

86강 특잇값분해를 이용한 손실 이미지 압축 시뮬레이션 (SVD)

* 고유값 분해 : 정사각행렬, 대칭행렬

$A: m \times n$

$$A = \underbrace{U}_{m \times m} \underbrace{\Sigma}_{m \times n} \underbrace{V^T}_{n \times n}$$

↗ basis 변환

$$A^T A = V D V^T$$

* 축소된 특잇값분해

$$k = \text{rank}(A) = \text{rank}(A^T A) = \text{rank}(b)$$

$\lambda_1 \sim \lambda_k$ $\sqrt{\lambda_1} \sim \sqrt{\lambda_k}$ $v_1 \sim v_k$: 정규 직교화된 상태.

$$U = [u_1, u_2, \dots, u_k, \underbrace{u_{k+1}, \dots, u_m}_{\text{0 벡터}}] \quad u_i = \frac{1}{\sqrt{\lambda_i}} A v_i \quad i > k \Rightarrow \text{0 벡터}$$

$$\begin{aligned} A &= U \Sigma V^T = \begin{bmatrix} u_1 & u_2 & \dots & u_k & u_{k+1} & \dots & u_m \end{bmatrix} \begin{bmatrix} \sqrt{\lambda_1} & & & & & \\ & \sqrt{\lambda_k} & & & & \\ & & 0 & \dots & 0 & \\ & & & \ddots & & \end{bmatrix} \begin{bmatrix} v_1 & v_2 & \dots & v_k & v_{k+1} & \dots & v_n \end{bmatrix} \\ &= \begin{bmatrix} u_1 & \dots & u_k \end{bmatrix} \begin{bmatrix} \sqrt{\lambda_1} & & \\ & \ddots & \\ & & \sqrt{\lambda_k} \end{bmatrix} \begin{bmatrix} v_1 & \dots & v_k \end{bmatrix}^T \\ &= \begin{bmatrix} u_1 & \dots & u_k & | & u_{k+1} & \dots & u_m \end{bmatrix} \begin{bmatrix} \sqrt{\lambda_1} & & & & 0 \\ & \ddots & & & 0 \\ & & \sqrt{\lambda_k} & & 0 \\ & & & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1^T & \dots & v_k^T \\ \vdots & & \vdots & & v_n^T \end{bmatrix} \\ &= \begin{bmatrix} u_1 & \dots & u_k & | & 0 \end{bmatrix} \begin{bmatrix} \sqrt{\lambda_1} & & & & 0 \\ & \ddots & & & 0 \\ & & \sqrt{\lambda_k} & & 0 \\ & & & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1^T & \dots & v_k^T \\ \vdots & & \vdots & & v_n^T \end{bmatrix} \\ &= \begin{bmatrix} u_1 & \dots & u_k & | & 0 \end{bmatrix} \begin{bmatrix} \sqrt{\lambda_1} & & & & 0 \\ & \ddots & & & 0 \\ & & \sqrt{\lambda_k} & & 0 \\ & & & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1^T & \dots & v_k^T \\ \vdots & & \vdots & & v_n^T \end{bmatrix} \\ &= \sqrt{\lambda_1} u_1 v_1^T + \sqrt{\lambda_2} u_2 v_2^T + \dots + \sqrt{\lambda_k} u_k v_k^T \\ A &= \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \dots + \sigma_k u_k v_k^T \end{aligned}$$