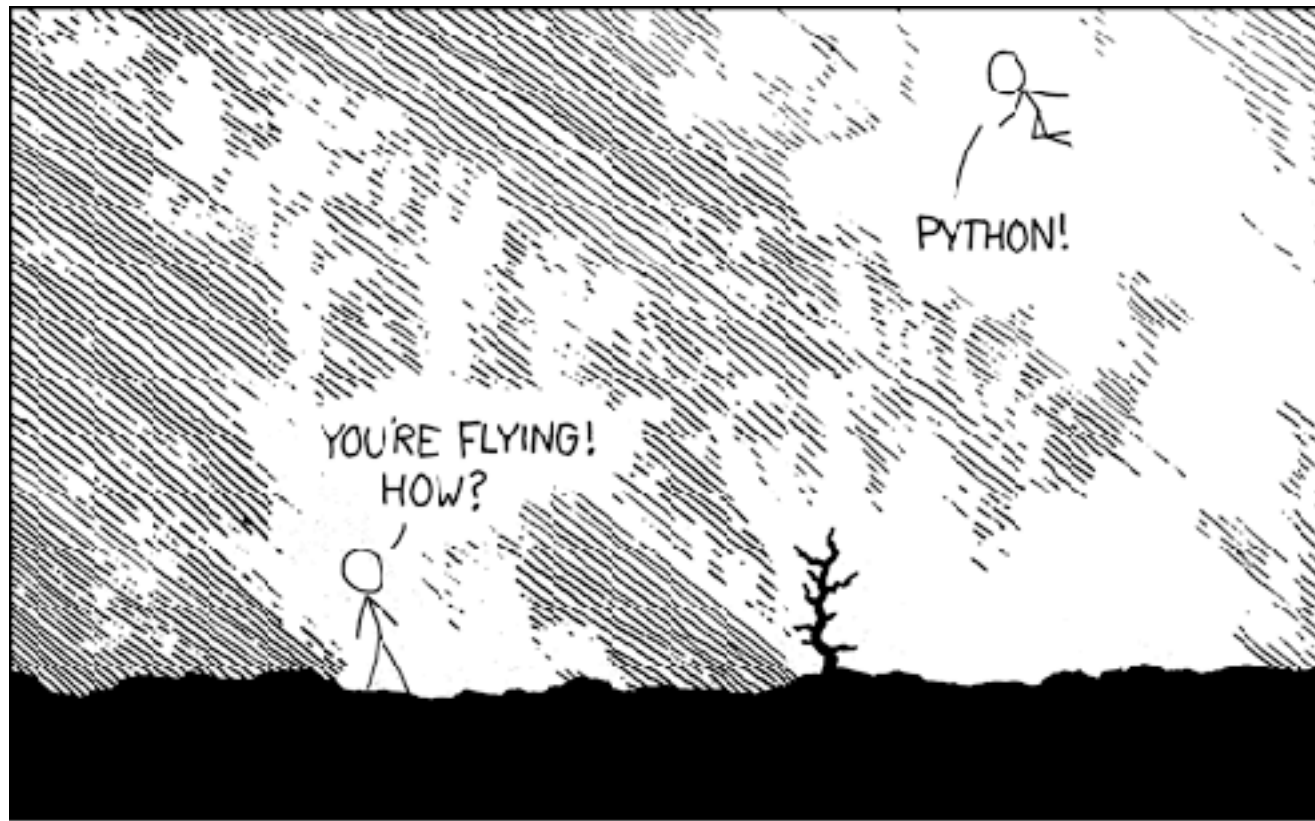


Introduction to python



14.5-16.5
@ UKE Hamburg

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Easy syntax

Readability

High-level language

Object oriented

Why Python?

Free +

open source

Cross-platform

“Batteries included”

Widely supported

**Used by
industry**



PsychoPy

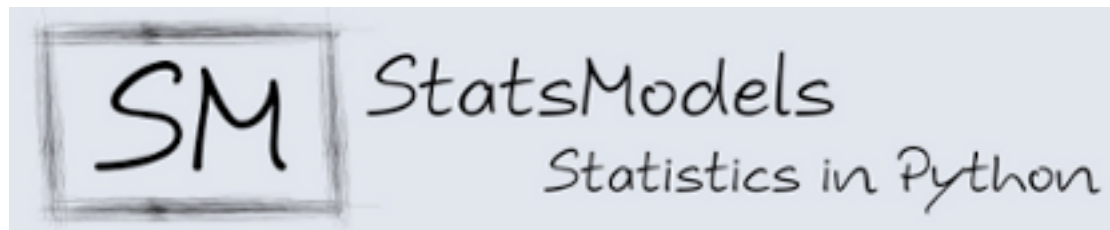
Psychology software in Python



Nipype:
Neuroimaging in Python
Pipelines and Interfaces

MNE

MEG + EEG ANALYSIS & VISUALIZATION



StatsModels

Statistics in Python

pandas

$$y_{it} = \beta' x_{it} + \mu_i + \epsilon_{it}$$



matplotlib



python™

IP[y]:

IPython

Interactive Computing





python™

IP[y]:

IPython
Interactive Computing

```
~ > ipython
Python 2.7.11 |Anaconda 4.0.0 (x86_64)| (default, Dec 6 2015, 18:57:58)
Type "copyright", "credits" or "license" for more information.
```

```
IPython 5.3.0 -- An enhanced Interactive Python.
```

```
? -> Introduction and overview of IPython's features.
%quickref -> Quick reference.
help -> Python's own help system.
object? -> Details about 'object' or 'object()' method.
```

```
In [1]:
```

Jupyter QtConsole 4.2.0

```
Python 2.7.11 |Anaconda 4.0.0 (x86_64)| (default, Dec 6 2015, 18:57:58)
Type "copyright", "credits" or "license" for more information.
```

```
IPython 5.3.0 -- An enhanced Interactive Python.
```

```
? -> Introduction and overview of IPython's features.
```

```
%quickref -> Quick reference.
```

```
help -> Python's own help system.
```

```
object? -> Details about 'object' or 'object()' method.
```

```
In [1]:
```



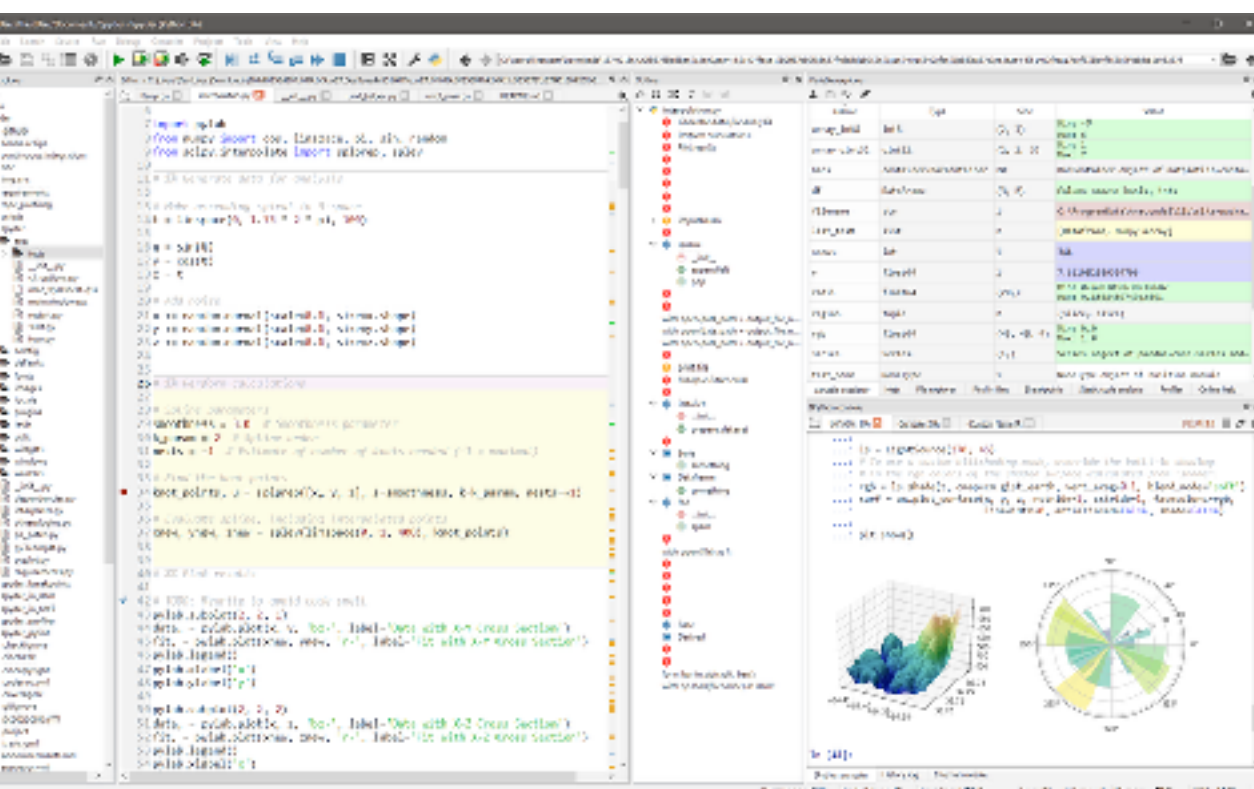
jupyter

Grid cell analysis

Last Checkpoint: 10/28/2016 (unsaved changes)

File Edit View Insert Cell Kernel Help

Code



```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

# 3D plot
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
ax.plot_surface(X, Y, Z, color=(.8,.8,.8))
ax.plot(X[5000], Y[5000], Z[5000], color='m')
ax.plot(X[idx], Y[idx], Z[idx], color='ko')
ax.set_xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')

# 2D plot
fig = plt.figure()
ax = fig.add_subplot(111)
ax.plot(X[5000], Y[5000], color='m')
ax.plot(X[idx], Y[idx], color='ko')
ax.set_xlabel('X')
ax.set_ylabel('Y')
```

```
subplot(1,4,2)
xlabel('Time')
ylabel('Firing rate')
plot(ratefct[5000], 'm')
plot(idx, ratefct[idx], 'ko')
yticks(yticks()[0], [])

subplot(1,4,3)
xlabel('Time')
ylabel('Firing rate')
plot(ratefct[5000], 'm')
plot(idx, ratefct[idx], 'ko')
in plot samples(samples 0, h=0.015, end=5000, col=
```

OUTLINE

Monday

10:00 Introduction to python (we talk)

12:30: Lunch

14:00: 1st practical

Discuss solution (someones code)

Tuesday

10:00 Introduction to numpy/scipy (we talk)

Lunch

2nd practical: implement AI for bot

Wednesday

9:00: implement AI for bot

Tournament

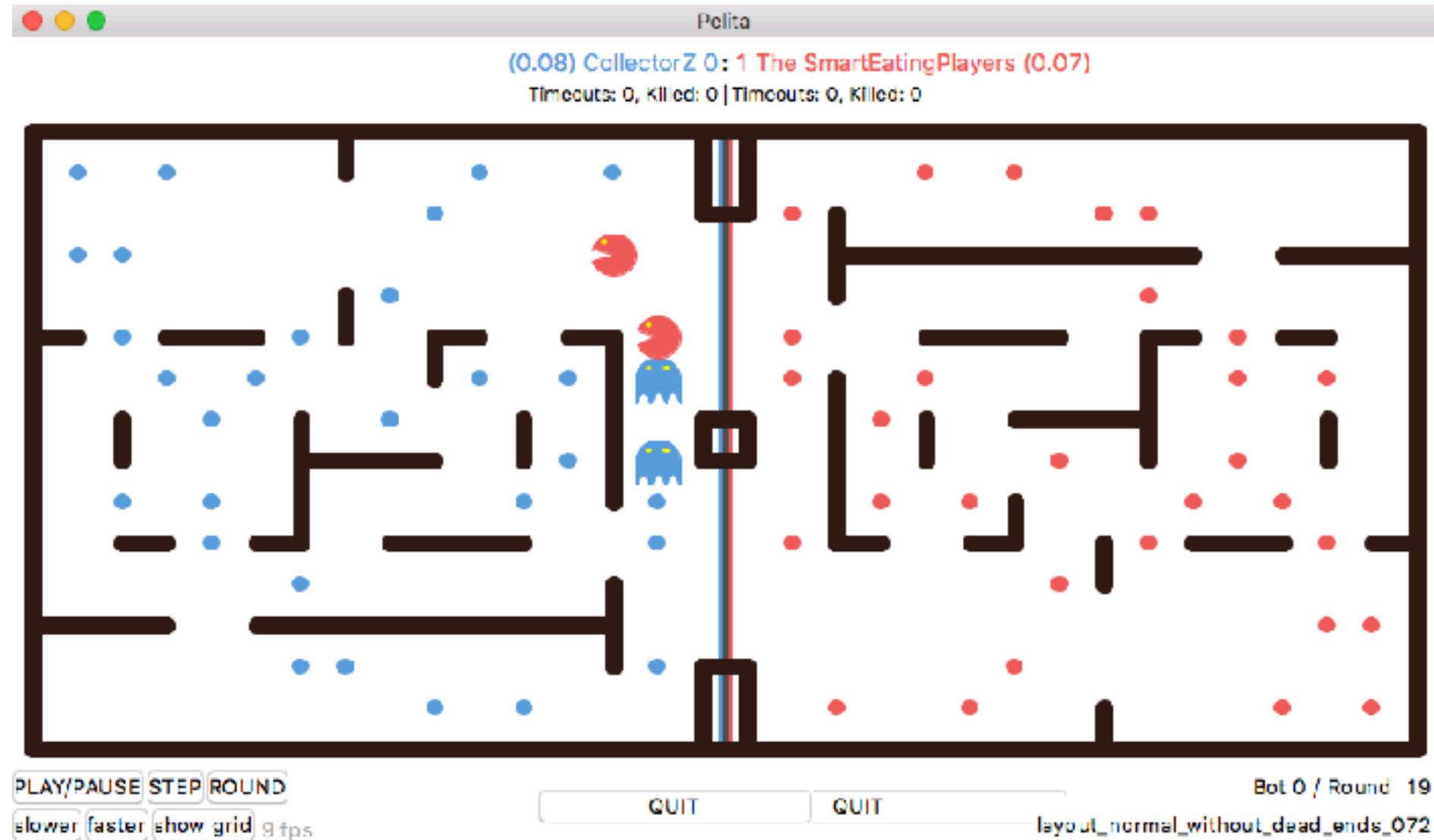
Outlook

13:00 End

During the practicals: ASK US!

OUTLINE

2nd practical:
implement AI for
pelita bot



During the practicals: ASK US!

Dynamic typing

No need to declare variable types.

But: Python keeps track of types.

Need explicit casts

(e.g. `int()` or `str()`)

Operators

`=` assignment

`==` comparison

`+-*/` math

Code Indentation

No `{}` or end statements. Code is grouped by indentation. Use 4 spaces and no tabs.

Control flow

```
if statement:
    foo()
elif statement:
    bar()
else:
    foobar()
```

Loops

```
for i in collection:
    foobar()
```

```
while statement:
    foobar()
```

(remember **continue** and **break**)

Errors

```
try:
    foo()
except Exception as e:
    #fix error
finally:
    #cleanup
```

Miscellaneous

```
# Comments
"""Multi line strings"""
```

Indexing & Slicing

	-4	-3	-2	-1	
	0	1	2	3	
	A	B	C	D	
0		1	2	3	4
	-4	-3	-2	-1	

`lst[0] = ,A'` `lst[-3] = ,B'` `lst[2:] = [,C', ,D']` `lst[-1:] = ,D'`

`lst[::2] = [,A', ,C']` `lst[::-2] = [,D', ,B']` `lst[-1:-3] = []`

Comprehensions

[statement loop conditional]

```
['#' if x > y else '.' for x in range(10)] for y in range(10)]
```

```
lst = []  
for y in range(10):  
    for x in range(10):  
        if x > y:  
            lst.append(',')  
        else:  
            lst.append('.')
```

```
['#' for x in range(10) if x > 5]
```

```
lst = []  
for x in range(10):  
    if x > 5:  
        lst.append(',')
```

Indexing

**Starts at 0. Think interval.
negative indices start from
the end**

Slicing

Slice and step through lists

Unpacking

**Containers can be
unpacked into variables:**
`a, b = [1, 2]`

References!

```
a = b = [1, 2]
a.extend([5])
b == [1, 2]
```

Tuples

Immutable lists.

Dictionaries

**Easy key-value store.
(The thing that Matlab
users didn't know they
were missing)**

Comprehensions

**Compact statement of simple
for loops. Not shown:
set comprehensions.**

Anatomy of function!

```
def name(argument):  
    '''  
    Doc string  
    '''  
    body  
    return value
```

Anatomy of function!

```
def name(a, *args, b=1, **kw):  
    '''  
    Doc string  
    '''  
    body  
    return value1, value2, ...
```

Return values

return a, b, c -> **tuple**

omitting a return = return None

Tuple unpacking

```
a, b, c = (1,2,3)
```

```
func(*(1,2,3), {,a':1})
```

Keyword arguments

```
def func(a=1, b=2, c=3)
```

Variable #arguments

```
def func(a, *args, b=1, **kw):
```

Functions are objects!

Have properties and can be assigned to other variables.

lambdas

Simple functions that map statement to output.

Decorators

Replace a function with a function that takes original function as input.
Logging and Memoize/caching.

import / packages / modules

foobar/

 foobar/

 __init__.py

Tells python to treat this as a pkg.

 spirals.py

A module within the package foobar.

 setup.py

Install file

 README

Doc.

`__init__.py`: **Can be empty or provide global variables/functions.**

`setup.py`: **Contains logic to make package installable**

```
#!/usr/bin/env python
```

```
#!/usr/bin/env python
```

```
from setuptools import setup, find_packages
```

```
setup(name='foobar',  
      description='Foobar foobars foobar',  
      author='Foo bar',  
      packages=find_packages(),  
      )
```


__init__.py

Turns folders into packages!

imports

```
import x
import x as y
from x import y
from x import y as z, b
```

Install packages

easy_install / pip / conda

setup.py

`python setup.py develop/install`

Variable #arguments

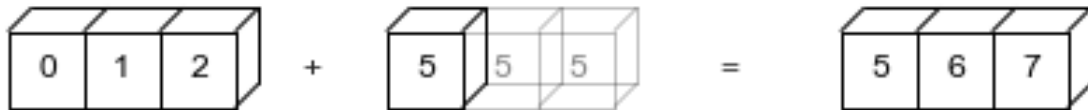
```
def func(a, *args, b=1, **kw):
```

Roll your own

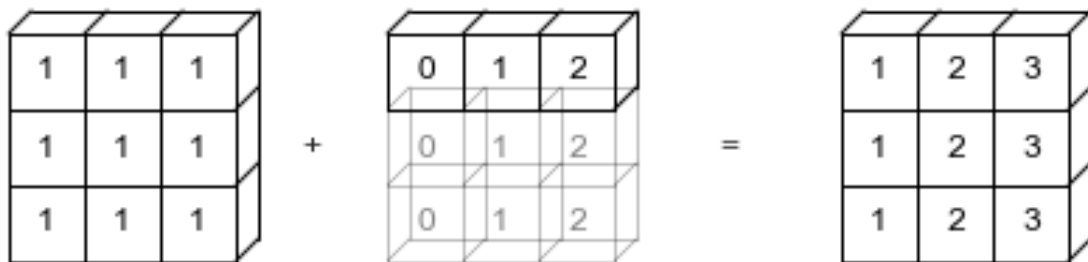
**Doesn't matter where you start
python interpreter.**

Broadcasting

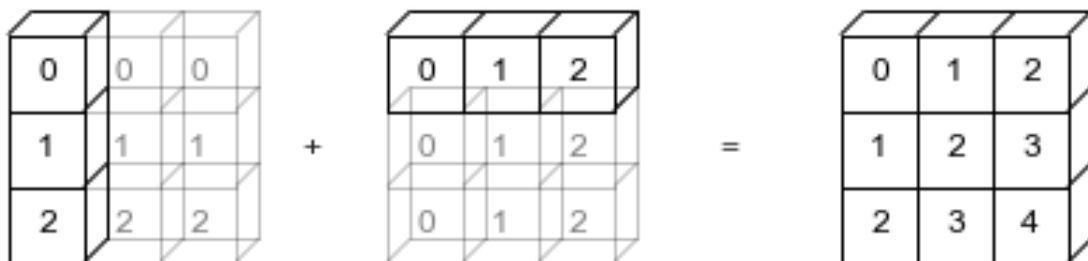
`np.arange(3)+5`



`np.ones((3, 3))+np.arange(3)`



`np.arange(3).reshape((3, 1))+np.arange(3)`



When operating on two arrays, NumPy compares their shapes element-wise. It starts with the trailing dimensions, and works its way forward. Two dimensions are compatible when:

1. they are equal, or
2. one of them is 1

A	(1d array):	3
B	(1d array):	1
Result	(1d array):	3

A	(2d array):	3 x 3
B	(1d array):	3
Result	(2d array):	3 x 3

A	(2d array):	3 x 1
B	(1d array):	3
Result	(2d array):	3 x 3

Table 1

A	(2d array):	2 x 1
B	(3d array):	8 x 4 x 3

NumPy

Arrays

```
np.array([[1,2],[3,4]])  
np.linspace(0, 10, 25)  
np.ones((3,3), dtype=bool)
```

Matrix algebra

```
np.dot(M, v)
```

Data processing

```
np.mean(X, axis=0)
```

Reshaping & stacking

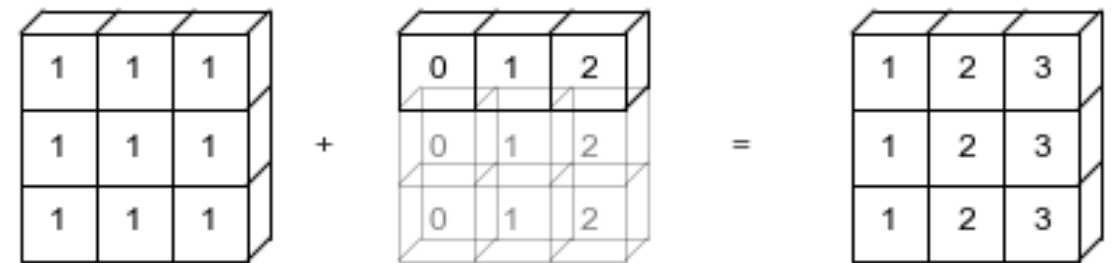
```
M.reshape((2,8))  
np.vstack((M1, M2))
```

Broadcasting

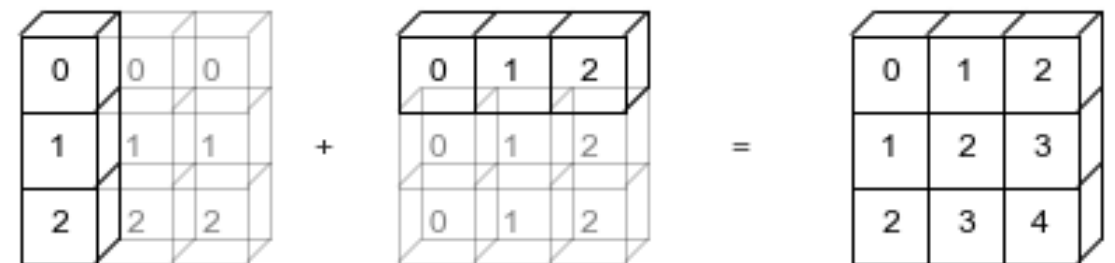
`np.arange(3)+5`



`np.ones((3,3))+np.arange(3)`



`np.arange(3).reshape((3,1))+np.arange(3)`



Task one

The riddle: 100 prisoners are in solitary cells, unable to see, speak or communicate in any way from those solitary cells with each other. There's a central living room with one light bulb; the bulb is initially off. No prisoner can see the light bulb from his own cell. Everyday, the warden picks a prisoner at random, and that prisoner goes to the central living room. While there, the prisoner can toggle the bulb if he or she wishes. Also, the prisoner has the option of asserting the claim that all 100 prisoners have been to the living room. If this assertion is false (that is, some prisoners still haven't been to the living room), all 100 prisoners will be shot for their stupidity. However, if it is indeed true, all prisoners are set free. Thus, the assertion should only be made if the prisoner is 100 percent certain of its validity.

Before the random picking begins, the prisoners are allowed to get together to discuss a plan. So - what plan should they agree on, so that eventually, someone will make a correct assertion?

Question: How can the prisoners tell, with certainty, that all 100 of them have visited the central living room with the light bulb?

Task: Once you've decided on a strategy simulate how many turns the prisoners will have to take.

```
from random import choice # Choose a random number

def prisoner(N=100):
    """
    Computes how many turns the prisoners need before being freed.

    Arguments:
        N : int, default=100

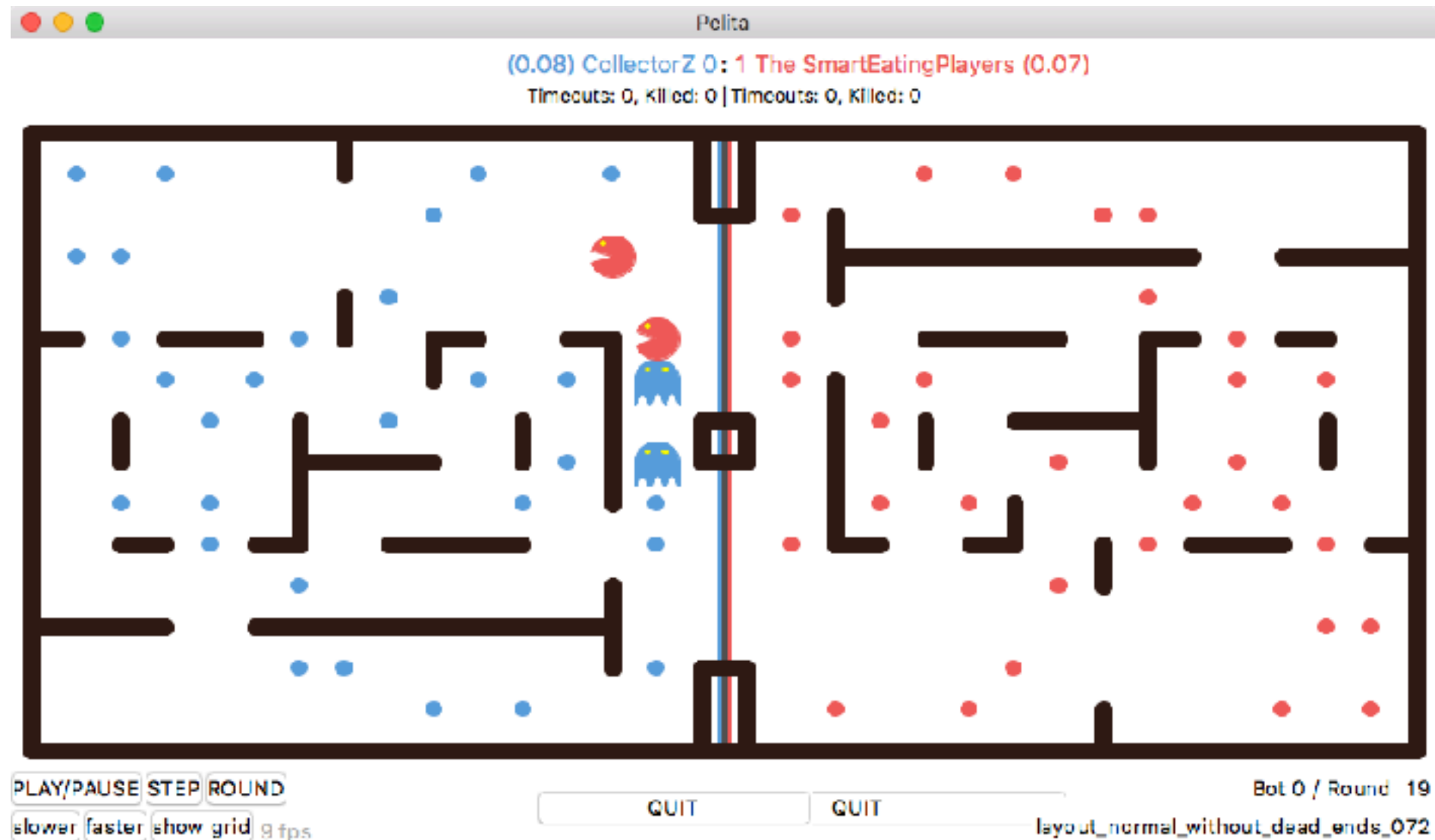
    Returns:
        The number of turns required by the prisoners.

    """

    # Implement your solution here
    return turns

if __name__ == '__main__':
    nr_prisoners = 100
    turns = prisoner(N=nr_prisoners)
    print( "total turns (days) required: {}".format(turns))
```

Task two



Use git to clone this repository:

```
git clone https://github.com/nwilming/pelita  
cd pelita  
python setup.py install
```

Download documentation:

Task two

Use git to clone this repository:

```
git clone https://github.com/nwilming/pelita  
cd pelota  
python setup.py install
```

Download documentation:

Clone the tournament repository and create a folder for your team_

```
git clone https://github.com/nwilming/NINPelitaTournament  
cd NINPelitaTournament  
mkdir groupN  
cd groupN  
... add your stuff ...  
git pull origin master  
git add ...  
git commit  
git push origin master
```

Task two

```
from pelita.datamodel import stop
from pelita.player import AbstractPlayer, SimpleTeam
```

```
class SmartRandomPlayer(AbstractPlayer):
    def get_move(self):

        dangerous_enemy_pos = [bot.current_pos
                                for bot in self.enemy_bots if bot.is_destroyer]
        killable_enemy_pos = [bot.current_pos
                               for bot in self.enemy_bots if bot.is_harvester]

        smart_moves = []
        for move, new_pos in list(self.legal_moves.items()):
            if (move == stop or
                new_pos in dangerous_enemy_pos):
                continue # bad idea
            elif (new_pos in killable_enemy_pos or
                  new_pos in self.enemy_food):
                return move # get it!
            else:
                smart_moves.append(move)

        if smart_moves:
            return self.rnd.choice(smart_moves)
        else:
            # we ran out of smart moves
            return stop

def factory():
    return SimpleTeam("The Smart Random Players", SmartRandomPlayer(), SmartRandomPlayer())
```