Joint Matrix: A Unified SYCL Extension for Matrix Hardware Programming

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oneAPI AI SIG Forum, Mar. 15th, 2023

Collaborating with many colleagues from Intel and Codeplay



Executive Summary

Goal

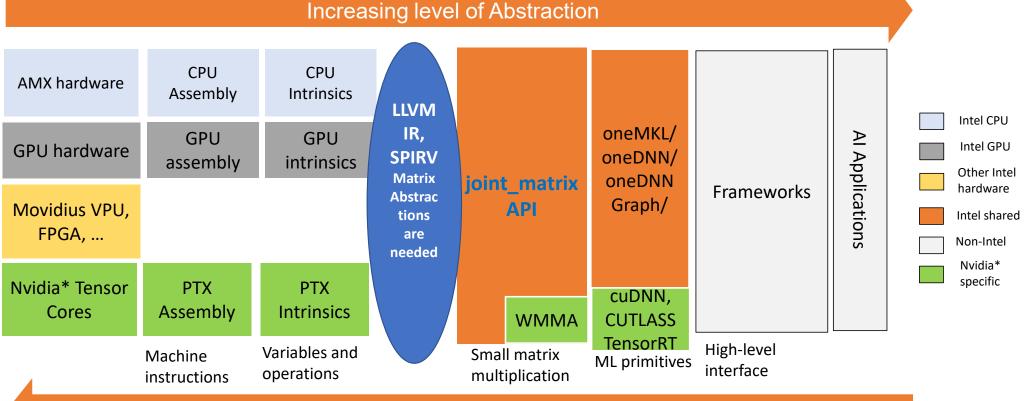
- Deliver unified SYCL matrix interface across matrix hardware: Intel AMX, Intel XMX and Nvidia Tensor Cores
 - Programmer productivity: Allow the customer to express their applications for matrix hardware with minimal changes
 - Performance: Maps directly to low-level intrinsics/assembly for maximum performance

• Status

- Implementation: Unified interface will be part of oneAPI 2023.1 release (March 21st)
- Current Users: Code porting from CUDA wmma, MLIR SPIRV-based joint matrix code generation



Programming Abstractions for Matrix Computing



Increasing programmer control



Ninja programmer - Focus on performance through hardware

Application programmer - Focus on algorithmic improvements

Lead Users

Performance portability across all hardware without extra effort of optimizations for specific hardware



Al Scientists

 New operations such as tensor contractions, BRGEMM, quantized gemm, fused operations



Library Developers

Different DNN and BLAS libraries

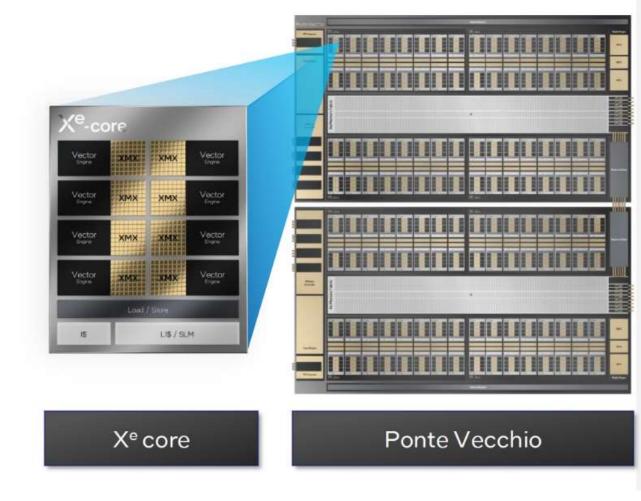


Matrix Hardware



Intel XMX in Intel® Data Center GPU Max Series

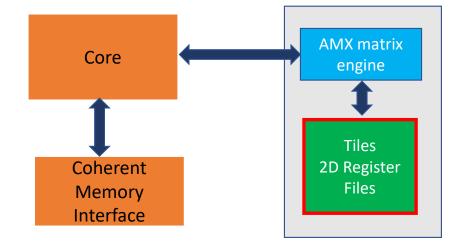
- Code-named Ponte Vecchio (PVC)
- Xe -HPC 2-Stack Ponte Vecchio GPU
- 8 slices
- Xe slice contains 16 Xe core
- An Xe -core contains 8 vector and 8 matrix engines





Intel AMX High-Level Architecture

- Intel[®] Xeon[®] processor codenamed Sapphire Rapids
- Intel AMX, an Intel x86
 extension for multiplication
 of matrices of bf16/int8
 elements





SYCL Joint Matrix Extension



SYCL Matrix Extension

Namespace

- namespace sycl::ext::oneapi::experimental::matrix
- New matrix data type with group scope (WG or SG)
- Defined with a specified type, use (a, b, accumulator), size, and layout.
- Separate memory operations from the compute
- enum class layout {row_major, col_major, dynamic };
- Group execution scope → joint, Group as argument

- template <typename Group, typename T, use Use, size_t
 Rows, size_t Cols, layout Layout = layout::dynamic>
 struct joint_matrix;
- enum class use { a, b, accumulator};
- joint_matrix_fill(Group g, joint_matrix<>&dst, T v);
- void joint_matrix_load(Group g, joint_matrix<>dst, T
 *base, unsigned stride, Layout layout);
- void joint_matrix_store(Group g, joint_matrix<>src, T
 *base, unsigned stride, Layout layout);

- Multiply and add
- Element-wise ops
- Extensible to add more operations
- joint_matrix<> joint_matrix_mad(Group g, joint matrix<>A, joint matrix<>B, joint matrix<>C);
- void joint_matrix_apply(Group g, joint_matrix<>A, F&& func);

SYCL joint *matrix* Example

```
using namespace sycl::ext::oneapi::experimental::matrix;
queue q;
range<2> G = \{M/tM, N/tN * SG SIZE\};
range<2> L = \{1, SG SIZE\};
auto bufA = sycl::buffer{memA, sycl::range{M*K}};
auto bufB = sycl::buffer{memB, sycl::range{K*N}};
auto bufC = sycl::buffer{memC, sycl::range{M*N}};
g.submit([&](sycl::handler& cgh) {
  auto accA = sycl::accessor{bufA, cqh, sycl::read only};
  auto accB = sycl::accessor{bufB, cgh, sycl::read only};
  auto accC = sycl::accessor{bufC, cgh, sycl::read write};
  cgh.parallel for(nd range<2>(G, L), [=](nd item<2> item) {
     const auto sg startx = item.get global id(0) - item.get local id(0);
     const auto sg starty = item.get global id(1) - item.get local id(1);
     sub group sg = item.get sub group();
     joint matrix<sub group, int8 t, use::a, tM, tK, layout::row major> subA;
     joint matrix<sub group, int8 t, use::b, tK, tN, layout::row major> subB;
     joint matrix<sub group, int32 t, use::accumulator, tM, tN> subC;
     joint matrix fill(sg, subC, 0);
     for (int k = 0; k < K; k += tk) {
       joint matrix load(sg, subA, accA + sg startx * tM * K + k, K);
       joint matrix load(sq, subB, accB + k * N + sq starty, N);
       subC = joint matrix mad(sq, subA, subB, subC);
     joint matrix apply(sg, subC, [=](T &x) { Relu(x); });
     joint matrix store(sg, subC, accC + sg startx * tM * N + sg starty, N, row major);
 });
});
q.wait;
```



intel. 10

oneAPI 2023.1: One Joint Matrix Code to Run on Intel AMX, Intel XMX and Nvidia* Tensor Cores

```
joint_matrix<sub_group, int8_t, use::a, tM, tK, layout::row_major> subA;
joint_matrix<sub_group, int8_t, use::b, tK, tN, layout::row_major> subB;
joint_matrix<sub_group, int32_t, use::accumulator, tM, tN> subC;
sub_group sg = item.get_sub_group();
joint_matrix_fill(sg, subC, 0);
for (int k = 0; k < K; k += tK) {
   joint_matrix_load(sg, subA, accA + sg_startx * tM * K + k, K);
   joint_matrix_load(sg, subB, accB + k * N + sg_starty/SG_SIZE*tN, N);
   subC = joint_matrix_mad(sg, subA, subB, subC);
}
joint_matrix_apply(sg, subC, [=](T x) { x *= alpha; });
joint_matrix_store(sg, subC, accC + sg_startx * tM * N + sg_starty/SG_SIZE*tN, N, layout::row_major);</pre>
```

Intel CPUs

Intel GPUs Nvidia*
GPUs



SYCL Matrix Extension: Intel Specific Features

CUDA Syntax

```
wmma::fragment<wmma::accumulator, 16, 16, 16, 16, float> frag;
for(int t=0; t<frag.num_elements; t++)
  frag.x[t] *= alpha;</pre>
```

SYCL namespace

namespace sycl::ext::intel::experimental::matrix

- Element-wise ops using indexing into work item slice of the joint matrix
- Mapping of WI element to original joint matrix element is implementation defined

```
→ get_coord()
```

```
oneAPI
```

```
    wi_data<> get_wi_data(Group g, joint_matrix<>C);
    class wi_data {
        size_t length();
        wi_element<> operator[](size_t i);
        };
    class wi_element {
        std::tuple<size_t, size_t> get_coord();
        };
        intel 12
```

SYCL joint matrix Indexing with Coordinates Example

- Element wise ops that apply to a set of elements of the matrix → Mapping is required
- Example: Quantization Calculations
- A*B + sum_rows_A + sum_cols_B + scalar_zero_point
- sum_rows_A returns a single row of A

```
using namespace sycl::ext::oneapi::experimental::matrix;
void sum rows A(joint matrix<T, rows, cols>& subA)
  auto data = ext::intel::experimental::matrix::get wi data(sq, subA);
  for (int i = 0; i < data.length(); ++i) {</pre>
    auto [row, col] = data[i].get coord();
    global index = row + global idx * rows;
    sum local rows[global index] += data[i];
}
```



Matrix Query Interface



AMX Supported Combinations

A type	Btype	Ctype	M	N	K
(u)int8_t	(u)int8_t	int32_t	<=16	<=16	<=64
bf16	bf16	float	<=16	<=16	<=32



Intel XMX Supported Combinations

A type	Btype	Ctype	M	N	K
(u)int8_t	(u)int8_t	int32_t	<=8	8 (ATS-M) 16 (PVC)	32
fp16	fp16	float	<=8	8 (ATS-M) 16 (PVC)	16
bf16	bf16	float	<=8	8 (ATS-M) 16 (PVC)	16
tf32	tf32	float	<=8	16 (PVC)	



Nvidia* Tensor Cores Supported Combinations

A type	Btype	Accumulator type	М	N	K
half	half	float	16	16	16
			32	8	16
			8	32	16
half	half	half	16	16	16
			32	8	16
			8	32	16
bfloat16	bfloat16	float	16	16	16
			32	8	16
			8	32	16
tf32	tf32	float	16	16	8
(u)int8_t	(u)int8_t	int32_t	16	16	16
			32	8	16
			8	32	16



Matrix Query

Namespace

namespace sycl::ext::oneapi::experimental::matrix

Provide a default shape if user does not provide a combination in a constexpr way

```
template<sycl::ext::oneapi::experimental::architecture Dev, typename Ta, typename Tb,
    typename Taccumulator>
struct matrix_params {
    static constexpr size_t M = /* implementation defined */;
    static constexpr size_t N = /* implementation defined */;
    static constexpr size_t K = /* implementation defined */;

    template <typename Group, layout Layout>
    using joint_matrix_a = joint_matrix<Group, Ta, use::a, M, K, Layout>;

    template <typename Group, layout Layout>
    using joint_matrix_b = joint_matrix<Group, Tb, use::b, K, N, Layout>;

    template <typename Group>
    using joint_matrix_accumulator = joint_matrix<Group, Taccumulator, use::accumulator, M, N>;
};
```



SYCL joint matrix Using the Default Query

```
using namespace sycl::ext::oneapi::experimental::matrix;
using myparams = matrix params<sycl::ext::oneapi::experimental::architecture::intel gpu pvc,
                               int8 t, int8 t, int>;
constexpr int tM = myparams::M;
constexpr int tN = myparams::N;
constexpr int tK = myparams::K;
range<2> G = \{M/tM, N/tN * SG SIZE\};
range<2> L = \{1, SG SIZE\};
// buffers
g.submit([&](sycl::handler& cgh) {
  // accessors
  cgh.parallel for(nd range<2>(G, L), [=](nd item<2> item) {
    const auto sq startx = item.get global id(0) - item.get local id(0);
    const auto sg starty = item.get global id(1) - item.get local id(1);
   sub group sg = item.get sub group();
   myparams::joint matrix a<sub group, layout::row major> tA;
   myparams::joint matrix b<sub group, layout::row major> tB;
   myparams::joint matrix accumulator<sub group> tC;
    joint matrix fill(sg, tC, 0);
    for (int k = 0; k < K; k += tk) {
     joint matrix load(sg, tA, memA + sg startx * tM * K + k, K);
     joint matrix load(sg, tB, memB + k * N + sg starty, N);
     tC = joint matrix mad(sq, tA, tB, tC);
   joint matrix store(sg, tC, memC + sg startx * tM * N + sg starty, N, row major);
  });
                                                                                         intel 19
});
```

SYCL joint_matrix

CUDA Fragments

```
// inputA is MxK, inputB is KxN, inputC is MxN
#define tM=16 tN=16 tK=16
void gemm(size t global_idx, size_t global_idy, size_t local_idx, size_t local_idy, sub_group sg) {
 joint_matrix<sub_group, half, use::a, tM, tK, row_major> matA;
 joint_matrix<sub_group, half, use::b, tK, tN, row_major> matB;
 joint matrix<sub group, float, use::accumulator, tM, tN> matC;
  const auto sg_startx = global_idx - local_idx;
 const auto sg starty = global idy - local idy;
 joint matrix fill(matC, 0.0f);
  for (int step = 0; step < K; step += tK) {
  uint AStart = sg startx * tM * K + step;
  uint BStart = step * N + sg starty;
  joint_matrix_load(sg, matA, inputA + AStart, K);
  joint_matrix_load(sg, matB, inputB + BStart, N);
  matC = joint matrix mad(sg, matA, matB, matC);
 joint matrix apply(sg, matC, [=](T&x) \{x *= alpha; \});
 joint matrix store(sg, matC, output + sg startx * tM * N + sg starty, N, row major);
```

```
// inputA is MxK, inputB is KxN, inputC is MxN
#define tM=16 tN=16 tK=16
 global void wmma ker(blockidx) {
 fragment<matrix a, 16, 16, 16, half, col major> a frag;
 fragment<matrix_b, 16, 16, 16, half, row_major> b_frag;
 fragment<accumulator, 16, 16, 16, float> c_frag;
 uint row = (blockIdx%x - 1)*tM + 1
 uint col = (blockIdx%y - 1)*tN + 1
 fill_fragment(c_frag, 0.0f);
 for (uint step = 0; step < K; step += matrixDepth) {
    uint AStart = row * rowStrideA + step;
    uint BStart = col * colStrideB + step;
    load matrix sync(matA, inputA + AStart, K);
    load_matrix_sync(matB, inputB + BStart, N);
    mma_sync(matC, matA, matB, matC);
  for(int t=0; t<matC.num_elements; t++)</pre>
    matC.x[t] *= alpha;
  store matrix sync(inputC+row*N+col, matC, N, mem row major);
```

Current Users of Joint Matrix

GEMM code using joint matrix

• AMX, XMX (ATS-M and PVC) high-performant GEMM using SYCL joint matrix

Porting code from wmma to joint matrix

• Porting an earthquake simulation code that makes direct use of the tensor cores through wmma from CUDA and wmma to SYCL and joint matrix

SYCL-DNN – By CodePlay

Using joint matrix for enabling Nvidia Tensor Cores in SYCL-DNN

SYCL-BLAS – By CodePlay

• Using joint_matrix for enabling Nvidia Tensor Cores in SYCL-BLAS GEMM

SPIRV MLIR Dialect

• XMX Support using MLIR SPIRV dialect by adding SPIRV joint matrix



Conclusion and Next Steps

- Full support of SYCL joint matrix extension on Intel AMX, Intel XMX, and Nvidia Tensor Cores
- Extensions to LLVM IR and SPIRV
- Effective usage in MLIR integration and CUDA code migration
- Next steps:
 - Standardization of SYCL joint matrix to Khronos SYCL
 - Standardization of SPIRV joint matrix to Khronos SPIRV
- Contributions/feedback are welcome



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