CE100 Algorithms and Programming II

Week-6 (Matrix Chain Order / LCS)

Spring Semester, 2021-2022

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Matrix Chain Order / Longest Common Subsequence

Outline

- Elements of Dynamic Programming
 - Optimal Substructure
 - Overlapping Subproblems



- Recursive Matrix Chain Order Memoization
 - Top-Down Approach
 - RMC
 - MemoizedMatrixChain
 - LookupC
 - Dynamic Programming vs Memoization Summary



- Dynamic Programming
 - Problem-2 : Longest Common Subsequence
 - Definitions
 - LCS Problem
 - Notations
 - Optimal Substructure of LCS
 - Proof Case-1
 - Proof Case-2
 - Proof Case-3



- A recursive solution to subproblems (inefficient)
- Computing the length of and LCS
 - LCS Data Structure for DP
 - Bottom-Up Computation
- Constructing and LCS
 - PRINT-LCS
 - Back-pointer space optimization for LCS length



Most Common Dynamic Programming Interview Questions



Elements of Dynamic Programming

- When should we look for a DP solution to an optimization problem?
- Two key ingredients for the problem
 - Optimal substructure
 - Overlapping subproblems



DP Hallmark #1

- Optimal Substructure
 - A problem exhibits optimal substructure
 - if an optimal solution to a problem contains within it optimal solutions to subproblems
 - Example: matrix-chain-multiplication
 - lacktriangledown Optimal parenthesization of $A_1A_2\ldots A_n$ that splits the product between A_k and A_{k+1} , contains within it **optimal soln's** to the problems of parenthesizing $A_1A_2\ldots A_k$ and $A_{k+1}A_{k+2}\ldots A_n$



Optimal Substructure

- Finding a suitable space of subproblems
 - Iterate on subproblem instances
 - **Example:** *matrix-chain-multiplication*
 - Iterate and look at the structure of optimal soln's to subproblems, subsubproblems, and so forth
 - lacktriangle Discover that all subproblems consists of subchains of $\langle A_1,A_2,\ldots,A_n
 angle$
 - lacksquare Thus, the set of chains of the form $\langle A_i, A_{i+1}, \dots, A_j
 angle$ for $1 \leq i \leq j \leq n$
 - Makes a natural and reasonable space of subproblems



DP Hallmark #2

- Overlapping Subproblems
 - o Total number of distinct subproblems should be polynomial in the input size
 - When a recursive algorithm revisits the same problem over and over again,
 - We say that the optimization problem has overlapping subproblems



Overlapping Subproblems

- DP algorithms typically take advantage of overlapping subproblems
 - by solving each problem once
 - then storing the solutions in a table
 - where it can be looked up when needed
 - using constant time per lookup



Overlapping Subproblems

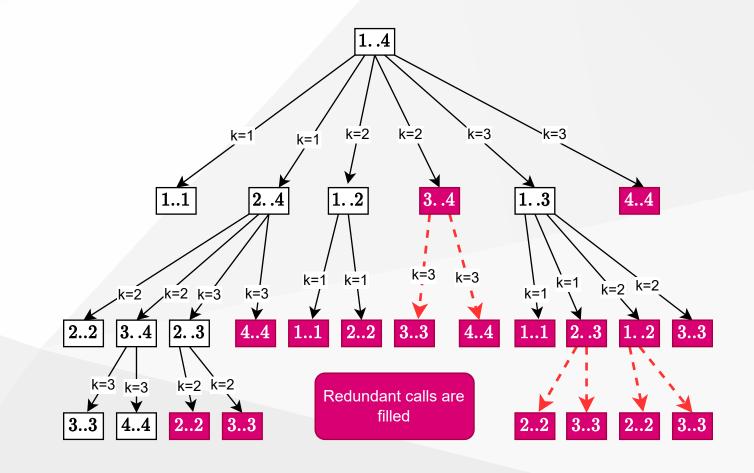
• Recursive matrix-chain order

$$egin{aligned} &\operatorname{RMC}(p,i,j) \{ \ &\operatorname{if}\ i=j\ \operatorname{then} \ &\operatorname{return}\ 0 \ &m[i,j] \leftarrow \infty \ &\operatorname{for}\ k \leftarrow i \operatorname{to}\ j-1 \operatorname{do} \ &q \leftarrow \operatorname{RMC}(p,i,k) + \operatorname{RMC}(p,k+1,j) + p_{i-1}p_kp_j \ &if\ q < m[i,j]\ \operatorname{then} \ &m[i,j] \leftarrow q \ &\operatorname{return}\ m[i,j]\ \} \end{aligned}$$



Direct Recursion: Inefficient!

- Recursion tree for RMC(p,1,4)
- ullet Nodes are labeled with i and j values





Running Time of RMC

$$T(1) \geq 1$$
 $T(n) \geq 1 + \sum\limits_{k=1}^{n-1} (T(k) + T(n-k) + 1) ext{ for } n > 1$

- ullet For $i=1,2,\ldots,n$ each term T(i) appears twice \circ Once as T(k), and once as T(n-k)
- ullet Collect $n-1,\,1$'s in the summation together with the front 1

$$T(n) \geq 2\sum_{i=1}^{n-1}T(i)+n$$

ullet Prove that $T(n)=\Omega(2n)$ using the substitution method



Running Time of RMC: Prove that $T(n) = \Omega(2n)$

- Try to show that $T(n) \geq 2^{n-1}$ (by substitution)
- ullet Base case: $T(1) \geq 1 = 2^0 = 2^{1-1}$ for n=1
- Ind. Hyp.:

$$T(i) \geq 2^{i-1} ext{ for all } i=1,2,\ldots,n-1 ext{ and } n \geq 2$$

$$T(n) \geq 2 \sum_{i=1}^{n-1} 2^{i-1} + n$$

$$egin{aligned} &= 2\sum_{i=1}^{n-1} 2^{i-1} + n \ &= 2(2^{n-1}-1) + n \ &= 2^{n-1} + (2^{n-1}-2+n) \ &\Rightarrow T(n) \geq 2^{n-1} \;\; ext{Q.E.D.} \end{aligned}$$



Running Time of RMC: $T(n) \geq 2^{n-1}$

Whenever

- a recursion tree for the natural recursive solution to a problem contains the same subproblem repeatedly
- the total number of different subproblems is small
 - lacktriangledown it is a good idea to see if $DP(Dynamic\ Programming)$ can be applied



Memoization

- ullet Offers the efficiency of the usual DP approach while maintaining ${f top-down}$ strategy
- Idea is to memoize the natural, but inefficient, recursive algorithm



Memoized Recursive Algorithm

- Maintains an entry in a table for the soln to each subproblem
- Each table entry contains **a special value** to indicate that the entry has yet to be filled in
- When the subproblem is first encountered its solution is computed and then stored in the table
- Each **subsequent** time that the subproblem encountered the value stored in the table is simply **looked up** and **returned**



Memoized Recursive Matrix-chain Order

Shaded subtrees are looked-up rather than recomputing

```
\Longrightarrow \operatorname{LookupC}(p,i,j)
  if m[i,j] = \infty then
     if i = j then
        m[i,j] \leftarrow 0
     else
        for k \leftarrow i to j - 1 do
            q \leftarrow \text{LookupC}(p, i, k) + \text{LookupC}(p, k + 1, j) + p_{i-1}p_kp_j
            if q < m[i, j] then
               m[i,j] \leftarrow q
  return m[i,j]
```

Memoized Recursive Algorithm

- The approach assumes that
 - The set of all possible subproblem parameters are known
 - The relation between the table positions and subproblems is established
- Another approach is to memoize
 - by using hashing with subproblem parameters as key



Dynamic Programming vs Memoization Summary (1)

- ullet Matrix-chain multiplication can be solved in $O(n^3)$ time
 - o by either a top-down memoized recursive algorithm
 - or a bottom-up dynamic programming algorithm
- Both methods exploit the **overlapping subproblems** property
 - \circ There are only $\Theta(n^2)$ different subproblems in total
 - Both methods compute the soln to each problem once
- Without memoization the natural recursive algorithm runs in exponential time since subproblems are solved repeatedly



Dynamic Programming vs Memoization Summary (2)

- In general practice
 - If all subproblems must be solved at once
 - a bottom-up DP algorithm always outperforms a top-down memoized algorithm by a constant factor
 - because, bottom-up DP algorithm
 - Has no overhead for recursion
 - Less overhead for maintaining the table
 - DP: Regular pattern of table accesses can be exploited to reduce the time and/or space requirements even further
 - Memoized: If some problems need not be solved at all, it has the advantage of avoiding solutions to those subproblems



Problem 3: Longest Common Subsequence

Definitions

- A subsequence of a given sequence is just the given sequence with some elements (possibly none) left out
- Example:

$$\circ X = \langle A, B, C, B, D, A, B \rangle$$

$$egin{aligned} \circ \ Z = \langle B, C, D, B
angle \end{aligned}$$

lacksquare Z is a subsequence of X

Problem 3: Longest Common Subsequence

Definitions

- ullet Formal definition: Given a sequence $X=\langle x_1,x_2,\ldots,x_m
 angle$, sequence $Z=\langle z_1,z_2,\ldots,z_k
 angle$ is a subsequence of X
 - \circ if \exists a **strictly increasing sequence** $\langle i_1,i_2,\ldots,i_k
 angle$ of indices of X such that $x_{i_j}=z_j$ for all $j=1,2,\ldots,k$, where $1\leq k\leq m$
- Example: $Z=\langle B,C,D,B
 angle$ is a subsequence of $X=\langle A,B,C,B,D,A,B
 angle$ with the index sequence $\langle i_1,i_2,i_3,i_4
 angle=\langle 2,3,5,7
 angle$



Problem 3: Longest Common Subsequence

Definitions

- ullet If Z is a subsequence of both X and Y, we denote Z as a **common subsequence** of X and Y.
- Example:

$$X = \langle A, B^*, C^*, B, D, A^*, B \rangle$$

 $Y = \langle B^*, D, C^*, A^*, B, A \rangle$

- ullet $Z_1=\langle B^*,C^*,A^*
 angle$ is a common subsequence (**of length 3**) of X and Y.
- ullet Two longest common subsequence (LCSs) of X and Y?

$$\circ \ Z2 = \langle B, C, B, A
angle$$
 of length 4

$$\circ \ Z3 = \langle B, D, A, B
angle$$
 of length 4

■ The optimal solution value = 4



Longest Common Subsequence (LCS) Problem

• LCS problem: Given two sequences

$$\circ \; X = \langle x_1, x_2, \ldots, x_m
angle$$
 and

$$\circ \; Y = \langle y_1, y_2, \ldots, y_n
angle$$
, find the **LCS** of $X\&Y$

- Brute force approach:
 - \circ Enumerate all subsequences of X
 - \circ Check if each subsequence is also a subsequence of Y
 - Keep track of the LCS
 - What is the complexity?
 - \circ There are 2^m subsequences of X
 - Exponential runtime



Notation

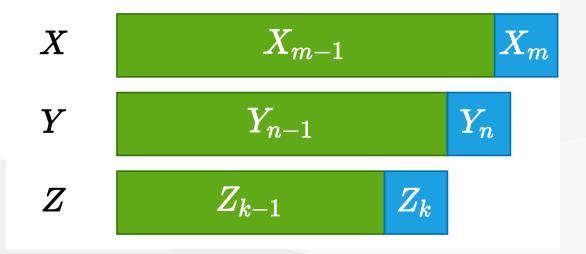
- ullet Notation: Let X_i denote the i^{th} prefix of X \circ i.e. $X_i = \langle x_1, x_2, \dots, x_i
 angle$
- Example:

$$X = \langle A, B, C, B, D, A, B
angle$$
 $X_4 = \langle A, B, C, B
angle$ $X_0 = \langle
angle$



Optimal Substructure of an LCS

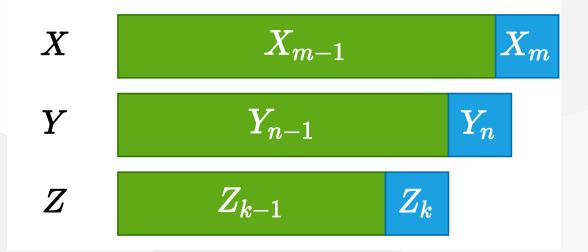
- ullet Let $X=< x1, x2, \ldots, xm>$ and $Y=\langle y_1, y_2, \ldots, y_n
 angle$ are given
- ullet Let $Z=\langle z_1,z_2,\ldots,z_k
 angle$ be an **LCS** of X and Y



- Question 1: If $x_m=y_n$, how to define the optimal substructure?
 - \circ We must have $z_k=x_m=y_n$ and
 - $egin{aligned} \circ \ Z_{k-1} = \mathrm{LCS}(X_{m-1}, Y_{n-1}) \end{aligned}$

Optimal Substructure of an LCS

- ullet Let $X=< x1, x2, \ldots, xm>$ and $Y=\langle y_1, y_2, \ldots, y_n
 angle$ are given
- ullet Let $Z=\langle z_1,z_2,\ldots,z_k
 angle$ be an **LCS** of X and Y

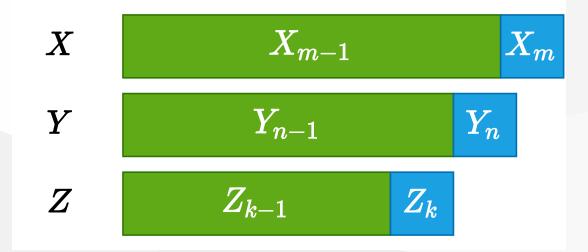


- Question 2: If $x_m \neq y_n \text{ and } z_k \neq x_m$, how to define the optimal substructure?
 - \circ We must have $Z=\mathrm{LCS}(X_{m-1},Y)$



Optimal Substructure of an LCS

- ullet Let $X=< x1, x2, \ldots, xm>$ and $Y=\langle y_1, y_2, \ldots, y_n
 angle$ are given
- ullet Let $Z=\langle z_1,z_2,\ldots,z_k
 angle$ be an **LCS** of X and Y



- Question 3: If $x_m \neq y_n$ and $z_k \neq y_n$, how to define the optimal substructure?
 - \circ We must have $Z = \mathrm{LCS}(X, Y_{n-1})$



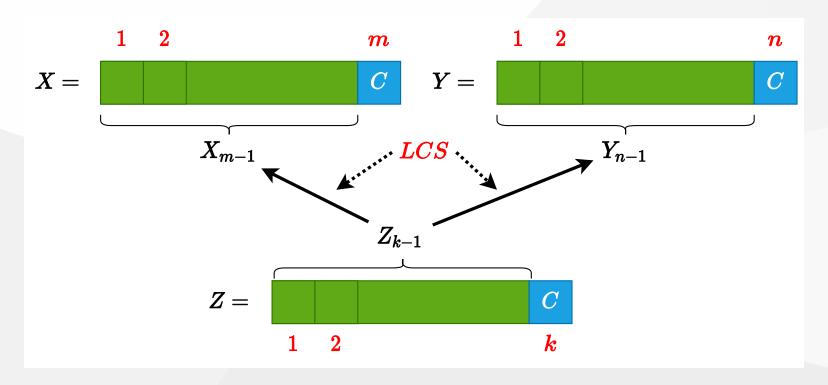
Theorem: Optimal Substructure of an LCS

- ullet Let $X=\langle x_1,x_2,\ldots,x_m
 angle$ and Y = <y1, y2, ..., yn> are given
- ullet Let $Z=\langle z_1,z_2,\ldots,z_k
 angle$ be an **LCS** of X and Y
- Theorem: Optimal substructure of an LCS:
 - \circ If $x_m=y_n$
 - lacksquare then $z_k=x_m=y_n$ and Z_{k-1} is an **LCS** of X_{m-1} and Y_{n-1}
 - \circ If $x_m
 eq y_n$ and $z_k
 eq x_m$
 - lacktriangle then Z is an **LCS** of X_{m-1} and Y
 - \circ If $x_m
 eq y_n$ and $z_k
 eq y_n$
 - lacktriangle then Z is an **LCS** of X and Y_{n-1}



Optimal Substructure Theorem (case 1)

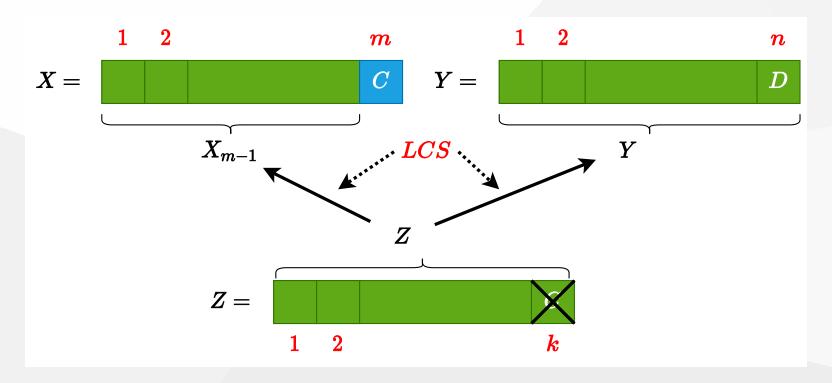
ullet If $x_m=y_n$ then $z_k=x_m=y_n$ and Z_{k-1} is an **LCS** of X_{m-1} and Y_{n-1}





Optimal Substructure Theorem (case 2)

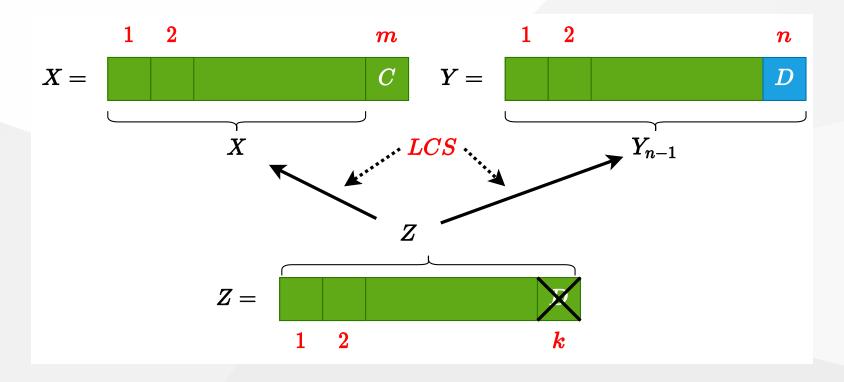
ullet If $x_m
eq y_n$ and $z_k
eq x_m$ then Z is an **LCS** of X_{m-1} and Y

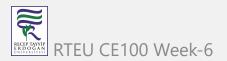




Optimal Substructure Theorem (case 3)

ullet If $x_m
eq y_n$ and $z_k
eq y_n$ then Z is an **LCS** of X and Y_{n-1}





Proof of Optimal Substructure Theorem (case 1)

- ullet If $x_m=y_n$ then $z_k=x_m=y_n$ and Z_{k-1} is an LCS of X_{m-1} and Y_{n-1}
- ullet Proof: If $z_k
 eq x_m = y_n$ then
 - \circ we can append $x_m=y_n$ to Z to obtain a common subsequence of length $k+1\Longrightarrow {\sf contradiction}$
 - \circ Thus, we must have $z_k=x_m=y_n$
 - \circ Hence, the prefix Z_{k-1} is a **length-(**k-1**) CS** of X_{m-1} and Y_{n-1}
- ullet We have to show that Z_{k-1} is in fact an LCS of X_{m-1} and Y_{n-1}
- Proof by contradiction:
 - \circ Assume that \exists a CS W of X_{m-1} and Y_{n-1} with |W|=k
 - \circ Then appending $x_m=y_n$ to W produces a **CS** of length k+1



Proof of Optimal Substructure Theorem (case 2)

- ullet If $x_m
 eq y_n$ and $z_k
 eq x_m$ then Z is an **LCS** of X_{m-1} and Y
- ullet Proof : If $z_k
 eq x_m$ then Z is a CS of X_{m-1} and Y_n
 - \circ We have to show that Z is in fact an LCS of X_{m-1} and Y_n
- (Proof by contradiction)
 - \circ Assume that \exists a CS W of X_{m-1} and Y_n with |W|>k
 - \circ Then W would also be a CS of X and Y
 - Contradiction to the assumption that
 - lacksquare Z is an LCS of X and Y with |Z|=k
- Case 3: Dual of the proof for (case 2)



A Recursive Solution to Subproblems

- Theorem implies that there are one or two subproblems to examine
- if $x_m = y_n$ then
 - \circ we must solve the subproblem of finding an **LCS** of $X_{m-1}\&Y_{n-1}$
 - \circ appending $x_m=y_n$ to this **LCS** yields an **LCS** of X&Y
- else
 - we must solve two subproblems
 - finding an LCS of $X_{m-1}\&Y$
 - finding an LCS of $X\&Y_{n-1}$
 - \circ longer of these two **LCS**s is an **LCS** of X&Y
- endif



Recursive Algorithm (Inefficient)

```
LCS(X,Y) {
   m \leftarrow length[X]
   n \leftarrow length[Y]
   if x_m = y_n then
       Z \leftarrow \mathrm{LCS}(X_{m-1}, Y_{n-1}) \triangleright \text{solve one subproblem}
       return \langle Z, x_m = y_n \rangle \triangleright append x_m = y_n to Z
   else
       Z^{'} \leftarrow \mathrm{LCS}(X_{m-1},Y) 	riangleright 	ext{solve two subproblems}
       Z^{''} \leftarrow \mathrm{LCS}(X, Y_{n-1})
       return longer of Z^{'} and Z^{''}
```

A Recursive Solution

ullet c[i,j] : length of an LCS of X_i and Y_j

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$



- We can easily write an **exponential-time recursive algorithm** based on the given recurrence. \Longrightarrow **Inefficient!**
- How many distinct subproblems to solve?
 - $\circ~\Theta(mn)$
- Overlapping subproblems property: Many subproblems share the same subsubproblems.
 - \circ e.g. Finding an LCS to $X_{m-1}\&Y$ and an LCS to $X\&Y_{n-1}$
 - \circ has the sub-subproblem of finding an **LCS** to $X_{m-1}\&Y_{n-1}$
- Therefore, we can use dynamic programming.



Data Structures

- Let:
 - $\circ\ c[i,j]:$ length of an LCS of X_i and Y_j
 - \circ b[i,j]: direction towards the table entry corresponding to the optimal subproblem solution chosen when computing c[i,j].
 - Used to simplify the construction of an optimal solution at the end.
- Maintain the following tables:
 - $\circ \ c[0 \dots m, 0 \dots n]$



Bottom-up Computation

• Reminder:

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$

- ullet How to choose the order in which we process c[i,j] values?
- ullet The values for c[i-1,j-1], c[i,j-1], and c[i-1,j] must be computed before computing c[i,j].



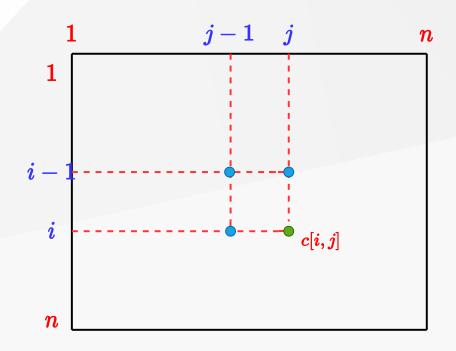
Bottom-up Computation

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$

Need to process:

after computing:

$$egin{aligned} c[i-1,j-1],\ c[i,j-1],\ c[i-1,j] \end{aligned}$$



Bottom-up Computation

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$

 \Downarrow

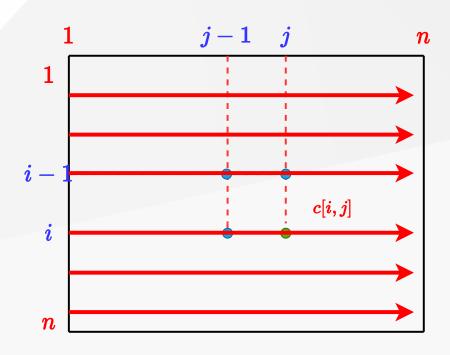
for $i \leftarrow 1$ to m

for $j \leftarrow 1$ to n

• •

. . .

$$c[i,j] = \cdots$$



```
LCS-LENGTH(X,Y)
   m \leftarrow length[X]; n \leftarrow length[Y]
   for i \leftarrow 0 to m \operatorname{do} c[i, 0] \leftarrow 0
   for j \leftarrow 0 to n do c[0,j] \leftarrow 0
   for i \leftarrow 1 to m do
       for j \leftarrow 1 to n do
          if x_i = y_i then
             c[i,j] \leftarrow c[i-1,j-1]+1
             b[i,j] \leftarrow " \nwarrow "
          else if c[i - 1, j] \ge c[i, j - 1]
             c[i,j] \leftarrow c[i-1,j]
              b[i,j] \leftarrow ``\uparrow
          else
              c[i,j] \leftarrow c[i,j-1]
              b[i,j] \leftarrow " \leftarrow "
```

$$rac{ ext{Total Runtime} = \Theta(mn)}{ ext{Total Space} = \Theta(mn)}$$



$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j$	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0						
2B	0						
3C	0						
4B	0						
5D	0						
6A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} \rangle$$
 $Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} \rangle$

1	. i/j $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	†	†	1	← 1	1
	2B	0						
	3~C	0						
	4 B	0						
	5 D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

	. i/j $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	† 0	1 0	1	← 1	1
	2 B	0	1	← 1	← 1	1	2	\leftarrow 2
	3 C	0						
	4 B	0						
	5D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

1	. i/j $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\stackrel{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	1 0	1 0	1 0	<u>۲</u>	← 1	1
	2 B	0	1	\leftarrow 1	\leftarrow 1	1	2	\leftarrow 2
	3 C	0	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	$\leftarrow 2$	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	$egin{pmatrix} igwedge \ 2 \end{matrix}$
	4 B	0						
	5D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

-	$\downarrow i/j - i$	$ ightarrow 0 y_j$	1 <i>B</i>	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\stackrel{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	1 0	1 0	1 0	1	<u>←</u>	1
	2 B	0	1	← 1	← 1	1	2	\leftarrow 2
	3 C	0	1	1	2	\leftarrow 2	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1					
	5D	0						
	6~A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1A	0	† 0	1 0	† 0	<u>ر</u> 1	← 1	1
2 B	0	1	\leftarrow 1	<u>←</u>	1	2	\leftarrow 2
3 C	0	$egin{pmatrix} igwedge \ 1 \end{matrix}$	1	2	\leftarrow 2	$egin{array}{c} \uparrow \ 2 \end{array}$	1 2
4B	0	1	1				
5D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j - i$	$ ightarrow 0 y_j$	$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	†	1 0	\uparrow	1	<u>←</u>	1
2 B	0	1	<u>←</u>	← 1	1	2	$iggraphi_{f 2}$
3 C	0	$egin{pmatrix} igwedge \ 1 \end{matrix}$	1	2	$\leftarrow 2$	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	1	1	$egin{pmatrix} igwedge 2 \end{matrix}$			
5D	0						
6~A	0						
7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	† 0	† 0	† 0	<u>ر</u> 1	← 1	1
2 B	0	1	\leftarrow 1	<u>←</u>	1	2	\leftarrow 2
3 C	0	\uparrow 1	1	2	\leftarrow 2	1 2	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	1	1	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$		
5 D	0						
6~A	0						
7B	0						
			_				

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	† 0	† 0	† 0	1	← 1	1
2 B	0	1	\leftarrow 1	<u>←</u>	1	2	\leftarrow 2
3 C	0	\uparrow 1	1	2	\leftarrow 2	$egin{pmatrix} \uparrow & \ 2 & \ \end{matrix}$	† 2
4B	0	1	1	$egin{pmatrix} igwedge 2 \end{matrix}$	1 2	3	
5 D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	† 0	† 0	† 0	1	<u>←</u>	1
2 B	0	1	\leftarrow 1	<u>←</u>	1	2	$\leftarrow 2$
3 C	0	\uparrow 1	1	2	\leftarrow 2	$egin{pmatrix} \uparrow & \ 2 & \ \end{matrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$
4B	0	1	1	1 2	1 2	3	$\frac{\leftarrow}{3}$
5 D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

$\downarrow i/j$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	0	0	1 0	1	\leftarrow 1	1
2 B	0	1	\leftarrow 1	\leftarrow 1	1	2	$iggraphi_{f 2}$
3 C	0	\uparrow 1	1	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4 B	0	<u>۲</u>	1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	† 1	2	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	† 3	$egin{pmatrix} \uparrow \ 3 \end{bmatrix}$
6 A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B}
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A}
angle$$

1	i/j - i	$\rightarrow 0y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	0	0	1	\leftarrow 1	<u>ر</u> 1
	2 B	0	1	\leftarrow 1	\leftarrow 1	1	2	$\leftarrow 2$
	3 C	0	1	\uparrow 1	2	\leftarrow 2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$
	4B	0	1	1	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\frac{\leftarrow}{3}$
	5 D	0	1	2	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{pmatrix} igspace 2 \end{matrix}$	\uparrow 3	3
	6A	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0						

Operation of LCS-LENGTH on the sequences

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} \rangle$$
 $Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} \rangle$

• Running-time = O(mn)since each table entry takes O(1) time to compute

↓	. $i/j ightarrow$	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	1 0	†	†	1	← 1	1
	2 B	0	1	← 1	← 1	$egin{pmatrix} \uparrow \\ 1 \end{bmatrix}$	2	$\leftarrow 2$
	3 C	0	1 1	$egin{pmatrix} lack \ 1 \end{matrix}$	2	\leftarrow 2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	$egin{pmatrix} \uparrow & & \\ 1 & & \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} igwedge 2 \end{matrix}$	3	$\leftarrow 3$
	5 D	0	$egin{pmatrix} \uparrow & \ 1 & \ \end{matrix}$	2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$	\uparrow 3	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	$egin{pmatrix} \uparrow \\ 1 \end{bmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	\uparrow 3	† 3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{bmatrix}$

$$X = \langle \stackrel{1}{A}, \stackrel{2}{B}, \stackrel{3}{C}, \stackrel{4}{B}, \stackrel{5}{D}, \stackrel{6}{A}, \stackrel{7}{B} \rangle$$
 $Y = \langle \stackrel{1}{B}, \stackrel{2}{D}, \stackrel{3}{C}, \stackrel{4}{A}, \stackrel{5}{B}, \stackrel{6}{A} \rangle$

- Running-time = O(mn)since each table entry takes O(1) time to compute
- LCS of $X\&Y = \langle B,C,B,A \rangle$

1	. i/j $ ightarrow$	$0y_j$	$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$egin{array}{c} 6 \ A \end{array}$
	$0x_i$	0	0	0	0	0	0	0
	1 <i>A</i>	0	$ \uparrow $	$ \uparrow $	1 0	1	← 1	1
	2 B	0	<u>ر</u> 1	← 1	← 1	\uparrow 1	2	$iggrup rac{\leftarrow}{2}$
	3 C	0	1	$egin{pmatrix} lack \ 1 \end{matrix}$	2	$\overset{\longleftarrow}{2}$	$egin{array}{c} oldsymbol{\uparrow} \ oldsymbol{2} \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	<u>ر</u> 1	$egin{pmatrix} lacktriangle & lacktriangle$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} oldsymbol{\uparrow} \ oldsymbol{2} \end{array}$	3	iggraphsize
	5 D	0	\uparrow 1	2	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$\stackrel{ o}{3}$	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	\uparrow 1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	\uparrow 3	\uparrow 3	4	↑ 4

Constructing an LCS

- ullet The b table returned by **LCS-LENGTH** can be used to quickly construct an **LCS** of X&Y
- ullet Begin at b[m,n] and trace through the table following arrows
- ullet Whenever you encounter a "igwedge" in entry b[i,j] it implies that $x_i=y_j$ is an element of **LCS**
- The elements of LCS are encountered in reverse order



Constructing an LCS

- The recursive procedure PRINT-LCS prints out LCS in proper order
- ullet This procedure takes O(m+n) time since at least one of i and j is decremented in each stage of the recursion

```
PRINT-LCS(b, X, i, j)
  if i = 0 or j = 0 then
  return
  if b[i,j] = " \nwarrow " then
    PRINT-LCS(b, X, i-1, j-1)
    print x_i
  else if b[i,j] = "\uparrow" then
    PRINT-LCS(b, X, i - 1, j)
  else
    PRINT-LCS(b, X, i, j - 1)
```

• The initial invocation: PRINT-LCS(b, X, length[X], length[Y])

RTEU CE100 Week-6

Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- Answer: Upper-left neighbor, because X[i] = Y[j].

\	. $i/j ightarrow$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\overset{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	1 0	0	1 0	1	\leftarrow 1	
	2 B	0	1	\leftarrow 1	← 1	$egin{pmatrix} ightarrow \ 1 \end{matrix}$	2	$oxed{\leftarrow 2}$
	3 C	0	1	1	2	\leftarrow 2	$egin{pmatrix} egin{pmatrix} egi$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$oxed{\leftarrow 3}$
	5 D	0	1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	$egin{array}{c} \uparrow \ 3 \end{array}$	$egin{array}{c} \uparrow \ 3 \end{array}$
	6 A	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	† 3	† 3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{bmatrix}$

Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- ullet Answer: Left neighbor, because X[i]
 eq Y[j] and LCS[i,j-1] > LCS[i-1,j].

↓	. $i/j ightarrow i$	$0y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	↑ 0	†	1	← 1	1
	2 B	0	1	\leftarrow 1	\leftarrow 1	1	2	$iggraphi_{f 2}$
	3 C	0	1	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5 D	0	1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	† 3	$egin{pmatrix} \uparrow \ 3 \end{bmatrix}$
	6A	0	1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	† 3	† 3	4	$egin{array}{c} \uparrow \ oldsymbol{4} \end{array}$

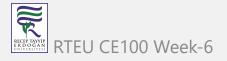
Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- ullet Answer: Upper neighbor,because X[i]
 eq Y[j] and LCS[i,j-1] = LCS[i-1,j]. (See pseudo-code to see how ties are handled.)

↓ 1	i/j ightarrow	$0y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1A	0	†	1 0	†	1	← 1	
	2B	0	1	\leftarrow 1	\leftarrow 1	1 1	2	$oxed{\leftarrow 2}$
	3 C	0	\uparrow 1	1 1	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1	1 1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	3	iggraphsize
	5D	0	\uparrow 1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	† 3	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	1	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} egin{pmatrix} egi$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	† 3	† 3	4	$egin{array}{c} \uparrow \ 4 \end{array}$

Improving the Space Requirements

- We can eliminate the b table altogether
 - \circ each c[i,j] entry depends only on 3 other c table entries: c[i-1,j-1], c[i-1,j] and c[i,j-1]
- Given the value of c[i,j]:
 - \circ We can determine in O(1) time which of these 3 values was used to compute c[i,j] without inspecting table b
 - \circ We save $\Theta(mn)$ space by this method
 - \circ However, space requirement is still $\Theta(mn)$ since we need $\Theta(mn)$ space for the c table anyway



- ullet To compute c[i,j], we only need c[i-1,j-1], c[i-1,j],and c[i-1,j-1]
- So, we can store only the last two rows.

$\downarrow i/j -$	$0y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	\uparrow	1 0	1 0	1	← 1	1
2 B	0	1	← 1	$\stackrel{\longleftarrow}{1}$	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	2	$oxed{\leftarrow 2}$
3 C	0	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	<u>ر</u> 1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	† 3	$egin{array}{c} \uparrow \ 3 \end{array}$
6~A	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} egi$	3	† 3	4
7 B	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	1 3	1 3	4	$egin{pmatrix} \uparrow \\ 4 \end{bmatrix}$

- $oldsymbol{\circ}$ To compute c[i,j], we only need c[i-1,j-1], c[i-1,j], and c[i-1,j-1]
- So, we can store only the last two rows.

$\downarrow i/j$ $-$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	†	† 0	†	1	← 1	1
2 B	0	1	\leftarrow 1	← 1	$egin{pmatrix} ightarrow \ egin{pmatrix} ightarrow \ ightarrow \ \end{bmatrix}$	2	$oxed{\leftarrow 2}$
3 C	0	1	1	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4 B	0	<u>ر</u> 1	† 1	\uparrow 2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	† 1	2	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} egi$	\uparrow 3	↑ 3
6 A	0	† 1	$egin{pmatrix} igspace 2 \end{matrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
7 B	0	<u>۲</u>	$egin{pmatrix} ightarrow{1}{2} \ \end{array}$	† 3	† 3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

- $oldsymbol{\circ}$ To compute c[i,j], we only need c[i-1,j-1], c[i-1,j], and c[i-1,j-1]
- So, we can store only the last two rows.
- This reduces space complexity from $\Theta(mn)$ to $\Theta(n)$.
- Is there a problem with this approach?

1	i/j ightharpoonup i	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\stackrel{ extbf{2}}{D}$	$\overset{3}{C}$	$egin{array}{c} A \ A \end{array}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	0	†	1	← 1	1
	2 B	0	1	\leftarrow 1	$\stackrel{\longleftarrow}{1}$	1	2	$iggrup_{f 2}$
	3 C	0	1	1	2	$\leftarrow 2$	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5D	0	† 1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$	$\uparrow 3$	↑ 3
	6A	0	† 1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	† 3	3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

- Is there a problem with this approach?
 - We cannot construct the optimal solution because we cannot backtrace anymore.
 - This approach works if we only need the length of an LCS, not the actual LCS.

↓	. $i/j ightarrow$	$0y_j$	$\overset{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	†	1 0	†	1	← 1	1
	2 B	0	1	\leftarrow 1	← 1	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	iggraphi
	3 C	0	1	1	2	\leftarrow 2	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5 D	0	† 1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 3 \end{array}$	↑ 3
	6A	0	† 1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	† 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	† 3	3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

Problem 4 Optimal Binary Search Tree



- Problem-1: Longest Increasing Subsequence
 - https://www.geeksforgeeks.org/longest-increasing-subsequence-dp-3/
 - https://en.wikipedia.org/wiki/Longest_increasing_subsequence#:~:text=In
 computer science%2C the longest,not necessarily contiguous%2C or unique.
 - https://www.youtube.com/watch?v=22s1xxRvy28&ab_channel=StableSort



- Problem-2: Edit Distance
 - https://www.geeksforgeeks.org/edit-distance-dp-5/
 - https://www.youtube.com/watch?
 v=tU2f2JwHmfQ&feature=youtu.be&ab_channel=PrepForTech
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- Problem-3: Partition a set into two subsets such that the difference of subset sums is minimum
 - https://www.geeksforgeeks.org/partition-a-set-into-two-subsets-such-thatthe-difference-of-subset-sums-is-minimum/
- Problem-4: Count number of ways to cover a distance
 - https://www.geeksforgeeks.org/count-number-of-ways-to-cover-a-distance/
- Problem-5: Find the longest path in a matrix with given constraints
 - https://www.geeksforgeeks.org/find-the-longest-path-in-a-matrix-with-givenconstraints/



- Problem-6: Subset Sum Problem
 - https://www.geeksforgeeks.org/subset-sum-problem-dp-25/
- Problem-7: Optimal Strategy for a Game
 - https://www.geeksforgeeks.org/optimal-strategy-for-a-game-dp-31/
- Problem-8: 0-1 Knapsack Problem
 - https://www.geeksforgeeks.org/0-1-knapsack-problem-dp-10/



- Problem-9: Boolean Parenthesization Problem
 - https://www.geeksforgeeks.org/boolean-parenthesization-problem-dp-37/
- Problem-10: Shortest Common Supersequence
 - https://www.geeksforgeeks.org/shortest-common-supersequence/
 - https://en.wikipedia.org/wiki/Shortest_common_supersequence_problem
- Problem-11: Partition Problem
 - https://www.geeksforgeeks.org/partition-problem-dp-18/
- Problem-12: Cutting a Rod
 - https://www.geeksforgeeks.org/cutting-a-rod-dp-13/



- Problem-13: Coin Change
 - https://www.geeksforgeeks.org/coin-change-dp-7/
- Problem-14: Word Break Problem
 - https://www.geeksforgeeks.org/word-break-problem-dp-32/
- Problem-15: Maximum Product Cutting
 - https://www.geeksforgeeks.org/maximum-product-cutting-dp-36/

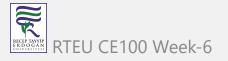


- Problem-16: Dice Throw
 - https://www.geeksforgeeks.org/dice-throw-dp-30/
- Problem-17: Box Stacking Problem
 - https://www.geeksforgeeks.org/box-stacking-problem-dp-22/
- Problem-18: Egg Dropping Puzzle
 - https://www.geeksforgeeks.org/egg-dropping-puzzle-dp-11/



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- Bilkent CS473 Course Notes (old)



$$-End-Of-Week-6-Course-Module-$$

