

J1a

SwapForth

Reference

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Adapted to Olimex ICE40 board by pbrier (pbrier@pbrier.nl)

ANS Forth Compliance Label

J1a SwapForth is an ANS Forth System

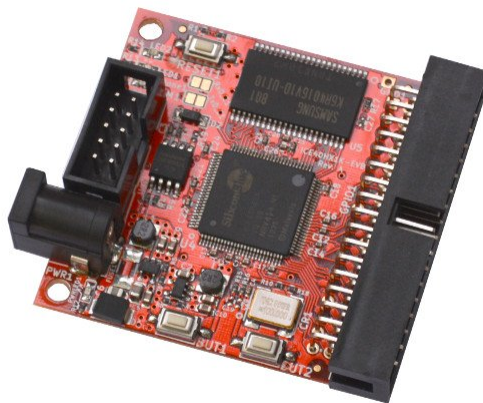
Providing names from the **Core Extensions** word set
Providing names from the **Double-Number** word set
Providing names from the **Facility** word set
Providing names from the **Facility Extensions** word set
Providing names from the **String** word set
Providing names from the **Programming-Tools** word set
Providing names from the **Programming-Tools Extensions** word set

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Chapter 1

Getting started



J1a SwapForth is a 16-bit version of SwapForth, intended as an interactive Forth system using very little logic and RAM. The system currently fits on a Lattice iCE40HX-1k FPGA. The J1a and peripherals use 1200 logic elements. SwapForth uses 4.7 Kbytes of RAM, leaving about 3.3 Kbytes for the application.

After installing the [icestorm](#) tools, you can run on a [Olimex ICE40 board](#) like this

```
git clone https://github.com/pbrier/swapforth.git
cd swapforth/j1a
iceprogduino icestorm/j1a.bin
python shell.py -h /dev/ttyUSB0
```

(where `/dev/ttyUSB0` is the appropriate port your serial adaptor was assigned). You should see something like

```
Contacting... established
Loaded 208 words
>
```

And you can now try the usual Forth things, e.g.

```
1 2 + .
3    ok
```

There is a fairly complete [core ANS-compatible Forth system](#) running on the board, including a compiler.

1.1 Some demos

You can control the five on-board LEDs

```
-1 leds
ok

0 leds
ok
```

and to make them blink

```
: blink
  32 0 do
    i leds
    100 ms
  loop
;
blink
```

There is an [Easter date calculator](#)

```
new
#include ../demos/easter.fs
```

Now you can do

```
>2015 .easter
2015 April 5   ok
```

Or even

```
>: 20easters
+ 2035 2015 do
+   cr i .easter
+ loop
+;
  ok
>20easters

2015 April 5
```

```
2016 March 27
2017 April 16
2018 April 1
2019 April 21
2020 April 12
2021 April 4
2022 April 17
2023 April 9
2024 March 31
2025 April 20
2026 April 5
2027 March 28
2028 April 16
2029 April 1
2030 April 21
2031 April 13
2032 March 28
2033 April 17
2034 April 9    ok
```

1.2 Building from scratch

After installing the icestorm tools, run

```
~/Documents/ice/swapforth/j1a $ make clean
~/Documents/ice/swapforth/j1a $ make j1a
```

This will produce `j1a.bin` - but it only contains the very bare-bones system; the rest of SwapForth still needs to be compiled. To do this, load `j1a.bin` and start the shell (assuming your icestorm board's serial appears at `ttyUSB1`):

```
$ iceprog icestorm/j1a.bin
$ python shell.py -h /dev/ttyUSB1 -p ../common/
Contacting... established
Loaded 143 words
-
```


Then compile the rest of SwapForth and write the finished executable with these commands:

```
#include swapforth.fs
#flash build/nuc.hex
#bye
```

Now run `make -C icestorm` again - this compiles an FPGA image with the complete code base built-in, which has the full set of words defined:

```
$ iceprog icestorm/j1a.bin
$ python shell.py -h /dev/ttyUSB1 -p ../common/
Contacting... established
Loaded 207 words
-
```


Chapter 2

Available Words

2.1 ANS Core Words

J1a SwapForth implements most of the core ANS 94 Forth standard. Implemented words are:

```
! # #> #s ' ( * */ */mod + +! +loop , - . ." / /mod 0< 0=
1+ 1- 2! 2* 2/ 2@ 2drop 2dup 2over 2swap : ; < <# = > >body
>in >number >r ?dup @ abort abort" abs accept align aligned
allot and base begin bl c! c, c@ cell+ cells char char+ chars
constant count cr create decimal depth do does> drop dup else
emit environment? evaluate execute exit fill find fm/mod here
hold i if immediate invert j key leave literal loop lshift m*
max min mod move negate or over postpone quit r> r@ recurse
repeat rot rshift s" s>d sign sm/rem source space spaces state
swap then type u. u< um* um/mod unloop until variable while
word xor [ ' ] [char] ]
```

The core word `environment?` is not implemented. J1a SwapForth also implements the following standard words:

```
.( .r .s /string 0<> 0> :noname <> ?do again ahead case
cmove cmove> compile, d+ d. d.r d0= d2* dabs dnegate dump
endcase endof erase false hex key? m+ marker ms nip of pad
parse refill restore-input save-input sliteral throw true tuck
u.r u> unused within words [compile] \
```

Double numbers are supported using the standard `.` suffix. The Forth 200x number prefixes are supported: `$` for hex, `#` for decimal, `%` for binary, and `'c'` for character literals. `parse-name` is also implemented.

2.2 Additional Words

The following words are not standard. Some are traditional Forth words, others are specific to the J1a SwapForth implementation.

.x

(n --)

display n as a 4-digit hex number

-rot

(x1 x2 x3 -- x3 x1 x2)

rotate the top three stack entries

bounds

(start cnt -- start+cnt start)

prepare to loop on a range

forth

(-- a)

variable: most recent dictionary entry

io!

(x a --)

store x to IO port a

io@

(a -- x)

fetch from IO port a

leds

(x --)

write **x** to the onboard LEDs

new

(--)

restore code and data pointers to the power-up state

s,

(a u --)

add the **u**-character string **a** to the data space

tth

(-- a)

variable: tethered mode

Chapter 3

Using SwapForth

3.1 Raw UART access

At boot, SwapForth listens for a command on the UART. Connection parameters are 230400 8N1, and any terminal program should be able to connect. Note that the hardware board uses DTR as a reset signal, so you should make sure that it is set OFF by the terminal program:

```
$ miniterm.py --dtr=0 /dev/ttyUSB5 230400
--- Miniterm on /dev/ttyUSB5: 460800,8,N,1 ---
--- Quit: Ctrl+] | Menu: Ctrl+T | Help: Ctrl+T followed by Ctrl+H ---
--- forcing DTR inactive

ok
ok
ok
```

3.2 The SwapForth shell

The SwapForth shell is a Python program that runs on the host PC. It has a number of advantages over raw UART access:

- command-line editing
- command history
- word completion on TAB

- local file `include`
- `^C` for interrupt

3.2.1 Invocation

The shell is a Python program. To run it, go to the appropriate directory and type:

```
python shell.py -h /dev/ttyUSB0
```

3.2.2 Command reference

#bye - quit SwapForth shell

#flash - copy the target state to a local file

#include - send local source file

#noverbose - turn off include echo

#time - measure execution time

3.3 Tethered Mode

J1b SwapForth supports *tethered mode*, which makes the UART protocol easier to use for host programs. The SwapForth shell uses tethered mode. To enter tethered mode, write one to the variable **tth** :

```
1 tth !
```

In tethered mode, **accept** transmits byte value 30 (hex **1e**, ASCII code RS). This allows the listening program to know that the target machine is ready to accept a line of input. In addition, **accept** does not echo characters as they are typed.

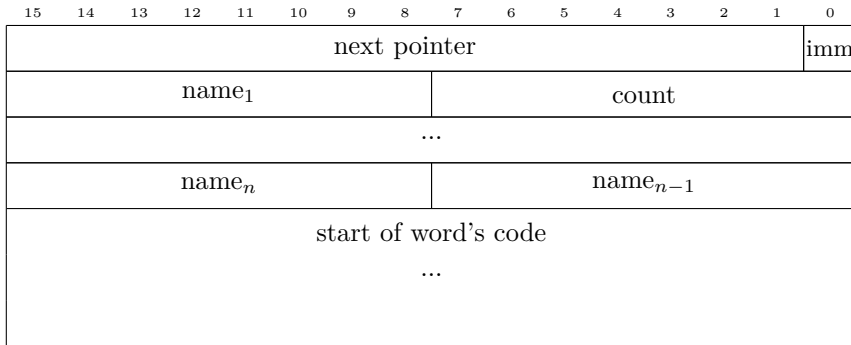
Chapter 4

Memory

4.1 Memory map

The J1a SwapForth implementation uses 8Kbytes of RAM for code and data. The standard Forth words access this RAM. Cells are 16-bits, and must be aligned to a 16-bit boundary.

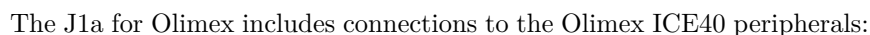
4.2 Dictionary Layout



The SwapForth dictionary is a linked list; the variable `forth` holds the start of this list. Each dictionary entry has the following fields:

- **next pointer** - address of the next dictionary entry, or zero for the last dictionary entry
- **imm** - immediate bit, set if the word is immediate
- **count** - length of the name, in characters, 1-31
- **name₁ - name_n** - characters in name. If the length of the name is even, then a padding byte is appended

Olimex ICE40 Hardware interface



- SPI flash
- 2x LEDs
- 2x Button
- GPIO connector
- UART
- SRAM (64k x 16bit accessible)

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As an example of direct port access, this reads the buttons and sets the Leds while also reporting the value to the serial console blinks the on-board LEDs when a signal on IrDA is detected.

```
\ output buttons to leds and terminal
: .bleds
begin
    $2000 io@
    3 rshift
    3 xor
    dup .x
    $0004 io!
again
;
```

5.1 Port Map

5.1.1 \$0001: data

The read-write port at address \$0001 is for direct access to the connector. The port pins are assigned:

connection	Left row pins	right row pins	connection
bit 0	1	7	bit 4
bit 1	2	8	bit 5
bit 2	3	9	bit 6
bit 3	4	10	bit 7
ground	5	11	ground
3.3v	6	12	3.3v

Correspondingly the port bits are assigned to pins as follows:

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
								10	9	8	7	4	3	2	1

Note that pin direction is controlled by the corresponding bit the port at address \$0002.

5.1.2 \$0002: direction

Each of the 8 bits controls the direction of the corresponding pin of the connector. 0 sets the pin to input, 1 means sets the pin to output. The bit-to-pin mapping is the same as for port \$0001.

5.1.3 \$0004: LEDs

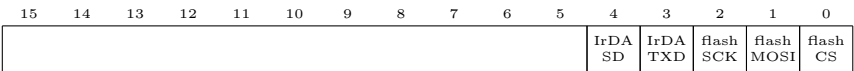
The five on-board LEDS are controlled by write-only port at address \$0004. Setting a bit to 1 lights the corresponding LED.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
											LED5	LED4	LED3	LED2	LED1

Built-in word `leds` writes to this port.

5.1.4 \$0008: PIO output

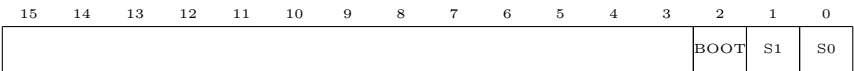
Write-only port \$0008 controls the flash and IrDA outputs.



5.1.5 \$0800: SB_WARMBOOT control

Write-only port \$0800 is an interface to the SB_WARMBOOT module. When activated, the FPGA loads a new configuration from external flash. There can be up to four external configurations; configuration 0 is the base SwapForth, and configurations 1-3 are available for other uses. So to reload the base system:

```
4 $800 io!
```



5.1.6 \$1000: UART data

The read-write port at address \$1000 is for UART transmission or reception. Writing to the port starts transmission of a byte, reading the port returns the incoming byte.

Standard words **key** , **key?** and **emit** can be used to access this port.



5.1.7 \$2000: IrDA, flash and UART inputs

Read-only port \$2000 contains the input signals from the IrDA receiver, SPI flash, and UART.

