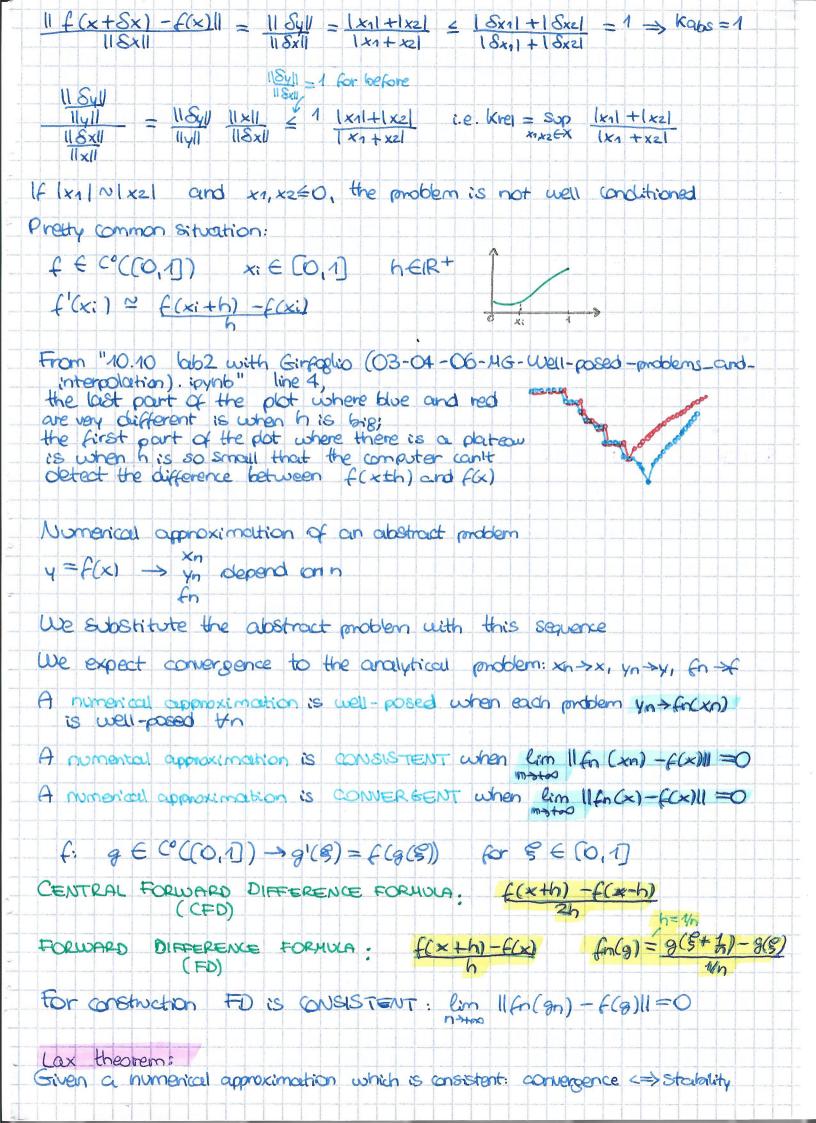
```
ABSTRACT PROBLEMS X input space, Y output space, x \in X, y \in Y, y = f(x):
   1) \forall x \in \mathbb{X} \quad \exists y \in \mathbb{Y} \quad | \quad y = f(x)
   2) 3! y
   3) \forall perturbation 8x \in X \mid x + 8x \in X
                                                                                                                                                                                                                                                                   ABSOUTE
            I constant Kabs: 11 Sylly & Kabs 11 Sxlly STABILITY
  31) \( \times \in \times \) \( 
                                                                                                                                                                                                                                                                                         RELATIVE
          3 constant Knel: 11 Sylly 2 Knel 11 Sxllx
                                                                                                                                                                                                                                                                                      STABILITY
                                                                                                                         llylly
                                                                                                                                                                                                              11 x11y
    If it satisfies 1,2,3, it's a well posed molder in absolute terms
    If it also satisfies 3', it's a well posed problem in relative terms
                                                                                                                                                                                                                                                                                                                                               10/10
              * Well Posed Problems
   Based on y = f(x): || Sy(1) = || y + Sy - y|| = || f(x + Sx) - f(x)||
For absolute stability: II f (x+Sx) - f(x) 11, 4 Kabs 11 Sx 11,
       => 11 f(x+8x) - f(x)11 = f'(x) < kabs i.e. Kabs = Sup sup 11 f(x+8x) + f(x)11
Analogue for the relative stability but with normalization (: 11411 : 11X11)
  Example:

x \in X = (R^2 \times 1, x_2)  y = x_1 + x_2 \in Y = |R|
   Sx = (Sx_1, Sx_2) \in X Sy = Sx_1 + Sx_2
  11 f(x+8x)-f(x)11 = 11 8y11 = 11 8x1 + 8x211
   11 x 11 = 1 x 1 = 1 x 1 + 1 x 2 1
  le-norms = ( \( \times | \time
                                                                                                                                     For \rho = 1: ||y||_{V} = |y|
```



```
Compute the relacity of consistency (i.e. of the error):
                                                                                                                                                                                           Taylor
 (1 fn (g) - f (g) | = (1 g (g + f) - g (g) - g (g) | = (1 [g (g + f) - g (g)] n - g (g) | =
= \| \left( g(\xi) + g'(\xi)h + g''(\xi)h^2 + \sum_{k=3}^{8} g''(\xi)h^k - g(\xi) \right) n - g'(\xi) \| = h^{\frac{1}{2}} 
= | | g'(3) + g'(5) h + \(\frac{5}{4}\) \(\fra
  = \| \underbrace{\$}_{k_1} \underbrace{\$}_{k_1} (\$) h^{k-1} \| = \| \underbrace{\$}_{k_1} (\$) \underbrace{1}_{k_2} + O(\underbrace{1}_{h^2}) \|
                                                      TRONCATION ERROR
   Order of accuracy: 1 -> order 1
  Analogously (16n(g)-6(g)11=(19(8+4)-g(8-4n)-g'(8))1. In this case
 the transation error is better because it is of order 1/n2 => order 2.
 Consider A: IRM > IRM linear operation, it's a mount and we can use the
   p-norms previously defined in this operational norm
  In this case we have 11 All = 11 Allo 11 Axlo & 11 Allo 11 xlo
                                                                                  11 Allp = sop 11 1 xllp
  Example;
n=m X=Y=IRn y=Ax A E IRnxn
 We want to verify if the problem y= Ax is well posed or not, that is if
     3 Kabs | YXEX, Y SXEX: X + SX EX
                                \Rightarrow 11 f(x + Sx) - f(x) ||_{P} \leq kabs
                                 f(x+\delta x) = A(x+\delta x) = Ax + A\delta x
   f(x)=Ax
  => (IAX + ASX -AXI)e = (IA SXI)e = (IAI)e | I SXIIe
                                                                                                                                              = IAIIp = Kabs
                    11 Syl 11 x11 = 11 Alp 11 x11p
In some conditions it's possible to define also the inverse function
 f_y = f(x) but if y = f(x) is well posed, it is not true in general that f(x) = f(y) is again well posed
```

Now assume that in our case this operation is invertible, then new thing 11 Syll 11x1 2 (1Alip 11x1) 2 11Alip (1A-1/1p light = 11Alip 11A-1/1p = Krei 11 Ul 118x11 11 11 11 11 11 Kabs = 11 Allp So we need our mouthix A to be invertible and the product small enough (Krel = 11 Alle 11 A-11p