ C code is portable to other μ Cs with little or no modification

C Data Types for AVR C

- To create smaller hex file
 - You need, A good understanding of C data types
- Most common and widely used data types

Some Data Types Widely Used by C Compilers

Data Type	Size in Bits	Data Range/Usage
unsigned char	8-bit	0 to 255
char	8-bit	−128 to +127
unsigned int	16-bit	0 to 65,535
int	16-bit	−32,768 to +32,767
unsigned long	32-bit	0 to 4,294,967,295
long	32-bit	−2,147,483,648 to +2,147,483,648
float	32-bit	±1.175e-38 to ±3.402e38
double	32-bit	±1.175e-38 to ±3.402e38

Unsigned char

- Because the AVR is an 8-bit μ C
 - The character data type is the most natural choice
- Range: 0-255 (00-FF H)
- In situations, such as setting a counter value
- We must pay careful attention to the size of data
 - Try to use unsigned char instead of int, if possible
- C compilers use the signed char as the default
 - Unless we put the keyword unsigned in front of the char
- In situations where + and – are needed to represent a given quantity such as temperature
 - The use of signed char is necessary

Unsigned int

- Unsigned int is a 16-bit data type
- Used to define 16-bit variables such as memory addresses
 - Also set counter values of more than 256
- Because AVR is an 8-bit μ C, int data type takes 2 bytes of RAM
 - We must not use int data type unless we have to!
 - Misuse of int result in
 - Larger hex files
 - Slower execution
 - More memory usage
 - Such misuse is not problem in PCs (with 512 MB, bus speed 133 Mhz, ...)

Other Data Types

- Unsigned int is limited to 0-65,535 (0000-FFFF H)
- For values greater than 16-bit
 - AVR C compiler supports long data types
- Also to deal with fractional numbers
 - Float
 - Double

Data Types

Write an AVR C program to toggle all bits of Port B 50,000 times.

```
#include <avr/io.h>           //standard AVR header
int main(void)
{
    unsigned int z;
    DDRB = 0xFF;               //PORTB is output

    for(z=0; z<50000; z++)
    {
        PORTB = 0x55;
        PORTB = 0xAA;
    }

    while(1);                  //stay here forever
    return 0;
}
```


Data Types

Write an AVR C program to toggle all bits of Port B 100,000 times.

```
//toggle PB 100,00 times
#include <avr/io.h>                                //standard AVR header
int main(void)
{
    unsigned long z;                                //long is used because it should
                                                    //store more than 65535.
    DDRB = 0xFF;                                     //PORTB is output

    for(z=0; z<100000; z++){
        PORTB = 0x55;
        PORTB = 0xAA;
    }

    while(1);                                        //stay here forever
    return 0;
}
```

Time Delay

- There are three ways to create a time delay in AVR C:
 - Using a simple for loop
 - Using predefined C functions
 - Using AVR timers
- In creating a time delay using for loop, there are two factors that can affect the accuracy of the delay:
 - The Crystal frequency
 - The Compiler used to compile the C program
 - Because it is the C compiler that convert C statements and functions to assembly language instructions
 - Different compilers produce different code
 - For the above reasons, we must use oscilloscope to measure the exact duration

Time Delay

Write an AVR C program to toggle all the bits of Port B continuously with a 100 ms delay. Assume that the system is ATmega 32 with XTAL = 8 MHz.

```
#include <avr/io.h>                //standard AVR header
void delay100ms(void)
{
    unsigned int i;
    for(i=0; i<42150; i++);        //try different numbers on your
    //compiler and examine the result.

int main(void)
{
    DDRB = 0xFF;                  //PORTB is output
    while (1)
    {
        PORTB = 0xAA;
        delay100ms();
        PORTB = 0x55;
        delay100ms();
    }
    return 0;
}
```

Predefined Functions Time Delay

- Generating time delay using predefined functions:
 - `delay_ms()`
 - `delay_us()`
- Drawback of using these functions
 - Portability problem
 - Because different compilers do not use the same name for delay functions
 - You have to change every place in which the delay functions are used
 - To compile the program on another compiler
 - To overcome the problem
 - Use macro or wrapper function
 - Wrapper functions do nothing more than call the predefined delay function
 - Instead of changing all instances of predefined delay functions, you simply change the wrapper function

Predefined Functions Time Delay

Write an AVR C program to toggle all the pins of Port C continuously with a 10 ms delay. Use a predefined delay function in Win AVR.

```
#include <util/delay.h>           //delay loop functions
#include <avr/io.h>               //standard AVR header

int main(void)
{
    void delay_ms(int d)          //delay in d microseconds
    {
        _delay_ms(d);
    }
    DDRB = 0xFF;                  //PORTA is output
    while (1){
        PORTB = 0xFF;
        delay_ms(10);
        PORTB = 0x55;
        delay_ms(10);
    }
    return 0;
}
```

I/O programming in C

- To access a PORT register as a byte
 - We use the PORTx label
 - x indicates the name of the port
- To access the data direction register
 - We use DDRx label
 - x indicates the name of the port
- To access a PIN register
 - We use PINx label
 - x indicates the name of the port

I/O programming in C

LEDs are connected to pins of Port B. Write an AVR C program that shows the count from 0 to FFH (0000 0000 to 1111 1111 in binary) on the LEDs.

```
#include <avr/io.h>                //standard AVR header
int main(void)
{
    DDRB = 0xFF;                    //Port B is output
    while (1)
    {
        PORTB = PORTB + 1;
    }
    return 0;
}
```

I/O programming in C

Write an AVR C program to get a byte of data from Port B, and then send it to Port C.

```
#include <avr/io.h>                //standard AVR header
int main(void)
{
    unsigned char temp;

    DDRB = 0x00;                    //Port B is input
    DDRC = 0xFF;                    //Port C is output

    while(1)
    {
        temp = PINB;
        PORTC = temp;
    }
    return 0;
}
```


I/O programming in C

Write an AVR C program to get a byte of data from Port C. If it is less than 100, send it to Port B; otherwise, send it to Port D.

```
#include <avr/io.h>                //standard AVR header
int main(void)
{
    DDRC = 0;                      //Port C is input
    DDRB = 0xFF;                   //Port B is output
    DDRD = 0xFF;                   //Port D is output
    unsigned char temp;
    while(1)
    {
        temp = PINC;               //read from PINB
        if ( temp < 100 )
            PORTB = temp;
        else
            PORTD = temp;
    }
    return 0;
}
```

Bit size I/O

- I/O ports of ATmega32 are bit-accessible
 - But some AVR C compilers do not support this features
 - Also, there is no standard way of using it
- To set the first pin of Port B
 - In Code Vision, we can use
`PORTB.0=1`
 - But it can not be used in other compilers such as WinAVR
- To write portable code
 - We must use AND or OR bit-wise operations

Logic Operations in C

- Bit-Wise operators in C
 - Widely used in software engineering for embedded system and control

Bit-wise Logic Operators for C

		AND	OR	EX-OR	Inverter
A	B	A&B	A B	A^B	Y= ~B
0	0	0	0	0	1
0	1	0	1	1	0
1	0	0	1	1	
1	1	1	1	0	

The following shows some examples using the C bit-wise operators:

1. `0x35 & 0x0F = 0x05` `/* ANDing */`
2. `0x04 | 0x68 = 0x6C` `/* ORing */`
3. `0x54 ^ 0x78 = 0x2C` `/* XORing */`
4. `~0x55 = 0xAA` `/* Inverting 55H */`

Logic Operations in C

```
#include <avr/io.h>           //standard AVR header
int main(void)
{
    DDRB = 0xFF;               //make Port B output
    DDRC = 0xFF;               //make Port C output
    DDRD = 0xFF;               //make Port D output
    PORTB = 0x35 & 0x0F;       //ANDing
    PORTC = 0x04 | 0x68;       //ORing
    PORTD = 0x54 ^ 0x78;       //XORing
    PORTB = ~0x55;             //inverting
    while (1);
    return 0;
}
```

Logic Operations in C

Write an AVR C program to toggle only bit 4 of Port B continuously without disturbing the rest of the pins of Port B.

```
#include <avr/io.h>                                //standard AVR header

int main(void)
{
    DDRB = 0xFF;                                     //PORTB is output

    while(1)
    {
        PORTB = PORTB | 0b00010000;                //set bit 4 (5th bit) of PORTB
        PORTB = PORTB & 0b11101111;                //clear bit 4 (5th bit) of PORTB
    }

    return 0;
}
```

Logic Operations in C

Write an AVR C program to monitor bit 5 of port C. If it is HIGH, send 55H to Port B; otherwise, send AAH to Port B.

```
#include <avr/io.h>           //standard AVR header

int main(void)
{
    DDRB = 0xFF;               //PORTB is output
    DDRC = 0x00;               //PORTC is input
    DDRD = 0xFF;               //PORTB is output

    while(1)
    {
        if (PINC & 0b00100000) //check bit 5 (6th bit) of PINC
            PORTB = 0x55;
        else
            PORTB = 0xAA;
    }

    return 0;
}
```

Logic Operations in C

A door sensor is connected to bit 1 of Port B, and an LED is connected to bit 7 of Port C. Write an AVR C program to monitor the door sensor and, when it opens, turn on the LED.

```
#include <avr/io.h>                //standard AVR header

int main(void)
{
    DDRB = DDRB & 0b11111101;      //pin 1 of Port B is input
    DDRC = DDRC | 0b10000000;      //pin 7 of Port C is output

    while(1)
    {
        if (PINB & 0b000000010)    //check pin 1 (2nd pin) of PINB
            PORTC = PORTC | 0b10000000; //set pin 7 (8th pin) of PORTC
        else
            PORTC = PORTC & 0b01111111; //clear pin 7 (8th pin) of PORTC
    }
    return 0;
}
```

Compound Assignment Operators in C

- To reduce coding (typing)
 - We can use compound statements

Compound Assignment Operator in C

Operation	Abbreviated Expression	Equal C Expression
And assignment	<code>a &= b</code>	<code>a = a & b</code>
OR assignment	<code>a = b</code>	<code>a = a b</code>

```
#include <avr/io.h>           //standard AVR header
int main(void)
{
    DDRB &= 0b11011111;      //bit 5 of Port B is input
    DDRC |= 0b10000000;      //bit 7 of Port C is output

    while (1)
    {
        if(PINB & 0b00100000)
            PORTC |= 0b10000000; //set bit 7 of Port C to 1
        else
            PORTC &= 0b01111111; //clear bit 7 of Port C to 0
    }
    return 0;
}
```


Bit-wise Shift Operation in C

Bit-wise Shift Operators for C

Operation	Symbol	Format of Shift Operation
Shift right	>>	data >> number of bits to be shifted right
Shift left	<<	data << number of bits to be shifted left

The following shows some examples of shift operators in C:

1. `0b00010000 >> 3 = 0b00000010` `/* shifting right 3 times */`
2. `0b00010000 << 3 = 0b10000000` `/* shifting left 3 times */`
3. `1 << 3 = 0b00001000` `/* shifting left 3 times */`

Bit-wise Shift Operation in C

Write code to generate the following numbers:

- (a) A number that has only a one in position D7
- (b) A number that has only a one in position D2
- (c) A number that has only a one in position D4
- (d) A number that has only a zero in position D5
- (e) A number that has only a zero in position D3
- (f) A number that has only a zero in position D1

- (a) `(1<<7)`
- (b) `(1<<2)`
- (c) `(1<<4)`
- (d) `~(1<<5)`
- (e) `~(1<<3)`
- (f) `~(1<<1)`

Bit-wise Shift Operation in C

Write an AVR C program to monitor bit 7 of Port B. If it is 1, make bit 4 of Port B input; else, change pin 4 of Port B to output.

```
#include <avr/io.h>                //standard AVR header

int main(void)
{
    DDRB = DDRB & ~(1<<7);          //bit 7 of Port B is input

    while (1)
    {
        if(PINB & (1<<7))
            DDRB = DDRB & ~(1<<4);  //bit 4 of Port B is input
        else
            DDRB = DDRB | (1<<4);    //bit 4 of Port B is output
    }

    return 0;
}
```

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