# **Notes on R - Examples**

### **Partition**

The obtained dataset has been randomly partitioned into two sets, where 70% of the volunteers was selected for generating the training data and 30% the test data.

## **Subject**



#### partition

The obtained dataset has been randomly partitioned into two sets, where 70% of the volunteers was selected for generating the training data and 30% the test data.

# **Activity**

Each subject performed six activities (WALKING, WALKING\_UPSTAIRS, WALKING\_DOWNSTAIRS, SITTING, STANDING, LAYING) and each activity is identified with 1-6 in activity\_labels.txt.

Label	Activity
1	WALKING
2	WALKING_UPSTAIRS
3	WALKING_DOWNSTAIRS
4	SITTING
5	STANDING
6	LAYING

# Input Data X

Measurement records of the study are stored in X\_<partition>.txt.

#### **Features**

Triaxial acceleration from the accelerometer (total acceleration), the estimated body acceleration, and triaxial Angular velocity from the gyroscope. There are 561 features as specified in the features.txt. Refer to features\_info.txt and features.txt provided with the original data for specifications.

The features selected for this database come from the accelerometer and gyroscope 3-axial raw signals tAcc-XYZ and tGyro-XYZ. These time domain signals (prefix 't' to denote time) were captured at a constant rate of 50 Hz. Then they were filtered using a median filter and a 3rd order low pass Butterworth filter with a corner frequency of 20 Hz to remove noise. Similarly, the acceleration signal was then separated into body and gravity acceleration signals (tBodyAcc-XYZ and tGravityAcc-XYZ) using another low pass Butterworth filter with a corner frequency of 0.3 Hz.

Subsequently, the body linear acceleration and angular velocity were derived in time to obtain Jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ). Also the magnitude of these three-dimensional signals were calculated using the Euclidean norm (tBodyAccMag, tGravityAccMag, tBodyAccJerkMag, tBodyGyroMag, tBodyGyroJerkMag).

Finally a Fast Fourier Transform (FFT) was applied to some of these signals producing fBodyAcc-XYZ, fBodyAccJerk-XYZ, fBodyGyro-XYZ, fBodyAccJerkMag, fBodyGyroMag, fBodyGyroJerkMag. (Note the 'f' to indicate frequency domain signals).

These signals were used to estimate variables of the feature vector for each pattern:

'-XYZ' is used to denote 3-axial signals in the X, Y and Z directions.

tBodyAcc-XYZ tGravityAcc-XYZ tBodyAccJerk-XYZ tBodyGyro-XYZ tBodyGyroJerk-XYZ tBodyAccMag tGravityAccMag tBodyAccJerkMag tBodyGyroMag tBodyGyroJerkMag fBodyAcc-XYZ fBodyAccJerk-XYZ fBodyGyro-XYZ fBodyAccMag fBodyAccJerkMag fBodyGyroMag fBodyGyroJerkMag

The set of variables that were estimated from these signals are:

mean(): Mean value std(): Standard deviation

mad(): Median absolute deviation max(): Largest value in array min(): Smallest value in array sma(): Signal magnitude area

energy(): Energy measure. Sum of the squares divided by the number of values.

iqr(): Interquartile range entropy(): Signal entropy

arCoeff(): Autorregresion coefficients with Burg order equal to 4

correlation(): correlation coefficient between two signals

maxInds(): index of the frequency component with largest magnitude

meanFreq(): Weighted average of the frequency components to obtain a mean frequency

skewness(): skewness of the frequency domain signal kurtosis(): kurtosis of the frequency domain signal

bandsEnergy(): Energy of a frequency interval within the 64 bins of the FFT of each window.

angle(): Angle between to vectors.

Additional vectors obtained by averaging the signals in a signal window sample. These are used on the angle() variable:

gravityMean tBodyAccMean tBodyAccJerkMean tBodyGyroMean tBodyGyroJerkMean

## Subject of each record of X

Subject of each row data in X\_<partition> is identified with the label of the corresponding row in subject\_<partition>.txt.

## Activity of each record of X

Activity type of each row data in X\_<partition> is identified with the label of the corresponding row in y\_<partition>.txt.

# **Result output**

#### **Format**

means.txt holds the result data as in the format below.

Subject Activity Features (multiple)

### **Features**

The feature column names are below. Fox instance, time\_bodyacc\_mean\_x is the mean value of the time domain signal of the body acceleration for X direction.

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```
time_bodyacc_mean_x
time_bodyacc_mean_y
time_bodyacc_mean_z
time_bodyacc_std_x
time_bodyacc_std_y
{\tt time\_bodyacc\_std\_z}
time_gravityacc_mean_x
time_gravityacc_mean_y
time_gravityacc_mean_z
time_gravityacc_std_x
time_gravityacc_std_y
time_gravityacc_std_z
\verb|time_bodyaccjerk_mean_x|
time_bodyaccjerk_mean_y
time_bodyaccjerk_mean_z
time_bodyaccjerk_std_x
time_bodyaccjerk_std_y
time_bodyaccjerk_std_z
time_bodygyro_mean_x
time_bodygyro_mean_y
{\tt time\_bodygyro\_mean\_z}
{\tt time\_bodygyro\_std\_x}
time_bodygyro_std_y
time_bodygyro_std_z
time_bodygyrojerk_mean_x
time_bodygyrojerk_mean_y
time_bodygyrojerk_mean_z
time_bodygyrojerk_std_x
time_bodygyrojerk_std_y
{\tt time\_bodygyrojerk\_std\_z}
time_bodyaccmag_mean
time_bodyaccmag_std
time_gravityaccmag_mean
time_gravityaccmag_std
time_bodyaccjerkmag_mean
time_bodyaccjerkmag_std
time_bodygyromag_mean
time_bodygyromag_std
time_bodygyrojerkmag_mean
time_bodygyrojerkmag_std
freq_bodyacc_mean_x
freq_bodyacc_mean_y
freq_bodyacc_mean_z
freq_bodyacc_std_x
freq_bodyacc_std_y
freq_bodyacc_std_z
freq_bodyacc_meanfreq_x
freq_bodyacc_meanfreq_y
freq_bodyacc_meanfreq_z
freq_bodyaccjerk_mean_x
freq_bodyaccjerk_mean_y
freq_bodyaccjerk_mean_z
freq_bodyaccjerk_std_x
freq_bodyaccjerk_std_y
freq_bodyaccjerk_std_z
freq_bodyaccjerk_meanfreq_x
freq_bodyaccjerk_meanfreq_y
freq_bodyaccjerk_meanfreq_z
{\tt freq\_bodygyro\_mean\_x}
freq_bodygyro_mean_y
freq_bodygyro_mean_z
{\tt freq\_bodygyro\_std\_x}
freq_bodygyro_std_y
freq_bodygyro_std_z
freq_bodygyro_meanfreq_x
freq_bodygyro_meanfreq_y
freq_bodygyro_meanfreq_z
freq_bodyaccmag_mean
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freq\_bodyaccmag\_std freq\_bodyaccmag\_meanfreq freq\_bodybodyaccjerkmag\_mean freq\_bodybodyaccjerkmag\_std freq\_bodybodyaccjerkmag\_meanfreq  ${\tt freq\_bodybodygyromag\_mean}$ freq\_bodybodygyromag\_std freq\_bodybodygyromag\_meanfreq freq\_bodybodygyrojerkmag\_mean

freq\_bodybodygyrojerkmag\_std
freq\_bodybodygyrojerkmag\_meanfreq