Trade-Offs and Non-Relational Moves

DB/AI Bootcamp
2018 Summer
Datalab, CS, NTHU

- SAE revisited
- Non-relational partitioned DDBMS
 - Trade-off: load balancing vs. short latency
 - DDBMS moves: DBA or even graph cuts
 - Non-relational moves
- Non-relational replicated DDBMS
 - Trade-Off: C vs. short Latency
 - Trade-Off: CA@P
 - DDBMS moves: L-(A@P)
 - Non-relational moves
- Elasticity in non-relational DDBMS
- Remarks

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Why So Hard to Get SAE?

- Horizontal S requires good data partitioning
 - I/O overhead < communication overhead
- Extreme A requires cross-WAN replication
 - Network quality affects system performance
- E means workload-aware data (re-)partitioning + live migration

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Load balancing vs. Short Latency

- Data are partitioned to avoid hot zones
- When a tx access data across multiple partitions, it becomes slow
 - Distributed locking (may be)
 - **2PC**
- How to avoid such slowdown?
- Partition data such that
 - Each machine gets equal load
 - #dist. txs are minimized

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DDBMS Solution: Hire an Experienced DBA

- Traditionally, data partitioning requires careful examination of the target workload
 - Usually done by experienced DBA
- Cons:
 - Experienced DBAs are expensive
 - Time-consuming
 - Cannot adapt to the fast-changing workloads

Automation: Graph Partitioner

- Model the recent workload as a graph
 - Nodes: data objects, with weight denoting their access frequency
 - Edges: common access by txs, also weighted
- Find the minimal balanced partition of this graph
 - Machines are evenly loaded
 - Dist. txs are minimized

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Industry: It's Too Complicated!

- Balanced graph partitioning is an NP-hard problem
- Why not just drop the support relational model?
 - NoSQL data model: key-value, document based, entity-group based, etc.
- Data are perfectly partitionable \rightarrow no dist. Txs
 - → ultimate scalability

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C vs. Short Latency

	Eager MM	Lazy M/S	Lazy MM
Consistency	Strong	Eventual	Weak
Latency	High	Low	Low
Throughput	Low	High	High
Availability upon failure	Read/write	Read-only	Read/write
Data loss upon failure	None	Some	Some
Reconciliation	No need	No need	User or rules
Bottleneck, SPF	None	Master	None

Short latency wins in traditional DDBMS

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Failures in a Cross-WAN DDBMS

- Machine failure
- Network partition
 - May be temporal, but frequent (due to, e.g., packet delay/loss)
 - Including single-node partition
- What's the difference?
 - Nodes are alive!
 - Some may commit users something that others don't agree
- Covers machine failure

CAP Theorem

- Consistency
 - Data in every node are consistent
- All-node availability
 - Every node (if not failed) always serve requests
- Partition tolerance
 - The system operates even if network partition happens.
- CAP theorem: in presence of P, choose one
- All-node Av ≠ service Av
 - Paxos allows C and service Av @P
- Nodes in "quorum" (e.g., majority) partition:
 - Keeps the service availability
- Nodes not in quorum partition:
 - Need not to make any progress (i.e., act as if they were dead)
 - When partition resolved, need to enter the "recovery" mode first

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DDBMS with Network Partition

- Lazy M/S replication
 - One master for each data object (globally)
- If a client can reach the masters:
 - No consistency (short latency wins)
- If a client is partitioned from the masters:
 - No availability
 - Data in a master is always correct and durable
- We say DDBMS choose C in present of P
- Overall: L-(A@P)

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Dynamo/Cassandra/Riak: L-(C@P)

- In normal case: lazy M/S replication
 - L
- In the presence of failure: lazy M/M replication
 - Degraded consistency level
 - But R/W availability

Google BigTable/MegaStore: C-(A@P)

- In normal case: eager replication
 - -c
 - Long latency but scalable, as each partition (entity group) runs an instance of eager replication protocol
- @P: adopt eager replication protocol that is robust to P
 - Paxos
 - If a client can reach any machine in the quorum, the system acts normally

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Elasticity

- Targets: workload-aware (re-)partitioning + live migration
- Challenges: distributed txs, 2PC/log shipping, etc.
 - How?
- NoSQL makes it easy: achieved using a "master" in each datacenter
 - Monitors the loads of "working" servers
 - Split/merge loads if they are too hot/cold
- Example?
 - GFS, MapReduce, BigTable
- Elasticity is usually per-datacenter basis
 - Enough to cope with "hot datacenters" (due to concentrated active users)
 - No data partitioning across datacenters (i.e., fully replicated)

Problems

- Master is a single point of failure
 - Solution: hot-stand-by's
- Master may be the performance bottleneck
 - Solution: preventing master from dealing with data traffic (but control messages)
- Hard to develop apps:
 - Non-relational data model
 - No/reduced dist. tx support
- Data migration vs. A and C

Data Migration vs. Tx execution

- If data being migrated are locked, conflict txs stall
 - No A
- Otherwise, no C
- Current approach: "live migration" (A -> B)
 - A continues executing txs, and additionally pushes the results sets to B
 - B takes over tx execution only it catches up A (after receiving data and applying result sets)
- Keeps A and C
- But B cannot help system performance timely
 - Many txs are still executed by A after the migration decision
- Still a research problem!

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Why So Hard to Get SAE?

- Horizontal S requires good partitioning (and replication)
 - Experienced DBA is needed
 - Dist. Txs are too costly (due to 2PC)
- Extreme A requires cross-WAN replication
 - Trade-off in normal operations: consistency vs. latency
 - Trade-off when failure occurs: consistency vs. availability (CAP theorem)
- E means workload-aware (re-)partitioning + live migration
 - Trade-off in deciding partitions: equal volume vs. few dist.
 txs
 - Join optimization needed for multi-tenant DBMS
 - Migration blocks ongoing txs

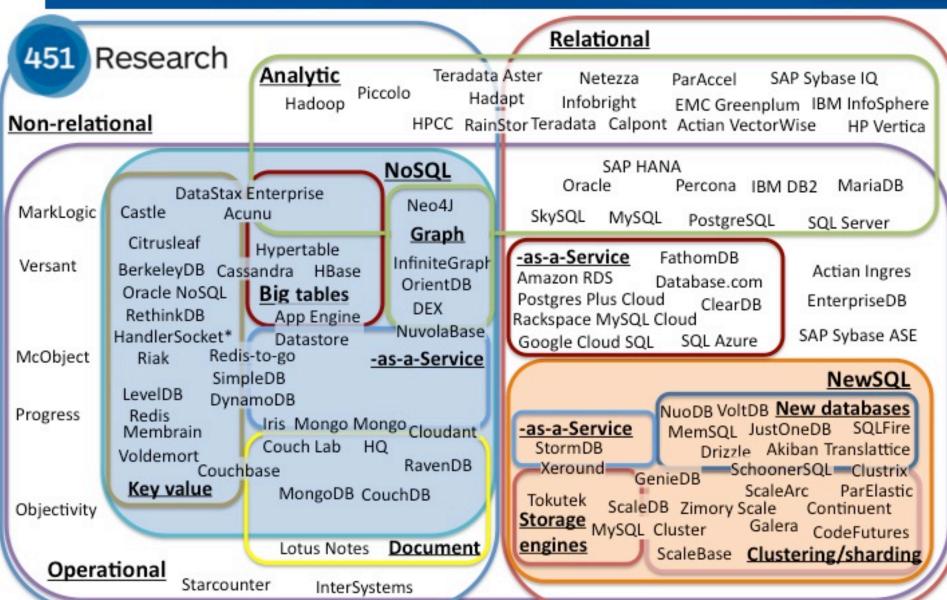
The NoSQL Move

- Drop relational model
 - Assume data can be partitioned
 - No dist. tx → S and easier E (although migration still blocks txs)
- Further compromise C (except Google) in both normal and failure cases
 - For low latency in normal case
 - For A in failure case

The Score Sheet

	DDBMS	Dynamo/Cassandra/Riak
Data model	Relational	Key-value
Tx boundary	Unlimited	Key-value
Consistency	W strong, R eventual	W strong, R eventual
Latency	Low (local partition only)	Low
Throughput	High (scale-up)	High (scale-out)
Bottleneck/SPF	Masters	Masters
Consistency (F)	W strong, R eventual	WR eventual
Availability (F)	Read-only	Read-write
Data loss (F)	Some	Some
Reconciliation	Not needed	Needed
Elasticity	No	Manual, blocking migration

The evolving database landscape



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