[Deep Learning Using PyTorch] [cheatsheet]

Tensor Creation and Manipulation

- Create a tensor from a list: tensor = torch.tensor([1, 2, 3])
- Create a tensor of zeros: tensor = torch.zeros(shape)
- Create a tensor of ones: tensor = torch.ones(shape)
- Create α tensor with random values: tensor = torch.rand(shape)
- Create a tensor with normally distributed random values: tensor = torch.randn(shape)
- Create a tensor with a range of values: tensor = torch.arange(start, end, step)
- Create α tensor with evenly spaced values: tensor = torch.linspace(start, end, steps)
- Reshape a tensor: tensor = tensor.view(new_shape)
- Transpose a tensor: tensor = tensor.transpose(dim1, dim2)
- Flαtten α tensor: tensor = tensor.flatten()
- Concαtenate tensors along a dimension: tensor = torch.cat([tensor1, tensor2], dim)
- Stack tensors along a new dimension: tensor = torch.stack([tensor1, tensor2], dim)
- Squeeze α tensor (remove dimensions of size 1): tensor = tensor.squeeze()
- Unsqueeze a tensor (add a dimension of size 1): tensor = tensor.unsqueeze(dim)
- Permute the dimensions of a tensor: tensor = tensor.permute(dims)

Tensor Operations

- Addition: result = tensor1 + tensor2
- Subtraction: result = tensor1 tensor2
- Multiplication (element-wise): result = tensor1 * tensor2
- Division (element-wise): result = tensor1 / tensor2
- Matrix multiplication: result = tensor1.matmul(tensor2)
- Exponential: result = torch.exp(tensor)
- Logarithm: result = torch.log(tensor)
- Square root: result = torch.sqrt(tensor)
- Sine: result = torch.sin(tensor)
- Cosine: result = torch.cos(tensor)

- Tangent: result = torch.tan(tensor)
- Sigmoid: result = torch.sigmoid(tensor)
- ReLU: result = torch.relu(tensor)
- Tanh: result = torch.tanh(tensor)
- Softmax: result = torch.softmax(tensor, dim)

Neural Network Layers

- Lineαr layer: layer = nn.Linear(in_features, out_features)
- Convolutional layer: layer = nn.Conv2d(in_channels, out_channels, kernel_size, stride, padding)
- Transposed convolutional layer: layer = nn.ConvTranspose2d(in_channels, out_channels, kernel_size, stride, padding)
- Max pooling layer: layer = nn.MaxPool2d(kernel_size, stride, padding)
- Average pooling layer: layer = nn.AvgPool2d(kernel_size, stride, padding)
- Batch normalization layer: layer = nn.BatchNorm2d(num_features)
- Dropout layer: layer = nn.Dropout(p)
- Recurrent layer (RNN): layer = nn.RNN(input_size, hidden_size, num_layers)
- Long Short-Term Memory lαyer (LSTM): layer = nn.LSTM(input_size, hidden_size, num_layers)
- Gated Recurrent Unit layer (GRU): layer = nn.GRU(input_size, hidden_size, num_layers)
- Embedding layer: layer = nn.Embedding(num_embeddings, embedding_dim)

Loss Functions

- Mean Squared Error (MSE) loss: loss_fn = nn.MSELoss()
- Cross-Entropy loss: loss_fn = nn.CrossEntropyLoss()
- Binary Cross-Entropy loss: loss_fn = nn.BCELoss()
- Negative Log-Likelihood loss: loss_fn = nn.NLLLoss()
- Kullback-Leibler Divergence loss: loss_fn = nn.KLDivLoss()
- Margin Ranking loss: loss_fn = nn.MarginRankingLoss()
- Triplet Margin loss: loss_fn = nn.TripletMarginLoss()
- Cosine Embedding loss: loss_fn = nn.CosineEmbeddingLoss()
- Hinge Embedding loss: loss_fn = nn.HingeEmbeddingLoss()

Optimization Algorithms

- Stochastic Gradient Descent (SGD): optimizer = torch.optim.SGD(model.parameters(), lr)
- Adam: optimizer = torch.optim.Adam(model.parameters(), lr)
- RMSprop: optimizer = torch.optim.RMSprop(model.parameters(), lr)
- Adagrad: optimizer = torch.optim.Adagrad(model.parameters(), lr)
- Adadelta: optimizer = torch.optim.Adadelta(model.parameters(), lr)
- Adamax: optimizer = torch.optim.Adamax(model.parameters(), lr)
- Sparse Adam: optimizer = torch.optim.SparseAdam(model.parameters(), lr)
- LBFGS: optimizer = torch.optim.LBFGS(model.parameters(), lr)

Learning Rate Schedulers

- Step LR: scheduler = torch.optim.lr_scheduler.StepLR(optimizer, step_size, gamma)
- Multi-Step LR: scheduler = torch.optim.lr_scheduler.MultiStepLR(optimizer, milestones, gamma)
- Exponential LR: scheduler = torch.optim.lr_scheduler.ExponentialLR(optimizer, gamma)
- Cosine Annealing LR: scheduler = torch.optim.lr_scheduler.CosineAnnealingLR(optimizer, T_max)
- Reduce LR on Plateau: scheduler = torch.optim.lr_scheduler.ReduceLROnPlateau(optimizer, mode, factor, patience)
- Cyclic LR: scheduler = torch.optim.lr_scheduler.CyclicLR(optimizer, base_lr, max_lr, step_size_up)

Model Training and Evaluation

- Move model to device: model = model.to(device)
- Set model to training mode: model.train()
- Set model to evaluation mode: model.eval()
- Forward pass: outputs = model(inputs)
- Compute loss: loss = loss_fn(outputs, targets)
- Backward pass: loss.backward()
- Update model parameters: optimizer.step()
- Zero gradients: optimizer.zero_grad()
- Get model parameters: parameters = model.parameters()
- Get model state dictionary: state_dict = model.state_dict()
- Load model state dictionary: model.load_state_dict(state_dict)
- Save model checkpoint: torch.save(model.state_dict(), 'checkpoint.pth')

• Load model checkpoint: model.load_state_dict(torch.load('checkpoint.pth'))

Data Loading and Processing

- Create α dataset: dataset = torch.utils.data.TensorDataset(inputs, targets)
- Create α data loader: data_loader = torch.utils.data.DataLoader(dataset, batch_size, shuffle)
- Iterate over data loader: for batch in data_loader: inputs, targets =
- Normαlize dαtα: data = (data data.mean()) / data.std()
- Resize images: images = torch.nn.functional.interpolate(images, size)
- Random crop images: images = torchvision.transforms.RandomCrop(size)(images)
- Random horizontal flip images: images = torchvision.transforms.RandomHorizontalFlip()(images)
- Convert images to tensors: images = torchvision.transforms.ToTensor()(images)
- Normalize images: images = torchvision.transforms.Normalize(mean, std)(images)

Pretrained Models

- Load a pretrained model: model = torchvision.models.resnet18(pretrained=True)
- Freeze model weights: for param in model.parameters(): param.requires_grad = False
- Replace the last layer of a pretrained model: model.fc = nn.Linear(512, num_classes)
- Extract features from a pretrained model: features = model(inputs)

Model Evaluation Metrics

- Accuracy: accuracy = (predicted == targets).float().mean()
- Precision: precision = torch.sum(predicted * targets) / torch.sum(predicted)
- Recall: recall = torch.sum(predicted * targets) / torch.sum(targets)
- F1 score: f1_score = 2 * (precision * recall) / (precision + recall)
- Mean Absolute Error (MAE): mae = torch.abs(predicted targets).mean()

- Mean Squared Error (MSE): mse = torch.square(predicted targets).mean()
- Root Mean Squared Error (RMSE): rmse = torch.sqrt(mse)
- Intersection over Union (IoU): iou = torch.sum(predicted * targets) / torch.sum((predicted + targets) > 0)
- Area Under the ROC Curve (AUC): auc = torchmetrics.functional.auroc(predicted, targets)
- Average Precision (AP): ap = torchmetrics.functional.average_precision(predicted, targets)
- Confusion Matrix: cm = torchmetrics.functional.confusion_matrix(predicted, targets)

Model Visualization

- Visualize the model architecture: print(model)
- Visualize the model graph: torchviz.make_dot(outputs, params=dict(model.named_parameters())).render('model_graph', format='png')
- Visualize the model summary: torchsummary.summary(model, input_size)

Transfer Learning

- Freeze the weights of the feature extractor: for param in model.features.parameters(): param.requires_grad = False
- Fine-tune the last layer: for param in model.classifier.parameters(): param.requires_grad = True
- Load a pretrained model and replace the last layer: model = torchvision.models.resnet18(pretrained=True); model.fc = nn.Linear(512, num_classes)

Adversarial Attacks

- Fast Gradient Sign Method (FGSM) attack: perturbed_inputs = inputs + epsilon * torch.sign(inputs.grad)
- Projected Gradient Descent (PGD) attack: for _ in range(num_steps): perturbed_inputs = torch.clamp(perturbed_inputs + alpha * torch.sign(perturbed_inputs.grad), min=inputs-epsilon, max=inputs+epsilon)
- Carlini & Wagner (C&W) attack: adversarial_inputs = torch.clamp(inputs + perturbations, min=0, max=1)

Model Pruning

- Prune model weights: pruned_model = torch.nn.utils.prune.random_unstructured(model, name='weight', amount=pruning_ratio)
- Prune model biases: pruned_model = torch.nn.utils.prune.l1_unstructured(model, name='bias', amount=pruning_ratio)
- Prune model layers: pruned_model = torch.nn.utils.prune.ln_structured(model, name='conv', amount=pruning_ratio, n=2, dim=0)

Model Quantization

- Quantize model weights: quantized_model = torch.quantization.quantize_dynamic(model, {torch.nn.Linear}, dtype=torch.gint8)
- Quantize model activations: quantized_model = torch.quantization.quantize_dynamic(model, {torch.nn.ReLU}, dtype=torch.quint8)
- Convert model to quantized version: quantized_model = torch.guantization.convert(model)

Distributed Training

- Initialize distributed training:
 - torch.distributed.init_process_group(backend='nccl', init_method='tcp://localhost:23456', rank=args.rank, world_size=args.world_size)
- Wrap model with DistributedDataParallel: model = torch.nn.parallel.DistributedDataParallel(model, device_ids=[args.local_rank])
- Synchronize gradients across devices: torch.distributed.barrier()
- Reduce gradients across devices: torch.distributed.all_reduce(tensor, op=torch.distributed.ReduceOp.SUM)

Model Interpretability

• Compute gradients w.r.t. inputs: gradients = torch.autograd.grad(outputs, inputs, grad_outputs=torch.ones_like(outputs))

- Compute saliency maps: saliency_maps = torch.abs(gradients).max(dim=1, keepdim=True)[0]
- Compute guided backpropagation: guided_backprop = torch.clamp(gradients, min=0)
- Compute class activation maps (CAM): cam = torch.sum(features * weights.view(num_classes, -1), dim=1).view(batch_size, -1)
- Compute Grαd-CAM: grad_cam = torch.sum(features * gradients.view(batch_size, num_channels, -1), dim=2).view(batch_size, num_channels, 1, 1)

Model Debugging

- Print model gradients: for name, param in model.named_parameters(): if param.requires_grad: print(name, param.grad)
- Print model activations: for name, module in model.named_modules(): if isinstance(module, nn.ReLU): module.register_forward_hook(lambda module, input, output: print(name, output))
- Print model parameters: for name, param in model.named_parameters(): print(name, param)
- Print model buffers: for name, buffer in model.named_buffers(): print(name, buffer)
- Set anomaly detection for debugging: torch.autograd.set_detect_anomaly(True)