Lanczos-based typicality methods for Quantum Thermodynamics

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chen.pw/slides

This talk

Topic: We'll see some recent progress on the design and analysis of typicality methods for spectral densities.

Throughout: I'll try to provide an accessible introduction to ideas from numerical analysis that might be relevant to computational physicists.

Takeaway: numerical analysis and computational physics can benefit from more collaboration.

What is a matrix function?

A $d \times d$ symmetric matrix **H** has real eigenvalues and orthonormal eigenvectors:

$$\mathbf{H} = \sum_{n=1}^{d} \lambda_n |\mathbf{u}_n\rangle \langle \mathbf{u}_n|.$$

The matrix function $f(\mathbf{H})$, induced by $f: \mathbb{R} \to \mathbb{R}$ and \mathbf{A} , is defined as

$$f(\mathbf{H}) = \sum_{n=1}^{d} f(\lambda_n) |\mathbf{u}_n\rangle\langle\mathbf{u}_n|$$

In this talk, think of the dimension d as $\operatorname{big}!$ E.g. $d=10^6$ or $d=10^{10}$, etc.

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Often, we don't need $f(\mathbf{H})$ itself. In this talk we will discuss:

$$f(\mathbf{H})\mathbf{v}, \qquad \mathbf{v}^{\mathsf{T}}f(\mathbf{H})\mathbf{v}, \qquad \operatorname{tr}(f(\mathbf{H})) = \sum_{n=1}^{d} f(\lambda_n)$$

Example. If $f(x) = x^{-1}$, then $f(\mathbf{H}) = \mathbf{A}^{-1}$ and $f(\mathbf{H})\mathbf{v} = \mathbf{A}^{-1}\mathbf{v}$ is the solution to the linear system $\mathbf{A}\mathbf{x} = \mathbf{v}$.

- More computationally efficient to compute an approximation to the solution $A^{-1}v$ rather than computing A^{-1} and then multiplying with v.
 - Even if **A** is sparse, $f(\mathbf{H})$ is typically dense. Storing a $n \times n$ dense matrix might be intractable.
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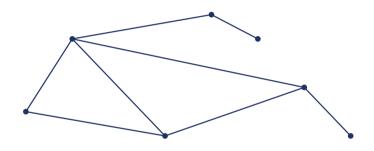
Applications

Applications in many fields: physics, chemistry, biology, statistics, high performance computing, machine learning, etc.

Common functions: inverse, exponential, square root, sign function.

Example application: network science

Let G be a graph (nodes and edges). How many triangles are there?

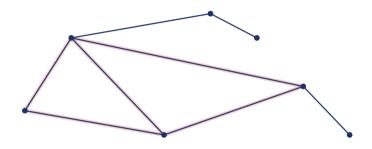


Fact. If **A** is the adjacency matrix for *G*, then

of triangles in
$$G = \frac{\operatorname{tr}(\mathbf{A}^3)}{6}$$

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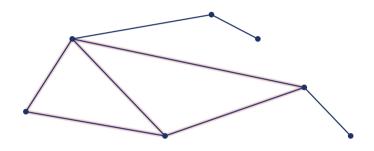


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State of the art parallel eigensolvers such as FEAST and EVSL work by splitting the spectrum of **A** into pieces, which can each be solved on different machines in parallel.

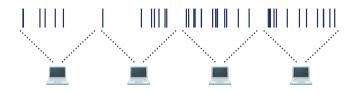


Let
$$\mathbb{1}[a \le x \le b] = 1$$
 if $x \in [a, b]$ and 0 otherwise. Then

of eigenvalues in $[a, b] = tr(1[a \le A \le b])$.

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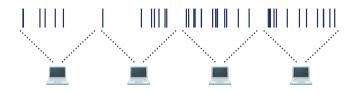


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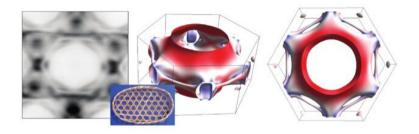
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Example application: quantum thermodynamics

Let **A** be the Hamiltonian of a quantum system.



If the system is held in thermal equilibrium at inverse temperature $\beta = k_B/T$, then thermodynamic observables such as the specific heat, magnetization, heat capacity, etc. can be obtained from the partition function:

$$Z(\beta) = tr(exp(-\beta A)).$$

Ohttps://phys.org/news/2023-06-quantum-materials-electron.html

Part I

Algorithms and convergence theory

Spectral densities

Given **H** (Hamiltonian), we're interested in the density of states (DOS):

$$\rho(x) = \sum_{n=1}^{d} \frac{1}{d} \delta(x - \lambda_n)$$

We probably can't efficiently (in $\ll d^3$ time) compute $\rho(x)$. Why?

Note that

$$tr(f(\mathbf{H})) = d \int f(x)\rho(x)dx$$

We might be interested in functions like:

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Weighted spectral densities

Given a state $|\mathbf{r}\rangle$, we can define the local density of states (LDOS)

$$\hat{\rho}(x) = \sum_{n=1}^{d} |\langle \mathbf{r} | \mathbf{u}_n \rangle|^2 \delta(x - \lambda_n).$$

Note that

$$\langle \mathbf{r}|f(\mathbf{H})|\mathbf{r}\rangle = \int f(x)\hat{\rho}(x)\mathrm{d}x.$$

We still can't efficiently compute $\hat{\rho}(x)$, but we can efficiently compute moments

$$\langle \mathbf{r} | \mathbf{H}^k | \mathbf{r} \rangle = \int x^k \hat{\rho}(x) \mathrm{d}x$$

Can compute moments through degree s using s/2 matrix-vector products with \mathbf{H} .

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Weighted spectral densities

Note that we can compute moments through degree s using s/2 matrix-vector products with \mathbf{H} :

Iteratively compute

$$|\mathbf{r}\rangle$$
, $\mathbf{H}|\mathbf{r}\rangle$, $\mathbf{H}^2|\mathbf{r}\rangle = \mathbf{H}(\mathbf{H}|\mathbf{r}\rangle)$, ...

Then use $\mathbf{H}^i|\mathbf{r}\rangle$ and $\mathbf{H}^j|\mathbf{r}\rangle$ to compute

$$\langle \mathbf{r}|\mathbf{H}^{j}\mathbf{H}^{i}|\mathbf{r}\rangle = \langle \mathbf{r}|\mathbf{H}^{i+j}|\mathbf{r}\rangle.$$

Typicality

If
$$|\mathbf{r}\rangle = \frac{1}{\sqrt{d}}(|\mathbf{u}_1\rangle + \dots + |\mathbf{u}_d\rangle)$$
, then $|\langle \mathbf{r}|\mathbf{u}_n\rangle|^2 = d^{-1}$ and LDOS is exactly DOS.

Let $|\mathbf{r}\rangle$ be a (uniform) random state. By symmetry $|\langle \mathbf{r}|\mathbf{u}_n\rangle|^2$ all have the same distribution, so

$$|\langle \mathbf{r} | \mathbf{u}_n \rangle|^2 \approx d^{-1}$$

and hence

$$\hat{\rho}(x) \approx \rho(x)$$
.

Algorithmically, this lets us approxiamte DOS with LDOS (perhaps averaged over several random states).¹

¹can also be use for partial traces Chen and Cheng 2022

Implicit trace estimation

In numerical analysis and theoretical computer science we use this idea for trace estimation. Other distributions for $|\mathbf{r}\rangle$ are common (e.g. ± 1 entries, Gaussian entries).

If $|\mathbf{r}_1\rangle$, ..., $|\mathbf{r}_m\rangle$ are independent copies of $|\mathbf{r}\rangle$, we can get concentration inequalities² such as:

$$\mathbb{P}\left[\left|d^{-1}\operatorname{tr}(\mathbf{A}) - \frac{1}{m}\sum_{i=1}^{m} \langle \mathbf{r}_i | \mathbf{A} | \mathbf{r}_i \rangle\right| > \epsilon\right] < 2\exp\left(-C\frac{d\epsilon^2}{\|\mathbf{A}\|_2^2}\right).$$

This roughly says we can approximate $d^{-1}\operatorname{tr}(\mathbf{A})$ to accuracy ϵ using $O(d^{-1}\epsilon^{-2})$ matrix-vector products with \mathbf{A} .

²Reimann 2007; Popescu, Short, and Winter 2006; Avron and Toledo 2011; Roosta-Khorasani and Ascher 2014; Cortinovis and Kressner 2021.

Implicit trace estimation: beyond Monte Carlo

Recent trace estimation algorithms³ can improve this to $O(d^{-1}\epsilon^{-1})$. These produce a low-rank approximation $\tilde{\bf A}$ to ${\bf A}$ and make use of the fact that

$$tr(\mathbf{A}) = tr(\tilde{\mathbf{A}}) + tr(\mathbf{A} - \tilde{\mathbf{A}}).$$

This is closely related to deflation.⁴

A number of improvements:

- Practical parameters⁵
- More efficient deflation⁶
- What if $\mathbf{A} = f(\mathbf{H})$?

³Meyer, Musco, Musco, and Woodruff 2021.

⁴Girard 1987; Weiße, Wellein, Alvermann, and Fehske 2006; Gambhir, Stathopoulos, and Orginos 2017.

⁵Persson, Cortinovis, and Kressner 2022.

⁶Epperly, Tropp, and Webber 2023.

⁷Persson and Kressner 2023: Chen and Hallman 2023.

Back to spectral densities: approximating a density from its moments

We can't (efficiently) compute LDOS $\hat{\rho}(x)$, but we can compute it's moments. How can we use this to approximate $\hat{\rho}(x)$ and in turn integrals against $\hat{\rho}(x)$?

Both KPM and SLQ address use the moment data to get approximations:

KPM: Approximate a function with it's Chebyshev approximation of degree *s*, then integrate this approximation using moment data.

SLQ: Construct a discrete approximation with k Diracs and use moment data to enforce that polynomials up to degree 2k-1 are integrated exactly.

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The kernel polynomial method

Fix a reference density $\sigma(x)$ and let $\{p_n\}$ be the orthonormal polynomials:

$$\int p_n(x)p_m(x)\sigma(x)\mathrm{d}x = \delta_{mn}.$$

Expand the ratio $\hat{\rho}(x)/\sigma(x)$ in the orthogonal polynomial basis:

$$\frac{\hat{\rho}(x)}{\sigma(x)} = \sum_{n=0}^{\infty} \left(\int \frac{\hat{\rho}(x)}{\sigma(x)} p_n(x) \sigma(x) dx \right) p_n(x) = \sum_{n=0}^{\infty} \left(\int p_n(x) \hat{\rho}(x) dx \right) p_n(x).$$

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How do we compute the moments?

The main computational cost is to compute the moments $\langle \mathbf{r} | p_n(\mathbf{H}) | \mathbf{r} \rangle$.

A common reference density⁸ is $\sigma(x) \propto (1+x)^{-1/2}(1-x)^{-1/2}$ in which case the orthonoral polynomials are (up to scaling) the Chebyshev polynomials:

$$T_n(x) = 2xT_{n-1}(x) - T_{n-2}(x), T_1(x) = 2x, T_0(x) = 1.$$

One can compute $T_n(\mathbf{H})|\mathbf{r}\rangle$ by

$$T_n(\mathbf{H})|\mathbf{r}\rangle = 2\mathbf{H}T_{n-1}(\mathbf{H})|\mathbf{r}\rangle - T_{n-2}(\mathbf{H})|\mathbf{r}\rangle, \qquad T_1(\mathbf{H})|\mathbf{r}\rangle = 2\mathbf{H}|\mathbf{r}\rangle, \quad T_0(\mathbf{H})|\mathbf{r}\rangle = |\mathbf{r}\rangle.$$

To get additional cost saving, use the identities

$$T_{2n}(x) = 2T_n(x)^2 - 1,$$
 $T_{2n+1}(x) = 2T_{n+1}(x)T_n(x) - T_1(x).$

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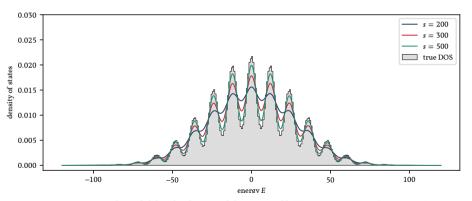
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Numerical Example

The higher the degree s, the better the approximation: resolution $\sim s^{-1}$.



Cost to get moments should be balanced how well LDOS approximates DOS.

Lanczos

The Lanczos algorithm iteratively produces an orthonormal basis $\{|\mathbf{v}_n\rangle\}$ for the Krylov subspace

$$\operatorname{span}\{|\mathbf{r}\rangle, \mathbf{H}|\mathbf{r}\rangle, \dots, \mathbf{H}^k|\mathbf{r}\rangle\} = \{p(\mathbf{H})|\mathbf{r}\rangle : \deg(p) \le k\}. \tag{1}$$

This is done via a symmetric three-term recurrence

$$|\mathbf{v}_{n+1}\rangle = \frac{1}{\beta_n} (\mathbf{H}|\mathbf{v}_n\rangle - \alpha_n |\mathbf{v}_n\rangle - \beta_{n-1} |\mathbf{v}_{n-1}\rangle)$$
 (2)

with initial conditions $|\mathbf{v}_1\rangle = (1/\beta_0)(\mathbf{H}|\mathbf{v}_0\rangle - \alpha_0|\mathbf{v}_0\rangle)$ and $|\mathbf{v}_0\rangle = |\mathbf{r}\rangle$.

At each step α_n is chosen so that $\langle \mathbf{v}_{n+1} | \mathbf{v}_n \rangle = 0$ and then β_n is chosen so that $\langle \mathbf{v}_{n+1} | \mathbf{v}_{n+1} \rangle = 1$.

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Lanczos

We can write this in matrix form: $\mathbf{H}\mathbf{V} = \mathbf{V}\mathbf{H}_k + |\mathbf{v}\rangle\langle\mathbf{e}_k|$

$$\mathbf{H}\begin{bmatrix} | & | & & | \\ \mathbf{v}_0 & \mathbf{v}_1 & \cdots & \mathbf{v}_k \\ | & | & & | \end{bmatrix} = \begin{bmatrix} | & | & & | \\ \mathbf{v}_0 & \mathbf{v}_1 & \cdots & \mathbf{v}_k \\ | & | & & | \end{bmatrix} \begin{bmatrix} \alpha_0 & \beta_0 & & & \\ \beta_0 & \alpha_1 & \ddots & & \\ & \ddots & \ddots & \beta_{n-1} & \alpha_k \end{bmatrix} + \beta_k |\mathbf{q}_{n+1}\rangle \langle \mathbf{e}_k |.$$

The orthogonality of the $\{|\mathbf{v}_n\rangle\}$ implies:

$$\mathbf{H}_k = \mathbf{V}^\mathsf{T} \mathbf{H} \mathbf{V}.$$

A distribution function?

Define

$$\rho_{\rm SLQ}(x) = \sum_{n=1}^{k} |\langle \mathbf{s}_n | \mathbf{e}_n \rangle|^2 \delta(x - \theta_n),$$

where θ_n are the eigenvalues of \mathbf{H}_k and \mathbf{s}_n are the eigenvectors. Since this is a discrete distribution, it is common to replace $\delta(x-\theta_n)$ with a blurred version (i.e. a Gaussian of a given width).

Note that

$$\int f(x)\rho_{\rm SLQ}(x){\rm d}x = \langle \mathbf{e}_1|f(\mathbf{H}_k)|\mathbf{e}_1\rangle.$$

SLQ moments match LDOS momements

Let p be any polynomial of degree at most 2k - 1. Then

$$\langle \mathbf{r}|p(\mathbf{H})|\mathbf{r}\rangle = \int \hat{\rho}(e)p(x)\mathrm{d}x = \int \rho_{\mathrm{SLQ}}(x)p(E)\mathrm{d}x = \langle \mathbf{e}_1|p(\mathbf{H}_k)|\mathbf{e}_1\rangle.$$

Proof: Suppose $\mathbf{H}^{n-1}|\mathbf{r}\rangle = \mathbf{V}\mathbf{H}_k^{n-1}|\mathbf{e}_1\rangle$. Since $|\mathbf{r}\rangle = \mathbf{V}|\mathbf{e}_1\rangle$, write

$$|\mathbf{H}^n|\mathbf{r}
angle = \mathbf{H}\mathbf{V}\mathbf{H}_k^{n-1}|\mathbf{e}_1
angle = \mathbf{V}\mathbf{H}_k^n|\mathbf{e}_1
angle + |\mathbf{v}
angle\langle\mathbf{e}_k|\mathbf{H}_k^n|\mathbf{e}_1
angle = \mathbf{V}_k\mathbf{H}_k^n|\mathbf{e}_1
angle$$

In last equality: since \mathbf{H}_k is tridiagonal, \mathbf{H}_k^n has bandwidth 2n+1 and $\langle \mathbf{e}_k | \mathbf{H}_k^n | \mathbf{e}_1 \rangle = 0$ provided n < k.

Now use $\mathbf{V}^{\mathsf{T}}\mathbf{V} = \mathbf{I}$ and $\mathbf{V}^{\mathsf{T}}\mathbf{H}\mathbf{V} = \mathbf{H}_{k}$ to get $\langle \mathbf{r}|\mathbf{H}^{n}|\mathbf{r}\rangle$ for n < 2k

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Proof: Suppose $\mathbf{H}^{n-1}|\mathbf{r}\rangle = \mathbf{V}\mathbf{H}_k^{n-1}|\mathbf{e}_1\rangle$. Since $|\mathbf{r}\rangle = \mathbf{V}|\mathbf{e}_1\rangle$, write

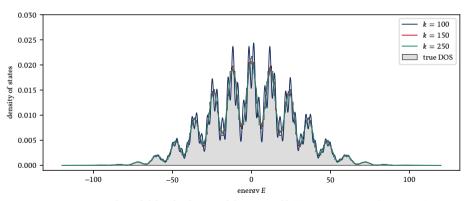
$$\mathbf{H}^{n}|\mathbf{r}\rangle = \mathbf{H}\mathbf{V}\mathbf{H}_{k}^{n-1}|\mathbf{e}_{1}\rangle = \mathbf{V}\mathbf{H}_{k}^{n}|\mathbf{e}_{1}\rangle + |\mathbf{v}\rangle\langle\mathbf{e}_{k}|\mathbf{H}_{k}^{n}|\mathbf{e}_{1}\rangle = \mathbf{V}_{k}\mathbf{H}_{k}^{n}|\mathbf{e}_{1}\rangle.$$

In last equality: since \mathbf{H}_k is tridiagonal, \mathbf{H}_k^n has bandwidth 2n+1 and $\langle \mathbf{e}_k | \mathbf{H}_k^n | \mathbf{e}_1 \rangle = 0$ provided n < k.

Now use $\mathbf{V}^{\mathsf{T}}\mathbf{V} = \mathbf{I}$ and $\mathbf{V}^{\mathsf{T}}\mathbf{H}\mathbf{V} = \mathbf{H}_{k}$ to get $\langle \mathbf{r}|\mathbf{H}^{n}|\mathbf{r}\rangle$ for n < 2k.

Numerical Example

The higher the degree s = 2k - 1, the better the approximation: resolution $\sim s^{-1}$.

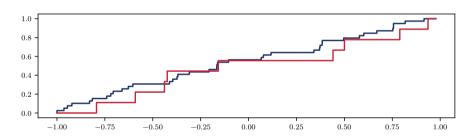


Cost to get moments should be balanced how well LDOS approximates DOS.

Measuring the similarity of distributions

The Wasserstein distance measures the similarity between distributions:

$$d_{W}(\psi_{1}, \psi_{2}) = \int |\Psi_{1}(x) - \Psi_{2}(x)| dx.$$



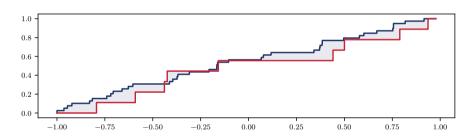
This is equivalent to

$$d_{W}(\psi_{1}, \psi_{2}) = \max \left\{ \left| \int f(x)\psi_{1}(x)dx - \int f(x)\psi_{2}(x)dx \right| : |f(x) - f(y)| \le |x - y| \ \forall x, y \right\}$$

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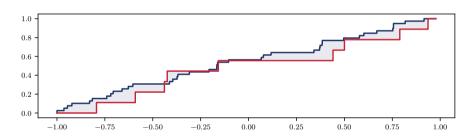
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Theoretical analysis (high level)⁹

Fact: 1-Lipshitz functions can be approximated to accuracy ϵ with a degree $s = O(\epsilon^{-1})$ polynomial. This polynomial has decaying Chebyshev coefficients.

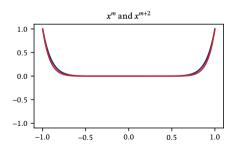
Fact: if two distributions have exactly the same moments through degree k, the the Wasserstein distance is $O(k^{-1})$.

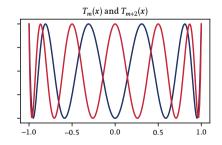
⁹Braverman, Krishnan, and Musco 2022; Chen, Trogdon, and Ubaru 2022.

Chebyshev moments vs monomial moments

While two distribution functions with exactly the same first k moments have Wasserstein distance $O(k^{-1})$, if the monomial moments are even a little different, the Wasserstein distance can be big.

Instead, one should look at Chebyshev moments, since Wasserstein distance is stable with respect to perturbations in these moments.

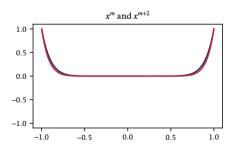


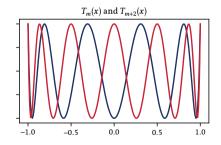


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Theoretical analysis (high level)¹⁰

Approach:

- Show KPM/SLQ approximation has almost the same Chebyshev moments as DOS (i.e. that Chebyshev polynomials are integrated almost exactly) through some degree (by averaging enough LDOSs).
- Show this implies all Lipshitz functions are integrated nearly correctly (my using enough moments)

For a single fixed Lipshitz function, there are easier approaches, but to get a Wasserstein bound, we need something that holds for all Lipshitz functions simultaneously.

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Claim. Suppose that for all n = 0, 1, ..., s:

$$\left|\int T_n(x)(\psi_1(x)-\psi_2(x))\mathrm{d}x\right|\leq \eta.$$

Then, for any degree s polynomial $p_s(x) = c_0 + c_1 T_1(x) + \cdots + c_s T_s(x)$,

$$\left| \int f(x) (\psi_1(x) - \psi_2(x)) dx \right| \le 2 \|f(x) - p_s(x)\|_{[-1,1]} + 2\eta \sum_{n=1}^s |c_n|.$$

Proof. Triangle inequality

$$\left| \int f(x)(\psi_1(x) - \psi_2(x)) \mathrm{d}x \right| \leq \left| \int (f(x) - p_s(x))(\psi_1(x) - \psi_2(x)) \mathrm{d}x \right| + \left| \int p_s(x)(\psi_1(x) - \psi_2(x)) \mathrm{d}x \right|.$$

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Proof. Triangle inequality:

$$\left|\int f(x)(\psi_1(x)-\psi_2(x))\mathrm{d}x\right| \leq \left|\int (f(x)-p_s(x))(\psi_1(x)-\psi_2(x))\mathrm{d}x\right| + \left|\int p_s(x)(\psi_1(x)-\psi_2(x))\mathrm{d}x\right|.$$

Fact. ¹¹ Suppose f(x) is 1-Lipshitz $(|f(x) - f(y)| \le |x - y|)$ and set $p_s(x)$ as the degree s Jackson's damped Chebyshev approximation to f(x). Then,

$$\|f(x)-p_s(x)\|_{[-1,1]}\leq \frac{6}{s}, \qquad \left|\int p_s(x)T_n(x)\mu_T(x)\mathrm{d}x\right|\leq \frac{4}{\pi n}.$$

Thus, since $1 + 1/2 + 1/3 + \cdots 1/s \le 1 + \ln(s)$,

$$\int f(x)(\psi_1(x) - \psi_2(x)) dx \le \frac{12}{s} + \frac{8\ln(s)\eta}{\pi}.$$

Maximizing over f , we then get

$$s = O(\varepsilon^{-1}), \ \eta = O(\ln(s)^{-1}\varepsilon) \implies d_{\mathcal{W}}(\psi_1, \psi_2) \le \varepsilon$$

This gives us gurantees for SLQ (slight modification for damped KPM).

¹¹Rivlin 1981: Trefethen 2019.

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Part II

Implementation and finite precision arithmetic

A spectrum adaptive KPM¹²

In the KPM, the only expensive computation was computing moments: $\langle \mathbf{r}|p_n(\mathbf{H})|\mathbf{r}\rangle$.

If we've compute \mathbf{H}_k using Lanczos, then we know for polyniams p(x) of degree < 2k:

$$\langle \mathbf{r}|p(\mathbf{H})|\mathbf{r}\rangle = \langle \mathbf{e}_1|p(\mathbf{H}_k)|\mathbf{e}_1\rangle.$$

So, we can use Lanczos to implement KPM!

This means we can test out lots of different reference densities $\sigma(x)$ for essentially free (i.e. without accessing **H** again).

¹²Chen 2023.

Demo

Some basic functionality is implemented in the spectral_density package. 13

```
pip install spectral_density
```

The design paradigm for spectral_density is that computation and approximation should be decoupled. In particular, approximations are obtained in two steps:

- computation: repeatedly run the Lanczos algorithm on the matrix of interest with random starting vectors
- approximation: use the output of the previous step to obtain spectral density approximations

This package focuses only on the second step; users are free to use any Lanczos implementation for the first step.

¹³https://github.com/tchen-research/spectral_density

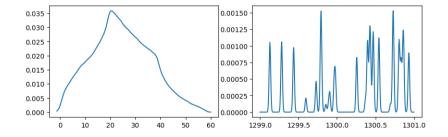
Demo: setup

```
import spectral density as spec
# import Hamiltonian
H = sp.io.mmread('./Ga41As41H72.mtx')
H.tocsr()
d = H.shape[0]
# run Lanczos several times
m = 3
αβ list = []
for in range(m):
    v = np.random.randn(d)
    v /= np.linalg.norm(v)
    k = 150
    aβ list.append(spec.lanczos(H,v,k,reorth=False))
```

Demo: SLQ

```
p_SLQ = spec.SLQ(αβ_list) # build SLQ instance

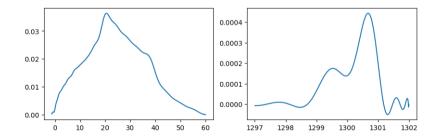
axs[0].plot(x,p_SLQ(x,width=.6)) # plot (specifying width)
axs[1].plot(x,p_SLQ(x,width=.01))
```



Demo: KPM

```
σ = spec.get_arcsin_density(-2,1302)  # specify reference density
ρ_KPM = spec.KPM(αβ_list,σ)  # build KPM instance

axs[0].plot(x,ρ_KPM(x))  # plot
axs[1].plot(x,ρ_KPM(x))
```



Demo: KPM

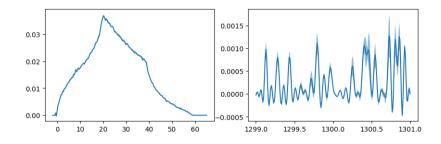
```
# use Lanczos output to determine two intervals containing spectrum
a L = np.min(\rho SLO.\theta)-4e-1
b L = np.max(\rho SLO.\theta[\rho SLO.\theta<200])+4e-1
a R = np.min(\rho SLQ.\theta[\rho SLQ.\theta>1200])-4e-1
b R = np.max(\rho SLO.\theta)+4e-1
# build a density on each interval
\sigma L = \text{spec.get uniform density}(a L,b L)
\sigma R = spec.get semicircle density(a R.b R)
# combine densities to specify reference density
\sigma = .95*\sigma_L + .05*\sigma R
```

Demo: KPM

```
p_{KPM} = spec.KPM(\alpha\beta_{list,\sigma}) # build KPM instance

axs[0].plot(x,p_{KPM}(x)) # plot

axs[1].plot(x,p_{KPM}(x))
```



Wait, isn't Lanczos unstable?

In the previous demo, we used the output of Lanczos without reorthogonalization!

There is a general fear of using Lanczos-based methods without expensive reorthogonalization schemes¹⁴

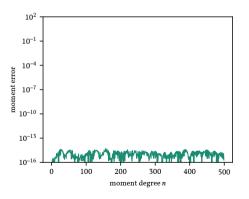
But... there is plenty of evidince that SLQ and related algorithms work fine without reorthogonalization:Long, Prelovšek, Shawish, Karadamoglou, and Zotos 2003; Schnack, Richter, and Steinigeweg 2020, etc.

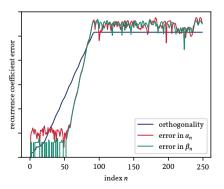
In fact, there is even theory.

¹⁴ Jaklič and Prelovšek 1994; Aichhorn, Daghofer, Evertz, and Linden 2003; Weiße, Wellein, Alvermann, and Fehske 2006; Ubaru, Chen, and Saad 2017; Granziol, Wan, and Garipov 2019.

Numerical Example

People worry about a loss of orthogonality, and appearence of "ghost eigenvalues". But do these impact the moments used for KPM?





Finite precision theory

In finite precision artihmetic, while **V** may no longer be orthogonal, we still have 15

$$\mathbf{HV} = \mathbf{VH}_k + |\mathbf{v}\rangle\langle\mathbf{e}_k| + \mathbf{F}, \qquad \|\mathbf{F}\| = O(\epsilon_{\mathrm{mach}} \operatorname{poly}(k)).$$

From this, one can derive¹⁶

$$\|\tilde{T}_n(\mathbf{H})|\mathbf{r}\rangle - \mathbf{V}\tilde{T}_n(\mathbf{H}_k)|\mathbf{e}_1\rangle\| = O(\epsilon_{\mathrm{mach}} \operatorname{poly}(k))$$

This can then be upgraded to 17

$$\left| \langle \mathbf{r} | \tilde{T}_n(\mathbf{H}) | \mathbf{r} \rangle - \langle \mathbf{e}_1 | \tilde{T}_n(\mathbf{H}_k) | \mathbf{e}_1 \rangle \right| = O(\epsilon_{\text{mach poly}}(k))$$

In other words, SLQ's Chebyshev moments are still almost exact.

¹⁵Paige 1971; Paige 1976; Paige 1980.

¹⁶Druskin and Knizhnerman 1992; Musco, Musco, and Sidford 2018.

¹⁷Knizhnerman 1996

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A taste of how these anlyses work

Recall we have a perturbed recurrence: $\mathbf{H}\mathbf{V} = \mathbf{V}\mathbf{H}_k + |\mathbf{v}\rangle\langle\mathbf{e}_k| + \mathbf{F}$.

Define:
$$|\mathbf{t}_n\rangle = T_n(\mathbf{H})|\mathbf{r}\rangle$$
, $|\bar{\mathbf{t}}_n\rangle = T_n(\mathbf{H}_k)|\mathbf{e}_1\rangle$, $|\mathbf{d}_n\rangle = |\mathbf{t}_n\rangle - \mathbf{V}|\bar{\mathbf{t}}_n\rangle$.

Then, using that
$$\langle \mathbf{e}_k | \bar{\mathbf{t}}_{n-1} \rangle = 0$$
 (bc \mathbf{H}_k is tridiagonal):
$$|\mathbf{d}_n \rangle = (2\mathbf{H} | \mathbf{t}_{n-1} \rangle - |\mathbf{t}_{n-2} \rangle) - (2\mathbf{V}\mathbf{H}_k | \bar{\mathbf{t}}_{n-1} \rangle - \mathbf{V} | \bar{\mathbf{t}}_{n-2} \rangle)$$

$$= 2(\mathbf{H} | \mathbf{t}_{n-1} \rangle - (\mathbf{H}\mathbf{V} - |\mathbf{v}\rangle \langle \mathbf{e}_k | - \mathbf{F}) | \bar{\mathbf{t}}_{n-1} \rangle) - (|\mathbf{t}_{n-2}\rangle - \mathbf{V} | \bar{\mathbf{t}}_{n-2} \rangle)$$

$$= 2\mathbf{H} |\mathbf{d}_{n-1}\rangle - |\mathbf{d}_{n-2}\rangle - \mathbf{F} | \bar{\mathbf{t}}_{n-1}\rangle$$

This is a perturbed Chebyshev recurrence. One can show:

$$|\mathbf{d}_n\rangle = U_{n-1}(\mathbf{H})\mathbf{F}|\bar{\mathbf{t}}_0\rangle + 2\sum_{i=2}^n U_{n-i}(\mathbf{H})\mathbf{F}|\bar{\mathbf{t}}_{i-1}\rangle$$

Note that Cheyshev-U polynomials don't grow quickly, so this implies $|\mathbf{d}_n\rangle$ is small!

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$$= 2(\mathbf{H} | \mathbf{t}_{n-1} \rangle - (\mathbf{H} \mathbf{V} - | \mathbf{v} \rangle \langle \mathbf{e}_k | - \mathbf{F}) | \bar{\mathbf{t}}_{n-1} \rangle) - (|\mathbf{t}_{n-2} \rangle - \mathbf{V} | \bar{\mathbf{t}}_{n-2} \rangle)$$

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Note that Cheyshev-*U* polynomials don't grow quickly, so this implies $|\mathbf{d}_n\rangle$ is small!

Outlook

- While Lanczos is unstable, the instability has structure
- partial traces Chen and Cheng 2022; Chen, Chen, Li, Nzeuton, Pan, and Wang 2023

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