

Command

Gimbal Velocity 1 0.00

Gimbal Velocity 2 0.00

Gimbal Velocity 3 0.00

Gimbal Velocity 4 0.00

RW Velocity 1 0.00

RW Velocity 2 0.00

RW Velocity 3 0.00

RW Velocity 4 0.00

Reset

Telemetry

Calibration

Quaternions

q 0 -0.03 q 1 -0.23 q 2 0.97 q 3 0.00

Euler Angles

Roll 178.80 Pitch 2.72 Yaw -26.80

Gimbal Angle

Delta 1 51.00

Delta 2 18.00

Delta 3 21.00

Delta 4 -46.00

Reaction Wheel Velocity

Omega 1 0.00

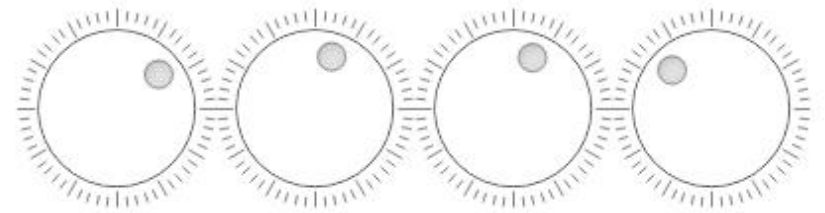
Omega 2 0.00

Omega 3 0.00

Omega 4 0.00

Body Rates

omega x 0.00 omega y 0.00 omega z 0.00



Control Mode

☐ Manual ☒ VSCMG Steering ☐ Neural Network ☐ None

Controller Gain

Kq 0.0000

Kw 0.1000

