Is the Lanczos-Method for Matrix Functions Nearly Optimal?

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chen.pw/slides

What is a matrix function?

An $n \times n$ symmetric matrix **A** has real eigenvalues and orthonormal eigenvectors:

$$\mathbf{A} = \sum_{i=1}^n \lambda_i \mathbf{u}_i \mathbf{u}_i^{\mathsf{T}}.$$

The matrix function f(A) is defined as

$$f(\mathbf{A}) := \sum_{i=1}^n f(\lambda_i) \mathbf{u}_i \mathbf{u}_i^{\mathsf{T}}.$$

What are we doing with matrix functions?

Common matrix functions include:

- $f(x) = x^{-1}$
- $f(x) = \exp(-\beta x)$ for all β in some range
- $f(x) = \sqrt{x}$
- f(x) = sign(x)

Computational Task. Approximate $f(\mathbf{A})\mathbf{b}$ (w.l.o.g. $\|\mathbf{b}\| = 1$).

Kryov subspace methods

Def. The k-th Krylov subspace (generated by \mathbf{A} and \mathbf{b}) is

$$\mathcal{K}_k(\mathbf{A}, \mathbf{b}) := \operatorname{span}\{\mathbf{b}, \mathbf{Ab}, \mathbf{A}^2\mathbf{b}, \dots, \mathbf{A}^{k-1}\mathbf{b}\}.$$

The Lanczos algorithm can be used to obtain a (graded) orthonormal basis $\mathbf{q}_0, \dots, \mathbf{q}_k$ for $K_{k+1}(\mathbf{A}, \mathbf{b})$.

This basis satisfies a symmetric three-term recurrence

$$\mathbf{A}\mathbf{q}_n = \beta_{n-1}\mathbf{q}_{n-1} + \alpha_n\mathbf{q}_n + \beta_n\mathbf{q}_{n+1},$$

with initial conditions $\mathbf{q}_{-1} = \mathbf{0}$ and $\beta_{-1} = 0$.

Lanczos matrix relation

The coefficients $\{\alpha_n\}$ and $\{\beta_n\}$ defining the three term recurrence are also generated by the algorithm. This recurrence can be written in matrix form as

$$\mathbf{A}\mathbf{Q}_k = \mathbf{Q}_k \mathbf{T}_k + \boldsymbol{\beta}_{k-1} \mathbf{q}_k \mathbf{e}_k^{\mathsf{T}}$$

where

The orthonormality of the Krylov basis implies that $\mathbf{Q}_k^{\mathsf{T}} \mathbf{A} \mathbf{Q}_k = \mathbf{T}_k$.

L

The Lanczos-method for matrix function approximation

Def. The *k*-th Lanczos-FA iterate is

$$\mathsf{Ian}\text{-}\mathsf{FA}_k(f) := \mathbf{Q}_k f(\mathbf{T}_k) \mathbf{e}_1.$$

Method introduced and studied in 1980s.1

Lots of competitors have better theoretical guarantees, but Lanczos-FA typically works best in practice!

Ongoing Reserach Program: Explain why Lanczos-FA works so well.

¹Nauts and Wyatt 1983; Park and Light 1986; Vorst 1987; Druskin and Knizhnerman 1988; Druskin and Knizhnerman 1989; Gallopoulos and Saad 1992; Saad 1992, etc.

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Lemma. Suppose deg(p) < k. Then $lan-FA_k(p) = p(A)b$.

Proof. By linearity, it suffices to verify for $\mathbf{A}^{j}\mathbf{b}$, j < k

Note that $\mathbf{Q}_k \mathbf{Q}_k^{\mathsf{T}}$ is the orthogonal projector onto $\mathcal{K}_k(\mathbf{A}, \mathbf{b})$. Hence

$$\mathbf{A}^{j}\mathbf{b} = \mathbf{Q}_{k}\mathbf{Q}_{k}^{\mathsf{T}}\mathbf{A}^{j}\mathbf{b}$$

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$$= \mathbf{Q}_{k}\mathbf{T}_{k}^{\mathsf{T}}\mathbf{e}_{k}.$$

lan-FA $_k(f)=p({f A}){f b}$ so that $f({f T}_k)=p({f T}_k);$ i.e. interpolating at the eigenvalues of ${f T}_k$.

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Optimality for the inverse: a connection to Conjugate Gradient

Theorem. If $f(x) = x^{-1}$ and **A** is positive definite, Lanczos-FA is **A**-norm optimal.

Proof. Any vector $\mathbf{x} \in \mathcal{K}_k(\mathbf{A}, \mathbf{b})$ can be written as $\mathbf{x} = \mathbf{Q}_k \mathbf{c}$ for some $\mathbf{c} \in \mathbb{R}^k$.

Therefore

$$\begin{aligned} \underset{\mathbf{x} \in K_k(\mathbf{A}, \mathbf{b})}{\operatorname{argmin}} & \| \mathbf{A}^{-1} \mathbf{b} - \mathbf{x} \|_{\mathbf{A}} = \mathbf{Q}_k \operatorname*{argmin}_{\mathbf{c} \in \mathbb{R}^k} \| \mathbf{A}^{-1} \mathbf{b} - \mathbf{Q}_k \mathbf{c} \|_{\mathbf{A}} \\ &= \mathbf{Q}_k \operatorname*{argmin}_{\mathbf{c} \in \mathbb{R}^k} \| \mathbf{A}^{-1/2} \mathbf{b} - \mathbf{A}^{1/2} \mathbf{Q}_k \mathbf{c} \|. \end{aligned}$$

The solution to this least squares problem is

$$\mathbf{Q}_{k}(\mathbf{Q}_{k}^{\mathsf{T}}\mathbf{A}^{1/2}\mathbf{A}^{1/2}\mathbf{Q}_{k})^{-1}\mathbf{Q}_{k}^{\mathsf{T}}\mathbf{A}^{1/2}\mathbf{A}^{-1/2}\mathbf{b} = \mathbf{Q}_{k}\mathbf{T}_{k}^{-1}\mathbf{e}_{1} = \mathsf{Ian-FA}_{k}(x^{-1}).$$

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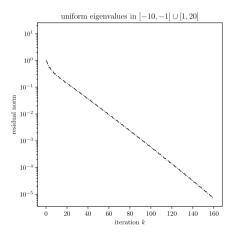
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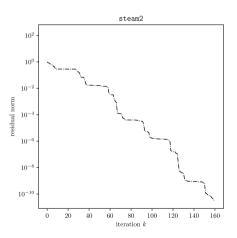
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Warm up: CG on indefinite systems?

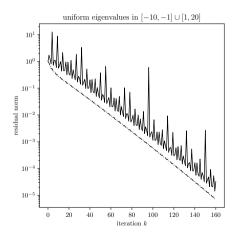
What happens to CG/Lanczos-FA if **A** is symmetric indefinite (or nonsymmetric)?

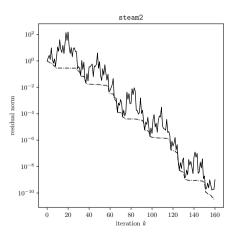




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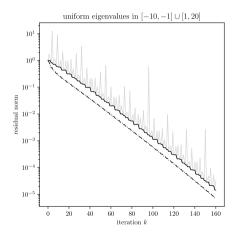
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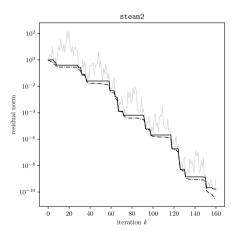




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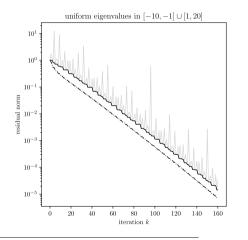
CG on indefinite systems³

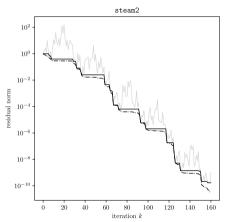
Theorem. Lanczos-FA satisfies $\min_{j \le k} \|\mathbf{b} - \mathbf{A} \text{lan-FA}_j(x^{-1})\| \le \sqrt{k+1} \min_{\mathbf{x} \in K_k(\mathbf{A}, \mathbf{b})} \|\mathbf{b} - \mathbf{A} \mathbf{x}\|.$

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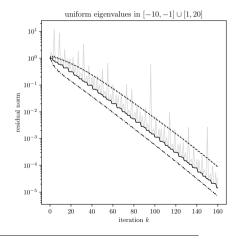


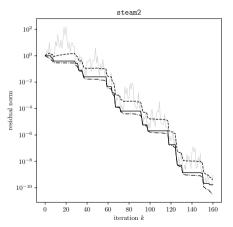


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What about the general case?

 $\textbf{Theorem.} \ \text{Lanczos-FA satisfies} \ \|f(\mathbf{A})\mathbf{b} - \text{lan-FA}_k(f)\| \leq 2 \min_{\deg(p) < k} \|f - p\|_{[\lambda_{\min'}\lambda_{\max}]}.$

Proof. Fix a polynomial p with deg(p) < k and define e(x) = f(x) - p(x). Then,

$$\begin{split} \|f(\mathbf{A})\mathbf{b} - \mathsf{lan}\text{-}\mathsf{FA}_k(f)\| &= \|f(\mathbf{A})\mathbf{b} - p(\mathbf{A})\mathbf{b} + \mathsf{lan}\text{-}\mathsf{FA}_k(p) - \mathsf{lan}\text{-}\mathsf{FA}_k(f)\| \\ &\leq \|p(\mathbf{A})\mathbf{b} - f(\mathbf{A})\mathbf{b}\| + \|\mathsf{lan}\text{-}\mathsf{FA}_k(f) - \mathsf{lan}\text{-}\mathsf{FA}_k(p)\|, \\ &\leq \|e(\mathbf{A})\mathbf{b}\| + \|\mathbf{Q}_k e(\mathbf{T}_k)\mathbf{e}_1\| \\ &\leq \|e(\mathbf{A})\|_2 + \|\mathbf{Q}_k\|_2 \|e(\mathbf{T}_k)\|_2 \\ &= \|e\|_{\Lambda(\mathbf{A})} + \|e\|_{\Lambda(\mathbf{T}_k)} \leq 2\|e\|_{[\lambda_{\min},\lambda_{\max}]}. \end{split}$$

Optimizing over *p* gives the result

This bound is essentially sharp, but hard instances aren't real-world instances.

What about the general case?

Theorem. Lanczos-FA satisfies $\|f(\mathbf{A})\mathbf{b} - \mathsf{Ian-FA}_k(f)\| \le 2 \min_{\deg(p) > k} \|f - p\|_{[\lambda_{\min}, \lambda_{\max}]}$.

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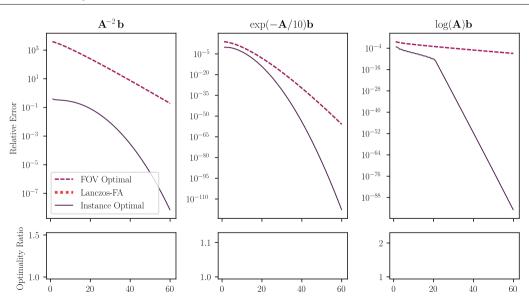
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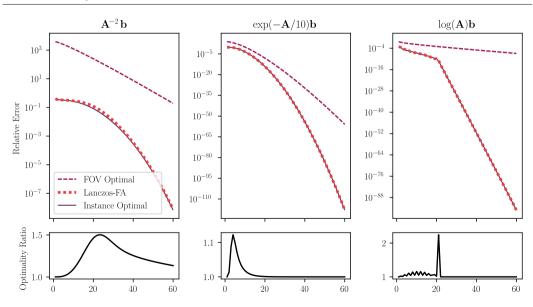
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Some examples



Some examples



Is Lanczos-FA nearly optimal?

Interval optimality bound is clearly not good enough!

– For CG, this amounts to the $\sqrt{\kappa}$ bound, which is not usually indicative of the algorithm's actual behavior!

Research Question: Can we prove convergence guarantees for Lanczos-FA in terms of the best-possible Krylov Subspace Methods? I.e. does

$$||f(\mathbf{A})\mathbf{b} - \operatorname{Ian-FA}_k(f)|| \le C \min_{\mathbf{x} \in K_k(\mathbf{A}, \mathbf{b})} ||f(\mathbf{A})\mathbf{b} - \mathbf{x}||$$
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An optimality bound⁴

Theorem. Let r(x) = n(x)/m(x) be a degree (p,q) rational function, where $m(x) = (x-z_1)(x-z_2)\cdots(x-z_q)$ and $z_i \in \mathbb{R} \setminus [\lambda_{\min}, \lambda_{\max}]$. Then, provided $k > \max\{p, q-1\}$, the Lanczos-FA iterate satisfies the bound

$$\|\mathsf{Ian}\text{-}\mathsf{FA}_k(r) - r(\mathbf{A})\mathbf{b}\| \leq C(r,\lambda_{\min},\lambda_{\max}) \min_{\mathbf{x} \in K_{k-a+1}(\mathbf{A},\mathbf{b})} \|r(\mathbf{A}) - \mathbf{x}\|.$$

This is a near-optimality guarantee for a very wide class of functions!

- Recovers CG bound when n(x) = 1 and m(x) = (x 0)
- Often more indicative of true behavior of Lanczos-FA than interval bound

⁴Amsel, Chen, Greenbaum, Musco, and Musco 2023.

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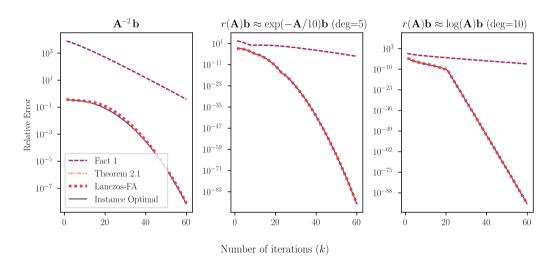
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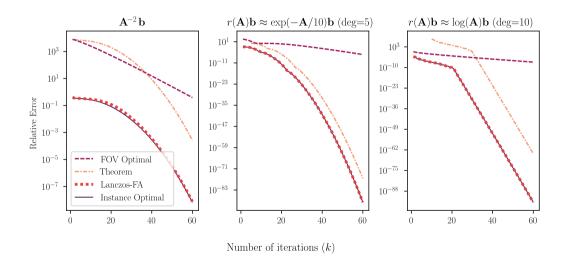
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Some examples (revisited)



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Proof sketch

Let's consider $r(x) = x^{-2}$ and PSD **A**. By the triangle inequality,

$$\begin{split} \|\mathbf{A}^{-2}\mathbf{b} - \mathsf{lan\text{-}FA}_k(x^{-2})\| &\leq \|\mathbf{A}^{-2}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}^{-1}\mathbf{b}\| + \|\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}^{-1}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-2}\mathbf{Q}^\mathsf{T}\mathbf{b}\| \\ &\leq \|\mathbf{A}^{-2}\mathbf{b} - \underbrace{\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}\mathbf{A}^{-2}\mathbf{b}}_{\mathbf{A}-\mathsf{norm\ optimal}}\| + \underbrace{\|\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\|}_{\leq \lambda_{\min}^{-1}}\underbrace{\|\mathbf{A}^{-1}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{b}\|}_{\mathrm{CG\ error}}. \end{split}$$

Now note if
$$p(x) \approx x^{-2}$$
, then $xp(x) \approx x^{-1}$. So,

$$\min_{\deg(p) < k} \|\mathbf{A}^{-1}\mathbf{b} - p(\mathbf{A})\mathbf{b}\| \leq \min_{\deg(p) < k-1} \|\mathbf{A}^{-1}\mathbf{b} - \mathbf{A}p(\mathbf{A})\mathbf{b}\|
\leq \min_{\deg(p) < k-1} \|\mathbf{A}(\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b})\|
\leq \min_{\deg(p) < k-1} \|\mathbf{A}\| \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\|.$$

Together, (and using that the **A**-norm and 2-norm are $\kappa^{1/2}$ -equivalent) we get

$$\|\mathbf{A}^{-2}\mathbf{b} - \mathsf{lan-FA}_k(x^{-2})\| \leq \kappa^{1/2} \min_{\deg(p) < k} \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\| + \kappa^{3/2} \min_{\deg(p) < k-1} \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\|.$$

Proof sketch

Let's consider $r(x) = x^{-2}$ and PSD **A**. By the triangle inequality,

$$\begin{split} \|\mathbf{A}^{-2}\mathbf{b} - \mathsf{lan\text{-}FA}_k(x^{-2})\| &\leq \|\mathbf{A}^{-2}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}^{-1}\mathbf{b}\| + \|\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}^{-1}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-2}\mathbf{Q}^\mathsf{T}\mathbf{b}\| \\ &\leq \|\mathbf{A}^{-2}\mathbf{b} - \underbrace{\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}\mathbf{A}^{-2}\mathbf{b}}_{\mathbf{A}-\mathsf{norm\ optimal}}\| + \underbrace{\|\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\|}_{\leq \lambda_{\min}^{-1}}\underbrace{\|\mathbf{A}^{-1}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{b}\|}_{\mathrm{CG\ error}}. \end{split}$$

Now note if
$$p(x) \approx x^{-2}$$
, then $xp(x) \approx x^{-1}$. So,

$$\begin{split} \min_{\deg(p) < k} \|\mathbf{A}^{-1}\mathbf{b} - p(\mathbf{A})\mathbf{b}\| &\leq \min_{\deg(p) < k-1} \|\mathbf{A}^{-1}\mathbf{b} - \mathbf{A}p(\mathbf{A})\mathbf{b}\| \\ &\leq \min_{\deg(p) < k-1} \|\mathbf{A}(\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b})\| \\ &\leq \min_{\deg(p) < k-1} \|\mathbf{A}\| \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\|. \end{split}$$

Together, (and using that the **A**-norm and 2-norm are $\kappa^{1/2}$ -equivalent) we get

$$\|\mathbf{A}^{-2}\mathbf{b} - \mathsf{lan-FA}_k(x^{-2})\| \leq \kappa^{1/2} \min_{\deg(p) < k} \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\| + \kappa^{3/2} \min_{\deg(p) < k-1} \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\|.$$

Proof sketch

Let's consider $r(x) = x^{-2}$ and PSD **A**. By the triangle inequality,

$$\begin{split} \|\mathbf{A}^{-2}\mathbf{b} - \mathsf{lan\text{-}FA}_k(x^{-2})\| &\leq \|\mathbf{A}^{-2}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}^{-1}\mathbf{b}\| + \|\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}^{-1}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-2}\mathbf{Q}^\mathsf{T}\mathbf{b}\| \\ &\leq \|\mathbf{A}^{-2}\mathbf{b} - \underbrace{\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{A}\mathbf{A}^{-2}\mathbf{b}}_{\mathbf{A}\text{-norm optimal}}\| + \underbrace{\|\mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\|}_{\leq \lambda_{\min}^{-1}}\underbrace{\|\mathbf{A}^{-1}\mathbf{b} - \mathbf{Q}\mathbf{T}^{-1}\mathbf{Q}^\mathsf{T}\mathbf{b}\|}_{\mathrm{CG\ error}}. \end{split}$$

Now note if $p(x) \approx x^{-2}$, then $xp(x) \approx x^{-1}$. So,

$$\begin{split} \min_{\deg(p) < k} \|\mathbf{A}^{-1}\mathbf{b} - p(\mathbf{A})\mathbf{b}\| &\leq \min_{\deg(p) < k-1} \|\mathbf{A}^{-1}\mathbf{b} - \mathbf{A}p(\mathbf{A})\mathbf{b}\| \\ &\leq \min_{\deg(p) < k-1} \|\mathbf{A}(\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b})\| \\ &\leq \min_{\deg(p) < k-1} \|\mathbf{A}\| \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\|. \end{split}$$

Together, (and using that the **A**-norm and 2-norm are $\kappa^{1/2}$ -equivalent) we get

$$\|\mathbf{A}^{-2}\mathbf{b} - \mathsf{Ian-FA}_k(x^{-2})\| \leq \kappa^{1/2} \min_{\deg(p) < k} \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\| + \kappa^{3/2} \min_{\deg(p) < k-1} \|\mathbf{A}^{-2}\mathbf{b} - p(\mathbf{A})\mathbf{b}\|.$$

Caveats

The prefactor $C(r, \lambda_{\min}, \lambda_{\max})$ is constant for fixed r and matrices with bounded spectrum. But the value we obtain is very bad (proof artifact?).

- If **A** is positive definite and z_i < 0, then $C(r, \lambda_{\min}, \lambda_{\max})$ ≤ $q\kappa(\mathbf{A})^q$.
- The worst dependence on κ and q we could find numerically is $\sqrt{q \cdot \kappa}$.

This bound does not account for finite precision arithmetic, but it can be connected⁵

⁵Greenbaum 1989.

Future work

- Improve the constant prefactor in the near-optimality bound
- Prove instance optimality guarantees for Markov/Stieltjes functions

$$- f(x) = \int w(z)(x-z)^{-1}.$$

- Extend the result to more general rational functions
 - conjugate pairs of poles
 - poles in $[\lambda_{\min}, \lambda_{\max}]$.
- Prove instance optimality guarantees for the exponential or other functions⁶

⁶Druskin, Greenbaum, and Knizhnerman 1998.

Markov/Stieltjes functions

Consider functions of the form

$$f(x) = \int_{-\infty}^{0} w(z)(x-z)^{-1} \approx \sum_{i} w_{i}(x-z_{i})^{-1}.$$

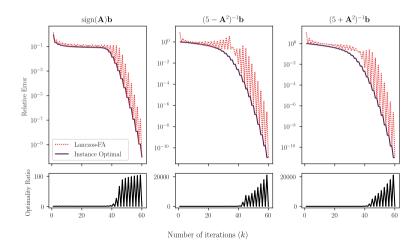
Then the Lanczos-FA iterate is

$$\mathsf{lan-FA}_k(f) = \int_{-\infty}^0 w(z) \mathsf{lan-FA}_k((x-z)^{-1}) \approx \sum_i w_i \mathsf{lan-FA}_k((x-z_i)^{-1}).$$

This is like CG on a bunch of shifted linear systems... (termwise optimal).

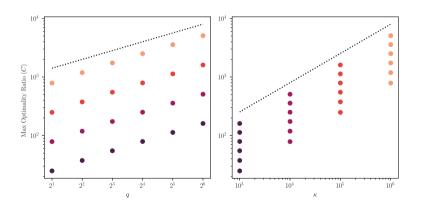
Indefinite problems

Even for other functions, Lanczos-FA seems nearly optimal in an overall sense.



Hard problems?

Different values of κ and q and the worst-case optimality ratio we could find.



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