Algorithm 1 Power iteration method

```
Inputs: \hat{H}, z, \epsilon_{\rm abs}, \epsilon_{\rm rel}, \epsilon_{\rm buff}, j_{\rm max}
```

1:
$$\sigma \leftarrow \|z\|_2$$

Require: $\left\|z\right\|_2 > 0$

 $\, \rhd \, \, \text{initialization} \,$

2: for
$$j \leftarrow 1:j_{\max}$$
 do

$$\begin{aligned} &3: & & w \leftarrow \frac{1}{\sigma} \hat{H} z \\ &4: & & z \leftarrow \hat{H}^\top w \\ &5: & & \sigma^\star \leftarrow \|z\|_2 \end{aligned}$$

4:
$$z \leftarrow \hat{H}^{\top} u$$

5:
$$\sigma^{\star} \leftarrow \|z\|_{2}$$

6: if
$$|\sigma^{\star} - \sigma| \leq \epsilon_{abs} + \epsilon_{rel} \max{\{\sigma^{\star}, \sigma\}}$$
 then

 $\triangleright \ stopping \ criterion$

8: else if
$$j < j_{\text{max}}$$
 then
9: $\sigma \leftarrow \sigma^*$

9:
$$\sigma \leftarrow \sigma^*$$

$$10$$
: end if

$$11$$
: end for

12:
$$\sigma \leftarrow (1 + \epsilon_{\text{buff}}) \sigma^*$$

 \triangleright buffer the estimated maximum singular value

Return:
$$\sigma$$

$$\triangleright \approx \max \operatorname{spec} \hat{H}^{\top} \hat{H} = \sigma_{\max} (\hat{H}^{\top} \hat{H}) = \|\hat{H}\|_2^2$$

Algorithm 2 Customized power iteration method

```
\textbf{Inputs:} \ \ \hat{A}^{-}_{[1:N-1]}, \ \hat{A}^{+}_{[1:N-1]}, \ \hat{B}^{-}_{[1:N-1]}, \ \hat{B}^{+}_{[1:N-1]}, \ x_{[1:N]}, \ u_{[1:N]}, \ u_{[1:N]}, \ \phi_{[1:N-1]}, \ \psi_{[1:N-1]}, \ \epsilon_{\text{abs}}, \ \epsilon_{\text{rel}}, \ \epsilon_{\text{buff}}, \ j_{\text{max}}, \ j_{\text{max}
Require: ||x_{[1:N]}||_2 > 0, ||u_{[1:N]}||_2 > 0, ||\phi_{[1:N-1]}||_2 > 0, ||\psi_{[1:N-1]}||_2 > 0
    1: \sigma \leftarrow 0
    2: for k \leftarrow 1: N-1 do
                                                                                                                                                                                                                                                                                                                                                                                                                                    ⊳ Algorithm 1, Line 1
   3: \sigma \leftarrow \sigma + \|x_k\|_2^2 + \|u_k\|_2^2 + \|\phi_k\|_2^2 + \|\psi_k\|_2^2
    5: \sigma \leftarrow \sigma + \|x_N\|_2^2 + \|u_N\|_2^2
    6: \sigma \leftarrow \sqrt{\sigma}
    7: for j \leftarrow 1: j_{\text{max}} do
                              for k \leftarrow 1:N-1 do
                                                                                                                                                                                                                                                                                                                                                                                                                                    ▷ Algorithm 1, Line 3
                                             w_k \leftarrow \frac{1}{\sigma} (\hat{A}_k^- x_k + \hat{A}_k^+ x_{k+1} + \hat{B}_k^- u_k + \hat{B}_k^+ u_{k+1} + \phi_k - \psi_k)
                                             v_k \leftarrow \frac{1}{\sigma}(y_{k+1} - y_k)
                                                                                                                                                                                                                                                                                                                                                                                                                         \triangleright y_k := [0_{1 \times (n_r - 1)}, 1] x_k
10:
                              end for
11:
                              x_1 \leftarrow \hat{A}_1^{-\top} w_1 - \tilde{v}_1
                                                                                                                                                                                                                                                                                                                                                                                                                            \triangleright \tilde{v}_k := [0_{1 \times (n_x - 1)}, v_k]^\top
12:
                              u_1 \leftarrow \hat{B}_1^{-\top} w_1 \\ \phi_1 \leftarrow w_1
13:
14:
15:
                              \psi_1 \leftarrow -w_1
                              \mathbf{for}\ k \leftarrow 2\!:\!N\!-\!1\ \mathbf{do}
                                                                                                                                                                                                                                                                                                                                                                                                                                    ⊳ Algorithm 1, Line 4
16:
                                          x_{k} \leftarrow \hat{A}_{k}^{-\top} w_{k} + \hat{A}_{k-1}^{+\top} w_{k-1} - \tilde{v}_{k} + \tilde{v}_{k-1}
u_{k} \leftarrow \hat{B}_{k}^{-\top} w_{k} + \hat{B}_{k-1}^{+\top} w_{k-1}
\phi_{k} \leftarrow w_{k}
\psi_{k} \leftarrow -w_{k}
17:
18:
19:
20:
                              end for
21:
                             x_N \leftarrow \hat{A}_{N-1}^{+^{\top}} w_{N-1} + \tilde{v}_{N-1}
22:
                              u_N \leftarrow \hat{B}_{N-1}^{+} w_{N-1}
23:
                               \sigma^{\star} \leftarrow 0
24:
                              for k \leftarrow 1: N-1 do \sigma^{\star} \leftarrow \sigma^{\star} + \|x_k\|_2^2 + \|u_k\|_2^2 + \|\phi_k\|_2^2 + \|\psi_k\|_2^2
25:
                                                                                                                                                                                                                                                                                                                                                                                                                                    ▷ Algorithm 1, Line 5
26:
27:
                              \sigma^{\star} \leftarrow \sigma + \|x_N\|_2^2 + \|u_N\|_2^2
28:
                              \sigma^{\star} \leftarrow \sqrt{\sigma^{\star}}
29:
                              if |\sigma^{\star} - \sigma| \leq \epsilon_{\rm abs} + \epsilon_{\rm rel} \, \max\{\sigma^{\star}, \, \sigma\} then
30:

⊳ stopping criterion

31:
                               else if j < j_{\text{max}} then
32:
                                            \sigma \leftarrow \sigma^*
33:
                              end if
34:
35: end for
36: \sigma \leftarrow (1 + \epsilon_{\text{buff}}) \sigma^{\star}
                                                                                                                                                                                                                                                                                                                       ▷ buffer the estimated maximum singular value
                                                                                                                                                                                                                                                                                                                                          \triangleright \approx \max \operatorname{spec} \hat{H}^{\top} \hat{H} = \sigma_{\max} (\hat{H}^{\top} \hat{H}) = \|\hat{H}\|_{2}^{2}
Return: \sigma
```

Algorithm 3 PIPG

```
Inputs: q, H, h, \mathbb{D}, \bar{z}, \lambda, \sigma, \rho, \epsilon_{abs}, \epsilon_{rel}, j_{check}, j_{max},
                       z^{\star}, w^{\star}
                                                                                                                                                                                                                                                                                     \triangleright warm start
 1: \ \zeta^1 \leftarrow z^* \\ 2: \ \eta^1 \leftarrow w^* 
                                                                                                                                                                                                                                                   \triangleright initialize primal variable
                                                                                                                                                                                                                                                        \trianglerightinitialize dual variable
 3: \alpha \leftarrow \frac{2}{\lambda + \sqrt{\lambda^2 + 4\sigma}}
                                                                                                                                                                                                                                                                                           ⊳ step-size
  4: for j \leftarrow 1: j_{\text{max}} do
                 \begin{split} z^{j+1} &= \pi_{\mathbb{D}}[\zeta^{j} - \alpha \left(\lambda \, \zeta^{j} + q + H^{\top} \eta^{j}\right) + \bar{z}] - \bar{z} \\ w^{j+1} &= \eta^{j} + \alpha \left(H(2 \, z^{j+1} - \zeta^{j}) - h\right) \\ \zeta^{j+1} &= (1 - \rho) \, \zeta^{j} + \rho \, z^{j+1} \\ \eta^{j+1} &= (1 - \rho) \, \eta^{j} + \rho \, w^{j+1} \end{split}
  5:
                                                                                                                                                                                                                                                      ▷ projected gradient step
                                                                                                                                                                                  \triangleright PI feedback of affine equality constraint violation
  6:
                                                                                                                                                                                                                                            \triangleright extrapolate primal variable
  7:
                                                                                                                                                                                                                                                 \triangleright extrapolate dual variable
  8:
  9:
                  if j \mod j_{\text{check}} = 0 then
                                                                                                                                                                                          \triangleright check stopping criterion every j_{\rm check} iterations
                          \begin{split} & \mathbf{if} \ \left\| z^{j+1} - z^{j} \right\|_{\infty} \leq \epsilon_{\mathrm{abs}} + \epsilon_{\mathrm{rel}} \ \max \left\{ \left\| z^{j+1} \right\|_{\infty}, \, \left\| z^{j} \right\|_{\infty} \right\} \mathbf{and} \\ & \left\| w^{j+1} - w^{j} \right\|_{\infty} \leq \epsilon_{\mathrm{abs}} + \epsilon_{\mathrm{rel}} \ \max \left\{ \left\| w^{j+1} \right\|_{\infty}, \, \left\| w^{j} \right\|_{\infty} \right\} \mathbf{then} \end{split}
10:

⊳ stopping criterion

11:
12:
                           end if
13:
14:
                  end if
15: end for
16: z^{\star} \leftarrow z^{j+1}
                                                                                                                                                                                                                                                       \triangleright update primal variable
17: w^{\star} \leftarrow w^{j+1}
                                                                                                                                                                                                                                                            \trianglerightupdate dual variable
Return: z^*, w^*
```

Algorithm 4 PIPG_{custom}

```
Inputs: q_{x_{[1:N]}}, q_{u_{[1:N]}}, q_{\phi_{[1:N-1]}}, q_{\psi_{[1:N-1]}},
                                   \hat{A}_{[1:N-1]}^{-},\,\hat{A}_{[1:N-1]}^{+},\,\hat{B}_{[1:N-1]}^{-},\,\hat{B}_{[1:N-1]}^{+},\,\hat{d}_{[2:N]},\,\hat{\overline{x}}_{[1:N]},\,\hat{\overline{u}}_{[1:N]},
                                   \hat{\mathbb{D}}_{x_{[1:N]}},\,\hat{\mathbb{D}}_{u_{[1:N]}},\,\mathbb{D}_{\phi_{[1:N-1]}},\,\mathbb{D}_{\psi_{[1:N-1]}},\,\varepsilon,
                                   \lambda, \, \sigma, \, \omega, \, \rho, \, \epsilon_{
m abs}, \, \epsilon_{
m rel}, \, j_{
m check}, \, j_{
m max},
                                   \Delta \hat{x}_{[1:N]}^{\star}, \ \Delta \hat{u}_{[1:N]}^{\star}, \ \phi_{[1:N-1]}^{\star}, \ \psi_{[1:N-1]}^{\star}, \ w_{[1:N-1]}^{\star}, \ v_{[1:N-1]}^{\star}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                           1: \Delta x_{\zeta_{[1:N]}}^1 \leftarrow \Delta \hat{x}_{[1:N]}^{\star}
                                                                                                                                                                                                                                                                                                                                                                                                                     \triangleright initialize primal variables
   2: \Delta u_{\zeta_{[1:N]}}^{1} \leftarrow \Delta \hat{u}_{[1:N]}^{\star}
   3: \phi^1_{\zeta_{[1:N-1]}} \leftarrow \phi^{\star}_{[1:N-1]}
   4: \psi_{\zeta_{[1:N-1]}}^{1} \leftarrow \psi_{[1:N-1]}^{\star}
   5: \eta_{[1:N-1]}^{\uparrow} \leftarrow w_{[1:N-1]}^{\star}
6: \gamma_{[1:N-1]}^{1} \leftarrow v_{[1:N-1]}^{\star}
                                                                                                                                                                                                                                                                                                                                                                                                                             7: \alpha \leftarrow \frac{2}{\lambda + \sqrt{\lambda^2 + 4\omega\sigma}}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  8: \beta \leftarrow \omega \alpha
   9: for j \leftarrow 1: j_{\text{max}} do
                             \Delta \hat{x}_{1}^{j} \leftarrow \pi_{\hat{\mathbb{D}}_{x_{1}}} [\Delta x_{\zeta_{1}}^{j} - \alpha (\lambda \Delta x_{\zeta_{1}}^{j} + q_{x_{1}} + \hat{A}_{1}^{-\top} \eta_{1}^{j} - \tilde{\gamma}_{1}^{j}) + \hat{\overline{x}}_{1}^{j}] - \hat{\overline{x}}_{1}^{j}
10:
                                                                                                                                                                                                                                                                                                                                                                                                                              \triangleright \tilde{\gamma}_k := [0_{1 \times (n_n-1)}, \gamma_k]^{\top}
                             \Delta \hat{u}_1^j \leftarrow \pi_{\hat{\mathbb{D}}_{u_1}} \left[ \Delta u_{\zeta_1}^j - \alpha \left( \lambda \, \Delta u_{\zeta_1}^j + q_{u_1} + \hat{B}_1^{-\intercal} \eta_1^j \right) + \hat{\overline{u}}_1^j \right] - \hat{\overline{u}}_1^j
11:
12:
                             \phi_1^j \leftarrow \pi_{\mathbb{D}_{\phi_1}} [\phi_{\zeta_1}^j - \alpha (\lambda \phi_{\zeta_1}^j + q_{\phi_1} + \eta_1^j)]
                            \psi_{1}^{j} \leftarrow \pi_{\mathbb{D}_{\psi_{1}}} [\psi_{\zeta_{1}}^{j} - \alpha (\lambda \psi_{\zeta_{1}}^{j} + q_{\psi_{1}} - \eta_{1}^{j})]
13:
                             for k \leftarrow 2: N-1 do
14:
                                                                                                                                                                                                                                                                                                                                                                                                                             ▷ projected gradient step
                                         \Delta \hat{x}_{k}^{j+1} \leftarrow \pi_{\hat{\mathbb{D}}_{x_{k}}} [\Delta x_{\zeta_{k}}^{j} - \alpha \left(\lambda \, \Delta x_{\zeta_{k}}^{j} + q_{x_{k}} + \hat{A}_{k}^{-\top} \eta_{k}^{j} + \hat{A}_{k-1}^{+\top} \eta_{k-1}^{j} - \tilde{\gamma}_{k}^{j} + \tilde{\gamma}_{k-1}^{j}\right) + \hat{\bar{x}}_{k}^{j}] - \hat{\bar{x}}_{k}^{j}
15:
                                         \Delta \hat{u}_{k}^{j+1} \leftarrow \pi_{\hat{\mathbb{D}}_{u_{k}}} \left[ \Delta u_{\zeta_{k}}^{j} - \alpha \left( \lambda \Delta u_{\zeta_{k}}^{j} + q_{u_{k}} + \hat{B}_{k}^{-\top} \eta_{k}^{j} + \hat{B}_{k-1}^{+\top} \eta_{k-1}^{j} \right) + \hat{\overline{u}}_{k}^{j} \right] - \hat{\overline{u}}_{k}^{j}
16:
                                         \begin{aligned} \boldsymbol{\phi}_k^{j+1} &\leftarrow \boldsymbol{\pi}_{\mathbb{D}_{\phi_k}} [\boldsymbol{\phi}_{\zeta_k}^j - \alpha \left(\lambda \, \boldsymbol{\phi}_{\zeta_k}^j + q_{\phi_k} + \boldsymbol{\eta}_k^j\right)] \\ \boldsymbol{\psi}_k^{j+1} &\leftarrow \boldsymbol{\pi}_{\mathbb{D}_{\psi_k}} [\boldsymbol{\psi}_{\zeta_k}^j - \alpha \left(\lambda \, \boldsymbol{\psi}_{\zeta_k}^j + q_{\psi_k} - \boldsymbol{\eta}_k^j\right)] \end{aligned}
17:
18:
19:
                             \Delta \hat{x}_N^{j+1} \leftarrow \pi_{\hat{\mathbb{D}}_{TN}}[\Delta x_{\zeta_N}^j - \alpha \left(\lambda \, \Delta x_{\zeta_N}^j + q_{x_N} + \hat{A}_{N-1}^{+\intercal} \eta_{N-1}^j + \hat{\gamma}_{N-1}^j \right) + \hat{\overline{x}}_N^j] - \hat{\overline{x}}_N^j
20:
                             \Delta \hat{u}_N^{j+1} \leftarrow \pi_{\hat{\mathbb{D}}_{u_N}} [\Delta u_{\zeta_N}^j - \alpha \left(\lambda \, \Delta u_{\zeta_N}^j + q_{u_N} + \hat{\boldsymbol{B}}_{N-1}^{+\top} \eta_{N-1}^j \right) + \hat{\bar{u}}_N^j] - \hat{\bar{u}}_N^j
21:
                             for k \leftarrow 1: N-1 do
                                                                                                                                                                                                                                                                                                                        ▷ PI feedback of affine equality constraint violation
22:
                                         w_k^{j+1} \leftarrow \eta_k^j + \beta \left(\hat{A}_k^- \left(2\Delta \hat{x}_k^{j+1} - \Delta x_{\zeta_k}^j\right) + \hat{A}_k^+ \left(2\Delta \hat{x}_{k+1}^{j+1} - \Delta x_{\zeta_{k+1}}^j\right) + \hat{B}_k^- \left(2\Delta \hat{x}_k^{j+1} - \Delta u_{\zeta_k}^j\right) + \hat{B}_k^+ \left(2\Delta \hat{x}_{k+1}^{j+1} - \Delta u_{\zeta_{k+1}}^j\right) + \hat{B}_k^+ \left(2\Delta \hat{x}_{k+
23:
                                                                                                          +(2\phi_{k}^{j+1}-\phi_{k}^{j})+(2\psi_{k}^{j+1}-\psi_{k}^{j})+\hat{d}_{k+1})
24:
                                        v_k^{j+1} \leftarrow \max\{0,\, \gamma_k^j + \beta\, ((2\Delta \hat{y}_{k+1}^{j+1} - \Delta y_{\zeta_{k+1}}^j) - (2\Delta \hat{y}_k^{j+1} - \Delta y_{\zeta_k}^j) + (\hat{\overline{y}}_{k+1} - \hat{\overline{y}}_k) - \varepsilon)\}
                                                                                                                                                                                                                                                                                                                                                                                                     \triangleright \Box_{y_k}^{\Diamond} := [0_{1 \times (n_x - 1)}, 1] \Box_{x_k}^{\Diamond}
25:
26:
                             \begin{split} & \Delta x_{\zeta_{[1:N]}}^{j+1} \leftarrow (1-\rho) \, \Delta x_{\zeta_{[1:N]}}^{j} + \rho \, \Delta \hat{x}_{[1:N]}^{j+1} \\ & \Delta u_{\zeta_{[1:N]}}^{j+1} \leftarrow (1-\rho) \, \Delta u_{\zeta_{[1:N]}}^{j} + \rho \, \Delta \hat{u}_{[1:N]}^{j+1} \end{split}
27:
                                                                                                                                                                                                                                                                                                                                                                                                         28:
                             \phi_{\zeta_{[1:N-1]}}^{j+1} \leftarrow (1-\rho) \phi_{\zeta_{[1:N-1]}}^{j} + \rho \phi_{[1:N-1]}^{j+1}
29:
                             \psi_{\zeta_{[1:N-1]}}^{j+1} \leftarrow (1-\rho) \, \psi_{\zeta_{[1:N-1]}}^{j} + \rho \, \psi_{[1:N-1]}^{j+1}
30:
                             \eta_{[1:N-1]}^{j+1} \leftarrow (1-\rho) \, \eta_{[1:N-1]}^j + \rho \, w_{[1:N-1]}^{j+1}
31:
                                                                                                                                                                                                                                                                                                                                                                                                                  32:
                             \gamma_{[1:N-1]}^{j+1} \leftarrow (1-\rho) \gamma_{[1:N-1]}^{j} + \rho v_{[1:N-1]}^{j+1}
                             if j \mod j_{\mathrm{check}} = 0 then
                                                                                                                                                                                                                                                                                                                                  \triangleright check stopping criterion every j_{\rm check} iterations
33:
                                         \texttt{TERMINATE} \leftarrow \texttt{STOPPING}_{\texttt{custom}}(\Delta \hat{x}^{j+1}_{[1:N]}, \Delta \hat{u}^{j+1}_{[1:N]}, \phi^{j+1}_{[1:N-1]}, \psi^{j+1}_{[1:N-1]}, w^{j+1}_{[1:N-1]}, v^{j+1}_{[1:N-1]}
34:
                                                                                                                                                                  \Delta \hat{x}^{j}_{[1:N]},\,\Delta \hat{u}^{j}_{[1:N]},\,\phi^{j}_{[1:N-1]},\,\psi^{j}_{[1:N-1]},\,w^{\jmath}_{[1:N-1]},\,v^{\jmath}_{[1:N-1]}\,\epsilon_{\mathrm{abs}},\,\epsilon_{\mathrm{rel}})
35:
36:
                                          if terminate = true then

⊳ stopping criterion

37:
                                                        break
38:
                                          end if
                             end if
39:
40: end for
41: \Delta \hat{x}_{[1:N]}^{\star} \leftarrow \Delta \hat{x}_{[1:N]}^{j+1}
                                                                                                                                                                                                                                                                                                                                                                                                                           ▶ update primal variables
42: \Delta \hat{u}_{[1:N]}^{\star} \leftarrow \Delta \hat{u}_{[1:N]}^{j+1}
43: \phi_{[1:N-1]}^{\star} \leftarrow \phi_{[1:N-1]}^{j+1}
44: \psi_{[1:N-1]}^{\star} \leftarrow \psi_{[1:N-1]}^{j+1}
45: w_{[1:N-1]}^{\star} \leftarrow w_{[1:N-1]}^{j+1}
                                                                                                                                                                                                                                                                                                                                                                                                                                   ▶ update dual variables
46: v_{[1:N-1]}^{\star} \leftarrow v_{[1:N-1]}^{j+1}
\textbf{Return:} \ \Delta x^{\star}_{[1:N]}, \ \Delta u^{\star}_{[1:N]}, \ \phi^{\star}_{[1:N-1]}, \ \psi^{\star}_{[1:N-1]}, \ w^{\star}_{[1:N-1]}, \ v^{\star}_{[1:N-1]}
```

Algorithm 5 Customized stopping criterion evaluation:

$$\begin{split} \text{STOPPING}_{\text{custom}}(\Delta \hat{x}_{[1:N]}^{j+1}, \, \Delta \hat{u}_{[1:N]}^{j+1}, \, \phi_{[1:N-1]}^{j+1}, \, \psi_{[1:N-1]}^{j+1}, \, w_{[1:N-1]}^{j+1}, \, v_{[1:N-1]}^{j+1}, \\ \Delta \hat{x}_{[1:N]}^{j}, \, \Delta \hat{u}_{[1:N]}^{j}, \, \phi_{[1:N-1]}^{j}, \, \psi_{[1:N-1]}^{j}, \, w_{[1:N-1]}^{j}, \, v_{[1:N-1]}^{j}, \, \epsilon_{\text{abs}}, \, \epsilon_{\text{rel}}) \end{split}$$

Inputs:
$$\Delta \hat{x}_{[1:N]}^{j+1}$$
, $\Delta \hat{u}_{[1:N]}^{j+1}$, $\phi_{[1:N-1]}^{j+1}$, $\psi_{[1:N-1]}^{j+1}$, $w_{[1:N-1]}^{j+1}$, $\Delta \hat{x}_{[1:N]}^{j}$, $\Delta \hat{u}_{[1:N]}^{j}$, $\phi_{[1:N-1]}^{j}$, $\psi_{[1:N-1]}^{j}$, $w_{[1:N-1]}^{j}$, ϵ_{abs} , ϵ_{rel}

$$\begin{split} &1:\ z_{\infty}^{j+1} \leftarrow \max \Big\{ \|\Delta \hat{x}_{[1:N]}^{j+1}\|_{\infty},\ \|\Delta \hat{u}_{[1:N]}^{j+1}\|_{\infty},\ \|\phi_{[1:N-1]}^{j+1}\|_{\infty},\ \|\psi_{[1:N-1]}^{j+1}\|_{\infty} \Big\} \\ &2:\ z_{\infty}^{j} \ \leftarrow \max \Big\{ \|\Delta \hat{x}_{[1:N]}^{j}\|_{\infty},\ \|\Delta \hat{u}_{[1:N]}^{j}\|_{\infty},\ \|\phi_{[1:N-1]}^{j}\|_{\infty},\ \|\psi_{[1:N-1]}^{j}\|_{\infty} \Big\} \\ &3:\ z_{\infty}^{\Delta j} \ \leftarrow \max \Big\{ \|\Delta \hat{x}_{[1:N]}^{j+1} - \Delta \hat{x}_{[1:N]}^{j}\|_{\infty},\ \|\Delta \hat{u}_{[1:N]}^{j+1} - \Delta \hat{u}_{[1:N]}^{j}\|_{\infty},\ \|\phi_{[1:N-1]}^{j+1} - \phi_{[1:N-1]}^{j}\|_{\infty},\ \|\psi_{[1:N-1]}^{j+1} - \psi_{[1:N-1]}^{j}\|_{\infty} \Big\} \end{split}$$

3:
$$z_{\infty}^{\Delta j} \leftarrow \max \left\{ \|\Delta \hat{x}_{[1:N]}^{j+1} - \Delta \hat{x}_{[1:N]}^{j}\|_{\infty}, \|\Delta \hat{u}_{[1:N]}^{j+1} - \Delta \hat{u}_{[1:N]}^{j}\|_{\infty}, \|\phi_{[1:N-1]}^{j+1} - \phi_{[1:N-1]}^{j}\|_{\infty}, \|\psi_{[1:N-1]}^{j+1} - \psi_{[1:N-1]}^{j}\|_{\infty} \right\}$$

$$4: r_{\infty}^{j+1} \leftarrow \max \left\{ \|w_{[1:N-1]}^{j+1}\|_{\infty}, \|v_{[1:N-1]}^{j+1}\|_{\infty} \right\}$$

$$\begin{aligned} &4:\ r_{\infty}^{j+1} \leftarrow \max \left\{ \|w_{[1:N-1]}^{j+1}\|_{\infty}, \|v_{[1:N-1]}^{j+1}\|_{\infty} \right\} \\ &5:\ r_{\infty}^{j} \ \leftarrow \max \left\{ \|w_{[1:N-1]}^{j}\|_{\infty}, \|v_{[1:N-1]}^{j}\|_{\infty} \right\} \\ &6:\ r_{\infty}^{\Delta j} \ \leftarrow \max \left\{ \|w_{[1:N-1]}^{j+1} - w_{[1:N-1]}^{j}\|_{\infty}, \|v_{[1:N-1]}^{j+1} - v_{[1:N-1]}^{j}\|_{\infty} \right\} \end{aligned}$$

7: if
$$z_{\infty}^{\Delta j} \leq \epsilon_{\mathrm{abs}} + \epsilon_{\mathrm{rel}} \, \max \left\{ z_{\infty}^{j+1}, \, z_{\infty}^{j} \right\}$$
 and $r_{\infty}^{\Delta j} \leq \epsilon_{\mathrm{abs}} + \epsilon_{\mathrm{rel}} \, \max \left\{ r_{\infty}^{j+1}, \, r_{\infty}^{j} \right\}$ then

8: TERMINATE ← TRUE

9: **else**

10: TERMINATE \leftarrow FALSE

11: end if

Return: TERMINATE