Algorithms

Algorithm 1 Power iteration method

```
Inputs: \hat{H}, z, \epsilon_{\rm abs}, \epsilon_{\rm rel}, \epsilon_{\rm buff}, j_{\rm max}
Require: \left\|z\right\|_2 > 0
  1:\ \sigma \leftarrow \left\Vert z\right\Vert _{2}
                                                                                                                                                                                                                                               \,\rhd\,\, \text{initialization}
  2: for j \leftarrow 1:j_{\text{max}} do
             w \leftarrow \frac{1}{\sigma} \hat{H} zz \leftarrow \hat{H}^{\top} w\sigma^{\star} \leftarrow \|z\|_{2}
  4:
  5:
               if |\sigma^{\star} - \sigma| \le \epsilon_{abs} + \epsilon_{rel} \max{\{\sigma^{\star}, \sigma\}} then
  6:
                                                                                                                                                                                                                                   \rhd \ stopping \ criterion
  7:
  8:
                else if j < j_{\text{max}} then
  9:
                       \sigma \leftarrow \sigma^{\star}
                end if
10:
11: end for
12: \sigma \leftarrow (1 + \epsilon_{\text{buff}}) \sigma^*
                                                                                                                                                                     \triangleright buffer the estimated maximum singular value
                                                                                                                                                                              \triangleright \approx \max \operatorname{spec} \hat{H}^{\top} \hat{H} = \sigma_{\max}(\hat{H}^{\top} \hat{H}) = \|\hat{H}\|_2^2
Return: \sigma
```

```
Algorithm 2 Customized power iteration method
```

```
Inputs: \hat{A}_{[1:N-1]}^-, \hat{A}_{[1:N-1]}^+, \hat{B}_{[1:N-1]}^-, \hat{B}_{[1:N-1]}^+, x_{[1:N]}, x_{[1:N]}, y_{[1:N-1]}, y_{[1:N-1]}, x_{[1:N-1]}, x_{[1:N]}, y_{[1:N-1]}, y_{[1:N-1]}
Require: \left\|x_{[1:N]}\right\|_{2} > 0, \left\|u_{[1:N]}\right\|_{2} > 0, \left\|\phi_{[1:N-1]}\right\|_{2} > 0, \left\|\psi_{[1:N-1]}\right\|_{2} > 0
    1: \sigma \leftarrow 0
  2: for k \leftarrow 1: N-1 do 3: \sigma \leftarrow \sigma + \|x_k\|_2^2 + \|u_k\|_2^2 + \|\phi_k\|_2^2 + \|\psi_k\|_2^2 4: end for
                                                                                                                                                                                                                                                                                                                                                                                     ⊳ Algorithm 1, Line 1
    5: \sigma \leftarrow \sigma + \|x_N\|_2^2 + \|u_N\|_2^2
    6: \sigma \leftarrow \sqrt{\sigma}
    7: for j \leftarrow 1: j_{\text{max}} do
                           for k \leftarrow 1:N-1 do
                                                                                                                                                                                                                                                                                                                                                                                     ▷ Algorithm 1, Line 3
    8:
                                        w_k \leftarrow \frac{1}{\sigma} (\hat{A}_k^- x_k + \hat{A}_k^+ x_{k+1} + \hat{B}_k^- u_k + \hat{B}_k^+ u_{k+1} + \phi_k - \psi_k)
    9:
                                        v_k \leftarrow \frac{1}{\sigma}(y_{k+1} - y_k)
                                                                                                                                                                                                                                                                                                                                                                            \triangleright y_k := [0_{1 \times (n_r - 1)}, 1] x_k
10:
                           end for
11:
                         \begin{aligned} x_1 &\leftarrow \hat{A}_1^{-\top} w_1 - \tilde{v}_1 \\ u_1 &\leftarrow \hat{B}_1^{-\top} w_1 \\ \phi_1 &\leftarrow w_1 \end{aligned}
                                                                                                                                                                                                                                                                                                                                                                              \triangleright \tilde{v}_k := [0_{1 \times (n_x - 1)}, v_k]^\top
12:
13:
14:
15:
                           for k \leftarrow 2:N-1 do
16:
                                                                                                                                                                                                                                                                                                                                                                                     ▷ Algorithm 1, Line 4
                                     x_{k} \leftarrow \hat{A}_{k}^{\top} w_{k} + \hat{A}_{k-1}^{+\top} w_{k-1} - \tilde{v}_{k} + \tilde{v}_{k-1}
u_{k} \leftarrow \hat{B}_{k}^{\top} w_{k} + \hat{B}_{k-1}^{+\top} w_{k-1}
\phi_{k} \leftarrow w_{k}
\psi_{k} \leftarrow -w_{k}
17:
18:
19:
20:
21:
                           end for
                          x_N \leftarrow \hat{A}_{N-1}^{+^{\top}} w_{N-1} + \tilde{v}_{N-1}
22:
                            u_N \leftarrow \hat{B}_{N-1}^{+^{\top}} w_{N-1}
23:
24:
                            \begin{aligned} & \mathbf{for} \ k \leftarrow 1 \colon\! N - 1 \ \mathbf{do} \\ & \sigma^{\star} \leftarrow \sigma^{\star} + \left\| x_k \right\|_2^2 + \left\| u_k \right\|_2^2 + \left\| \phi_k \right\|_2^2 + \left\| \psi_k \right\|_2^2 \end{aligned} 
                                                                                                                                                                                                                                                                                                                                                                                     ▷ Algorithm 1, Line 5
25:
26:
27:
                           \sigma^{\star} \leftarrow \sigma + \|x_N\|_2^2 + \|u_N\|_2^2
28:
                           \sigma^\star \leftarrow \sqrt{\sigma^\star}
29:
30:
                           if |\sigma^{\star} - \sigma| \leq \epsilon_{abs} + \epsilon_{rel} \max{\{\sigma^{\star}, \sigma\}} then

⊳ stopping criterion

31:
                                        break
32:
                            else if j < j_{\text{max}} then
33:
                                       \sigma \leftarrow \sigma
                            end if
34:
35: end for
36: \sigma \leftarrow (1 + \epsilon_{\text{buff}}) \sigma^*
                                                                                                                                                                                                                                                                                     ▷ buffer the estimated maximum singular value
                                                                                                                                                                                                                                                                                                     \triangleright \approx \max \operatorname{spec} \hat{H}^{\top} \hat{H} = \sigma_{\max} (\hat{H}^{\top} \hat{H}) = \|\hat{H}\|_{2}^{2}
Return: \sigma
```

Algorithm 3 PIPG

```
Inputs: q, H, h, \mathbb{D}, \mathbb{K}^{\circ}, \bar{z}, \lambda, \sigma, \rho, \epsilon_{\text{abs}}, \epsilon_{\text{rel}}, j_{\text{check}}, j_{\text{max}},
                                                                                                                                                                                                                                                                                                        ⊳ warm start
  \begin{array}{l} 1: \ \zeta^1 \leftarrow z^\star \\ 2: \ \eta^1 \leftarrow w^\star \end{array}
                                                                                                                                                                                                                                                                   ⊳ initialize primal variable
                                                                                                                                                                                                                                                                         \trianglerightinitialize dual variable
  3: \alpha \leftarrow \frac{2}{\lambda + \sqrt{\lambda^2 + 4\omega\sigma}}
4: \beta \leftarrow \omega\alpha

⊳ step-sizes

   5: for j \leftarrow 1:j_{\text{max}} do
                  \begin{split} z^{j+1} &= \pi_{\mathbb{D}}[\zeta^{j} - \alpha \left(\lambda \, \zeta^{j} + q + H^{\top} \eta^{j}\right) + \bar{z}] - \bar{z} \\ w^{j+1} &= \pi_{\mathbb{K}^{\circ}}[\eta^{j} + \beta \left(H(2 \, z^{j+1} - \zeta^{j}) - h\right)] \\ \zeta^{j+1} &= (1 - \rho) \, \zeta^{j} + \rho \, z^{j+1} \\ \eta^{j+1} &= (1 - \rho) \, \eta^{j} + \rho \, w^{j+1} \end{split}
                                                                                                                                                                                                                                                                      \triangleright projected gradient step
  7:
                                                                                                                                                                                              \triangleright PI feedback of affine equality constraint violation
  8:
                                                                                                                                                                                                                                                           \trianglerightextrapolate primal variable
  9:
                                                                                                                                                                                                                                                                 \triangleright extrapolate dual variable
                   if j \mod j_{\text{check}} = 0 then
                                                                                                                                                                                                      \triangleright check stopping criterion every j_{\text{check}} iterations
10:
                            \begin{aligned} & \text{if } \left\| z^{j+1} - z^{j} \right\|_{\infty} \leq \epsilon_{\text{abs}} + \epsilon_{\text{rel}} \, \max \left\{ \left\| z^{j+1} \right\|_{\infty}, \, \left\| z^{j} \right\|_{\infty} \right\} \, \text{and} \\ & \left\| w^{j+1} - w^{j} \right\|_{\infty} \leq \epsilon_{\text{abs}} + \epsilon_{\text{rel}} \, \max \left\{ \left\| w^{j+1} \right\|_{\infty}, \, \left\| w^{j} \right\|_{\infty} \right\} \, \text{then} \end{aligned}
11:
                                                                                                                                                                                                                                                                                     \triangleright stopping criterion
12:
13:
                             end if
14:
                   end if
15:
16: end for
17: z^{\star} \leftarrow z^{j+1}
                                                                                                                                                                                                                                                                       ▷ update primal variable
18: w^{\star} \leftarrow w^{j+1}
                                                                                                                                                                                                                                                                             ▷ update dual variable
Return: z^{\star}, w^{\star}
```

Algorithm 4 PIPG_{custom}

```
Inputs: q_{x_{[1:N]}}, q_{u_{[1:N]}}, q_{\phi_{[1:N-1]}}, q_{\psi_{[1:N-1]}},
                                        \hat{A}_{[1:N-1]}^{-},\,\hat{A}_{[1:N-1]}^{+},\,\hat{B}_{[1:N-1]}^{-},\,\hat{B}_{[1:N-1]}^{+},\,\hat{d}_{[2:N]},\,\hat{\bar{x}}_{[1:N]},\,\hat{\bar{u}}_{[1:N]},
                                        \hat{\mathbb{D}}_{x_{[1:N]}},\,\hat{\mathbb{D}}_{u_{[1:N]}},\,\mathbb{D}_{\phi_{[1:N-1]}},\,\mathbb{D}_{\psi_{[1:N-1]}},\,\varepsilon,
                                       \begin{array}{l} \lambda, \sigma, \omega, \rho, \epsilon_{\rm abs}, \epsilon_{\rm rel}, j_{\rm check}, j_{\rm max}, \\ \Delta \hat{x}^{\star}_{[1:N]}, \Delta \hat{u}^{\star}_{[1:N]}, \phi^{\star}_{[1:N-1]}, \psi^{\star}_{[1:N-1]}, w^{\star}_{[1:N-1]}, v^{\star}_{[1:N-1]} \end{array}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    \triangleright warm start
    1: \ \Delta x^1_{\zeta_{[1:N]}} \leftarrow \Delta \hat{x}^\star_{[1:N]}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    ▷ initialize primal variables
    2: \Delta u_{\zeta_{[1:N]}}^{1} \leftarrow \Delta \hat{u}_{[1:N]}^{\star}
   3: \phi^1_{\zeta_{[1:N-1]}} \leftarrow \phi^{\star}_{[1:N-1]}
   4: \psi_{\zeta_{[1:N-1]}}^{1} \leftarrow \psi_{[1:N-1]}^{\star}
   5: \eta^1_{[1:N-1]} \leftarrow w^{\star}_{[1:N-1]}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              ▷ initialize dual variables
   6: \gamma^1_{[1:N-1]} \leftarrow v^{\star}_{[1:N-1]}
   7: \alpha \leftarrow \frac{2}{\lambda + \sqrt{\lambda^2 + 4\omega\sigma}}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           9: for j \leftarrow 1: j_{\text{max}} do
                                 \Delta \hat{x}_{1}^{j} \leftarrow \pi_{\hat{\mathbb{D}}_{x_{1}}} [\Delta x_{\zeta_{1}}^{j} - \alpha \left(\lambda \, \Delta x_{\zeta_{1}}^{j} + q_{x_{1}} + \hat{A}_{1}^{-\top} \eta_{1}^{j} - \tilde{\gamma}_{1}^{j}\right) + \hat{\overline{x}}_{1}^{j}] - \hat{\overline{x}}_{1}^{j}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              \triangleright \tilde{\gamma}_k := [0_{1 \times (n_x - 1)}, \gamma_k]^\top
10:
                                 \Delta \hat{u}_1^j \leftarrow \pi_{\hat{\mathbb{D}}_{u_1}}[\Delta u_{\zeta_1}^j - \alpha \left(\lambda \, \Delta u_{\zeta_1}^j + q_{u_1} + \hat{\boldsymbol{B}}_1^{-\top} \eta_1^j\right) + \hat{\boldsymbol{x}}_1^j] - \hat{\boldsymbol{x}}_1^j
11:
                                 for k \leftarrow 2: N-1 do
12:
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             ▷ projected gradient step
                                                \Delta \hat{x}_{k}^{j+1} \leftarrow \pi_{\hat{\mathbb{D}}_{T_{k}}} \left[ \Delta x_{\zeta_{k}}^{j} - \alpha \left( \lambda \Delta x_{\zeta_{k}}^{j} + q_{x_{k}} + \hat{A}_{k}^{-\top} \eta_{k}^{j} + \hat{A}_{k-1}^{+\top} \eta_{k-1}^{j} - \tilde{\gamma}_{k}^{j} + \tilde{\gamma}_{k-1}^{j} \right) + \hat{\bar{x}}_{k}^{j} \right] - \hat{\bar{x}}_{k}^{j}
13:
                                               \Delta \hat{u}_{k}^{j+1} \leftarrow \pi_{\hat{\mathbb{D}}_{k+1}} \left[ \Delta u_{\zeta_{k}}^{j} - \alpha \left( \lambda \Delta u_{\zeta_{k}}^{j} + q_{u_{k}} + \hat{B}_{k}^{-\top} \eta_{k}^{j} + \hat{B}_{k-1}^{+\top} \eta_{k-1}^{j} \right) + \hat{\overline{u}}_{k}^{j} \right] - \hat{\overline{u}}_{k}^{j}
14:
15:
                                 end for
                                \Delta \hat{x}_N^{j+1} \leftarrow \pi_{\hat{\mathbb{D}}_{x_N}} [\Delta x_{\zeta_N}^j - \alpha \left(\lambda \, \Delta x_{\zeta_N}^j + q_{x_N} + \hat{A}_{N-1}^{+\intercal} \eta_{N-1}^j + \hat{\gamma}_{N-1}^j \right) + \hat{\overline{x}}_N^j] - \hat{\overline{x}}_N^j
16:
                                \Delta \hat{u}_{N}^{j+1} \leftarrow \pi_{\hat{\mathbb{D}}_{NN}} [\Delta u_{\zeta_{N}}^{j} - \alpha \left(\lambda \Delta u_{\zeta_{N}}^{j} + q_{u_{N}} + \hat{B}_{N-1}^{+\top} \eta_{N-1}^{j}\right) + \hat{\overline{u}}_{N}^{j}] - \hat{\overline{u}}_{N}^{j}
17:
                                \phi_{[1:N-1]}^{j} \leftarrow \pi_{\mathbb{D}_{\phi_{[1:N-1]}}} [\phi_{\zeta_{[1:N-1]}}^{j} - \alpha \left( q_{\phi_{[1:N-1]}} + \eta_{[1:N-1]}^{j} \right)]
18:
                                \psi_{[1:N-1]}^{j} \leftarrow \pi_{\mathbb{D}_{\psi_{[1:N-1]}}} [\psi_{\zeta_{[1:N-1]}}^{j} - \alpha \left( q_{\psi_{[1:N-1]}} - \eta_{[1:N-1]}^{j} \right)]
19:
                                 for k \leftarrow 1: N-1 do
                                                                                                                                                                                                                                                                                                                                                                       ▷ PI feedback of affine equality constraint violation
20:
                                               w_{k}^{j+1} \leftarrow \eta_{k}^{j} + \beta \left( \hat{A}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta x_{\zeta_{k}}^{j} \right) + \hat{A}_{k}^{+} \left( 2\Delta \hat{x}_{k+1}^{j+1} - \Delta x_{\zeta_{k+1}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{+} \left( 2\Delta \hat{x}_{k+1}^{j+1} - \Delta u_{\zeta_{k+1}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{+} \left( 2\Delta \hat{x}_{k+1}^{j+1} - \Delta u_{\zeta_{k+1}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j+1} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat{x}_{k}^{j} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{+} \left( 2\Delta \hat{x}_{k}^{j} - \Delta u_{\zeta_{k}}^{j} \right) + \hat{B}_{k}^{-} \left( 2\Delta \hat
21:
                                                                                                                          +(2\phi_k^{j+1}-\phi_{\zeta_k}^j)-(2\psi_k^{j+1}-\psi_{\zeta_k}^j)+\hat{d}_{k+1})
22:
                                                v_k^{j+1} \leftarrow \max\{0,\, \gamma_k^j + \beta \, ((2\Delta \hat{y}_{k+1}^{j+1} - \Delta y_{\zeta_{k+1}}^j) - (2\Delta \hat{y}_k^{j+1} - \Delta y_{\zeta_k}^j) + (\hat{\overline{y}}_{k+1} - \hat{\overline{y}}_k) - \varepsilon)\}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                  \triangleright \Box \hat{y}_k := [0_{1 \times (n_x - 1)}, 1] \Box \hat{x}_k
23:
24:
                                 end for
                                 \begin{split} & \Delta x_{\zeta_{[1:N]}}^{j+1} \leftarrow (1-\rho) \, \Delta x_{\zeta_{[1:N]}}^{j} + \rho \, \Delta \hat{x}_{[1:N]}^{j+1} \\ & \Delta u_{\zeta_{[1:N]}}^{j+1} \leftarrow (1-\rho) \, \Delta u_{\zeta_{[1:N]}}^{j} + \rho \, \Delta \hat{u}_{[1:N]}^{j+1} \end{split}
25:
                                                                                                                                                                                                                                                                                                                                                                                                                                                                      26:
                                27:
28:
                                 \eta_{[1:N-1]}^{j+1} \leftarrow (1-\rho) \, \eta_{[1:N-1]}^{j} + \rho \, w_{[1:N-1]}^{j+1}
29:
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                \gamma_{[1:N-1]}^{j+1} \leftarrow (1-\rho) \gamma_{[1:N-1]}^{j} + \rho v_{[1:N-1]}^{j+1}
30:
                                 if j \mod j_{\text{check}} = 0 then
31:
                                                                                                                                                                                                                                                                                                                                                                                    \triangleright check stopping criterion every j_{\text{check}} iterations
                                                \text{Terminate} \leftarrow \text{Stopping}_{\text{custom}}(\Delta \hat{x}_{[1:N]}^{j+1}, \Delta \hat{u}_{[1:N]}^{j+1}, \phi_{[1:N-1]}^{j+1}, \psi_{[1:N-1]}^{j+1}, w_{[1:N-1]}^{j+1}, v_{[1:N-1]}^{j+1}, v_{[1:N-1]}^{j+1}, w_{[1:N-1]}^{j+1}, w_{[
32:
                                                                                                                                                                                           \Delta \hat{x}^{j}_{[1:N]}, \, \Delta \hat{u}^{j}_{[1:N]}, \, \phi^{j}_{[1:N-1]}, \, \psi^{j}_{[1:N-1]}, \, w^{j}_{[1:N-1]}, \, v^{j}_{[1:N-1]}, \, \epsilon_{\mathrm{abs}}, \, \epsilon_{\mathrm{rel}})
33:
                                                 if terminate = true then
34:

⊳ stopping criterion

35:
                                                                break
                                                 end if
36:
37:
                                 end if
38: end for
39: \Delta \hat{x}_{[1:N]}^{\star} \leftarrow \Delta \hat{x}_{[1:N]}^{j+1}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           ▶ update primal variables
40: \Delta \hat{u}_{[1:N]}^{\star} \leftarrow \Delta \hat{u}_{[1:N]}^{j+1}
41: \phi_{[1:N-1]}^{\star} \leftarrow \phi_{[1:N-1]}^{j+1}
42: \psi_{[1:N-1]}^{\star} \leftarrow \psi_{[1:N-1]}^{j+1}
43: w_{[1:N-1]}^{\star} \leftarrow w_{[1:N-1]}^{j+1}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    \triangleright update dual variables
44: v_{[1:N-1]}^{\star} \leftarrow v_{[1:N-1]}^{j+1}
Return: \Delta x_{[1:N]}^{\star}, \Delta u_{[1:N]}^{\star}, \phi_{[1:N-1]}^{\star}, \psi_{[1:N-1]}^{\star}, w_{[1:N-1]}^{\star}, v_{[1:N-1]}^{\star}
```

Algorithm 5 Customized stopping criterion evaluation:

$$\begin{split} \text{STOPPING}_{\text{custom}}(\Delta \hat{x}_{[1:N]}^{j+1}, \, \Delta \hat{u}_{[1:N]}^{j+1}, \, \phi_{[1:N-1]}^{j+1}, \, \psi_{[1:N-1]}^{j+1}, \, w_{[1:N-1]}^{j+1}, \, v_{[1:N-1]}^{j+1} \\ \Delta \hat{x}_{[1:N]}^{j}, \, \Delta \hat{u}_{[1:N]}^{j}, \, \phi_{[1:N-1]}^{j}, \, \psi_{[1:N-1]}^{j}, \, w_{[1:N-1]}^{j}, \, v_{[1:N-1]}^{j}, \, \epsilon_{\text{abs}}, \, \epsilon_{\text{rel}}) \end{split}$$

Inputs:
$$\Delta \hat{x}_{[1:N]}^{j+1}$$
, $\Delta \hat{u}_{[1:N]}^{j+1}$, $\phi_{[1:N-1]}^{j+1}$, $\psi_{[1:N-1]}^{j+1}$, $w_{[1:N-1]}^{j+1}$, $\Delta \hat{x}_{[1:N]}^{j}$, $\Delta \hat{u}_{[1:N]}^{j}$, $\phi_{[1:N-1]}^{j}$, $\psi_{[1:N-1]}^{j}$, $w_{[1:N-1]}^{j}$, ϵ_{abs} , ϵ_{rel}

$$\begin{split} &1:\ z_{\infty}^{j+1} \leftarrow \max \left\{ \|\Delta \hat{x}_{[1:N]}^{j+1}\|_{\infty},\, \|\Delta \hat{u}_{[1:N]}^{j+1}\|_{\infty},\, \|\phi_{[1:N-1]}^{j+1}\|_{\infty},\, \|\psi_{[1:N-1]}^{j+1}\|_{\infty} \right\} \\ &2:\ z_{\infty}^{j} \quad \leftarrow \max \left\{ \|\Delta \hat{x}_{[1:N]}^{j}\|_{\infty},\, \|\Delta \hat{u}_{[1:N]}^{j}\|_{\infty},\, \|\phi_{[1:N-1]}^{j}\|_{\infty},\, \|\psi_{[1:N-1]}^{j}\|_{\infty} \right\} \\ &3:\ z_{\infty}^{\Delta j} \quad \leftarrow \max \left\{ \|\Delta \hat{x}_{[1:N]}^{j+1} - \Delta \hat{x}_{[1:N]}^{j}\|_{\infty},\, \|\Delta \hat{u}_{[1:N]}^{j+1} - \Delta \hat{u}_{[1:N]}^{j}\|_{\infty},\, \|\phi_{[1:N-1]}^{j+1} - \phi_{[1:N-1]}^{j}\|_{\infty},\, \|\psi_{[1:N-1]}^{j+1} - \psi_{[1:N-1]}^{j}\|_{\infty} \right\} \end{split}$$

$$\begin{aligned} &4\colon\,r_{\infty}^{j+1}\leftarrow\max\biggl\{\|w_{[1:N-1]}^{j+1}\|_{\infty},\,\|v_{[1:N-1]}^{j+1}\|_{\infty}\biggr\}\\ &5\colon\,r_{\infty}^{j}\quad\leftarrow\max\biggl\{\|w_{[1:N-1]}^{j}\|_{\infty},\,\|v_{[1:N-1]}^{j}\|_{\infty}\biggr\} \end{aligned}$$

6:
$$r_{\infty}^{\Delta j} \leftarrow \max \left\{ \|w_{[1:N-1]}^{j+1} - w_{[1:N-1]}^{j}\|_{\infty}, \|v_{[1:N-1]}^{j+1} - v_{[1:N-1]}^{j}\|_{\infty} \right\}$$

7: if
$$z_{\infty}^{\Delta j} \leq \epsilon_{\mathrm{abs}} + \epsilon_{\mathrm{rel}} \max \left\{ z_{\infty}^{j+1}, z_{\infty}^{j} \right\}$$
 and $r_{\infty}^{\Delta j} \leq \epsilon_{\mathrm{abs}} + \epsilon_{\mathrm{rel}} \max \left\{ r_{\infty}^{j+1}, r_{\infty}^{j} \right\}$ then

8: TERMINATE \leftarrow TRUE

9: else

10: TERMINATE \leftarrow FALSE

11: **end if**

Return: TERMINATE