



$$M = \{I, 0, S, S_0, \delta, \lambda\}$$

$$I = \phi$$

(No Input; rst & clk are directly fed to D-Flipflops)

$$O = \{00, 01, 10, 11\} \quad (\text{count is the output})$$

$$S = \{0, 1, 2, 3\} \quad \# \text{states} = 4 \rightarrow \# \text{state variables} = 2$$

$$S_0 = 0$$

	$x_1$	$x_0$
0	0	0
1	0	1
2	1	0
3	1	1

Transition and Output Table

$x_1$	$x_0$	$t_1$	$t_0$	count <sub>1</sub>	count <sub>0</sub>
0	0	0	1	0	0
0	1	1	0	0	1
1	0	1	1	1	0
1	1	0	0	1	1

Very clearly,

$$\lambda_1(x_1, x_0) = x_1$$

$$\lambda_0(x_1, x_0) = x_0$$

( $t_1$ )

$x_0$	$x_1$	0	1
0	0	0	1
1	1	1	0

$$\delta_1(x_1, x_0) = x_1 \cdot \bar{x}_0 + \bar{x}_1 \cdot x_0 = x_1 \oplus x_0$$

( $t_0$ )

$x_0$	$x_1$	0	1
0	1	1	1
1	0	0	0

$$\delta_0(x_1, x_0) = \bar{x}_0$$

