# **Stochastic Processes**



Week 06 (version 2.0)

**Estimation Theory - Part I** 

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### **Outline of Week 06 Lectures**

- Introduction to Estimation Theory
- Sufficient Statistic
- Minimal Sufficient Statistic
- Complete Sufficient Statistic
- Likelihood Principle
- Frequentist's Estimators: MLE, MM

- Estimation Theory: is a branch of statistics that deals with estimating the values of parameters based on observed data that has a random component.
- In this course we focus on point estimation: Given  $X = \{x_1, x_2, ..., x_n\}$  where  $x_i$ s are independent and identically distributed (i.i.d) observations with  $f(x_i|\theta)$ , we want to find an statistics  $T(X) = \hat{\theta}$  that is a good estimator for  $\theta$ .

### • Three basic Questions:

- 1) Do we need all the i.i.d observations to estimate  $\theta$ ?
- 2) What do we mean by "good estimator"?
- 3) Do we need prior information on  $\theta$  (i.e.  $f(\theta)$ ) to estimate it?

### • Answers:

- 1) Not necessarily! We may use Sufficient Statistic (SS); a function or statistic of observations, instead.
- 2) The goodness of an estimator is measured by three properties: unbiasedness, efficiency (minimum variance) and consistency.

### • Unbiasedness:

An estimator  $\hat{\theta}$  is said to be unbiased if its expected value is identical to  $\theta$ ;  $E(\hat{\theta}) = \theta$ .

### • Efficiency:

If two competing estimators are both unbiased, the one with the smaller variance is said to be relatively more efficient.

### • Consistency:

If an estimator  $\hat{\theta}$  approaches the parameter  $\theta$  closer and closer as the sample size n increases,  $\hat{\theta}$  is said to be a consistent estimator of  $\theta$  (not a rigorous definition).

3) The frequentist believe we do not need prior information on  $\theta$  (i.e.  $f(\theta)$ ) to estimate it. However, the Bayesian believe we do need prior information on  $\theta$ .

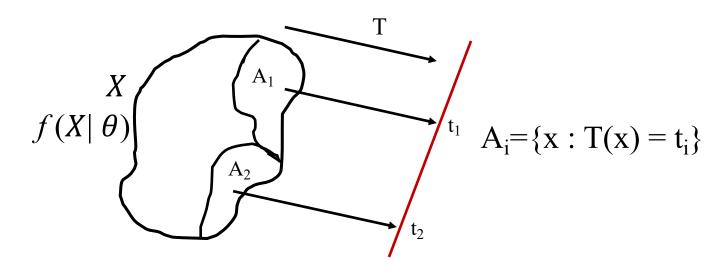
In the following we focus on Sufficient Statistic.

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### **Sufficient Statistic (SS)**

Assume the statistic T partitions the sample space into sets.



**Goal of SS**: Data reduction without discarding information about  $\theta$ . Examples of statistics:

$$T(X) = 2$$
$$T(X) = X$$

- A statistic T(X) is a sufficient statistic for  $\theta$  if the conditional density of X given the value of T(X) does not depend on  $\theta$ .
- In other words, if T(X) is a sufficient statistic for  $\theta$  then any inference about  $\theta$  should depend on the sample X only through T(X); meaning  $\hat{\theta}$  is a function of T(X).
- How to find sufficient statistics for  $\theta$ ?

#### **Factorization Theorem:**

Let  $f(x|\theta)$  be the pdf of X.

T(X) is a sufficient stat for  $\theta$  iff  $\exists$  functions g and h such that:

$$f(x|\theta) = g(T(x)|\theta) h(x) \quad \forall x \in \chi, \quad \theta \in \Theta$$

proof: (discrete case)

⇒: Assume T is a sufficient statistic:

$$f(x|\theta) = P_{\theta}(X = x) = P_{\theta}(X = x, T(X) = T(x))$$

$$= P_{\theta}(T(X) = T(x))P_{\theta}(X = x|T(X) = T(x))$$

$$g(T(x)|\theta) \qquad h(x)$$

 $\Leftarrow$ : Assume factorization holds, let  $q(t|\theta)$  be the pmf of T(X)

Let 
$$A_t = \{y : T(y) = t\}$$

$$q(t|\theta) = P_{\theta}(T(X) = t) = \sum_{x \in A_t} f(x|\theta) = \sum_{x \in A_t} g(T(x)|\theta)h(x)$$

$$P_{\theta}(X=x|T(X)=T(x)) = \frac{P_{\theta}(X=x,T(X)=T(x))}{P_{\theta}(T(X)=T(x))} = \frac{P_{\theta}(X=x)}{q(t|\theta)}$$

$$= \frac{g(T(x)|\theta)h(x)}{g(T(x)|\theta)\sum_{x \in A_t} h(x)} = \frac{h(x)}{\sum_{x \in A_t} h(x)} \text{ does not depend on } \theta.$$

**Example**:  $x_1, ..., x_n$  be i.i.d Bernoulli( $\theta$ ),  $0 < \theta < 1$ .

Then  $T(x) = \sum_{i=1}^{n} x_i$  is a sufficient statistic for  $\theta$ .

$$f(x|\theta) = \prod_{i=1}^{n} \theta^{x_i} (1-\theta)^{1-x_i} = \theta^{\sum x_i} (1-\theta)^{n-\sum x_i}$$

$$g(t|\theta) \coloneqq \theta^t (1-\theta)^{n-t}$$

$$h(x) \coloneqq 1$$

**Example**:  $x_1, ..., x_n$  be i.i.d U(0,  $\theta$ ).

$$f(x_1, \dots, x_n | \theta) = \begin{cases} \frac{1}{\theta} & all \ x_i \ in \ [0, \theta] \\ 0 & o. \ w. \end{cases}$$

Recall: 
$$I_A(x) = \begin{cases} 1 & \text{if } x \in A \\ 0 & \text{o. w.} \end{cases}$$

Let:  $T(x) = \max_{i} x_i$ 

Define: 
$$g(t|\theta) := \frac{1}{\theta^n} 1_{(-\infty,\theta]}(t)$$
  $h(x) = 1_{[0,+\infty)} \left( \min_i x_i \right)$ 

$$\Rightarrow g(T(x)|\theta)h(x) = \frac{1}{\theta^n} 1_{(-\infty,\theta]} \left( \max_i x_i \right) \cdot 1_{[0,+\infty)} \left( \min_i x_i \right) = f(x_1, \dots, x_n|\theta)$$

 $\Rightarrow T(X)$  is sufficient statistic.

**Example**:  $x_1, ..., x_n$  be i.i.d Normal $(\mu, \delta^2)$ .

$$f(x|\mu,\delta^2) = (2\pi\delta^2)^{-\frac{n}{2}} \exp\left(-\frac{\sum_{i=1}^n (x_i - \bar{x})^2 + n(\bar{x} - \mu)^2}{2\delta^2}\right)$$

We show that following  $t_1$  and  $t_2$  together is a sufficient statistic.

$$t_1 = \sum_{i=1}^{n} (x_i - \bar{x})^2$$
,  $t_2 = \bar{x}$ 

need:  $g(t_1, t_2|\theta)$ 

$$g(t|\theta) = g(t_1, t_2|\mu, \delta^2) = (2\pi\delta^2)^{-\frac{n}{2}} \exp\left(-\frac{(t_2 + n(t_1 - \mu))}{2\delta^2}\right)$$

h(x) = 1

 $\Rightarrow T(X)$  is sufficient statistic.

#### **Exponential Family:**

Family of pdf or pmfs is called a k-parameter exponential family if:

$$f(x|\theta) = h(x) c(\theta) \exp\left(\sum_{i=1}^{k} w_i(\theta) t_i(x)\right)$$

**Example**:  $x_1, ..., x_n$  be i.i.d Bernoulli( $\theta$ ),  $0 < \theta < 1$ .

$$f(x|\theta) = \theta^{\sum x_i} (1 - \theta)^{n - \sum x_i} = \exp\left(\ln \theta \sum_{i=1}^n x_i + \ln(1 - \theta) \left(n - \sum_{i=1}^n x_i\right)\right)$$
$$= \exp\left(\ln \frac{\theta}{1 - \theta} \sum_{i=1}^n x_i + n \ln(1 - \theta)\right) = \exp(n \ln(1 - \theta)) \cdot \exp\left(\ln \frac{\theta}{1 - \theta} \sum_{i=1}^n x_i\right)$$

$$k = 1,$$
  $h(x) = 1,$   $c(\theta) = \exp(n\ln(1-\theta)),$   $t_1 = \sum_{i=1}^{n} x_i,$   $w_1(\theta) = \ln\frac{\theta}{1-\theta}$ 

**Example**:  $x_1, ..., x_n$  be i.i.d Normal $(\mu, \delta^2)$ .

$$f(x|\mu,\delta^2) = \frac{1}{\sqrt{2\pi\delta^2}} \exp\left(-\frac{(x-\bar{\mu})^2}{2\delta^2}\right) = \frac{1}{\sqrt{2\pi}} \frac{1}{\delta} \exp\left(-\frac{\mu^2}{2\delta^2}\right) \exp\left(-\frac{x^2}{2\delta^2} + \frac{\mu x}{\delta^2}\right)$$

Exponential family:

$$f(x|\theta) = h(x) c(\theta) \exp\left(\sum_{i=1}^{k} w_i(\theta) t_i(x)\right)$$

 $\Rightarrow$ 

$$k = 2$$
,  $h(x) = 1$ ,  $c(\mu, \delta^2) = \frac{1}{\sqrt{2\pi}} \frac{1}{\delta} \exp\left(-\frac{\mu^2}{2\delta^2}\right)$ ,  $t_1(x) = \frac{x^2}{2}$ ,  $w_1(\mu, \delta^2) = \frac{1}{\delta^2}$ 

$$t_2(x) = x, w_2(\mu, \delta^2) = \frac{\mu}{\delta^2}$$

#### Sufficient statistic for exponential family:

Let  $x_1, ..., x_n$  be i.i.d observations from a pdf or pmf:  $f(x|\theta)$ . Suppose  $f(x|\theta)$  belongs to the exponential family:

$$f(x|\theta) = h(x) c(\theta) \exp\left(\sum_{i=1}^{k} w_i(\theta) t_i(x)\right)$$

Then

$$T(X)=(\sum_{i=1}^n t_1(x_i)$$
 ,  $\sum_{i=1}^n t_2(x_i)$  , ... ,  $\sum_{i=1}^n t_k(x_i)$  is a sufficient statistic for  $\theta$  .

**Example**:  $x_1, ..., x_n$  be i.i.d Normal $(\mu, \delta^2)$ .

$$t_1(x) = -\frac{x^2}{2} \qquad t_2(x) = x$$

$$\Rightarrow T(X) = \left(-\frac{1}{2}\sum_{i=1}^{n} x_i^2, \sum_{i=1}^{n} x_i\right) \text{ is sufficient statistic for } (\mu, \delta^2)$$

$$T'(X) = \left(\sum_{i=1}^{n} (x_i - \bar{x})^2, \bar{x}\right)$$

$$T(X) = T(Y) \quad iff \quad T'(X) = T'(Y)$$

#### **Results:**

1) T(X) = X is a sufficient statistic.

#### **Proof:**

$$f(x|\theta) = f(T(x)|\theta)h(x)$$
$$T(x) = x, \qquad h(x) = 1$$

2) Any one-to-one function of a sufficient statistic is also a sufficient statistic.

**Proof:** Suppose T is a sufficient statistic.

Define  $T^*(x) = r(T(x))$  where r is one-to-one and has inverse  $r^{-1}$ 

$$f(x|\theta) = g(T(x)|\theta)h(x) = g(r^{-1}(T^*(x))|\theta)h(x)$$

Define 
$$g^*(t|\theta) = g(r^{-1}(t)|\theta)h(x)$$

$$\Rightarrow f(x|\theta) = g^*(T^*(x)|\theta) h(x)$$
 so  $T^*$  is a sufficient static for  $\theta$ .

**Example:**  $x_1, ..., x_n$  be i.i.d Bernoulli( $\theta$ ),  $0 < \theta < 1$ .

All of the following are sufficient statics for  $\theta$ 

$$T_1(X) = \sum_{i=1}^n x_i, \qquad T_2(X) = (x_{(1)}, x_{(2)}, \dots, x_{(n)}), \qquad T_3(X) = (x_1, x_2, \dots, x_n)$$

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#### Minimal sufficient statistic:

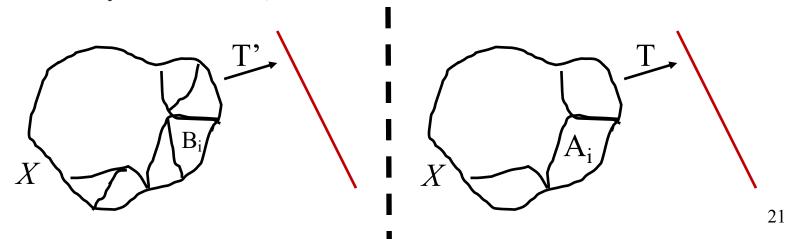
A sufficient statistic T(X) is called minimal sufficient statistic, if for any other sufficient statistic T'(X), T(X) is a function of T'(X).

It achieve maximum possible data reduction without losing info about  $\theta$ .

T partitions  $\chi$  into sets;  $A_t = \{\underline{X} : T(\underline{X}) = t\}$ 

T'partitions  $\chi$  into sets;  $B_{t'} = \{\underline{X} : T'(\underline{X}) = t'\}$ 

Each set  $B_{t'} \subset \text{ some set } A_t$ 



#### Theorem:

Let  $f(x|\theta)$  be pdf or pmf of  $\gamma$ . Suppose that for any 2 sample points  $\underline{X}$  and  $\underline{Y}$  then ratio:

$$\frac{f(\underline{X}|\theta)}{f(\underline{Y}|\theta)}$$

is constant as a function of  $\theta$  iff T(X) = T(Y), then T(X) is a minimal sufficient statistic for  $\theta$ .

**Proof**: assume  $f(x|\theta) > 0$ 

Let  $I = \{t: t = T(x) \text{ for some } x \in \chi\}$ 

$$A_t = \{ \underline{X} : T(\underline{X}) = t \}$$

for each  $A_t$ , choose a fix element  $X_t \in A_t$ . For any  $\underline{X}$ , let  $X_{T(x)}$  be the fixed element that is in the same  $A_t$  as  $\underline{X}$ , Hence:

$$T(\underline{X}) = T(X_{T(X)})$$

$$\Rightarrow \frac{f(\underline{X}|\theta)}{f(X_{T(x)}|\theta)} \text{ is constant as a function of } \theta.$$

$$g(t|\theta) \coloneqq f(X_{T(x)}|\theta)$$

$$f(x|\theta) = \frac{f(X_{T(x)}|\theta) f(\underline{x}|\theta)}{f(X_{T(x)}|\theta)} = g(T(x)|\theta) h(x)$$

 $\Rightarrow T(x)$  is sufficient.

 $\Leftarrow$  Let T' be an arbitrary sufficient statistic. Then from factorization theorem:

$$\exists$$
 functions  $g', h'$  s.t.  $f(x|\theta) = g'(T'(x)|\theta) h'(x)$ 

For any 2 sample points like  $\underline{x}$ ,  $\underline{y}$  with T'(x) = T'(y):

$$\frac{f(x|\theta)}{f(y|\theta)} = \frac{g'(T'(x)|\theta)h'(x)}{g'(T'(y)|\theta)h'(y)} = \frac{h'(x)}{h'(y)}$$
 which is a constant as a function of  $\theta$ .

So by the assumption about T(x) we have:  $T(\underline{x}) = T(y)$ .

Therefore, T is a function of T'.

Hence *T* is minimal.

**Example**:  $x_1, ..., x_n$  be i.i.d Bernoulli( $\theta$ ),  $0 < \theta < 1$ 

$$f(x|\theta) = \prod_{i=1}^{n} \theta^{x_i} (1-\theta)^{1-x_i} = \theta^{\sum x_i} (1-\theta)^{n-\sum x_i}$$

$$\Rightarrow \frac{f(x|\theta)}{f(y|\theta)} = \theta^{\sum x_i - \sum y_i} (1 - \theta)^{\sum y_i - \sum x_i}$$

need: 
$$\sum x_i - \sum y_i = 0$$

So  $T(X) = \sum_{i=1}^{n} x_i$  is minimal sufficient for  $\theta$ .

**Example:**  $x_1, ..., x_n$  be i.i.d Normal $(\mu, \delta^2)$ .

$$f(x|\mu,\delta^2) = (2\pi\delta^2)^{-\frac{n}{2}} \exp\left(-\frac{\sum_{i=1}^n (x_i - \bar{x})^2 + n(\bar{x} - \mu)^2}{2\delta^2}\right)$$

$$\frac{f(x|\mu,\delta^2)}{f(y|\mu,\delta^2)} = \exp\left(\frac{-n(\bar{x}^2 - \bar{y}^2) + 2n\mu(\bar{x} - \bar{y}) - (n-1)(\sum_{i=1}^n (x_i - \bar{x})^2 - \sum_{i=1}^n (y_i - \bar{y})^2)}{2\delta^2}\right)$$

Need:

$$\bar{x} = \bar{y}$$

$$\sum_{i=1}^{n} (x_i - \bar{x})^2 = \sum_{i=1}^{n} (y_i - \bar{y})^2$$

So  $(\bar{x}, \sum_{i=1}^{n} (x_i - \bar{x})^2)$  is a minimal sufficient statistic for  $\theta$ .

But it is not unique. E.g.  $(\bar{x}, s^2)$  is also a minimal sufficient statistic for  $\theta$ .

Any 1-1 function of a minimal sufficient statistic is a minimal sufficient statistic.

**Example:**  $x_1, ..., x_n$  be i.i.d  $U(\theta, \theta + 1)$ 

$$f(x|\theta) = \begin{cases} 1 & all \ x_i \ in \ (\theta, \theta + 1) \\ 0 & o. \ w. \end{cases} = \begin{cases} 1 & \max(x_i) - 1 < \theta < \min(x_i) \\ o. \ w. \end{cases}$$

$$\frac{f(x|\theta)}{f(y|\theta)} \text{ is constant as a function of } \theta \text{ iff } \begin{cases} \max(x_i) = \max(y_i) \\ \min(x_i) = \min(y_i) \end{cases}$$

Hence,  $T(X) = (x_{(1)}, x_{(n)})$  is a minimal sufficient statistic for  $\theta$ .

Note:  $T'(x) = \left(x_{(n)} - x_{(1)}, \frac{x_{(1)} + x_{(n)}}{2}\right)$  is also minimal sufficient statistic.

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**Def:** let  $f(t|\theta)$  be family of pdfs (pmfs) for a statistic T(x), the family of probability distributions is called complete if:

$$E_{\theta} g(T) = 0 \quad \forall \theta$$

$$\Rightarrow p_{\theta}(g(T) = 0) = 1 \quad \forall \theta$$

Or T(x) is a complete statistic.

**Note:** completeness is a property of the family of distributions not a particular distribution.

Example: Let X be a random sample of size n such that each  $X_i$  has the same Bernoulli distribution with parameter p. Let T be the number of 1s observed in the sample, i.e.

$$T = \sum_{i=1}^n X_i$$

T is a statistic of X which has a binomial distribution with parameters (n,p). If the parameter space for p is (0,1), then T is a complete statistic:

$$\mathrm{E}_p(g(T)) = \sum_{t=0}^n g(t) inom{n}{t} p^t (1-p)^{n-t} = (1-p)^n \sum_{t=0}^n g(t) inom{n}{t} igg(rac{p}{1-p}igg)^t$$

neither p nor 1 - p can be 0.

Hence:  $E_p(g(T)) = 0$  iff:

$$\sum_{t=0}^{n} g(t) {n \choose t} \left(rac{p}{1-p}
ight)^t = 0$$

Replacing p/(1-p) by r:

$$\sum_{t=0}^n g(t)inom{n}{t}r^t=0$$

The range of r is the positive reals. Also, E(g(T)) is a polynomial in r and, therefore, can only be identical to 0 if all coefficients are 0, that is, g(t) = 0 for all t.

- It is important to notice that the result that all coefficients must be 0 was obtained because of the range of r.
- For example, for a single observation and a single parameter value; if n = 1 and the parameter space is  $\{0.5\}$ , T is not complete: g(t) = 2 (t 0.5) and then, E(g(T)) = 0 although g(t) is not 0 for t = 0 nor for t = 1.

### **Theorem:** (exponential family)

Let  $x_1, ..., x_n$  iid  $F(x|\theta)$   $f(x|\theta) = h(x) c(\theta) \exp(\sum w_i(\theta) t_i(x))$ Suppose that the range of  $(w_1(\theta), ..., w_k(\theta))$  contains an n dimensional rectangle.

Then:  $T(\underline{x}) = (\sum_{j=1}^{n} t_1(x_j), ..., \sum_{j=1}^{n} t_k(x_j))$  is complete.

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## The Likelihood Principle

### The likelihood principle:

**Def:** 
$$\underline{X} \sim f(x|\theta)$$

Then given X = x observed, then the function of  $\theta$  defined by:

$$L(\theta | \underline{X}) = f(\underline{X} | \theta)$$

Is called the likelihood function.

### **Interpretation:**

1) X discrete

$$L(\theta|X) = p_{\theta}(\underline{X} = x)$$

$$L_1(\theta_2|\underline{X}) > L_2(\theta_2|\underline{X})$$

Sample had a higher likelihood of occurring if  $\theta = \theta_1$  then  $\theta = \theta_2$ .

## The Likelihood Principle

2) *X* continuous (real valued pdf)

for small  $\varepsilon$ :

$$2\varepsilon L(\theta|X) = 2\varepsilon f(X|\theta) \cong p_{\theta}(X - \varepsilon < X < X + \varepsilon)$$

$$\frac{L(\theta_1|X)}{L(\theta_0|X)} = \frac{p_{\theta_1}(X - \varepsilon < X < X + \varepsilon)}{p_{\theta_0}(X - \varepsilon < X < X + \varepsilon)} > 1 ?$$

approx. the same interpretation as discrete.

**Example:**  $x_1, ..., x_n$  iid  $Bernoulli(\theta)$ 

$$L(\theta \mid x) = f(x \mid \theta) = \theta^{\sum x_i} (1 - \theta)^{n - \sum x_i}$$

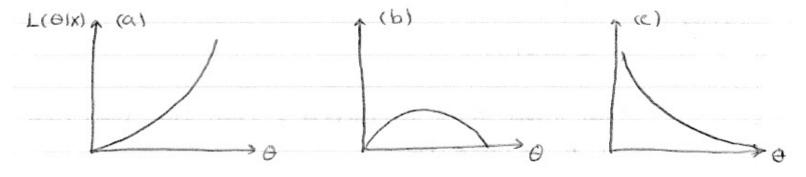
Let 
$$n = 2$$

## The Likelihood Principle

(a) 
$$\Sigma x_i = 2 \Rightarrow L(\theta \mid x) = \theta^2$$

(b) 
$$\Sigma x_i = 1 \Rightarrow L(\theta \mid x) = \theta(1 - \theta)$$

(a) 
$$\Sigma x_i = 2 \Rightarrow L(\theta \mid x) = \theta^2$$
  
(b)  $\Sigma x_i = 1 \Rightarrow L(\theta \mid x) = \theta(1 - \theta)$   
(c)  $\Sigma x_i = 0 \Rightarrow L(\theta \mid x) = (1 - \theta)^2$ 



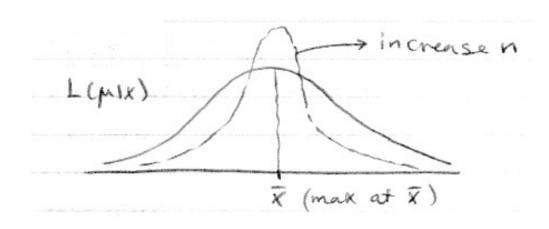
consider 
$$L\left(\frac{3}{4} \mid x\right)/L\left(\frac{1}{4} \mid x\right)$$
:

$$\frac{L(3/4|x)}{L(1/4|x)} = \begin{cases} 9 & \text{when } \sum x_i = 2\\ 1 & \text{whan } \sum x_i = 1\\ \frac{1}{9} & \text{when } \sum x_i = 0 \end{cases}$$

# The Likelihood Principle

**Example:**  $x_1, ..., x_n$  iid  $N(\mu, \delta^2)$ . Assume  $\delta^2$  is fixed.

$$egin{aligned} L(\mu \mid x) &= f(x \mid \mu) = \left(2\pi\delta^2
ight)^{-n/2} e^{-rac{1}{2\delta^2}\left[\sum_-(x_i-ar{x})^2+n(ar{x}-\mu)^2
ight]} \ &= k(x)e^{-n(ar{x}-\mu)^2/2\delta^2} \end{aligned}$$



# The Likelihood Principle

#### Likelihood principle:

If  $\underline{X}$  and  $\underline{Y}$  are two sample points s.t.  $L(\theta | \underline{X})$  is proportional to  $L(\theta | Y)$ :

$$L(\theta|X) = C(X,Y) L(\theta|Y) \quad \forall \theta$$

Then the conclusions drown from *X* and *Y* should be identical.

**Idea:** use the likelihood function to compare the "probability" of various parameter values.

if  $L(\theta_2|X) = 2L(\theta_1|X)$   $\theta_2$  is twice as likely as  $\theta_1$  and:

$$L(\theta|X) = C(X,Y) L(\theta|y) \quad \forall \theta$$

Then:  $L(\theta_2|y) = 2L(\theta_1|y)$   $\theta_2$  is twice as likely as  $\theta_1$ 

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# Frequentist's Estimators

**Def:** A point estimator is any statistic T(x).

Estimator: function of sample.

Estimate: actual value of the estimator.

## Methods of finding estimators for this course:

- (1) Maximum Likelihood Estimator (MLE) ~ (frequentist)
- (2) Method of Moments (MM) ~ (frequentist)
- (3) UMVUE ~ (frequentist)
- (4) Maximum APosteriori (MAP) ~ (Bayes)
- (5) Bayes Minimum Risk ~ (Bayes)

#### Maximum likelihood estimator (MLE):

Given  $X_1, ..., X_n$  i.i.d. with  $f(X_i|\theta)$ :

$$L(\theta|X) = L(\theta_1, \dots, \theta_k|X_1, \dots, X_n) = \prod_{i=1}^n f(X_i|\theta)$$

#### Def:

for each X, let  $\hat{\theta}(X)$  be the value which maximizes  $L(\theta|X)$  then,

 $\hat{\theta}(X)$  is the maximum likelihood estimator (MLE) of  $\theta$ :

$$\hat{\theta}_{\mathrm{ML}}(X) = \arg\max_{\theta} L(\theta|X) = \arg\max_{\theta} f(X|\theta)$$

#### Log likelihood:

use  $\log L(\theta|X)$ :

$$\hat{\theta}_{\text{ML}}(X) = \arg \max_{\theta} \log(L(\theta|X)) = \arg \max_{\theta} \log(f(X|\theta))$$
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#### How to find MLE's:

#### (1) Differentiation

if  $L(\theta|X)$  is differentiable in  $\theta_i$ , possible  $\theta_i$ 's are solutions to:

$$\frac{\partial}{\partial \theta_i} L(\theta | X) = 0$$
 ,  $i = 1, ..., k$ 

#### a) 1-dimension

solve 
$$\frac{\partial}{\partial \theta} L(\theta|X) = 0$$
 for  $\hat{\theta}$ 

check 
$$\frac{\partial^2}{\partial \theta^2} L(\theta | X) < 0$$
 for  $\theta = \hat{\theta}$ 

(check boundaries)

**Example:**  $x_1, ..., x_n$  iid  $Bern(\theta)$ 

$$L(\theta \mid x) = \theta^{\sum x_i} (1 - \theta)^{n - \sum x_i}$$

$$\log L(\theta \mid x) = \sum x_i \log \theta + (n - \sum x_i) \log(1 - \theta)$$

$$\frac{\partial \log L(\theta \mid x)}{\partial \theta} = \frac{\sum x_i}{\theta} - \frac{n - \sum x_i}{1 - \theta} = 0 \Rightarrow \hat{\theta} = \bar{x}$$

$$\frac{\partial^2 \log L}{\partial \theta^2} = -\frac{\sum x_i}{\theta^2} - \frac{n - \sum x_i}{(1 - \theta)^2} < 0 \ @\theta = \hat{\theta}$$

check boundaries;  $\sum x_i = 0$ ,  $\sum x_i = n$ 

$$n \log(1 - \theta) \text{ if } \sum x_i = 0$$

$$\log L(\theta \mid x) =$$

$$n \log(\theta) \text{ if } \sum x_i = n$$

#### b) 2-dimensions

solve 
$$\frac{\partial}{\partial \theta_1} L(\theta_1, \theta_2 | X) = 0$$
  
 $, \frac{\partial}{\partial \theta_2} L(\theta_1, \theta_2 | X) = 0$  for  $\theta_1, \theta_2$   
check that  $\frac{\partial^2}{\partial \theta_1^2} L(\theta_1, \theta_2 | X) < 0$  for  $\theta_1 = \hat{\theta}_1, \theta_2 = \hat{\theta}_2$   
or:  $\frac{\partial^2}{\partial \theta_2^2} L(\theta_1, \theta_2 | X) < 0$  for  $\theta_1 = \hat{\theta}_1, \theta_2 = \hat{\theta}_2$ 

and: 
$$\frac{\partial^2}{\partial \theta_1^2} L(\theta_1, \theta_2 | X) \frac{\partial^2}{\partial \theta_2^2} L(\theta_1, \theta_2 | X) - \left[ \frac{\partial^2}{\partial \theta_1 \partial \theta_2} L(\theta_1, \theta_2 | X) \right]^2 > 0$$
 for  $\theta_1 = \hat{\theta}_1, \, \theta_2 = \hat{\theta}_2$ .

**Example:**  $x_1, ..., x_n$  iid  $N(\mu, \delta^2)$ 

$$\log Lig(\mu,\delta^2\mid xig) = -rac{n}{2}\log 2\pi - rac{n}{2}\log s^2 - rac{1}{2\delta^2}\sum \left(x_i - \mu
ight)^2$$

$$rac{\partial}{\partial \mu} {
m log}\, L = rac{1}{\delta^2} \sum (x_i - \mu) = 0 \Rightarrow \hat{\mu} = ar{x}$$

$$rac{\partial}{\partial \delta^2} {
m log} \, L = -rac{n}{2\delta^3} + rac{1}{2\delta^4} \sum \left(x_i - \mu
ight)^2 = 0 \Rightarrow \hat{\delta}^2 = \sum \left(x_i - ar{x}
ight)^2$$

(i) 
$$\frac{\partial^2}{\partial u^2} \log L = -\frac{n}{\delta^2}$$

$$( ext{ii}) \; rac{\partial^2}{\partial {(s^2)}^2} {\log L} = rac{n}{2\delta^4} - rac{1}{\delta^6} \sum \left(x_i - \mu
ight)^2 \; .$$

$$( ext{ii}) \; rac{\partial^2}{\delta \mu \partial \delta^2} {
m log} \, L = -rac{1}{\delta^4} \sum (x_i - \mu)$$

$$rac{1}{\delta^6}iggl[-rac{n^2}{2}+rac{n}{\delta^2}\sum{(x_i-\mu)^2}-rac{1}{\delta^2}\Bigl(\sum{(x_i-\mu)}\Bigr)^2iggr]iggl|_{\delta^2=\hat{\delta}^2}^{\mu=\hat{\mu}_i}$$

$$\hat{\hat{\delta}}^{6} \left[ -rac{n^{2}}{\hat{\delta}} + rac{n}{\hat{\delta}^{2}} n \hat{\delta}^{2} - rac{1}{\hat{z}^{2}} (0) 
ight] \ = rac{n^{2}}{2 \hat{s}^{2}} > 0 \, .$$

#### How to find MLE's:

- (2) Direct maximization
  - find global upper bound on likelihood function
  - show bound is attained

**Example:**  $x_1, \dots, x_n$  iid  $N(\mu, 1)$ 

$$L(\mu \mid x) = \left(rac{1}{\sqrt{2\pi}}
ight)^2 e^{-rac{1}{2}\sum (x_i-\mu)^2}$$

Recall for any number a:  $\sum (x_i - \bar{x})^2 \leqslant \sum (x_i - a)^2$  $\Rightarrow L(\mu \mid \underline{x}) \leqslant L(\bar{x} \mid \underline{x}) \Rightarrow \hat{\mu} = \bar{x}$ 

#### (3) Numerically (by computer)

With or without (1) and (2)

**Example:**  $x_1, ..., x_n$  iid truncated poisson:

$$p[x_i = r] = \frac{e^{-m}m^r}{(1 - e^{-m})r!}, m \le 0,1,...$$

$$L(m \mid x) = \prod_{i=1}^{n} \frac{e^{-m} m^{x_i}}{(1 - e^{-m}) x_i!} = \left(\frac{e^{-m}}{i - e^{-m}}\right)^r m^{\sum x_i} \prod_{i=1}^{n} \frac{1}{x_i!}$$

$$\log L = -mn - n\log(1 - e^{-m}) + \sum x_i \lg m - \sum \log(x_i!)$$

$$\frac{\partial \log L}{\partial m}s + n - \frac{ne^{-m}}{1 - e^{-m}} + \frac{\sum x_i}{m} = 0 \Rightarrow \hat{m} = ?$$

Define: 
$$\phi(m) = \frac{\partial \log L}{\partial m}$$
,  $n \operatorname{eed} \hat{m} s/t \phi(\hat{m}) = 0$ 

Let  $m_0$  be an initial estimate for  $\widehat{m}$ .

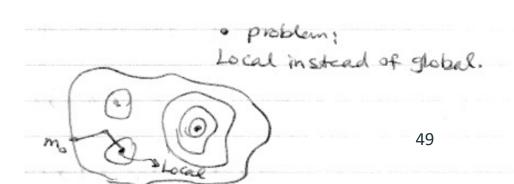
$$0\approx\phi\left(\overset{\circ}{m}\right)\approx\phi(m_0)+\left(\overset{\circ}{m}-m_0\right)\phi'(m_0)$$

$$\hat{m} \approx m_0 - \frac{\phi(m_0)}{\phi'(m_0)}$$

- (1) Choose an initial estimate  $m_0$
- (2) Define a sequence  $\{m_k\}$  of estimates by:

$$m_{k+1} = m_k - \frac{\phi(m_k)}{\phi'(m_k)}$$
 ,  $k = 0,1,2,...$ 

(3) Stop when 
$$|m_{k+1} - m_k| < \varepsilon$$
  
Let  $m = m_k$ 



**Note:** maximization takes place only over the range of parameter values.

**Example:** 
$$x_1, ..., x_n$$
 iid  $N(\mu, 1)$  but  $\mu \ge 0$ 

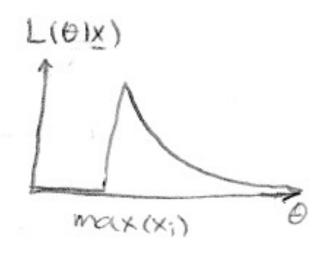
$$\hat{\mu} = \bar{x}$$
 what if  $\bar{x} < 0$ ?

$$\hat{\mu} = 0 \text{ if } \bar{x} < 0 \Rightarrow \hat{\mu} = \begin{cases} \bar{x}, & \bar{x} \geqslant 0 \\ 0 & \bar{x} < 0 \end{cases}$$

**Note:** maximization can occur on boundaries.

Example: 
$$x_1, ..., x_n$$
 iid  $U(0, \theta)$ 

$$L(\theta \mid X) = \begin{cases} \frac{1}{\theta^n} & \text{if } \theta \geqslant \max(x_i) \\ 0 & \text{else} \end{cases}$$
$$\therefore \hat{\theta}_{mLE} = \max(x_i)$$

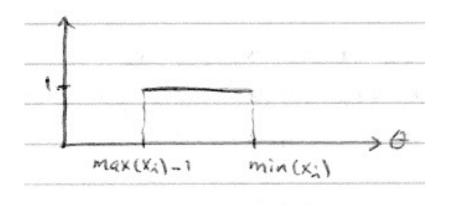


Note: maximum likelihood estimate may not be unique.

**Note:** maximum likelihood estimate may not be unique.

**Example:** 
$$x_1, ..., x_n$$
 iid  $U(\theta, \theta + 1)$ 

$$L(\theta \mid \underline{x}) = \begin{cases} 1 & \max(x_i) - 1 < \theta < \min(x_i) \\ 0 & 0, \omega. \end{cases}$$



$$\hat{\theta} = \text{any value in the interval} \\ \left( \max(x_i) - 1, \min(x_i) \right)$$

**Note:** MLE's can be numerically unstable.

**Example:** 
$$x_1, ..., x_n$$
 iid  $Bin(k, p)$ ;  $k, p$  unknowns

Can show:

if 
$$\underline{x} = (16,18,22,25,27) \Rightarrow \hat{k} = 99$$

if 
$$\underline{x} = (16,18,22,25,28) \implies \hat{k} = 190$$

**Theorem:** (invariance property)

If  $\hat{\theta}$  is the MLE of  $\theta$ , then for any function  $r(\theta)$ ,  $r(\hat{\theta})$  is the MLE of  $r(\theta)$ .

**Example:**  $x_1, ..., x_n$  iid  $N(\mu, 1)$ 

 $\overline{X}$  is the MLE of  $\mu$ , then  $\overline{X}^2$  is the MLE of  $\mu^2$ .

# **Method of Moments**

#### **Method of moments:**

$$x_1, \dots, x_n$$
 iid  $f(x|\theta_1, \dots, \theta_k)$ 

Equate the first k sample moments to the k first population moments.

Let 
$$m_1 = \frac{1}{n} \sum X_i$$
  $\mu_1 = E(X)$   $m_2 = \frac{1}{n} \sum X_i^2$   $\mu_2 = E(X^2)$   $\vdots$   $m_k = \frac{1}{n} \sum X_i^k$   $\mu_2 = E(X^k)$   $m_j = \mu_j(\theta_1, \dots, \theta_k)$  Let  $m_1 = \mu_1(\theta_1, \dots, \theta_k)$   $\vdots$   $m_k = \mu_k(\theta_1, \dots, \theta_k)$  solve for  $\theta_1, \dots, \theta_k$ 

# Method of moments

**Example:** 
$$x_1, ..., x_n$$
 iid  $N(\mu, \delta^2)$ 

$$m_{1} = \frac{1}{n} \sum x_{i}$$

$$\mu_{1} = \mu$$

$$m_{2} = \frac{1}{n} \sum x_{i}^{2}$$

$$\hat{\mu}_{2} = \delta^{2} + \mu^{2}$$

$$\bar{x} = \mu, \frac{1}{n} \sum x_{i}^{2} = s^{2} + \mu^{2} \Rightarrow \hat{\mu} = \bar{x} + \hat{\delta}^{2} = \frac{1}{n} \sum_{i=1}^{n} (x_{i} - \bar{x})^{2}$$

#### **Example:** $x_1, ..., x_n$ iid binomial(k, p) both unknown

$$egin{aligned} ar{x} &= kp \ rac{1}{n} \sum x_i^2 &= kp(1-p) + k^2 p^2 \end{aligned}$$

Solving to get: 
$$\hat{k} = rac{ar{x}^2}{\left[ar{x} - rac{1}{n}\sum \left(x_i - ar{x}
ight)^2
ight]}$$

$$\hat{p}=rac{ar{x}}{\hat{m{\iota}}}$$

# Method of moments

**Note:** this method can also be used for moment matching.

-match moments of distributions of statistics to obtain approximation to distributions.

Example: 
$$x_1, ..., x_n$$
 iid  $p(\lambda)$   $m_1 = \frac{1}{n} \Sigma x_i$  (1)  $E(x_1) = \lambda$   $m_2 = \frac{1}{n} \Sigma x_i^2$ 

$$(1) \,\hat{\lambda} = \bar{x}$$

(2) 
$$\hat{\lambda}^2 + \hat{\lambda} - \frac{1}{n} \sum x_{\hat{\lambda}}^2 = 0 \Rightarrow \hat{\lambda} = -\frac{1}{2} + \left[ \frac{1}{4} + \frac{1}{2} 3x_i^2 \right]^{1/2}$$

 $\hat{\lambda}$  is not unique, using method of moments.

## **Next Week:**

# Estimation Theory – Part II: UMVE & Bayes Comparison of Estimators

Have a good day!