

## 1 Question 2

Given,

$$g = f * h$$

Where,  $g$  is the derivative of the 1D image,  $h$  is the convolution kernel for the gradient and  $f$  is the original image.

### 1.1 PART 1

Given

$$g = f * h$$

Then, take Fourier transform on both sides. From parseval's theorem we get the following.

$$F(g) = F(f)F(h)$$

So, we can get  $f$  by dividing both sides by  $F(h)$  and taking inverse fourier transform. We get the following formula for  $f$ .

$$f = F^{-1} \frac{F(g)}{F(h)}$$

However, we will run into problems when  $F(h)$  is zero. This is where we would need boundary conditions to get the values at points where  $F(h) = 0$ . For instance we will require the values of the pixels of  $f$  at the boundaries so that we can manually solve for the pixel values of the original image.

### 1.2 PART 2

Now, we have the gradients of a 2D image in the X and Y directions and we need to find the original image. Given

$$g_x = f * h_x$$

$$g_y = f * h_y$$

Then, take Fourier transform on both sides. From parseval's theorem we get the following.

$$F(g_x) = F(f)F(h_x)$$

$$F(g_y) = F(f)F(h_y)$$

So, we can get  $f$  by dividing both sides by  $F(h_x)$  and  $F(h_y)$  respectively and taking inverse fourier transform. We get the following formula for  $f$ .

$$f = F^{-1} \frac{F(g_x)}{F(h_x)}$$

$$f = F^{-1} \frac{F(g_y)}{F(h_y)}$$

So now we can calculate  $f$  easily at all the non zero points of  $F(h_x)$  and  $F(h_y)$ . If any one is zero, then we can use the other equation with the non zero denominator to find  $f$ . If both the denominators are zero, then we will have to rely on boundary conditions - such as knowing the pixel values of the original image  $f$  at the boundaries so that the values at those pixels can be manually calculated by performing the convolution and solving the equations. ( for example if the kernels for X and Y direction were  $[-1, 1]$  and  $[-1, 1]^T$ , then with the boundary values, we can get the image from the derivatives by adding the adjacent pixel values).