MacCormack method

In <u>computational fluid dynamics</u>, the **MacCormack method** is a widely used discretization scheme for the numerical solution of <u>hyperbolic partial differential equations</u>. This second-order <u>finite difference method</u> was introduced by Robert W. MacCormack in 1969.^[1] The MacCormack method is elegant and easy to understand and program.

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The algorithm

The MacCormack method is a variation of the <u>two-step Lax–Wendroff scheme</u> but is much simpler in application. To illustrate the algorithm, consider the following first order hyperbolic equation

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0.$$

The application of MacCormack method to the above equation proceeds in two steps; a *predictor step* which is followed by a *corrector step*.

Predictor step: In the predictor step, a "provisional" value of u at time level n+1 (denoted by $u_i^{\overline{n+1}}$) is estimated as follows

$$u_i^{\overline{n+1}} = u_i^n - arac{\Delta t}{\Delta x}\left(u_{i+1}^n - u_i^n
ight)$$

The above equation is obtained by replacing the spatial and temporal derivatives in the previous first order hyperbolic equation using forward differences.

Corrector step: In the corrector step, the predicted value u_i^{n+1} is corrected according to the equation

$$u_i^{n+1} = u_i^{n+1/2} - arac{\Delta t}{2\Delta x}\left(u_i^{\overline{n+1}} - u_{i-1}^{\overline{n+1}}
ight)$$

Note that the corrector step uses <u>backward finite difference</u> approximations for spatial derivative. Note also that the time-step used in the corrector step is $\Delta t/2$ in contrast to the Δt used in the predictor step.

Replacing the $u_i^{n+1/2}$ term by the temporal average

$$u_i^{n+1/2}=rac{u_i^n+u_i^{\overline{n+1}}}{2}$$

to obtain the corrector step as

$$u_i^{n+1} = rac{u_i^n + u_i^{\overline{n+1}}}{2} - arac{\Delta t}{2\Delta x}\left(u_i^{\overline{n+1}} - u_{i-1}^{\overline{n+1}}
ight)$$

Some remarks

The MacComack method is well suited for <u>nonlinear equations</u> (Inviscid <u>Burgers equation</u>, <u>Euler equations</u>, etc.) The order of differencing can be reversed for the time step (i.e., forward/backward followed by backward/forward). For nonlinear equations, this procedure provides the best results. For linear equations, the MacCormack scheme is equivalent to tHax—Wendroff method. [3]

Unlike first-order <u>upwind scheme</u>, the MacCormack does not introduce <u>diffusive errors</u> in the solution. However, it is known to introduce dispersive errors (Gibbs phenomenon) in the region where the gradient is high.

See also

- Lax–Wendroff method
- Upwind scheme
- Hyperbolic partial diferential equations

References

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- 2. Anderson, J. D., Jr, Computational Fluid Dynamics: The Basics with Applications, McGraw Hill (1994).
- 3. Tannehill, J. C., Anderson, D. A., and Pletcher, R. H., Computational Fluid Dynamics and Heat Transfer, 2nd ed., Taylor & Francis (1997).

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This page was last edited on 7 July 2018, at 21:24UTC).

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