

## 1 Question 1

Given,  $f_1$  - The outside scene and  $f_2$  - the reflection the window and  $g_1$  and  $g_2$  are the images taken with  $f_1$  and  $f_2$  in focus respectively.

$$g_1 = f_1 + h_2 * f_2$$

$$g_2 = f_2 + h_1 * f_1$$

Taking Fourier transfer on both sides of both the equations, we get the following which is a result of Parseval's theorem.

$$F(g_1) = F(f_1) + F(h_2)F(f_2)$$

$$F(g_2) = F(f_2) + F(h_1)F(f_1)$$

Where  $F(x)$  is the fourier transform of the function  $x$ .

Solving for  $F(f_1)$  and  $F(f_2)$ , we get the following result.

$$F(f_1) = \frac{F(g_2)F(h_2) - F(g_1)}{F(h_1)F(h_2) - 1}$$

$$F(f_2) = \frac{F(g_1)F(h_1) - F(g_2)}{F(h_1)F(h_2) - 1}$$

Therefore, taking inverse fourier transform on both sides, we get the following for  $f_1$  and  $f_2$ .

$$f_1 = F^{-1}\left(\frac{F(g_2)F(h_2) - F(g_1)}{F(h_1)F(h_2) - 1}\right)$$

$$f_2 = F^{-1}\left(\frac{F(g_1)F(h_1) - F(g_2)}{F(h_1)F(h_2) - 1}\right)$$

- In the following derivation, if  $F(h_1)F(h_2) = 1$ , then we will not be able to find  $f_1$  and  $f_2$ .
- We are also not considering noise in our calculations. We are implicitly assuming that noise is zero from the equations for  $g_1$  and  $g_2$ . We should ideally try to find  $f_1$  and  $f_2$  by trying to minimize the noise or remove it.
- If the value of  $F(h_1)F(h_2) - 1$  is small, then it can cause problems in the Fourier transforms of  $f_1$  and  $f_2$  and cause them to shoot up in value and cause interfering patterns. This can happen at high frequencies.