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Monday 880.05Handout:

- PS #2 will be released on Tuesday.

Follow-ups:

- The seed of randn functions in MATLAB can be given a random seed by the statement: "randn('seed', 12345)" where 12345 is an example of an integer seed. Using randn('state', sum(100*clock)); will initial to a different state every time. (See PS#2)
- Calculating expm in MATLAB: in PS#2 we'll compare 3 methods.

Recap from last time:

- ① Functional derivatives $\frac{1}{\epsilon} \frac{\delta}{\delta f} \rightarrow \frac{\delta}{\delta f(T)}$ [Recall $N_p \epsilon = \beta$]
 • follow-up comments from "Aside: Functionals and Functional Derivatives" on next pages
 - ② Perturbation theory by extracting interaction from integral
- $$Z[f] = e^{\int_0^\beta dt \frac{1}{4} \left(\frac{\delta}{\delta f(t)} \right)^2} C \int_{x(0)=x(0)}^{\infty} dx e^{-\int_0^\beta dt \left[\frac{m}{2} \left(\frac{dx}{dt} \right)^2 + \frac{1}{2} \alpha x^2 - x f(t) \right]}$$
- $x(0)=x(0)$ S_E

• In the discrete version, this is a Gaussian integral

$$Z[f] = e^{-\epsilon \sum_{i=1}^N \frac{1}{4} \left(\frac{\delta}{\delta f_i} \right)^2} Z_0 e^{\frac{1}{2} f_i A_{ij} f_j}$$

$\leftarrow C' [\det A]^{-1/2}$

• A is just a matrix with 1's and 2's and $\frac{m}{\epsilon}$, $\epsilon \alpha$ factors.

- Now \Rightarrow start with continuum version \Rightarrow (89) [we repeat and update the next pages]
- make it look like a matrix problem.

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note the boundary conditions

or

$$\underline{A} = \frac{m}{\epsilon} \begin{pmatrix} 2 & -1 & 0 & -1 \\ -1 & 2 & -1 & \dots \\ 0 & -1 & 2 & \dots \\ \vdots & \vdots & \vdots & \ddots \\ -1 & \dots & \dots & 2 \end{pmatrix} + \epsilon a \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ 0 & & & 1 \end{pmatrix}$$

so we can construct \underline{A} explicitly in the discrete representation.
Then we have

$$Z[F] = e^{-\epsilon \sum_i \frac{1}{4} \left(\frac{\Delta x}{\Delta t} \right)^2} z_0 e^{\frac{1}{2} F_i A_{ik} F_k}$$

How do we understand the continuum version?

$$\int \mathcal{D}x(\tau) e^{-\int_0^{\beta} d\tau \left[\frac{m}{2} \left(\frac{dx}{d\tau} \right)^2 + \frac{1}{2} a x^2 - x F(\tau) \right]}$$

 $x(\beta) = x(0)$

make it
look like
a matrix
 $x(\tau) \rightarrow x_i$
as a vector

$$= \int \mathcal{D}x(\tau) e^{-\int_0^{\beta} d\tau \left\{ x \left[-\frac{m}{2} \frac{\partial^2}{\partial \tau^2} + \frac{1}{2} a \right] x - x F(\tau) \right\}}$$

like diagonal matrix

(what about
surface term?
Remember
boundary condition,
surface term = 0)

$$= \int \mathcal{D}x(\tau) e^{-\int_0^{\beta} d\tau \int_0^{\beta} d\tau' \left\{ x(\tau) \left[-\frac{m}{2} \frac{\partial^2}{\partial \tau^2} + \frac{1}{2} a \right] \delta(\tau - \tau') x(\tau') - x(\tau) \delta(\tau - \tau') F(\tau') \right\}}$$

 $\frac{1}{2} A(\tau, \tau')$

$$= \int \mathcal{D}x(\tau) e^{-\int_0^{\beta} d\tau \int_0^{\beta} d\tau' \frac{1}{2} (x + F A^{-1}) A (x + A^{-1} F) + \frac{1}{2} \int_0^{\beta} d\tau \int_0^{\beta} d\tau' F(\tau) A^{-1}(\tau, \tau') F(\tau')}$$

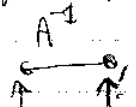
(after shift of $x(\tau)$)

$$\Rightarrow Z[F] = e^{-\int_0^{\beta} d\tau \frac{1}{4} \left(\frac{\Delta x}{\Delta t} \right)^2} z_0 e^{\frac{1}{2} \int_0^{\beta} d\tau \int_0^{\beta} d\tau' F(\tau) A^{-1}(\tau, \tau') F(\tau')}$$

$\Rightarrow A^{-1}(\tau, \tau')$ is the inverse of the differential operator $\left(-\frac{m}{2} \frac{\partial^2}{\partial \tau^2} + \frac{1}{2} a \right) \delta(\tau - \tau')$
or the Green's function, with the periodic boundary condition.

\Rightarrow solution to $\left(-\frac{m}{2} \frac{\partial^2}{\partial \tau^2} + \frac{1}{2} a \right) A^{-1}(\tau, \tau') = \delta(\tau - \tau')$ with $A^{-1}(\beta, \tau) = A^{-1}(\tau, 0)$
(we've used $A^{-1}(\tau, \tau') = A^{-1}(\tau' - \tau)$.)

• Can you solve this? Next week we'll look at diagrams:



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Try the first couple of orders of

$$\frac{Z[f]}{Z_0} = e^{-\int_0^\beta d\tau \frac{\lambda}{4} \left(\frac{\delta}{\delta f(\tau)} \right)^4} e^{\frac{1}{2} \int_0^\beta d\tau_1 \int_0^\beta d\tau_2 f(\tau_1) A'(\tau_1, \tau_2) f(\tau_2)}$$

$$= \left[1 - \int_0^\beta d\tau \frac{\lambda}{4} \left(\frac{\delta}{\delta f(\tau)} \right)^4 + \frac{1}{2} \int_0^\beta d\tau \frac{\lambda}{4} \left(\frac{\delta}{\delta f(\tau)} \right)^4 \int_0^\beta d\tau' \frac{\lambda}{4} \left(\frac{\delta}{\delta f(\tau')} \right)^4 + \dots \right]$$

$$\left[1 + \frac{1}{2} \int f(2) A^4(1,2) f(2) + \frac{1}{2!} \frac{1}{2} \int f(2) A^4(1,2) f(2) \frac{1}{2} \int f(3) A^4(3,4) f(4) + \dots \right]$$

Assume $A'(1,2) = A'(2,1)$ here. Take $f \rightarrow 0$ at end. $\left(\frac{1}{2}\right)^3$ symmetry factor

$$\int_0^\beta d\tau \left(\frac{\lambda}{4} \right) \cdot \left(\frac{1}{2} \right)^3 4! A^4(\tau, \tau) A^2(\tau, \tau) \Rightarrow \text{Diagram} \leftarrow A^4(\tau, \tau) \Big|_{\tau=\tau}$$

order in which to hit f's.
(permutations of 1,2,3,4)

added rule: Integrate τ from 0 to β .

$O(\lambda^2)$: connected and disconnected for $Z[f]/Z_0|_{f=0}$.

Consider

$$\int_0^\beta d\tau \int_0^\beta d\tau' \left(-\frac{\lambda}{4} 4! \right)^2 \left[\left(\frac{1}{2} \right)^2 \frac{1}{2} \cdot \frac{1}{2} \right] A^4(\tau, \tau) A^2(\tau, \tau') A^4(\tau', \tau) A^2(\tau', \tau')$$

$$\text{Diagram} \int_0^\beta d\tau \int_0^\beta d\tau' \left(-\frac{\lambda}{4} 4! \right)^2 \left[1 \cdot \frac{1}{4} \cdot \frac{1}{2} \right] (A^4(\tau, \tau'))^4 \quad \text{and so on.}$$

$$\langle X(\tau_a) X(\tau_b) \rangle = \frac{\left(\frac{\delta}{\delta f(\tau_a)} \frac{\delta}{\delta f(\tau_b)} \frac{Z[f]}{Z_0} \right)_{f=0}}{\left(\frac{Z[f]}{Z_0} \right)_{f=0}} = \frac{\int \int \frac{1}{2} \int f(1) A^4(1,2) f(2) + \dots}{\left(\frac{Z[f]}{Z_0} \right)_{f=0}} = A^4(\tau_a, \tau_b) + \dots$$

$$\text{Diagram} + \text{Diagram} \int_0^\beta \int_0^\beta A^4(\tau_a, \tau) A^4(\tau, \tau) A^4(\tau, \tau_b) \left(-\frac{\lambda}{4} \right)^4 \left(\frac{1}{2} \cdot \frac{1}{2} \cdot 1 \right)$$

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How do we generalize to a few- or many-body system?

• For the quantum mechanics approach with Hamiltonian:

$$\hat{H} = \sum_{i=1}^N \frac{(\hat{p}_i)^2}{2m} + \frac{1}{2} \sum_{i \neq j}^N V(\hat{x}_i - \hat{x}_j) + (3\text{-body } V) + \dots$$

For N particles with identical masses

• Since they are identical particles, the partition function has to be a sum (trace) over a complete basis that has the correct symmetry (bosons - symmetric, fermions - antisymmetric).

• So going from $|x\rangle$ to $|x^{(1)}\rangle |x^{(2)}\rangle \dots |x^{(N)}\rangle$

as a direct product seems problematic because it is not a definite symmetry

[Note: The indices written as superscripts here label the different particles. These are typically written as x_1, x_2, \dots, x_N . However, this directly clashes with our use of subscripts to indicate the x 's at different time steps. Negele and Orland just use the same notation for both.]

↑
Note, actually it does work if the states in the trace are symmetrized

← (note the curly bracket)

• So we use

$$\{|x^{(1)}\rangle |x^{(2)}\rangle \dots |x^{(N)}\rangle\} = \left\{ \frac{1}{N!} \sum_P \epsilon^P |x^{(1)}\rangle |x^{(2)}\rangle |x^{(3)}\rangle \dots |x^{(N)}\rangle \right\}$$

← ϵ^P is a symmetrizer or antisymmetrizer

where the P means a permutation of the particles and ϵ^P fixes up bosons ($\epsilon^P = 1$, all ϵ^P have same sign) and fermions ($\epsilon^P = \pm 1$ as P is even/odd).

The completeness relation is

$$\frac{1}{N!} \sum_{x^{(1)} \dots x^{(N)}} |x^{(1)}\rangle \dots |x^{(N)}\rangle \langle x^{(1)} \dots x^{(N)}| = 1$$

• More generally, let $x \rightarrow \infty$ represent a single-particle basis. This is not a normalized basis as yet, but that is not important for us.

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• At this stage, we simply need this basis to define the trace:

$$Z = \frac{1}{N!} \int \prod_{i=1}^N dx^{(i)} \{ x^{(1)} \dots x^{(N)} | e^{-\beta \hat{H}} | x^{(1)} \dots x^{(N)} \}$$

$$= \frac{1}{N!} \sum_P \int \prod_{i=1}^N dx^{(i)} \{ x^{(P1)} \dots x^{(PN)} | e^{-\beta \hat{H}} | x^{(1)} \dots x^{(N)} \}$$

Just as before, the "time interval" from 0 to β can be broken into N_T pieces and we insert complete sets of states.

• We can actually use either (anti)symmetrized or just product states. In the latter case, the final states of correct symmetry imposes the correct Fermi or Bose statistics.

• In the direct product case,

$$Z = \frac{1}{N!} \sum_P \int \prod_{i=1}^N dx^{(i)} [x^{(i)}] \dots [x^{(N)}] e^{-\int_0^\beta \left[\sum_{i=1}^N \left(\frac{dx^{(i)}(\tau)}{d\tau} \right)^2 + \frac{1}{2} \sum_{i,j} v(x^{(i)} - x^{(j)}) \right] d\tau}$$

$x^{(1)}(\beta) = x^{(1)}(0)$
 \vdots
 $x^{(N)}(\beta) = x^{(N)}(0)$

When we simulate fermions with this form, $e^{-\beta \hat{H}}$ filters out the lowest state of any symmetry \Rightarrow but the lowest symmetric will be lower than the antisymmetric \Rightarrow noise growing exponentially before projecting on antisymmetric states.

• Alternative is to project at each ϵ step:

$$\{ x^{(1)} \dots x^{(N)} | e^{-\epsilon \hat{H}} | y^{(1)} \dots y^{(N)} \} = \left(\frac{m}{2\pi\epsilon} \right)^{3N/2} \sum_P e^{-\frac{m}{2\epsilon} \sum_{i=1}^N (x^{(i)} - y^{(Pi)})^2 - \frac{\epsilon}{2} \sum_{i,j} v(y^{(i)} - y^{(j)})}$$

$$\stackrel{(i)}{\downarrow} = \left(\frac{m}{2\pi\epsilon} \right)^{3N/2} \text{Det } M e^{-\frac{m}{2\epsilon} \sum_{i=1}^N (x^{(i)} - y^{(i)})^2 - \frac{\epsilon}{2} \sum_{i,j} v(y^{(i)} - y^{(j)})}$$

with $M_{ij} = e^{-\frac{m}{2\epsilon} [(x^{(i)} - y^{(i)})^2 - (x^{(i)} - y^{(j)})^2]}$ but Det M has minus signs! More later on why this is bad.

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Let's fill in some detail on the calculation of $\{x^{(1)} \dots x^{(N)} | e^{-\epsilon H} | y^{(1)} \dots y^{(N)} \}$.

With $\hat{H} = \sum_{i=1}^N \frac{\hat{p}_i^2}{2m} + \frac{1}{2} \sum_{i \neq j=1}^N v(\hat{x}^{(i)} - \hat{x}^{(j)})$, the normal

ordering simply puts all of the \hat{p}^2 terms to the left and the v terms to the right. So insert a complete set of $|p^{(1)} \dots p^{(N)}\rangle$ states between these two terms.

The v 's pick up the sum of terms with $y^{(i)} - y^{(j)}$ arguments

$$e^{-\frac{\epsilon}{2} \sum_{i \neq j} v(y^{(i)} - y^{(j)})}$$

with no permutations in the end, (we count up the same terms when we sum over i and j if permuted).

If we didn't have the permutations to account for, then we would just get

$$\left(\frac{m}{2\pi\epsilon}\right)^{N/2} e^{-\frac{m}{2\epsilon} \sum_{i=1}^N (x^{(i)} - y^{(i)})^2}$$

for each $i=1$ to $N \Rightarrow$ just a summation in the exponent.

But the permutations mean that we have to sum over all ways of mixing up the x 's.

$$\Rightarrow \sum_P (-1)^P e^{-\frac{m}{2\epsilon} \sum_{i=1}^N (x^{(P(i))} - y^{(i)})^2} = e^{-\frac{m}{2\epsilon} \sum_{i=1}^N (x^{(i)} - y^{(i)})^2} \sum_P (-1)^P e^{-\frac{m}{2\epsilon} \sum_{i=1}^N [(x^{(P(i))} - y^{(i)})^2 - (x^{(i)} - y^{(i)})^2]}$$

We're assuming now we have fermions, so $\{^P \rightarrow (-1)^P$.

Try the $N=2$ case for the sum over P :

$$e^{-\frac{m}{2\epsilon} [(x^{(1)} - y^{(1)})^2 - (x^{(1)} - y^{(2)})^2]} - e^{-\frac{m}{2\epsilon} [(x^{(2)} - y^{(1)})^2 - (x^{(2)} - y^{(2)})^2]} = e^{-\frac{m}{2\epsilon} [(x^{(1)} - y^{(1)})^2 - (x^{(1)} - y^{(2)})^2]} - e^{-\frac{m}{2\epsilon} [(x^{(2)} - y^{(1)})^2 - (x^{(2)} - y^{(2)})^2]}$$

If we introduce $M_{ij} = e^{-\frac{m}{2\epsilon} [(x^{(i)} - y^{(j)})^2 - (x^{(i)} - y^{(i)})^2]}$, then this is $(\det M)$.

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Considering general N , we see that this does match the definition of a determinant: $(\det M_{ij} = \sum_p (-1)^p \prod_{i=1}^N M_{i, \pi(i)})$.

[In Wikipedia, this is called the "Leibniz Formula" for the determinant. They write it for $n \times n$ matrix A as

$$\det(A) = \sum_{\sigma \in S_n} \text{sgn}(\sigma) \prod_{i=1}^n A_{i, \sigma(i)}$$

\nwarrow \swarrow
 $\leftarrow (-1)^p$
 permutation group of n objects

]

So we get that

$$\{x^{(1)} \dots x^{(N)} | : e^{-\epsilon H} | y^{(1)} \dots y^{(N)}\} = \left(\frac{m}{2\pi\epsilon}\right)^{3N/2} (\det M) e^{-\frac{m}{2\epsilon} \sum_{i=1}^N (x^{(i)} - y^{(i)})^2 - \frac{\epsilon}{8} \sum_{i,j} V(y^{(i)} - y^{(j)})}$$

which, except for the determinant, looks like a simple generalization of the $N=1$ result.

The problem is that there are minus signs in $\det M$ that cause problems, "the sign problem".

A description of the problem is given in Chapter 8 of Negele and Orland.
 \Rightarrow we will probably return to this later.

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Aside: Finding Symmetrized States in Practice

- Suppose we have a single-particle basis $|a\rangle$ that we use to form a direct product (ie unsymmetrized) basis. How do we construct symmetrized or anti-symmetrized basis states in practice?
- We're particularly interested in implementing this on a computer.

So how do we represent our Hilbert space?

- We can see how it goes with a two level system and two particles.

- We have four possibilities: $|a\rangle, |b\rangle \otimes |a\rangle, |b\rangle$
or $|a a\rangle, |a b\rangle, |b a\rangle, |b b\rangle$, which we label: 1 2 3 4

- Now any operator can be represented as the 16 matrix elements O_{ij} with $(i,j) = 1, 2, 3, 4$.

- Two such operators are $S = \frac{1}{N!} \sum_P P$ and $A = \frac{1}{N!} \sum_P (-1)^P P$
each permutation takes a basis state (an i) to exactly one other one.

- We can label the $N=2$ P 's as P_{12} and P_{21} .
 - P_{12} is the identity \Rightarrow state of particle 1 \rightarrow 1, state of particle 2 \rightarrow 2
 - P_{21} takes state of particle 2 \rightarrow 1 and state of particle 1 \rightarrow 2.

$$\Rightarrow P_{12} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad P_{21} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow S = \frac{1}{2}(P_{12} + P_{21}) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad A = \frac{1}{2}(P_{12} - P_{21}) = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

- Now we simply diagonalize to find the symmetric and antisymmetric combinations.

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Now we diagonalize and find 4 unit eigenvalues for S and 0 unit eigenvalues for A .

- Why? (3 particle and 2 states for fermions means \rightarrow)
- Where are the 4 "missing" states?
- You should be able to write down the symmetric states by inspection, but it's nice to see this work out automatically with MATLAB.

 $|a a a\rangle$
 $|b b b\rangle$
 $\frac{1}{\sqrt{3}}(|a a b\rangle + |a b a\rangle + |b a a\rangle)$
 $\frac{1}{\sqrt{3}}(|a b b\rangle + |b a b\rangle + |b b a\rangle)$

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Aside: Functionals and Functional Derivatives

Ref.: Appendix B in the text by N. Nagaosa is the source for much of this presentation. Most field theory books have an introduction to functionals in their discussions of path integrals.

• First let's contrast Functions and Functionals:

- i) Function f : you give me a real number $x \in \mathbb{R}$ and I'll give you another real number:

$$f: x \in \mathbb{R} \rightarrow f(x) \in \mathbb{R}$$

- generalizations include different domains and ranges (eg. complex numbers)

- ii) Functional F : rather than a single x , give me an entire function $f(x)$ in an interval $\alpha \leq x \leq \beta$ and I'll give you a single real number back:

$$F: f(x) \in \mathcal{H} \rightarrow F(\{f(x)\}) \equiv F[f] \equiv F[f(x)] \in \mathbb{R}$$

- we've indicated a variety of notations you might find in the literature
- \mathcal{H} signifies a Hilbert space
- Note that when we use the notation $F[f(x)]$, there is no particular value of x involved; the entire function (in a relevant interval) is the input.

- It is useful (as usual) to imagine putting a functional on a computer.

- We can represent a function $f(x)$ as breaking up the interval $\alpha < x < \beta$ into a discrete mesh (set) of points $\{x_i\}$ with

$$\alpha \equiv x_1 < x_2 < \dots < x_{N-1} < x_N \equiv \beta$$

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- These numbers might be stored in an array, $x[i]$, for example, with $i=1$ to N .
- The function $f(x)$ is the set of N numbers $f_i \equiv f(x_i)$, (which we can also store as $f[i]$).

\Rightarrow A Functional F is a function of the N numbers $\{f_i\}$ (not of the N numbers $\{x_i\}$!)

- A functional derivative tells us about what happens to the value of a functional when we let $f(x)$ become $f(x) + \delta f(x) \Rightarrow$ a slightly different function.
- In the discrete version, we take $f_i \rightarrow f_i + \delta f_i$ (just like one takes $x_i \rightarrow x_i + \delta x_i$ in an ordinary derivative).

Suppose

$$F[f(x)] = \int_a^b f(x) g(x) dx$$

where $g(x)$ is some other fixed function of x .

- Note that we integrate over x , so there is no free $x \Rightarrow F$ is not a function of x !
- Let's make the simplest discrete version!

$$F[f(x)] \rightarrow \sum_i f(x_i) g(x_i) \Delta x_i \equiv \sum_i f_i g_i \Delta x_i$$

Now let $f_i \rightarrow f_i + \delta f_i$:

(we called this ϵ for breaking up the time interval)

$$\begin{aligned} \delta F &= F(f_1 + \delta f_1, \dots, f_N + \delta f_N) - F(f_1, \dots, f_N) \\ &\equiv \sum_{i=1}^N \frac{\partial F(f_1, \dots, f_N)}{\partial f_i} \delta f_i + O(\delta f_i^2) \end{aligned}$$

- Notice the δ 's instead of δ 's.

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We define the functional derivative $\frac{\delta F}{\delta f(x)}$ as

$$\frac{\delta F[f]}{\delta f(x)} = \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \frac{\partial F(f_1, \dots, f_n)}{\partial f_i} \quad \text{where } f_i = f(x_i)$$

↑
this x matters!

- The x on the left corresponds to x_i on the right; in the limit that we make the mesh very fine.
- \Rightarrow We look how much the functional changes when we change the function at the i^{th} mesh point.

• Apply this definition to the example:

$$\begin{aligned} \frac{\delta F[f(x)]}{\delta f(x)} &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \frac{\partial}{\partial f_i} (\sum f_i g_i \Delta x_i) \\ &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \sum \delta_{ii} g_i \Delta x_i \\ &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} g_i \Delta x_i = \lim_{\Delta x_i \rightarrow 0} g_i = g(x) \end{aligned}$$

• Rewriting this:

$$\frac{\delta F(x)}{\delta f(x)} \int f(x') g(x') dx' = g(x)$$

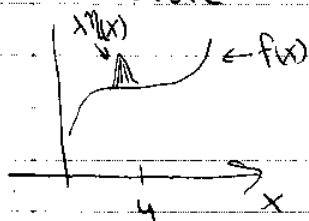
- note again that the " x " argument on the left is not a dummy argument.

• Special case: $F[F(x)] = \int f(x) dx$ (or $g(x) \equiv 1$)

$$\Rightarrow \frac{\delta F(x)}{\delta f(x)} \int f(x') dx' = 1$$

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For completeness, we present an alternative definition of the functional derivative that is more common in the literature.



As in the picture at the left we add a "bump" at y , which we take to be a delta function with strength λ , and see how much the functional changes!

$$\frac{\delta F[f]}{\delta f(y)} = \lim_{\lambda \rightarrow 0} \frac{F[f(x) + \lambda \delta(x-y)] - F[f(x)]}{\lambda}$$

Try it out on the example:

$$\begin{aligned} \frac{\delta}{\delta f(y)} \int f(x) g(x) dx &= \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} \left[\int [f(x) + \lambda \delta(x-y)] g(x) dx - \int f(x) g(x) dx \right] \\ &= \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} \lambda \int \delta(x-y) g(x) dx = g(y) \quad \text{as before.} \end{aligned}$$

Another special case, which can be used as the definition of the functional derivative as well: $g(x) = \delta(x-z)$

$$\Rightarrow \frac{\delta}{\delta f(x)} \int f(x') \delta(x'-z) dx' = \frac{\delta f(z)}{\delta f(x)} = \delta(x-z)$$

where the last equality is what we want.

Note that this is the analog of $\frac{\partial}{\partial j_i} j_i = 1$, which we used repeatedly in the model problem.

Here, if we let $f(x) \Rightarrow f_i \Rightarrow j_i$, then the equivalent formula is

$$\frac{\partial j_i}{\partial j_k} = \delta_{ik} \Rightarrow \frac{\delta j(x)}{\delta j(y)} = \delta(x-y)$$

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Let's try another example we'll come across

$$\begin{aligned}
 & \frac{\delta}{\delta f(x)} \int f(x_1) C(x_1, x_2) f(x_2) dx_1 dx_2 \quad \text{with } C(x_2, x_1) = C(x_1, x_2) \\
 &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \frac{\partial}{\partial f_i} \sum_{jk} f_j C_{jk} f_k \Delta x_j \Delta x_k \\
 &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \sum_{jk} (\delta_{ij} C_{jk} f_k + f_j C_{jk} \delta_{ik}) \Delta x_j \Delta x_k \\
 &= \lim_{\Delta x_i \rightarrow 0} \frac{2}{\Delta x_i} \sum_k C_{ik} f_k \Delta x_i \Delta x_k = 2 \int C(x, x_2) f(x_2) dx_2
 \end{aligned}$$

- More generally, if $C_n(x_1, x_2, \dots, x_n)$ is totally symmetric under interchange of any two x_i , then

$$\frac{\delta^n F[f]}{\delta f(x_1) \dots \delta f(x_n)} = n! C_n(x_1, \dots, x_n)$$

- We get the special case of $n=2$ by taking another functional derivative of the example up top.
- Exercise for the diligent reader: rederive these results using the alternative definition of a functional derivative.
- The familiar properties of ordinary (partial) derivatives, such as the product and chain rules, carry over to functional derivatives in a natural way.

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So consider

$$\begin{aligned}
 \frac{d}{dx} \int (f(x))^3 g(x) dx &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \frac{d}{df_i} \sum (f_i)^3 g_i \Delta x_i \\
 &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \sum 3(f_i)^2 \delta f_i g_i \Delta x_i \\
 &= \lim_{\Delta x_i \rightarrow 0} 3(f_i)^2 g_i = 3(f(x))^2 g(x)
 \end{aligned}$$

and so we have the chain rule:

$$\frac{d}{dx} \int g[f(x)] dy = g'[f(x)]$$

where g' means to take the derivative of g with respect to f as if it were a partial derivative.

• Another form of the chain rule we'll use a lot is:

$$\frac{d}{dx} e^{-\int dx (a^2 x^2 + j(x) \psi(x))} = -\psi(x) e^{-\int dx (a^2 x^2 + j(x) \psi(x))}$$

- What if we have a function of \vec{x} or \vec{x} and t (or \uparrow)?
- We can combine \vec{x} and t into a "four-vector" x^μ , so it is sufficient to consider an n -vector $\vec{x} = (x_1, \dots, x_n)$.
- Consider

$$F[f(\vec{x})] = \int_0^b f(\vec{x}) g(\vec{x}) dx_1 \cdots dx_n$$

$$\Rightarrow F[f(\vec{x})] \rightarrow \sum_{i_1, i_2, \dots, i_n} f_{i_1, \dots, i_n} g_{i_1, \dots, i_n} \Delta x_{i_1} \cdots \Delta x_{i_n}$$

where we now have n -dimensional arrays $x[i_1, \dots, i_n]$ and $f[i_1, \dots, i_n]$, where i_1 runs over the mesh for x_1 , i_2 runs over the mesh for x_2 , and so on.

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Let's take $n=2$ for clarity. Then our mesh is a two-dimensional grid and the function value is defined at each grid point (i,j) to be f_{ij} .

$$\Rightarrow F[\vec{f}] = \sum_{i,j} f_{ij} g_{ij} \Delta x_i \Delta y_j \quad \text{with } \vec{x} = (x,y)$$

and the functional derivative

$$\begin{aligned} \frac{\delta F[\vec{f}]}{\delta f(\vec{x})} &= \lim_{\substack{\Delta x_i \rightarrow 0 \\ \Delta y_j \rightarrow 0}} \frac{1}{\Delta x_i \Delta y_j} \frac{\partial}{\partial f_{ij}} \sum_{i',j'} f_{i'j'} g_{i'j'} \Delta x_{i'} \Delta y_{j'} \\ &= \lim_{\substack{\Delta x_i \rightarrow 0 \\ \Delta y_j \rightarrow 0}} \frac{1}{\Delta x_i \Delta y_j} \sum_{i',j'} \delta_{ii'} \delta_{jj'} g_{i'j'} \Delta x_{i'} \Delta y_{j'} \\ &= \lim_{\substack{\Delta x_i \rightarrow 0 \\ \Delta y_j \rightarrow 0}} g_{ij} = g(\vec{x}) \end{aligned}$$

Similarly,

$$\frac{\delta F(\vec{x})}{\delta f(\vec{x}')} = \delta^n(\vec{x} - \vec{x}')$$

and so on.

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• What if there is a derivative in the functional?

$$\sum_{\mathbf{f}(\mathbf{x})} \int \frac{d\mathbf{f}(\mathbf{x}')}{d\mathbf{x}'} g(\mathbf{x}') d\mathbf{x}' ?$$

• We can do this several ways. Here are two:

i) partially integrate

$$\begin{aligned} \sum_{\mathbf{f}(\mathbf{x})} \int \frac{d\mathbf{f}(\mathbf{x}')}{d\mathbf{x}'} g(\mathbf{x}') d\mathbf{x}' &= \sum_{\mathbf{f}(\mathbf{x})} \left[-\mathbf{f}(\mathbf{x}') \frac{dg(\mathbf{x}')}{d\mathbf{x}'} d\mathbf{x}' + \text{surface term} \right] \\ &= -\frac{dg(\mathbf{x})}{d\mathbf{x}} \quad (\text{if the surface term doesn't contribute}) \end{aligned}$$

or

ii) discrete version:

$$\begin{aligned} \sum_{\mathbf{f}(\mathbf{x})} \int \frac{d\mathbf{f}(\mathbf{x}')}{d\mathbf{x}'} g(\mathbf{x}') d\mathbf{x}' &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \sum_j \frac{f_{j+1} - f_j}{\Delta x_i} g_j \Delta x_j \\ &= \lim_{\Delta x_i \rightarrow 0} \frac{1}{\Delta x_i} \sum_j (f_{j+1} - f_j) g_j \\ &= \frac{1}{\Delta x_i} (g_{i-1} - g_i) = -\frac{dg}{dx} \end{aligned}$$

• note that the possible surface terms in this case are left over from taking $\sum f_{j+1} g_j - \sum f_j g_j$ and changing dummy indices in the first.

• OK, that's it for now \Rightarrow more later!

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In generalizing the path integral to many-particle systems (by which we mean more than a few particles to of order 10^{23} particles - effectively infinity) there are two choices:

- i) Work with many particle states built from a basis for each particle \Rightarrow path integral is direct generalization of the example of one-particle quantum mechanics we've been discussing.
 - main complication is dealing with proper, symmetrized states (which means antisymmetrizing for fermions, which leads to sign problems.)

- ii) Work with fields that operate in the space spanned by the number basis.

Let's pursue this second option.

• We will give a very brief introduction now and backfill details as needed.

• We'll assume our building blocks for the basis is a set of orthonormal single-particle states labeled $|\alpha\rangle$

• not necessary for most results that orthogonal, but easier.

• Basis for Hilbert space \mathcal{H}_1

$$\sum_{\alpha} |\alpha\rangle \langle \alpha| = 1$$

$$\langle \alpha | \beta \rangle = \delta_{\alpha\beta} \quad \leftarrow N \text{ copies}$$

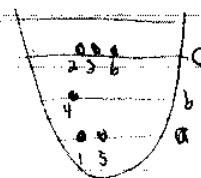
• Then \mathcal{H}_N is tensor product $\mathcal{H}_1^{(1)} \otimes \mathcal{H}_1^{(2)} \otimes \dots \otimes \mathcal{H}_1^{(N)} \equiv \mathcal{H}_N$

and

$$|\alpha_1 \alpha_2 \dots \alpha_N\rangle \leftarrow \text{must not symmetrize} \equiv |\alpha_1\rangle |\alpha_2\rangle \dots |\alpha_N\rangle$$

• order of kets refers to particle 1, 2, ...

$$|a c c b a c\rangle$$



Even outside of symmetrizing, this seems like a pain!

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Issues:

- i) Different \hat{H} for each N , or \hat{H} refers specifically to N
- ii) awkward at best for identical particles \rightarrow permutations
- iii) with one, two, three-body operators, only one, two, three states affected \rightarrow rest are bystanders

eg. $\hat{H} = \sum_i T_i + \sum_{i,j} V_{ij} + \dots = \dots + V_{12} + V_{13} + V_{23} + \dots$

so $\langle \alpha'_1 \alpha'_2 \alpha'_3 \alpha'_4 \alpha'_5 \alpha'_6 \dots | \hat{H} | \alpha_1 \alpha_2 \alpha_3 \alpha_4 \alpha_5 \alpha_6 \dots \rangle$
 $= \langle \alpha'_1 \alpha'_2 | V_{12} | \alpha_1 \alpha_2 \rangle \delta_{\alpha'_3 \alpha_3} \delta_{\alpha'_4 \alpha_4} \dots + \langle \alpha'_1 \alpha'_3 | V_{13} | \alpha_1 \alpha_3 \rangle \delta_{\alpha'_2 \alpha_2} \delta_{\alpha'_4 \alpha_4} + \dots$

but they are identical!

Alternative: number basis

- Line up single-particle states in some order and just say how many in each state

$|n_1 n_2 n_3 \dots n_\infty\rangle = |n_1\rangle |n_2\rangle \dots |n_\infty\rangle$
 $\begin{matrix} \uparrow & \uparrow & \uparrow \\ a & b & c \end{matrix}$
 eg. 2 1 3 in example ↑ separate harmonic oscillator for each "mode"

- complete and orthonormal: $\langle n'_1 n'_2 \dots n'_\infty | n_1 n_2 \dots n_\infty \rangle = \delta_{n_1 n'_1} \dots \delta_{n_\infty n'_\infty}$

$$\sum_{n_1, n_2, \dots, n_\infty} |n_1, n_2, \dots, n_\infty\rangle \langle n_1, n_2, \dots, n_\infty| = 1$$

• bosons $n_i = 0, 1, 2, \dots, \infty$

• fermions $n_i = 0, 1$

- Use raising and lowering operators to change n_i (creation and destruction)

$$[a_\alpha, a_\beta]_{\mp} = [a_\alpha^\dagger, a_\beta^\dagger]_{\mp} = 0$$

$$[a_\alpha, a_\beta^\dagger]_{\mp} = \delta_{\alpha\beta}$$

where $\mp \Rightarrow$ bosons $[a, b]_{\mp} = ab - ba$
 fermions $[a, b]_{\mp} = ab + ba \Rightarrow [a, a] = 0$

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$$a_k |n_k\rangle = (n_k)^{1/2} |n_k-1\rangle \text{ "destruction operator"}$$

$$a_k^\dagger |n_k\rangle = (n_k+1)^{1/2} |n_k+1\rangle \text{ "creation operator"}$$

For fermions, $a_k |0\rangle = |1\rangle$ $a_k |1\rangle = 0$
 $a_k^\dagger |1\rangle = 0$ $a |0\rangle = 0$

$$|n_1 \dots n_\infty\rangle \equiv (a_1^\dagger)^{n_1} \dots (a_\infty^\dagger)^{n_\infty} |0\rangle \text{ implies signs}$$

$$a_k^\dagger a_k |n_1 \dots n_\infty\rangle = n_k |n_1 \dots n_\infty\rangle \Rightarrow a_k^\dagger a_k \equiv n_k \text{ "number operator"}$$

Key point: $i\hbar \frac{d}{dt} |\psi(t)\rangle = \hat{H} |\psi(t)\rangle$

with

$$\hat{H} = \sum_{\alpha\beta} a_\alpha^\dagger \langle \alpha | T | \beta \rangle a_\beta + \frac{1}{6} \sum_{\alpha\beta\gamma\delta} a_\alpha^\dagger a_\beta^\dagger a_\gamma^\dagger a_\delta \langle \alpha\beta | V | \gamma\delta \rangle a_\delta a_\gamma$$

+ [what does 3-body look like?] note order

- The symmetrization is taken care of by the a 's and a^\dagger 's.
- \hat{H} doesn't reference N
- only the relevant orbitals play a role — don't worry about the other 10^{23} !

Can switch to x -representation $|x\rangle = \int d\alpha |x\rangle \langle x | \alpha \rangle = \int d\alpha \psi_\alpha(x) | \alpha \rangle$
 also with these operators:

$$\hat{\psi}(x) = \sum_\alpha \psi_\alpha(x) a_\alpha \quad \hat{\psi}^\dagger(x) = \sum_\alpha a_\alpha^\dagger \psi_\alpha^*(x)$$

"field operators" create and destroy at x .

• We'll use these a lot!



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Boson Coherent states: What are the eigenstates of $a_\alpha, a_\alpha^\dagger$?

- Start with a one-level system (one dof.)

$$|n\rangle = \frac{(a^\dagger)^n}{\sqrt{n!}} |0\rangle \quad n=0, 1, 2, \dots$$

$$a|n\rangle = \sqrt{n}|n-1\rangle \quad \text{and} \quad a^\dagger|n\rangle = \sqrt{n+1}|n+1\rangle$$

so not eigenstates of either,

- But now superpose the $|n\rangle$'s so that the factorials work out.
 • Let z be a complex number (any one - like x representation)

$$\Rightarrow |z\rangle = e^{a^\dagger z} |0\rangle = \left(1 + a^\dagger z + \frac{1}{2}(a^\dagger z)(a^\dagger z) + \dots\right) |0\rangle$$

$$= \sum_{n=0}^{\infty} \frac{z^n}{\sqrt{n!}} |n\rangle$$

$$\text{Then } a|z\rangle = a|0\rangle + a \frac{z}{\sqrt{1!}} |1\rangle + a \frac{z^2}{\sqrt{2!}} |2\rangle + a \frac{z^3}{\sqrt{3!}} |3\rangle + \dots$$

$$= 0 + \frac{z}{\sqrt{1!}} a|0\rangle + \frac{z^2}{\sqrt{2!}} a|1\rangle + \frac{z^3}{\sqrt{3!}} a|2\rangle + \dots$$

$$= z \left(|0\rangle + \frac{z}{\sqrt{1!}} |1\rangle + \frac{z^2}{\sqrt{2!}} |2\rangle + \dots \right)$$

$$= z|z\rangle! \quad \text{eigenstate}$$

$$\text{Further, } \langle z| = \langle 0| e^{z^* a} = \sum_{n=0}^{\infty} \langle n| \frac{z^{*n}}{\sqrt{n!}} \quad \text{and} \quad \langle z| a^\dagger = \langle z| z^*,$$

$$\text{Now } \langle z|z'\rangle = e^{z^* z'} \Rightarrow \text{not orthogonal.}$$

$$\text{key} \Rightarrow \frac{\langle z| : A(a^\dagger, a) : |z'\rangle}{\langle z|z'\rangle} = A(z^*, z') \quad \text{just what we need!}$$

$$\text{note } \langle 0|z\rangle = 1, |z=0\rangle = |n=0\rangle = |0\rangle$$

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Claim: close relation is

$$\int \frac{dz d\bar{z}}{2\pi i} e^{-\bar{z}^* z} |z\rangle \langle z| = 1$$

↑ This means $z = x + iy$, $\int \frac{dx dy}{\pi} \quad -\infty < x, y < +\infty$

Proof: Substitute $|z\rangle$, $\langle z|$ definitions:

$$\begin{aligned} \int \frac{dz d\bar{z}}{2\pi i} e^{-\bar{z}^* z} |z\rangle \langle z| &= \int \frac{dz d\bar{z}}{2\pi i} \sum_{n,m} \frac{z^n \bar{z}^m}{\sqrt{n!m!}} |n\rangle \langle m| e^{-\bar{z}^* z} \\ &= \sum_{n,m} |n\rangle \langle m| \frac{1}{\sqrt{n!m!}} \int \frac{rd\bar{r}}{\pi} \int_0^{2\pi} d\theta r^{nm} e^{i(n-m)\theta} e^{-r^2} \\ &= \sum_n |n\rangle \langle n| = 1. \end{aligned}$$

For fermions, \Rightarrow Grassmann numbers• More later. For now, works the same except no 2π .

In particular:

$$\frac{\langle z| :A(a^\dagger, a): |z'\rangle}{\langle z|z'\rangle} = A(z^*, z)$$

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Coherent State Functional Integral: First Pass

This discussion is based largely on Negele and Orland, chapters 1 and 2.

We want to use the same procedure for evaluating the partition function (or, more generally, an evolution operator) by splitting the interval from 0 to β into little steps of size ϵ for which

$$e^{\epsilon \hat{H}} = :e^{\epsilon \hat{H}}: + O(\epsilon^2)$$

and we can insert intermediate states to evaluate $:e^{\epsilon \hat{H}}:$. Except now we want \hat{H} to be expressed in 2nd quantized form: a^\dagger 's and a 's.

normal ordering in this case will mean that a 's appear to the right of a^\dagger 's.

It won't help to use the number basis in general, because we need the analogy of $\langle p_n | \hat{H}(\hat{p}, \hat{x}) | x_n \rangle = H(p_n, x_n) \langle p_n | x_n \rangle \Rightarrow$ we need states that are eigenstates of the annihilation operators — these are the coherent states.

The steps are the same as before, only now we have $\hat{H} \rightarrow \hat{H}(a^\dagger, a)$ (and we assume it is normal ordered $\Rightarrow a^\dagger$'s to left, a 's to right).

We break up $[0, \beta]$ into N_T steps of width ϵ .

The partition function we want to use now is the grand partition function $Z = \text{Tr} e^{-\beta(\hat{H} - \mu \hat{N})}$ (note that coherent states do not have a definite number of particles, so we really need μ !).

our starting expression is (up to an overall constant)

$$Z = \text{Tr} e^{-\beta(\hat{H} - \mu \hat{N})} = \int \prod_{\alpha} d\phi_{\alpha}^* d\phi_{\alpha} e^{-\sum_{\alpha} \phi_{\alpha}^* \phi_{\alpha}} \langle \phi | e^{-\beta(\hat{H} - \mu \hat{N})} | \phi \rangle$$

+ for bosons
- for fermions

$$\frac{d(\operatorname{Re} \phi_\alpha) d(\operatorname{Im} \phi_\alpha)}{\pi}$$

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For bosons, this comes from inserting $\hat{1} = \int \prod_\alpha \frac{d\phi_\alpha^* d\phi_\alpha}{2\pi i} e^{-\sum_\alpha \phi_\alpha^* \phi_\alpha} |\phi\rangle\langle\phi|$

$$\begin{aligned} \operatorname{Tr} A &= \sum_n \langle n|A|n\rangle = \int \prod_\alpha \frac{d\phi_\alpha^* d\phi_\alpha}{2\pi i} e^{-\sum_\alpha \phi_\alpha^* \phi_\alpha} \sum_n \langle n|\phi\rangle\langle\phi|A|n\rangle \\ &= \int \prod_\alpha \frac{d\phi_\alpha^* d\phi_\alpha}{2\pi i} e^{-\sum_\alpha \phi_\alpha^* \phi_\alpha} \langle\phi|A\left(\sum_n |n\rangle\langle n|\right)|\phi\rangle \\ &= \int \prod_\alpha \frac{d\phi_\alpha^* d\phi_\alpha}{2\pi i} e^{-\sum_\alpha \phi_\alpha^* \phi_\alpha} \langle\phi|A|\phi\rangle. \end{aligned}$$

For fermions it is the same except no $2\pi i$ factors and we get a minus sign (hence $\langle\phi|\phi\rangle$) when moving A through $|\phi\rangle\langle\phi|$.

So now we insert at each time step $k=1, \dots, N_T$

$$1 = \frac{1}{C} \prod_\alpha \frac{d\phi_{\alpha,k}^* d\phi_{\alpha,k}}{2\pi i} e^{-\sum_\alpha \phi_{\alpha,k}^* \phi_{\alpha,k}} |\phi_{\alpha,k}\rangle\langle\phi_{\alpha,k}|$$

(constant) \rightarrow

We have

$$e^{\epsilon \hat{H}(a_\alpha^\dagger, a_\alpha)} = e^{\epsilon \hat{H}(a_\alpha^\dagger, a_\alpha)} + O(\epsilon^2)$$

and

$$\langle\phi|A(a_\alpha^\dagger, a_\alpha)|\phi\rangle = A(\phi_\alpha^*, \phi_\alpha') e^{\sum_\alpha \phi_\alpha^* \phi_\alpha'} \quad \leftarrow \text{from } \langle\phi|\phi\rangle$$

normal ordered

(either side)

\Rightarrow

$$\begin{aligned} Z &= \lim_{N_T \rightarrow \infty} \int \prod_\alpha \frac{1}{C} d\phi_\alpha^* d\phi_\alpha e^{-\sum_\alpha \phi_\alpha^* \phi_\alpha} \prod_{k=1}^{N_T-1} \int \prod_\alpha \frac{1}{C} d\phi_{\alpha,k}^* d\phi_{\alpha,k} e^{-\sum_{k=1}^{N_T-1} \sum_\alpha \phi_{\alpha,k}^* \phi_{\alpha,k}} \\ &\quad \times \prod_{k=1}^{N_T} \langle\phi_k| e^{-\epsilon \hat{H}(a_\alpha^\dagger, a_\alpha)} + O(\epsilon^2) |\phi_{k-1}\rangle \quad \leftarrow \text{Here } H = H_{\text{eff}} \end{aligned}$$

$$\text{Now } \langle\phi_k| e^{-\epsilon \hat{H}(a_\alpha^\dagger, a_\alpha)} |\phi_{k-1}\rangle = e^{\sum_\alpha \phi_{\alpha,k}^* \phi_{\alpha,k-1} - \epsilon H(\phi_{\alpha,k}^*, \phi_{\alpha,k-1})}$$

so we get another sum on k and α . We can also combine with the trace bc's that $\phi_{\alpha,0} = \phi_\alpha$, $\phi_{\alpha,N_T}^* = \phi_\alpha^*$ to get: (with $\phi_\alpha \equiv \phi_{\alpha,N_T}$)

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$$Z = \lim_{N_T \rightarrow \infty} \int \prod_{k=1}^{N_T} \prod_{\alpha} \frac{1}{\epsilon} d\phi_{\alpha,k}^* d\phi_{\alpha,k} e^{-S(\phi^*, \phi)}$$

where

$$S(\phi^*, \phi) = \epsilon \sum_{k=2}^{N_T} \left[\sum_{\alpha} \phi_{\alpha,k}^* \left\{ \frac{(\phi_{\alpha,k} - \phi_{\alpha,k-1})}{\epsilon} - \mu \phi_{\alpha,k-1} \right\} + H(\phi_{\alpha,k}^*, \phi_{\alpha,k-1}) \right] \\ + \epsilon \left[\sum_{\alpha} \phi_{\alpha,1}^* \left\{ \frac{\phi_{\alpha,1} - \phi_{\alpha,N_T}}{\epsilon} - \mu \phi_{\alpha,N_T} \right\} + H(\phi_{\alpha,1}^*, \phi_{\alpha,N_T}) \right]$$

boundary condition \rightarrow

• With $H \rightarrow H_0 = \sum_{\alpha} \epsilon_{\alpha} a_{\alpha}^{\dagger} a_{\alpha}$, we can (and will!) show that we reproduce

$$Z_0 = \prod_{\alpha} (1 - e^{-\epsilon(\epsilon_{\alpha} - \mu)})^{-1}$$

• The trajectory notation is

$$\{\phi_{\alpha,1}, \dots, \phi_{\alpha,N_T}\} \rightarrow \phi_{\alpha}(\tau)$$

and

$$\phi_{\alpha,k}^* \frac{(\phi_{\alpha,k} - \phi_{\alpha,k-1})}{\epsilon} = \phi_{\alpha}^*(\tau) \frac{\partial}{\partial \tau} \phi_{\alpha}(\tau)$$

$$H(\phi_{\alpha,k}^*, \phi_{\alpha,k-1}) \equiv H(\phi_{\alpha}^*(\tau), \phi_{\alpha}(\tau))$$

$$\Rightarrow Z = \int_{\phi_{\alpha}(0) = \phi_{\alpha}(1)} \mathcal{D}(\phi_{\alpha}^*(\tau), \phi_{\alpha}(\tau)) e^{-\int_0^1 d\tau \left\{ \sum_{\alpha} \phi_{\alpha}^*(\tau) \left(\frac{\partial}{\partial \tau} - \mu \right) \phi_{\alpha}(\tau) + H(\phi_{\alpha}^*(\tau), \phi_{\alpha}(\tau)) \right\}}$$

• integrations are over complex variables satisfying periodic BC's
for bosons and Grassman variables satisfying antiperiodic BC's
for fermions

• We can now do perturbation theory as before (with some generalizations!)

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- Rather than general α , let's go to the \vec{x} representation
so $\phi_\alpha(\tau) \rightarrow \psi(\vec{x}, \tau)$ where now α is just a spin index
and x means (\vec{x}, τ) where used. Assume a spin-independent potential for now.

$$\Rightarrow Z = \text{Tr} e^{-\beta(\hat{H} - \mu \hat{N})}$$

$$= \int \mathcal{D}[\psi(\vec{x}, \tau)] \mathcal{D}[\bar{\psi}(\vec{x}, \tau)] e^{-\frac{1}{\hbar} \int_0^{\beta \hbar} d\tau \int d^3x \bar{\psi}(\vec{x}, \tau) \left(\frac{\partial}{\partial \tau} - \frac{\nabla^2}{2m} - \mu \right) \psi(\vec{x}, \tau)}$$

$$\psi(\vec{x}, \beta) = \pm \psi(\vec{x}, 0)$$

(boson
Fermion)

$$\times e^{-\frac{1}{\hbar} \int_0^{\beta \hbar} d\tau \int d^3x \int d^3x' \bar{\psi}_p(\vec{x}, \tau) \psi_\alpha(\vec{x}', \tau) V(\vec{x} - \vec{x}') \psi_\alpha(\vec{x}', \tau) \psi_p(\vec{x}, \tau)}$$

$$\begin{aligned} V \Rightarrow -\lambda \delta(\vec{x} - \vec{x}') &\rightarrow \int \mathcal{D}[\psi(\vec{x}, \tau)] \mathcal{D}[\bar{\psi}(\vec{x}, \tau)] e^{-\frac{1}{\hbar} \int_0^{\beta \hbar} d\tau \int d^3x \bar{\psi}(\vec{x}, \tau) \left(\frac{\partial}{\partial \tau} - \frac{\nabla^2}{2m} - \mu \right) \psi(\vec{x}, \tau)} \\ &\quad \times e^{-\frac{\lambda}{\hbar} \int_0^{\beta \hbar} d\tau \int d^3x \int d^3x' \bar{\psi}_p(\vec{x}, \tau) \psi_\alpha(\vec{x}', \tau) \psi_p(\vec{x}', \tau) \psi_\alpha(\vec{x}, \tau)} \end{aligned}$$

$\psi(\vec{x}, \beta) = \pm \psi(\vec{x}, 0)$

- Now this is suitable for perturbation theory, and we'll do that, but what about stochastic simulations?

• Neither the boson nor fermion form is suitable here.

\Rightarrow introduce an auxiliary field:

$$Z = \int \mathcal{D}[\psi] \mathcal{D}[\bar{\psi}] \mathcal{D}[\sigma(x)] e^{-\int d\tau d^3x \int d^3x' \bar{\psi}(\vec{x}, \tau) \left[\frac{\partial}{\partial \tau} - \mu - \frac{\nabla^2}{2m} + \frac{1}{2} \int d^3y V(\vec{x} - \vec{y}) \sigma(\vec{y}, \tau) \right] \psi(\vec{x}, \tau)}$$

integrate
over ψ

$$= \int \mathcal{D}[\sigma(x)] [\det M(x)]^2 e^{-\frac{1}{2} \int d\tau \int d^3x \int d^3x' \sigma(\vec{x}, \tau) V(\vec{x} - \vec{x}') \sigma(\vec{x}', \tau)}$$

$$\text{where } M_{x\tau, x'\tau'} = \left[\frac{\partial}{\partial \tau} - \mu - \frac{\nabla^2}{2m} + \frac{1}{2} \int d^3y V(\vec{x} - \vec{y}) \sigma(\vec{y}, \tau) \right]_{x\tau, x'\tau'}$$

• much simplified if $V(\vec{x} - \vec{y}) \rightarrow -\lambda \delta(\vec{x} - \vec{y})$