CE100 Algorithms and Programming II

Week-6 (Matrix Chain Order / LCS)

Spring Semester, 2021-2022

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Matrix Chain Order / Longest Common Subsequence

Outline

- Elements of Dynamic Programming
 - Optimal Substructure
 - Overlapping Subproblems



- Recursive Matrix Chain Order Memoization
 - Top-Down Approach
 - RMC
 - MemoizedMatrixChain
 - LookupC
 - Dynamic Programming vs Memoization Summary



- Dynamic Programming
 - Problem-2 : Longest Common Subsequence
 - Definitions
 - LCS Problem
 - Notations
 - Optimal Substructure of LCS
 - Proof Case-1
 - Proof Case-2
 - Proof Case-3



- A recursive solution to subproblems (inefficient)
- Computing the length of and LCS
 - LCS Data Structure for DP
 - Bottom-Up Computation
- Constructing and LCS
 - PRINT-LCS
 - Back-pointer space optimization for LCS length



Most Common Dynamic Programming Interview Questions



Elements of Dynamic Programming

- When should we look for a DP solution to an optimization problem?
- Two key ingredients for the problem
 - Optimal substructure
 - Overlapping subproblems



DP Hallmark #1

- Optimal Substructure
 - A problem exhibits optimal substructure
 - if an optimal solution to a problem contains within it optimal solutions to subproblems
 - Example: matrix-chain-multiplication
 - lacktriangledown Optimal parenthesization of $A_1A_2\ldots A_n$ that splits the product between A_k and A_{k+1} , contains within it **optimal soln's** to the problems of parenthesizing $A_1A_2\ldots A_k$ and $A_{k+1}A_{k+2}\ldots A_n$



Optimal Substructure

- Finding a suitable space of subproblems
 - Iterate on subproblem instances
 - **Example:** *matrix-chain-multiplication*
 - Iterate and look at the structure of optimal soln's to subproblems, subsubproblems, and so forth
 - lacktriangle Discover that all subproblems consists of subchains of $\langle A_1,A_2,\ldots,A_n
 angle$
 - lacksquare Thus, the set of chains of the form $\langle A_i, A_{i+1}, \dots, A_j
 angle$ for $1 \leq i \leq j \leq n$
 - Makes a natural and reasonable space of subproblems



DP Hallmark #2

- Overlapping Subproblems
 - o Total number of distinct subproblems should be polynomial in the input size
 - When a recursive algorithm revisits the same problem over and over again,
 - We say that the optimization problem has overlapping subproblems



Overlapping Subproblems

- DP algorithms typically take advantage of overlapping subproblems
 - by solving each problem once
 - then storing the solutions in a table
 - where it can be looked up when needed
 - using constant time per lookup



Overlapping Subproblems

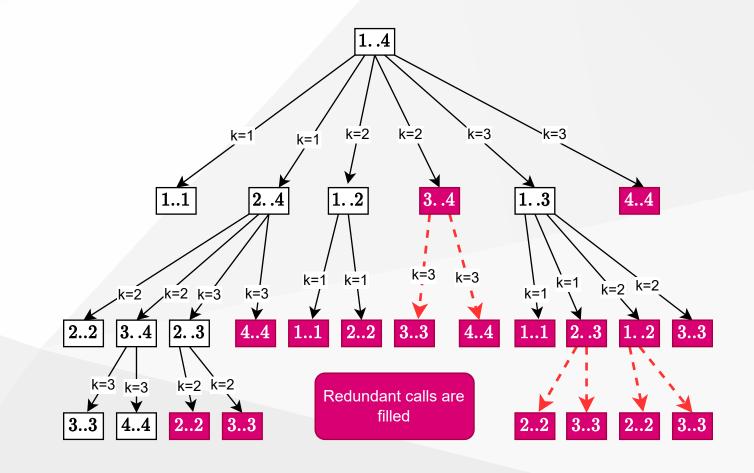
• Recursive matrix-chain order

$$egin{aligned} &\operatorname{RMC}(p,i,j) \{ \ &\operatorname{if}\ i=j\ \operatorname{then} \ &\operatorname{return}\ 0 \ &m[i,j] \leftarrow \infty \ &\operatorname{for}\ k \leftarrow i \operatorname{to}\ j-1 \operatorname{do} \ &q \leftarrow \operatorname{RMC}(p,i,k) + \operatorname{RMC}(p,k+1,j) + p_{i-1}p_kp_j \ &if\ q < m[i,j]\ \operatorname{then} \ &m[i,j] \leftarrow q \ &\operatorname{return}\ m[i,j]\ \} \end{aligned}$$



Direct Recursion: Inefficient!

- Recursion tree for RMC(p,1,4)
- ullet Nodes are labeled with i and j values





Running Time of RMC

$$T(1) \geq 1$$
 $T(n) \geq 1 + \sum\limits_{k=1}^{n-1} (T(k) + T(n-k) + 1) ext{ for } n > 1$

- ullet For $i=1,2,\ldots,n$ each term T(i) appears twice \circ Once as T(k), and once as T(n-k)
- ullet Collect $n-1,\,1$'s in the summation together with the front 1

$$T(n) \geq 2\sum_{i=1}^{n-1}T(i)+n$$

ullet Prove that $T(n)=\Omega(2n)$ using the substitution method



Running Time of RMC: Prove that $T(n) = \Omega(2n)$

- Try to show that $T(n) \geq 2^{n-1}$ (by substitution)
- ullet Base case: $T(1) \geq 1 = 2^0 = 2^{1-1}$ for n=1
- Ind. Hyp.:

$$T(i) \geq 2^{i-1} ext{ for all } i=1,2,\ldots,n-1 ext{ and } n \geq 2$$

$$T(n) \geq 2 \sum_{i=1}^{n-1} 2^{i-1} + n$$

$$egin{aligned} &= 2\sum_{i=1}^{n-1} 2^{i-1} + n \ &= 2(2^{n-1}-1) + n \ &= 2^{n-1} + (2^{n-1}-2+n) \ &\Rightarrow T(n) \geq 2^{n-1} \;\; ext{Q.E.D.} \end{aligned}$$



Running Time of RMC: $T(n) \geq 2^{n-1}$

Whenever

- a recursion tree for the natural recursive solution to a problem contains the same subproblem repeatedly
- the total number of different subproblems is small
 - lacktriangledown it is a good idea to see if $DP(Dynamic\ Programming)$ can be applied



Memoization

- ullet Offers the efficiency of the usual DP approach while maintaining ${f top-down}$ strategy
- Idea is to memoize the natural, but inefficient, recursive algorithm



Memoized Recursive Algorithm

- Maintains an entry in a table for the soln to each subproblem
- Each table entry contains **a special value** to indicate that the entry has yet to be filled in
- When the subproblem is first encountered its solution is computed and then stored in the table
- Each **subsequent** time that the subproblem encountered the value stored in the table is simply **looked up** and **returned**



Memoized Recursive Matrix-chain Order

Shaded subtrees are looked-up rather than recomputing

```
\Longrightarrow \operatorname{LookupC}(p,i,j)
  if m[i,j] = \infty then
     if i = j then
        m[i,j] \leftarrow 0
     else
        for k \leftarrow i to j - 1 do
            q \leftarrow \text{LookupC}(p, i, k) + \text{LookupC}(p, k + 1, j) + p_{i-1}p_kp_j
            if q < m[i, j] then
               m[i,j] \leftarrow q
  return m[i,j]
```

Memoized Recursive Algorithm

- The approach assumes that
 - The set of all possible subproblem parameters are known
 - The relation between the table positions and subproblems is established
- Another approach is to memoize
 - by using hashing with subproblem parameters as key



Dynamic Programming vs Memoization Summary (1)

- ullet Matrix-chain multiplication can be solved in $O(n^3)$ time
 - o by either a top-down memoized recursive algorithm
 - or a bottom-up dynamic programming algorithm
- Both methods exploit the **overlapping subproblems** property
 - \circ There are only $\Theta(n^2)$ different subproblems in total
 - Both methods compute the soln to each problem once
- Without memoization the natural recursive algorithm runs in exponential time since subproblems are solved repeatedly



Dynamic Programming vs Memoization Summary (2)

- In general practice
 - If all subproblems must be solved at once
 - a bottom-up DP algorithm always outperforms a top-down memoized algorithm by a constant factor
 - because, bottom-up DP algorithm
 - Has no overhead for recursion
 - Less overhead for maintaining the table
 - DP: Regular pattern of table accesses can be exploited to reduce the time and/or space requirements even further
 - Memoized: If some problems need not be solved at all, it has the advantage of avoiding solutions to those subproblems



Problem 3: Longest Common Subsequence

Definitions

- A subsequence of a given sequence is just the given sequence with some elements (possibly none) left out
- Example:

$$\circ X = \langle A, B, C, B, D, A, B \rangle$$

$$egin{aligned} \circ \ Z = \langle B, C, D, B
angle \end{aligned}$$

lacksquare Z is a subsequence of X

Problem 3: Longest Common Subsequence

Definitions

- ullet Formal definition: Given a sequence $X=\langle x_1,x_2,\ldots,x_m
 angle$, sequence $Z=\langle z_1,z_2,\ldots,z_k
 angle$ is a subsequence of X
 - \circ if \exists a **strictly increasing sequence** $\langle i_1,i_2,\ldots,i_k
 angle$ of indices of X such that $x_{i_j}=z_j$ for all $j=1,2,\ldots,k$, where $1\leq k\leq m$
- Example: $Z=\langle B,C,D,B
 angle$ is a subsequence of $X=\langle A,B,C,B,D,A,B
 angle$ with the index sequence $\langle i_1,i_2,i_3,i_4
 angle=\langle 2,3,5,7
 angle$



Problem 3: Longest Common Subsequence

Definitions

- ullet If Z is a subsequence of both X and Y, we denote Z as a **common subsequence** of X and Y.
- Example:

$$X = \langle A, B^*, C^*, B, D, A^*, B \rangle$$

 $Y = \langle B^*, D, C^*, A^*, B, A \rangle$

- ullet $Z_1=\langle B^*,C^*,A^*
 angle$ is a common subsequence (**of length 3**) of X and Y.
- ullet Two longest common subsequence (LCSs) of X and Y?

$$\circ \ Z2 = \langle B, C, B, A
angle$$
 of length 4

$$\circ \ Z3 = \langle B, D, A, B
angle$$
 of length 4

■ The optimal solution value = 4



Longest Common Subsequence (LCS) Problem

• LCS problem: Given two sequences

$$\circ \; X = \langle x_1, x_2, \ldots, x_m
angle$$
 and

$$\circ \; Y = \langle y_1, y_2, \ldots, y_n
angle$$
, find the **LCS** of $X\&Y$

- Brute force approach:
 - \circ Enumerate all subsequences of X
 - \circ Check if each subsequence is also a subsequence of Y
 - Keep track of the LCS
 - What is the complexity?
 - \circ There are 2^m subsequences of X
 - Exponential runtime



Notation

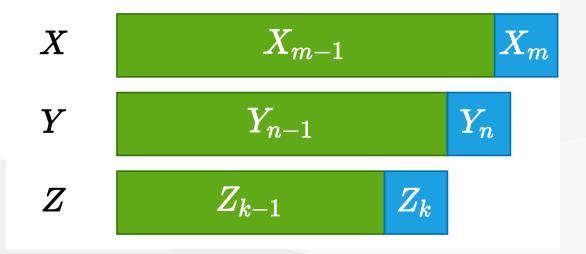
- ullet Notation: Let X_i denote the i^{th} prefix of X \circ i.e. $X_i = \langle x_1, x_2, \dots, x_i
 angle$
- Example:

$$X = \langle A, B, C, B, D, A, B
angle$$
 $X_4 = \langle A, B, C, B
angle$ $X_0 = \langle
angle$



Optimal Substructure of an LCS

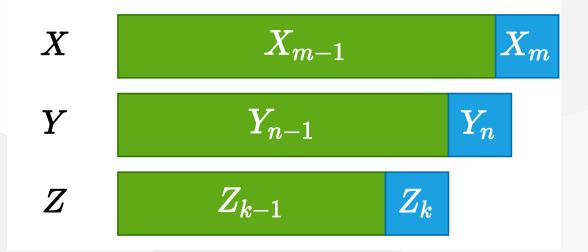
- ullet Let $X=< x1, x2, \ldots, xm>$ and $Y=\langle y_1, y_2, \ldots, y_n
 angle$ are given
- ullet Let $Z=\langle z_1,z_2,\ldots,z_k
 angle$ be an **LCS** of X and Y



- Question 1: If $x_m=y_n$, how to define the optimal substructure?
 - \circ We must have $z_k=x_m=y_n$ and
 - $egin{aligned} \circ \ Z_{k-1} = \mathrm{LCS}(X_{m-1}, Y_{n-1}) \end{aligned}$

Optimal Substructure of an LCS

- ullet Let $X=< x1, x2, \ldots, xm>$ and $Y=\langle y_1, y_2, \ldots, y_n
 angle$ are given
- ullet Let $Z=\langle z_1,z_2,\ldots,z_k
 angle$ be an **LCS** of X and Y

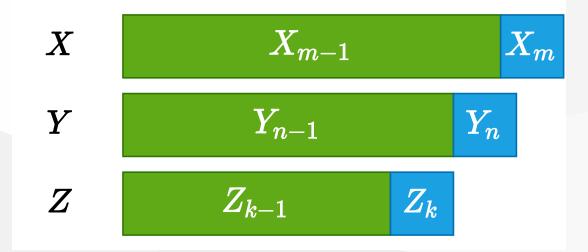


- Question 2: If $x_m \neq y_n \text{ and } z_k \neq x_m$, how to define the optimal substructure?
 - \circ We must have $Z=\mathrm{LCS}(X_{m-1},Y)$



Optimal Substructure of an LCS

- ullet Let $X=< x1, x2, \ldots, xm>$ and $Y=\langle y_1, y_2, \ldots, y_n
 angle$ are given
- ullet Let $Z=\langle z_1,z_2,\ldots,z_k
 angle$ be an **LCS** of X and Y



- Question 3: If $x_m \neq y_n$ and $z_k \neq y_n$, how to define the optimal substructure?
 - \circ We must have $Z = \mathrm{LCS}(X, Y_{n-1})$



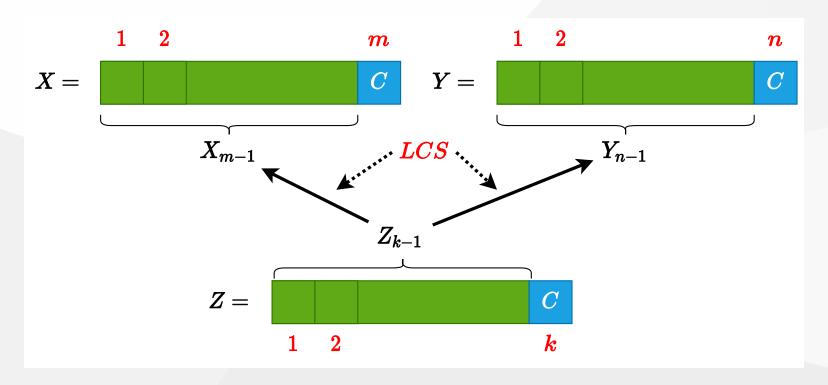
Theorem: Optimal Substructure of an LCS

- ullet Let $X=\langle x_1,x_2,\ldots,x_m
 angle$ and Y = <y1, y2, ..., yn> are given
- ullet Let $Z=\langle z_1,z_2,\ldots,z_k
 angle$ be an **LCS** of X and Y
- Theorem: Optimal substructure of an LCS:
 - \circ If $x_m=y_n$
 - lacksquare then $z_k=x_m=y_n$ and Z_{k-1} is an **LCS** of X_{m-1} and Y_{n-1}
 - \circ If $x_m
 eq y_n$ and $z_k
 eq x_m$
 - lacktriangle then Z is an **LCS** of X_{m-1} and Y
 - \circ If $x_m
 eq y_n$ and $z_k
 eq y_n$
 - lacktriangle then Z is an **LCS** of X and Y_{n-1}



Optimal Substructure Theorem (case 1)

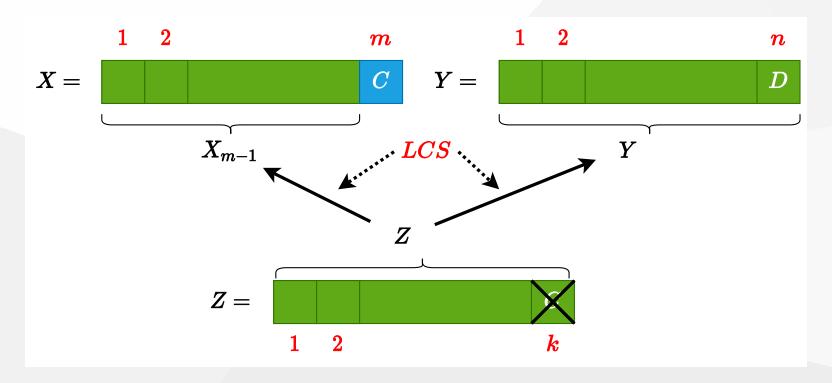
ullet If $x_m=y_n$ then $z_k=x_m=y_n$ and Z_{k-1} is an **LCS** of X_{m-1} and Y_{n-1}





Optimal Substructure Theorem (case 2)

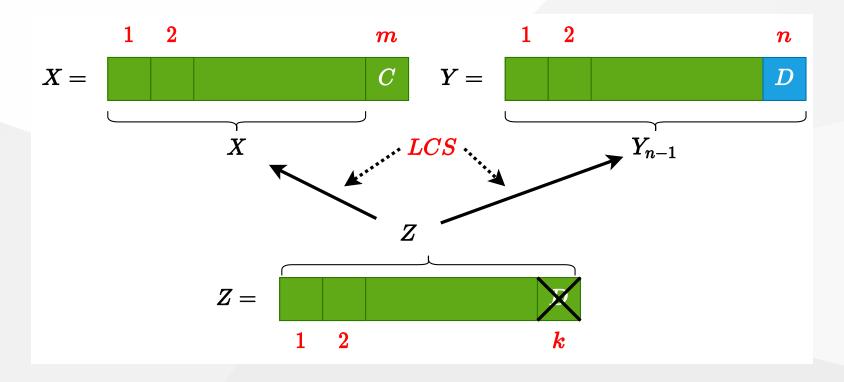
ullet If $x_m
eq y_n$ and $z_k
eq x_m$ then Z is an **LCS** of X_{m-1} and Y

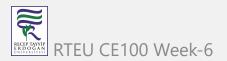




Optimal Substructure Theorem (case 3)

ullet If $x_m
eq y_n$ and $z_k
eq y_n$ then Z is an **LCS** of X and Y_{n-1}





Proof of Optimal Substructure Theorem (case 1)

- ullet If $x_m=y_n$ then $z_k=x_m=y_n$ and Z_{k-1} is an LCS of X_{m-1} and Y_{n-1}
- ullet Proof: If $z_k
 eq x_m = y_n$ then
 - \circ we can append $x_m=y_n$ to Z to obtain a common subsequence of length $k+1\Longrightarrow {\sf contradiction}$
 - \circ Thus, we must have $z_k=x_m=y_n$
 - \circ Hence, the prefix Z_{k-1} is a **length-(**k-1**) CS** of X_{m-1} and Y_{n-1}
- ullet We have to show that Z_{k-1} is in fact an LCS of X_{m-1} and Y_{n-1}
- Proof by contradiction:
 - \circ Assume that \exists a CS W of X_{m-1} and Y_{n-1} with |W|=k
 - \circ Then appending $x_m=y_n$ to W produces a **CS** of length k+1



Proof of Optimal Substructure Theorem (case 2)

- ullet If $x_m
 eq y_n$ and $z_k
 eq x_m$ then Z is an **LCS** of X_{m-1} and Y
- ullet Proof : If $z_k
 eq x_m$ then Z is a CS of X_{m-1} and Y_n
 - \circ We have to show that Z is in fact an LCS of X_{m-1} and Y_n
- (Proof by contradiction)
 - \circ Assume that \exists a CS W of X_{m-1} and Y_n with |W|>k
 - \circ Then W would also be a CS of X and Y
 - Contradiction to the assumption that
 - lacksquare Z is an LCS of X and Y with |Z|=k
- Case 3: Dual of the proof for (case 2)



A Recursive Solution to Subproblems

- Theorem implies that there are one or two subproblems to examine
- if $x_m = y_n$ then
 - \circ we must solve the subproblem of finding an **LCS** of $X_{m-1}\&Y_{n-1}$
 - \circ appending $x_m=y_n$ to this **LCS** yields an **LCS** of X&Y
- else
 - we must solve two subproblems
 - finding an LCS of $X_{m-1}\&Y$
 - finding an LCS of $X\&Y_{n-1}$
 - \circ longer of these two **LCS** s is an **LCS** of X&Y
- endif



Recursive Algorithm (Inefficient)

```
LCS(X,Y) {
   m \leftarrow length[X]
   n \leftarrow length[Y]
   if x_m = y_n then
       Z \leftarrow \mathrm{LCS}(X_{m-1}, Y_{n-1}) \triangleright \text{solve one subproblem}
       return \langle Z, x_m = y_n \rangle \triangleright append x_m = y_n to Z
   else
       Z^{'} \leftarrow \mathrm{LCS}(X_{m-1},Y) 	riangleright 	ext{solve two subproblems}
       Z^{''} \leftarrow \mathrm{LCS}(X, Y_{n-1})
       return longer of Z^{'} and Z^{''}
```

A Recursive Solution

ullet c[i,j] : length of an LCS of X_i and Y_j

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$



- We can easily write an **exponential-time recursive algorithm** based on the given recurrence. \Longrightarrow **Inefficient!**
- How many distinct subproblems to solve?
 - $\circ~\Theta(mn)$
- Overlapping subproblems property: Many subproblems share the same subsubproblems.
 - \circ e.g. Finding an LCS to $X_{m-1}\&Y$ and an LCS to $X\&Y_{n-1}$
 - \circ has the sub-subproblem of finding an **LCS** to $X_{m-1}\&Y_{n-1}$
- Therefore, we can use dynamic programming.



Data Structures

- Let:
 - $\circ\ c[i,j]:$ length of an LCS of X_i and Y_j
 - \circ b[i,j]: direction towards the table entry corresponding to the optimal subproblem solution chosen when computing c[i,j].
 - Used to simplify the construction of an optimal solution at the end.
- Maintain the following tables:
 - $\circ \ c[0 \dots m, 0 \dots n]$



Bottom-up Computation

• Reminder:

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$

- ullet How to choose the order in which we process c[i,j] values?
- ullet The values for c[i-1,j-1], c[i,j-1], and c[i-1,j] must be computed before computing c[i,j].



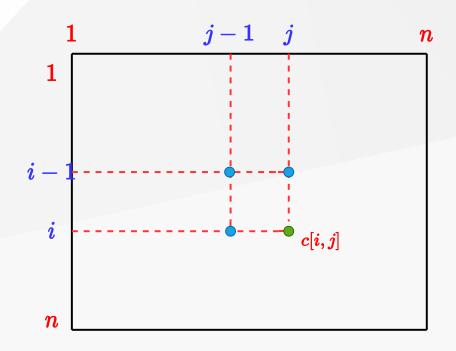
Bottom-up Computation

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$

Need to process:

after computing:

$$egin{aligned} c[i-1,j-1],\ c[i,j-1],\ c[i-1,j] \end{aligned}$$



Bottom-up Computation

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$

 \Downarrow

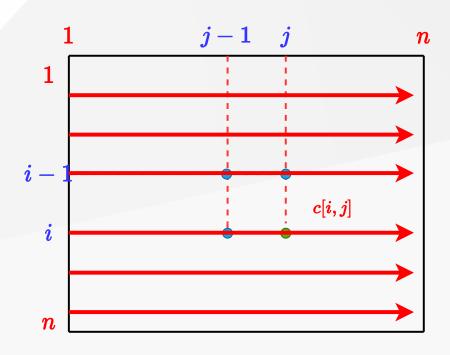
for $i \leftarrow 1$ to m

for $j \leftarrow 1$ to n

• •

. . .

$$c[i,j] = \cdots$$



$$rac{ ext{Total Runtime} = \Theta(mn)}{ ext{Total Space} = \Theta(mn)}$$

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j$	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0						
2B	0						
3C	0						
4B	0						
5D	0						
6A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} \rangle$$
 $Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} \rangle$

1	. i/j $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	†	†	1	← 1	1
	2B	0						
	3~C	0						
	4 B	0						
	5 D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

	. i/j $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	† 0	1 0	1	← 1	1
	2 B	0	1	← 1	← 1	1	2	\leftarrow 2
	3 C	0						
	4 B	0						
	5D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

1	. i/j $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\stackrel{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	1 0	1 0	1 0	<u>۲</u>	← 1	1
	2 B	0	1	\leftarrow 1	\leftarrow 1	1	2	\leftarrow 2
	3 C	0	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	$\leftarrow 2$	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	$egin{pmatrix} igwedge \ 2 \end{matrix}$
	4 B	0						
	5D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

-	$\downarrow i/j - i$	$ ightarrow 0 y_j$	1 <i>B</i>	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\stackrel{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	1 0	1 0	1 0	1	<u>←</u>	1
	2 B	0	1	← 1	← 1	1	2	\leftarrow 2
	3 C	0	1	1	2	\leftarrow 2	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1					
	5D	0						
	6~A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1A	0	† 0	1 0	† 0	<u>ر</u> 1	← 1	1
2 B	0	1	\leftarrow 1	<u>←</u>	1	2	\leftarrow 2
3 C	0	$egin{pmatrix} igwedge \ 1 \end{matrix}$	1	2	\leftarrow 2	$egin{array}{c} \uparrow \ 2 \end{array}$	1 2
4B	0	1	1				
5D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j - i$	$ ightarrow 0 y_j$	$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	†	1 0	\uparrow	1	<u>←</u>	1
2 B	0	1	<u>←</u>	← 1	1	2	$iggraphi_{f 2}$
3 C	0	$egin{pmatrix} igwedge \ 1 \end{matrix}$	1	2	$\leftarrow 2$	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	1	1	$egin{pmatrix} igwedge 2 \end{matrix}$			
5D	0						
6~A	0						
7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	† 0	† 0	† 0	<u>ر</u> 1	← 1	1
2 B	0	1	\leftarrow 1	<u>←</u>	1	2	\leftarrow 2
3 C	0	\uparrow 1	1	2	\leftarrow 2	1 2	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	1	1	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$		
5 D	0						
6~A	0						
7B	0						
			_				

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	† 0	† 0	† 0	1	← 1	1
2 B	0	1	\leftarrow 1	<u>←</u>	1	2	\leftarrow 2
3 C	0	\uparrow 1	1	2	\leftarrow 2	$egin{pmatrix} \uparrow & \ 2 & \ \end{matrix}$	† 2
4B	0	1	1	$egin{pmatrix} igwedge 2 \end{matrix}$	1 2	3	
5 D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	† 0	† 0	† 0	1	<u>←</u>	1
2 B	0	1	\leftarrow 1	<u>←</u>	1	2	$\leftarrow 2$
3 C	0	\uparrow 1	1	2	\leftarrow 2	$egin{pmatrix} \uparrow & \ 2 & \ \end{matrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$
4B	0	1	1	1 2	1 2	3	$\frac{\leftarrow}{3}$
5 D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	0	0	1 0	1	\leftarrow 1	1
2 B	0	1	\leftarrow 1	\leftarrow 1	1	2	$iggraphi_{f 2}$
3 C	0	\uparrow 1	1	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4 B	0	<u>۲</u>	1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	† 1	2	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	† 3	$egin{pmatrix} \uparrow \ 3 \end{bmatrix}$
6 A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

1	i/j - i	$\rightarrow 0y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	0	0	1	\leftarrow 1	<u>ر</u> 1
	2 B	0	1	\leftarrow 1	\leftarrow 1	1	2	$\leftarrow 2$
	3 C	0	1	\uparrow 1	2	\leftarrow 2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$
	4B	0	1	1	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\frac{\leftarrow}{3}$
	5 D	0	1	2	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{pmatrix} igspace 2 \end{matrix}$	\uparrow 3	3
	6A	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0						

Operation of LCS-LENGTH on the sequences

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} \rangle$$
 $Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} \rangle$

• Running-time = O(mn)since each table entry takes O(1) time to compute

↓	. $i/j ightarrow$	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	1 0	†	†	1	← 1	1
	2 B	0	1	← 1	← 1	$egin{pmatrix} \uparrow \\ 1 \end{bmatrix}$	2	$\leftarrow 2$
	3 C	0	1 1	$egin{pmatrix} lack \ 1 \end{matrix}$	2	\leftarrow 2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	$egin{pmatrix} \uparrow & & \\ 1 & & \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} igwedge 2 \end{matrix}$	3	$\leftarrow 3$
	5 D	0	$egin{pmatrix} \uparrow & \ 1 & \ \end{matrix}$	2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$	\uparrow 3	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	$egin{pmatrix} \uparrow \\ 1 \end{bmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	\uparrow 3	† 3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{bmatrix}$

$$X = \langle \stackrel{1}{A}, \stackrel{2}{B}, \stackrel{3}{C}, \stackrel{4}{B}, \stackrel{5}{D}, \stackrel{6}{A}, \stackrel{7}{B} \rangle$$
 $Y = \langle \stackrel{1}{B}, \stackrel{2}{D}, \stackrel{3}{C}, \stackrel{4}{A}, \stackrel{5}{B}, \stackrel{6}{A} \rangle$

- Running-time = O(mn)since each table entry takes O(1) time to compute
- LCS of $X\&Y = \langle B,C,B,A \rangle$

1	. i/j $ ightarrow$	$0y_j$	$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$egin{array}{c} 6 \ A \end{array}$
	$0x_i$	0	0	0	0	0	0	0
	1 <i>A</i>	0	$ \uparrow $	$ \uparrow $	1 0	1	← 1	1
	2 B	0	<u>ر</u> 1	← 1	← 1	\uparrow 1	2	$iggrup rac{\leftarrow}{2}$
	3 C	0	1	$egin{pmatrix} lack \ 1 \end{matrix}$	2	$\overset{\longleftarrow}{2}$	$egin{array}{c} oldsymbol{\uparrow} \ oldsymbol{2} \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	<u>ر</u> 1	$egin{pmatrix} lacktriangle & lacktriangle$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} oldsymbol{\uparrow} \ oldsymbol{2} \end{array}$	3	iggraphsize
	5 D	0	\uparrow 1	2	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$\stackrel{ o}{3}$	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	\uparrow 1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	\uparrow 3	\uparrow 3	4	↑ 4

Constructing an LCS

- ullet The b table returned by **LCS-LENGTH** can be used to quickly construct an **LCS** of X&Y
- ullet Begin at b[m,n] and trace through the table following arrows
- ullet Whenever you encounter a "widthick ullet" in entry b[i,j] it implies that $x_i=y_j$ is an element of **LCS**
- The elements of LCS are encountered in reverse order



Constructing an LCS

- The recursive procedure PRINT-LCS prints out LCS in proper order
- ullet This procedure takes O(m+n) time since at least one of i and j is decremented in each stage of the recursion

```
PRINT-LCS(b, X, i, j)
  if i = 0 or j = 0 then
  return
  if b[i,j] = " \nwarrow " then
    PRINT-LCS(b, X, i-1, j-1)
    print x_i
  else if b[i,j] = " \uparrow " then
    PRINT-LCS(b, X, i - 1, j)
  else
    PRINT-LCS(b, X, i, j - 1)
```

• The initial invocation: $\operatorname{PRINT-LCS}(b,X,length[X],length[Y])$

Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- Answer: Upper-left neighbor, because X[i] = Y[j].

\	. $i/j ightarrow$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\overset{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	1 0	0	1 0	1	\leftarrow 1	
	2 B	0	1	\leftarrow 1	← 1	$egin{pmatrix} ightarrow \ 1 \end{matrix}$	2	$oxed{\leftarrow 2}$
	3 C	0	1	1	2	\leftarrow 2	$egin{pmatrix} egin{pmatrix} egi$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$oxed{\leftarrow 3}$
	5 D	0	1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	$egin{array}{c} \uparrow \ 3 \end{array}$	$egin{array}{c} \uparrow \ 3 \end{array}$
	6 A	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	† 3	† 3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{bmatrix}$

Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- ullet Answer: Left neighbor, because X[i]
 eq Y[j] and LCS[i,j-1] > LCS[i-1,j].

↓	. $i/j ightarrow i$	$0y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	↑ 0	†	1	← 1	1
	2 B	0	1	\leftarrow 1	\leftarrow 1	1	2	$iggraphi_{f 2}$
	3 C	0	1	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5 D	0	1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	† 3	$egin{pmatrix} \uparrow \ 3 \end{bmatrix}$
	6A	0	1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	† 3	† 3	4	$egin{array}{c} \uparrow \ oldsymbol{4} \end{array}$

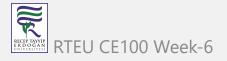
Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- ullet Answer: Upper neighbor,because X[i]
 eq Y[j] and LCS[i,j-1] = LCS[i-1,j]. (See pseudo-code to see how ties are handled.)

↓ 1	i/j ightarrow	$0y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1A	0	†	1 0	†	1	← 1	
	2B	0	1	\leftarrow 1	\leftarrow 1	1 1	2	$oxed{\leftarrow 2}$
	3 C	0	\uparrow 1	1 1	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1	1 1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	3	iggraphsize
	5D	0	\uparrow 1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	† 3	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	1	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} egin{pmatrix} egi$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	† 3	† 3	4	$egin{array}{c} \uparrow \ 4 \end{array}$

Improving the Space Requirements

- We can eliminate the b table altogether
 - \circ each c[i,j] entry depends only on 3 other c table entries: c[i-1,j-1], c[i-1,j] and c[i,j-1]
- Given the value of c[i,j]:
 - \circ We can determine in O(1) time which of these 3 values was used to compute c[i,j] without inspecting table b
 - \circ We save $\Theta(mn)$ space by this method
 - \circ However, space requirement is still $\Theta(mn)$ since we need $\Theta(mn)$ space for the c table anyway



- ullet To compute c[i,j], we only need c[i-1,j-1], c[i-1,j],and c[i-1,j-1]
- So, we can store only the last two rows.

$\downarrow i/j -$	$0y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	\uparrow	1 0	1 0	1	← 1	1
2 B	0	1	← 1	$\stackrel{\longleftarrow}{1}$	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	2	$oxed{\leftarrow 2}$
3 C	0	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	<u>ر</u> 1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	† 3	$egin{array}{c} \uparrow \ 3 \end{array}$
6~A	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} egi$	3	† 3	4
7 B	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	1 3	1 3	4	$egin{pmatrix} \uparrow \\ 4 \end{bmatrix}$

- $oldsymbol{\circ}$ To compute c[i,j], we only need c[i-1,j-1], c[i-1,j], and c[i-1,j-1]
- So, we can store only the last two rows.

$\downarrow i/j$ $-$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	†	† 0	†	1	← 1	1
2 B	0	1	\leftarrow 1	← 1	$egin{pmatrix} ightarrow \ egin{pmatrix} ightarrow \ ightarrow \ \end{bmatrix}$	2	$oxed{\leftarrow 2}$
3 C	0	1	1	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4 B	0	<u>ر</u> 1	† 1	\uparrow 2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	† 1	2	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} egi$	\uparrow 3	↑ 3
6 A	0	† 1	$egin{pmatrix} igspace 2 \end{matrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
7 B	0	<u>۲</u>	$egin{pmatrix} ightarrow{1}{2} \ \end{array}$	† 3	† 3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

- $oldsymbol{\circ}$ To compute c[i,j], we only need c[i-1,j-1], c[i-1,j], and c[i-1,j-1]
- So, we can store only the last two rows.
- This reduces space complexity from $\Theta(mn)$ to $\Theta(n)$.
- Is there a problem with this approach?

1	i/j ightharpoonup i	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\stackrel{ extbf{2}}{D}$	$\overset{3}{C}$	$egin{array}{c} A \ A \end{array}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	0	†	1	← 1	1
	2 B	0	1	\leftarrow 1	$\stackrel{\longleftarrow}{1}$	1	2	$iggrup_{f 2}$
	3 C	0	1	1	2	$\leftarrow 2$	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5D	0	† 1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$	$\uparrow 3$	↑ 3
	6A	0	† 1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	† 3	3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

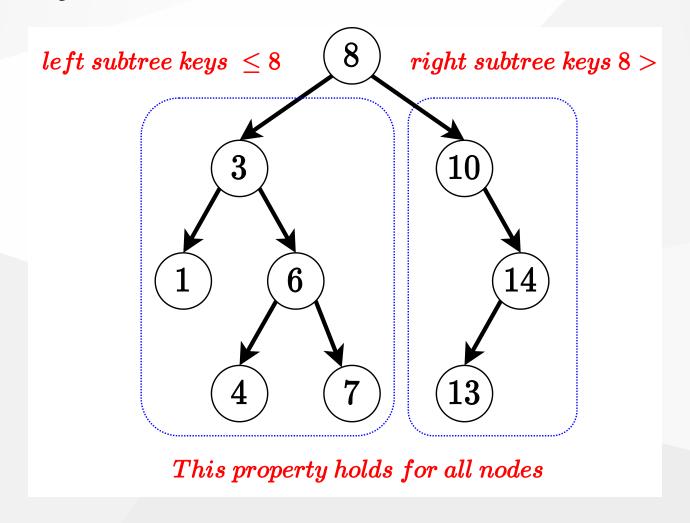
- Is there a problem with this approach?
 - We cannot construct the optimal solution because we cannot backtrace anymore.
 - This approach works if we only need the length of an LCS, not the actual LCS.

↓	. $i/j ightarrow$	$0y_j$	$\overset{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	1 0	†	1	← 1	1
	2 B	0	1	\leftarrow 1	← 1	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	iggraphi
	3 C	0	1	1	2	\leftarrow 2	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5 D	0	† 1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 3 \end{array}$	↑ 3
	6A	0	† 1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	† 3	3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

Problem 4 Optimal Binary Search Tree



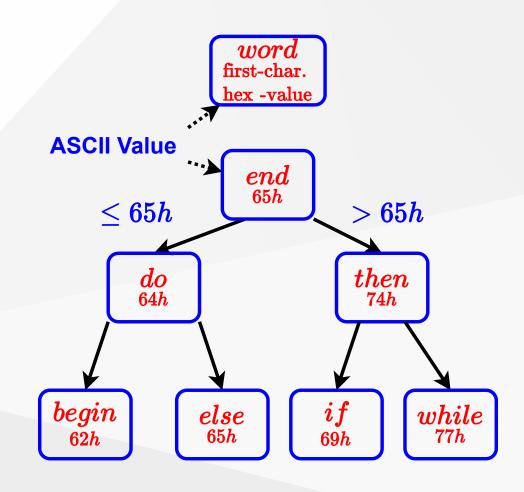
Reminder: Binary Search Tree (BST)





Binary Search Tree Example

- Example: English-to-French translation
 - Organize (English, French) word pairs in a BST
 - Keyword: English word
 - Satellite Data: French word
- We can search for an English word (node key) efficiently, and return the corresponding French word (satellite data).



ASCII Table

Dec	Hex	0ct	Char	Dec	Hex	0ct	Char	Dec	Hex	0ct	Char	Dec	Hex	0ct	Char
0	0	0		32	20	40	[space]	64	40	100	@	96	60	140	`
1	1	1		33	21	41	!	65	41	101	Α	97	61	141	a
2	2	2		34	22	42	"	66	42	102	В	98	62	142	b
3	3	3		35	23	43	#	67	43	103	С	99	63	143	С
4	4	4		36	24	44	\$	68	44	104	D	100	64	144	d
5	5	5		37	25	45	%	69	45	105	E	101	65	145	e
6	6	6		38	26	46	&	70	46	106	F	102	66	146	f
7	7	7		39	27	47		71	47	107	G	103	67	147	g
8	8	10		40	28	50	(72	48	110	Н	104	68	150	h
9	9	11		41	29	51)	73	49	111	1	105	69	151	i
10	Α	12		42	2A	52	*	74	4A	112	J	106	6A	152	j
11	В	13		43	2B	53	+	75	4B	113	K	107	6B	153	k
12	C	14		44	2C	54	,	76	4C	114	L	108	6C	154	1
13	D	15		45	2D	55	-	77	4D	115	M	109	6D	155	m
14	Е	16		46	2E	56		78	4E	116	N	110	6E	156	n
15	F	17		47	2F	57	/	79	4F	117	Ο	111	6F	157	0
16	10	20		48	30	60	0	80	50	120	Р	112	70	160	р
17	11	21		49	31	61	1	81	51	121	Q	113	71	161	q
18	12	22		50	32	62	2	82	52	122	R	114	72	162	r
19	13	23		51	33	63	3	83	53	123	S	115	73	163	S
20	14	24		52	34	64	4	84	54	124	Т	116	74	164	t
21	15	25		53	35	65	5	85	55	125	U	117	75	165	u
22	16	26		54	36	66	6	86	56	126	V	118	76	166	V
23	17	27		55	37	67	7	87	57	127	W	119	77	167	W
24	18	30		56	38	70	8	88	58	130	X	120	78	170	X
25	19	31		57	39	71	9	89	59	131	Υ	121	79	171	У
26	1A	32		58	3A	72	:	90	5A	132	Z	122	7A	172	Z
27	1B	33		59	3B	73	;	91	5B	133	[123	7B	173	{
28	1C	34		60	3C	74	<	92	5C	134	\	124	7C	174	
29	1D	35		61	3D	75	=	93	5D	135]	125	7D	175	}
30	1E	36		62	3E	76	>	94	5E	136	^	126	7E	176	~
31	1F	37		63	3F	77	?	95	5F	137	_	127	7F	177	

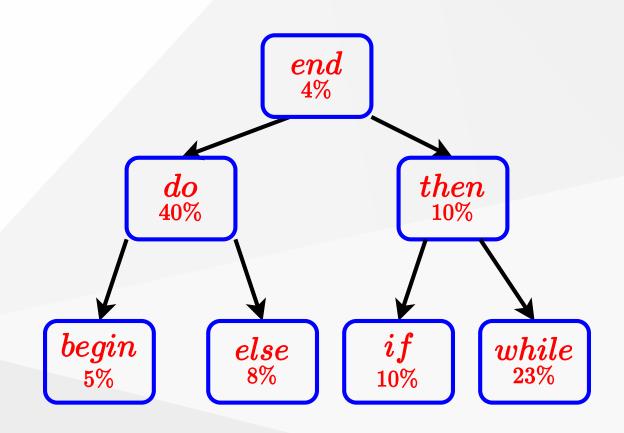


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Binary Search Tree Example

Suppose we know the frequency of each keyword in texts:

$$\frac{begin}{5\%}, \frac{do}{40\%}, \frac{else}{8\%}, \frac{end}{4\%}, \frac{if}{10\%}, \frac{then}{10\%}, \frac{while}{23\%},$$



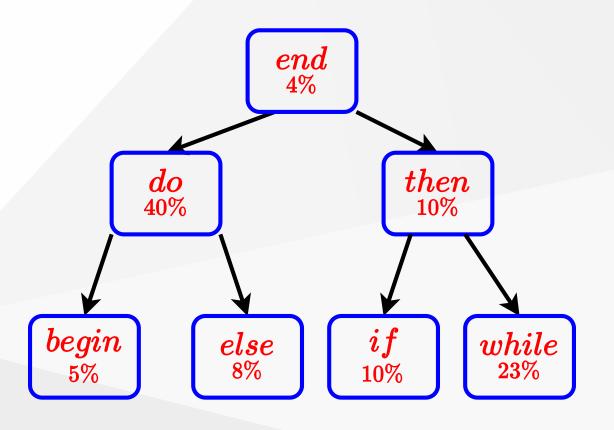


Cost of a Binary Search Tree

Example: If we search for keyword "while", we need

to access 3 nodes. So, 23 of the queries will have cost of 3.

$$egin{aligned} ext{Total Cost} &= \sum_i (ext{depth}(i) + 1) ext{freq}(i) \ &= 1 imes 0.04 + 2 imes 0.4 + \ 2 imes 0.1 + 3 imes 0.05 + \ 3 imes 0.08 + 3 imes 0.1 + \ 3 imes 0.23 \ &= 2.42 \end{aligned}$$





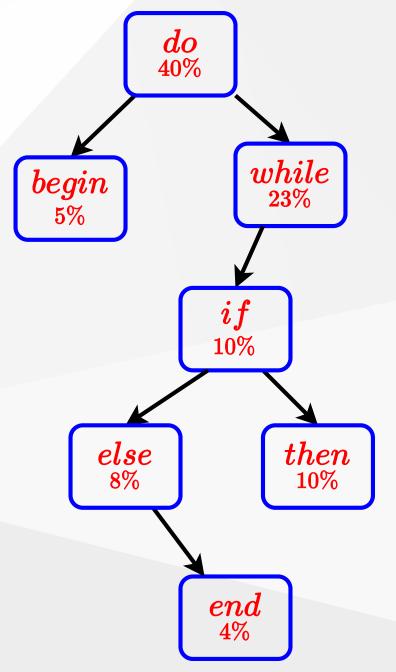
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This is in fact an optimal BST.





Optimal Binary Search Tree Problem

- Given:
 - \circ A collection of n keys $K_1 < K_2 < \ldots K_n$ to be stored in a **BST**.
 - \circ The corresponding p_i values for $1 \leq i \leq n$
 - p_i : probability of searching for key K_i
- Find:
 - An optimal BST with minimum total cost:

$$ext{Total Cost} = \sum_i (ext{depth}(i) + 1) ext{freq}(i)$$

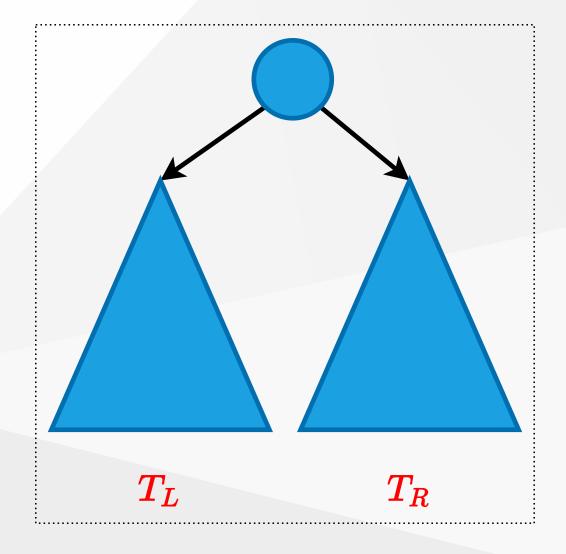
• Note: The BST will be static. Only search operations will be performed. No insert, no delete, etc.

Cost of a Binary Search Tree

• Lemma 1: Let Tij be a BST containing keys $K_i < K_{i+1} < \cdots < K_j$. Let T_L and T_R be the left and right subtrees of T. Then we have:

$$\mathrm{cost}(T_{ij}) = \mathrm{cost}(T_L) + \mathrm{cost}(T_R) + \sum_{h=i}^{j} p_h$$

Intuition: When we add the root node, the depth of each node in T_L and T_R increases by 1. So, the cost of node h increases by p_h . In addition, the cost of root node r is p_r . That's why, we have the last term at the end of the formula above.





Optimal Substructure Property

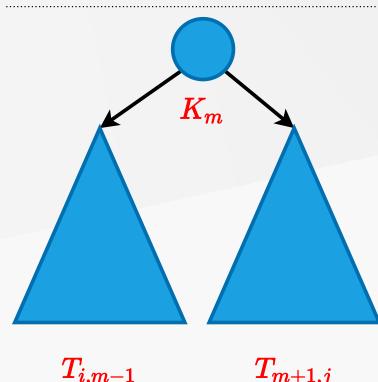
- Lemma 2: Optimal substructure property
 - \circ Consider an optimal BST T_{ij} for keys $K_i < K_{i+1} <$ $\cdots < K_i$
 - \circ Let K_m be the key at the root of T_{ij}
- Then:
 - $\circ T_{i,m-1}$ is an **optimal BST** for subproblem containing keys:

•
$$K_i < \cdots < K_{m-1}$$

 $\circ T_{m+1,j}$ is an **optimal BST** for subproblem containing keys:

•
$$K_{m+1} < \cdots < K_j$$

$$\operatorname{cost}(T_{ij}) = \operatorname{cost}(T_{i,m-1}) + \operatorname{cost}(T_{m+1,j}) + \sum_{h=i}^{j} p_h$$



Recursive Formulation

- Note: We don't know which root vertex leads to the minimum total cost. So, we need to try each vertex m, and choose the one with minimum total cost.
- ullet c[i,j]: cost of an optimal BST T_{ij} for the subproblem $K_i < \cdots < K_j$

$$c[i,j] = \left\{egin{array}{l} 0 & ext{if } i>j \ \min_{i \leq r \leq j} \{c[i,r-1] + c[r+1,j] + P_{ij}\} \end{array}
ight. ext{otherwise}
ight.$$
 where $P_{ij} = \sum_{h=i}^{j} p_h$



Bottom-up computation

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if } i>j \ \min_{i \leq r \leq j} \{c[i,r-1] + c[r+1,j] + P_{ij}\} & ext{otherwise} \end{array}
ight.$$

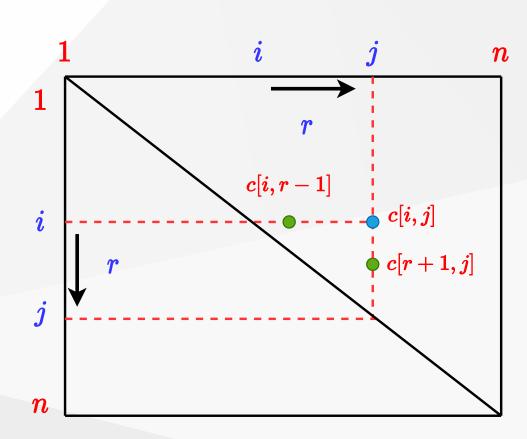
- ullet How to choose the order in which we process c[i,j] values?
- ullet Before computing c[i,j], we have to make sure that the values for c[i,r-1] and c[r+1,j] have been computed for all r.



Bottom-up computation

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if } i>j \ \min_{i \leq r \leq j} \{c[i,r-1] + c[r+1,j] + P_{ij}\} \end{array}
ight. ext{otherwise}$$

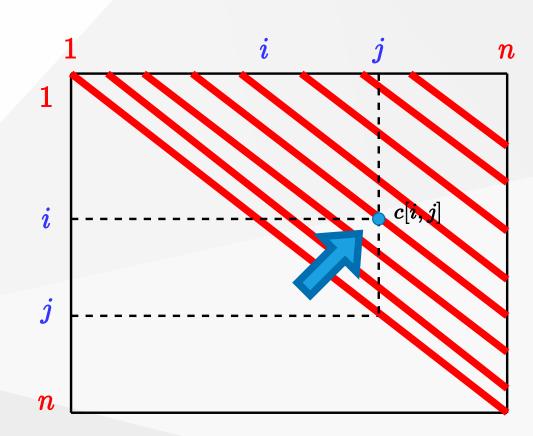
ullet c[i,j] must be processed after c[i,r-1] and c[r+1,j]



Bottom-up computation

$$c[i,j] = \left\{egin{array}{l} 0 & ext{if } i>j \ \min_{i \leq r \leq j} \{c[i,r-1] + c[r+1,j] + P_{ij}\} \end{array}
ight. ext{otherwise}$$

ullet If the entries c[i,j] are computed in the shown order, then c[i,r-1] and c[r+1,j] values are guaranteed to be computed before c[i,j].





Computing the Optimal BST Cost

```
OPTIMAL-BST-COST(p, n)
  for i \leftarrow 1 to n do
      c[i,i-1] \leftarrow 0
      c[i,i] \leftarrow p[i]
      R[i,j] \leftarrow i
  PS[1] \leftarrow p[1] \iff PS[i] \rightarrow \text{ prefix-sum } (i) : \text{Sum of all } p[j] \text{ values for } j \leq i
  for i \leftarrow 2 to n do
      PS[i] \leftarrow p[i] + PS[i-1] \iff \text{compute the prefix sum}
  for d \leftarrow 1 to n-1 do \iff BSTs with d+1 consecutive keys
      for i \leftarrow 1 to n-d do
        j \leftarrow i + d
         c[i,j] \leftarrow \infty
         for r \leftarrow i to j do
            q \leftarrow min\{c[i, r-1] + c[r+1, j]\} + PS[j] - PS[i-1]\}
            if q < c[i, j] then
               c[i,j] \leftarrow q
               R[i,j] \leftarrow r
  return c[1, n], R
```

Note on Prefix Sum

• We need P_{ij} values for each $i, j (1 \le i \le n \text{ and } 1 \le j \le n)$, where:

$$P_{ij} = \sum_{h=i}^{j} p_h$$

- If we compute the summation directly for every (i,j) pair, the runtime would be $\Theta(n^3)$.
- Instead, we spend O(n) time in preprocessing to compute the prefix sum array **PS**. Then we can compute each P_{ij} in O(1) time using **PS**.



Note on Prefix Sum

- In preprocessing, compute for each i:
 - $\circ \ PS[i]$: the sum of p[j] values for $1 \leq j \leq i$
- Then, we can compute P_{ij} in O(1) time as follows:

$$\circ \ P_{ij} = PS[i] – PS[j-1]$$

• Example:

$$p: 0.\overset{1}{05} \ 0.\overset{2}{02} \ 0.\overset{3}{06} \ 0.\overset{4}{07} \ 0.\overset{5}{20} \ 0.\overset{6}{05} \ 0.\overset{7}{08} \ 0.\overset{8}{02}$$

$$PS: 0.05 \stackrel{1}{0.07} \stackrel{2}{0.13} \stackrel{3}{0.20} \stackrel{4}{0.40} \stackrel{5}{0.45} \stackrel{6}{0.53} \stackrel{7}{0.55}$$

$$P_{27} = PS[7] - PS[1] = 0.53 - 0.05 = 0.48$$

$$P_{36} = PS[6] - PS[2] = 0.45 - 0.07 = 0.38$$



Most Common Dynamic Programming Interview Questions



- Problem-1: Longest Increasing Subsequence
 - https://www.geeksforgeeks.org/longest-increasing-subsequence-dp-3/
 - https://en.wikipedia.org/wiki/Longest_increasing_subsequence#:~:text=In
 computer science%2C the longest,not necessarily contiguous%2C or unique.
 - https://www.youtube.com/watch?v=22s1xxRvy28&ab_channel=StableSort



- Problem-2: Edit Distance
 - https://www.geeksforgeeks.org/edit-distance-dp-5/
 - https://www.youtube.com/watch?
 v=tU2f2JwHmfQ&feature=youtu.be&ab_channel=PrepForTech
 - Recursive
 - https://www.youtube.com/watch?v=8Q2IEIY2pDU&ab_channel=BenLangmead
 - o DP
 - https://www.youtube.com/watch? v=0KzWq118UNI&ab_channel=BenLangmead
 - https://www.youtube.com/watch? v=eAVGRWSryGo&ab_channel=BenLangmead



- Problem-3: Partition a set into two subsets such that the difference of subset sums is minimum
 - https://www.geeksforgeeks.org/partition-a-set-into-two-subsets-such-thatthe-difference-of-subset-sums-is-minimum/
- Problem-4: Count number of ways to cover a distance
 - https://www.geeksforgeeks.org/count-number-of-ways-to-cover-a-distance/
- Problem-5: Find the longest path in a matrix with given constraints
 - https://www.geeksforgeeks.org/find-the-longest-path-in-a-matrix-with-givenconstraints/



- Problem-6: Subset Sum Problem
 - https://www.geeksforgeeks.org/subset-sum-problem-dp-25/
- Problem-7: Optimal Strategy for a Game
 - https://www.geeksforgeeks.org/optimal-strategy-for-a-game-dp-31/
- Problem-8: 0-1 Knapsack Problem
 - https://www.geeksforgeeks.org/0-1-knapsack-problem-dp-10/



- Problem-9: Boolean Parenthesization Problem
 - https://www.geeksforgeeks.org/boolean-parenthesization-problem-dp-37/
- Problem-10: Shortest Common Supersequence
 - https://www.geeksforgeeks.org/shortest-common-supersequence/
 - https://en.wikipedia.org/wiki/Shortest_common_supersequence_problem
- Problem-11: Partition Problem
 - https://www.geeksforgeeks.org/partition-problem-dp-18/
- Problem-12: Cutting a Rod
 - https://www.geeksforgeeks.org/cutting-a-rod-dp-13/



- Problem-13: Coin Change
- Problem-14: Word Break Problem
- Problem-15: Maximum Product Cutting

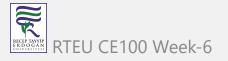


- Problem-16: Dice Throw
 - https://www.geeksforgeeks.org/dice-throw-dp-30/
- Problem-17: Box Stacking Problem
 - https://www.geeksforgeeks.org/box-stacking-problem-dp-22/
- Problem-18: Egg Dropping Puzzle
 - https://www.geeksforgeeks.org/egg-dropping-puzzle-dp-11/



References

- Introduction to Algorithms, Third Edition | The MIT Press
- Bilkent CS473 Course Notes (new)
- Bilkent CS473 Course Notes (old)



$$-End-Of-Week-6-Course-Module-$$

