## **CE100 Algorithms and Programming II**

Week-6 (Matrix Chain Order / LCS)

Spring Semester, 2021-2022

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# Matrix Chain Order / Longest Common Subsequence

#### **Outline**

- Elements of Dynamic Programming
  - Optimal Substructure
  - Overlapping Subproblems



- Recursive Matrix Chain Order Memoization
  - Top-Down Approach
  - RMC
  - MemoizedMatrixChain
    - LookupC
  - Dynamic Programming vs Memoization Summary



- Dynamic Programming
  - Problem-2 : Longest Common Subsequence
    - Definitions
    - LCS Problem
    - Notations
    - Optimal Substructure of LCS
      - Proof Case-1
      - Proof Case-2
      - Proof Case-3



- A recursive solution to subproblems (inefficient)
- Computing the length of and LCS
  - LCS Data Structure for DP
  - Bottom-Up Computation
- Constructing and LCS
  - PRINT-LCS
  - Back-pointer space optimization for LCS length



Most Common Dynamic Programming Interview Questions



### **Elements of Dynamic Programming**

- When should we look for a DP solution to an optimization problem?
- Two key ingredients for the problem
  - Optimal substructure
  - Overlapping subproblems



#### DP Hallmark #1

- Optimal Substructure
  - A problem exhibits optimal substructure
    - if an optimal solution to a problem contains within it optimal solutions to subproblems
  - Example: matrix-chain-multiplication
    - lacktriangledown Optimal parenthesization of  $A_1A_2\ldots A_n$  that splits the product between  $A_k$  and  $A_{k+1}$ , contains within it **optimal soln's** to the problems of parenthesizing  $A_1A_2\ldots A_k$  and  $A_{k+1}A_{k+2}\ldots A_n$



## **Optimal Substructure**

- Finding a suitable space of subproblems
  - Iterate on subproblem instances
  - **Example:** *matrix-chain-multiplication* 
    - Iterate and look at the structure of optimal soln's to subproblems, subsubproblems, and so forth
    - lacktriangle Discover that all subproblems consists of subchains of  $\langle A_1,A_2,\ldots,A_n
      angle$
    - lacksquare Thus, the set of chains of the form  $\langle A_i, A_{i+1}, \dots, A_j 
      angle$  for  $1 \leq i \leq j \leq n$
    - Makes a natural and reasonable space of subproblems



#### **DP Hallmark #2**

- Overlapping Subproblems
  - o Total number of distinct subproblems should be polynomial in the input size
  - When a recursive algorithm revisits the same problem over and over again,
    - We say that the optimization problem has overlapping subproblems



# **Overlapping Subproblems**

- DP algorithms typically take advantage of overlapping subproblems
  - by solving each problem once
  - then storing the solutions in a table
    - where it can be looked up when needed
  - using constant time per lookup



#### **Overlapping Subproblems**

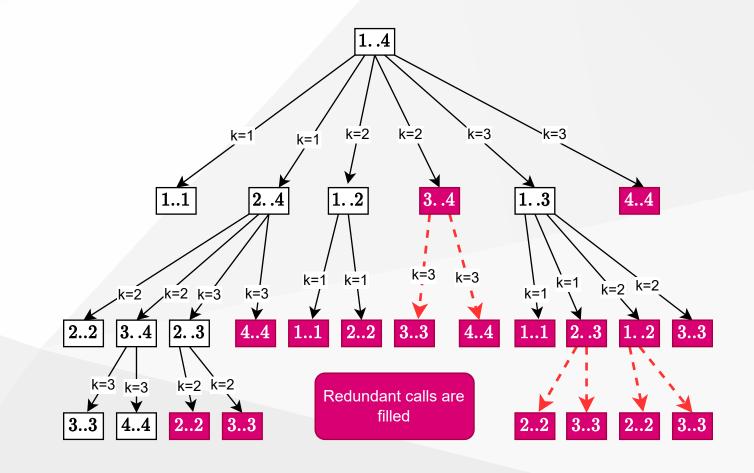
• Recursive matrix-chain order

$$egin{aligned} &\operatorname{RMC}(p,i,j) \{ \ &\operatorname{if}\ i=j\ \operatorname{then} \ &\operatorname{return}\ 0 \ &m[i,j] \leftarrow \infty \ &\operatorname{for}\ k \leftarrow i \operatorname{to}\ j-1 \operatorname{do} \ &q \leftarrow \operatorname{RMC}(p,i,k) + \operatorname{RMC}(p,k+1,j) + p_{i-1}p_kp_j \ &if\ q < m[i,j]\ \operatorname{then} \ &m[i,j] \leftarrow q \ &\operatorname{return}\ m[i,j]\ \} \end{aligned}$$



# Direct Recursion: Inefficient!

- Recursion tree for RMC(p,1,4)
- ullet Nodes are labeled with i and j values





#### **Running Time of RMC**

$$T(1) \geq 1$$
  $T(n) \geq 1 + \sum\limits_{k=1}^{n-1} (T(k) + T(n-k) + 1) ext{ for } n > 1$ 

- ullet For  $i=1,2,\ldots,n$  each term T(i) appears twice  $\circ$  Once as T(k), and once as T(n-k)
- ullet Collect  $n-1,\,1$ 's in the summation together with the front 1

$$T(n) \geq 2\sum_{i=1}^{n-1}T(i)+n$$

ullet Prove that  $T(n)=\Omega(2n)$  using the substitution method



### Running Time of RMC: Prove that $T(n) = \Omega(2n)$

- Try to show that  $T(n) \geq 2^{n-1}$  (by substitution)
- ullet Base case:  $T(1) \geq 1 = 2^0 = 2^{1-1}$  for n=1
- Ind. Hyp.:

$$T(i) \geq 2^{i-1} ext{ for all } i=1,2,\ldots,n-1 ext{ and } n \geq 2$$

$$T(n) \geq 2 \sum_{i=1}^{n-1} 2^{i-1} + n$$

$$egin{aligned} &= 2\sum_{i=1}^{n-1} 2^{i-1} + n \ &= 2(2^{n-1}-1) + n \ &= 2^{n-1} + (2^{n-1}-2+n) \ &\Rightarrow T(n) \geq 2^{n-1} \;\; ext{Q.E.D.} \end{aligned}$$



# Running Time of RMC: $T(n) \geq 2^{n-1}$

#### Whenever

- a recursion tree for the natural recursive solution to a problem contains the same subproblem repeatedly
- the total number of different subproblems is small
  - lacktriangledown it is a good idea to see if  $DP(Dynamic\ Programming)$  can be applied



#### Memoization

- ullet Offers the efficiency of the usual DP approach while maintaining  ${f top-down}$  strategy
- Idea is to memoize the natural, but inefficient, recursive algorithm



### **Memoized Recursive Algorithm**

- Maintains an entry in a table for the soln to each subproblem
- Each table entry contains **a special value** to indicate that the entry has yet to be filled in
- When the subproblem is first encountered its solution is computed and then stored in the table
- Each **subsequent** time that the subproblem encountered the value stored in the table is simply **looked up** and **returned**



#### Memoized Recursive Matrix-chain Order

Shaded subtrees are looked-up rather than recomputing

```
\Longrightarrow \operatorname{LookupC}(p,i,j)
  if m[i,j] = \infty then
     if i = j then
        m[i,j] \leftarrow 0
     else
        for k \leftarrow i to j - 1 do
            q \leftarrow \text{LookupC}(p, i, k) + \text{LookupC}(p, k + 1, j) + p_{i-1}p_kp_j
            if q < m[i, j] then
               m[i,j] \leftarrow q
  return m[i,j]
```

### **Memoized Recursive Algorithm**

- The approach assumes that
  - The set of all possible subproblem parameters are known
  - The relation between the table positions and subproblems is established
- Another approach is to memoize
  - by using hashing with subproblem parameters as key



#### Dynamic Programming vs Memoization Summary (1)

- ullet Matrix-chain multiplication can be solved in  $O(n^3)$  time
  - o by either a top-down memoized recursive algorithm
  - or a bottom-up dynamic programming algorithm
- Both methods exploit the **overlapping subproblems** property
  - $\circ$  There are only  $\Theta(n^2)$  different subproblems in total
  - Both methods compute the soln to each problem once
- Without memoization the natural recursive algorithm runs in exponential time since subproblems are solved repeatedly



#### Dynamic Programming vs Memoization Summary (2)

- In general practice
  - If all subproblems must be solved at once
    - a bottom-up DP algorithm always outperforms a top-down memoized algorithm by a constant factor
  - because, bottom-up DP algorithm
    - Has no overhead for recursion
    - Less overhead for maintaining the table
  - DP: Regular pattern of table accesses can be exploited to reduce the time and/or space requirements even further
  - Memoized: If some problems need not be solved at all, it has the advantage of avoiding solutions to those subproblems



## **Problem 3: Longest Common Subsequence**

#### **Definitions**

- A subsequence of a given sequence is just the given sequence with some elements (possibly none) left out
- Example:

$$\circ X = \langle A, B, C, B, D, A, B \rangle$$

$$egin{aligned} \circ \ Z = \langle B, C, D, B 
angle \end{aligned}$$

lacksquare Z is a subsequence of X

### **Problem 3: Longest Common Subsequence**

#### **Definitions**

- ullet Formal definition: Given a sequence  $X=\langle x_1,x_2,\ldots,x_m
  angle$  , sequence  $Z=\langle z_1,z_2,\ldots,z_k
  angle$  is a subsequence of X
  - $\circ$  if  $\exists$  a **strictly increasing sequence**  $\langle i_1,i_2,\ldots,i_k
    angle$  of indices of X such that  $x_{i_j}=z_j$  for all  $j=1,2,\ldots,k$ , where  $1\leq k\leq m$
- Example:  $Z=\langle B,C,D,B
  angle$  is a subsequence of  $X=\langle A,B,C,B,D,A,B
  angle$  with the index sequence  $\langle i_1,i_2,i_3,i_4
  angle=\langle 2,3,5,7
  angle$



#### **Problem 3: Longest Common Subsequence**

#### **Definitions**

- ullet If Z is a subsequence of both X and Y, we denote Z as a **common subsequence** of X and Y.
- Example:

$$X = \langle A, B^*, C^*, B, D, A^*, B \rangle$$
  
 $Y = \langle B^*, D, C^*, A^*, B, A \rangle$ 

- ullet  $Z_1=\langle B^*,C^*,A^*
  angle$  is a common subsequence (**of length 3**) of X and Y.
- ullet Two longest common subsequence (LCSs) of X and Y?

$$\circ \ Z2 = \langle B, C, B, A 
angle$$
 of length  $4$ 

$$\circ \ Z3 = \langle B, D, A, B 
angle$$
 of length  $4$ 

■ The optimal solution value = 4



### Longest Common Subsequence (LCS) Problem

• LCS problem: Given two sequences

$$\circ \; X = \langle x_1, x_2, \ldots, x_m 
angle$$
 and

$$\circ \; Y = \langle y_1, y_2, \ldots, y_n 
angle$$
, find the **LCS** of  $X\&Y$ 

- Brute force approach:
  - $\circ$  Enumerate all subsequences of X
  - $\circ$  Check if each subsequence is also a subsequence of Y
  - Keep track of the LCS
  - What is the complexity?
  - $\circ$  There are  $2^m$  subsequences of X
    - Exponential runtime



#### **Notation**

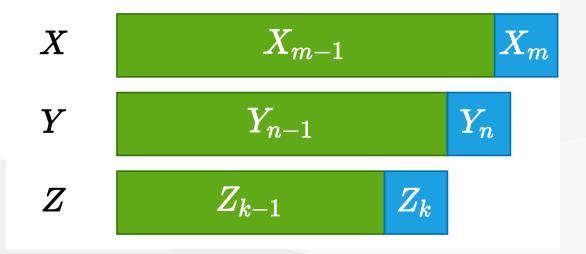
- ullet Notation: Let  $X_i$  denote the  $i^{th}$  prefix of X  $\circ$  i.e.  $X_i = \langle x_1, x_2, \dots, x_i 
  angle$
- Example:

$$X = \langle A, B, C, B, D, A, B 
angle$$
 $X_4 = \langle A, B, C, B 
angle$  $X_0 = \langle 
angle$ 



### **Optimal Substructure of an LCS**

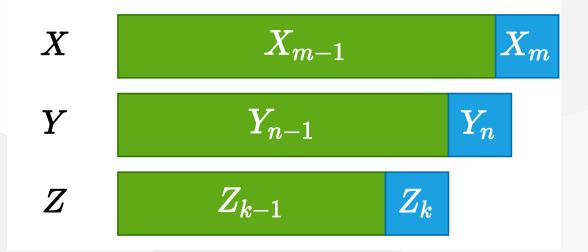
- ullet Let  $X=< x1, x2, \ldots, xm>$  and  $Y=\langle y_1, y_2, \ldots, y_n
  angle$  are given
- ullet Let  $Z=\langle z_1,z_2,\ldots,z_k
  angle$  be an **LCS** of X and Y



- Question 1: If  $x_m=y_n$ , how to define the optimal substructure?
  - $\circ$  We must have  $z_k=x_m=y_n$  and
  - $egin{aligned} \circ \ Z_{k-1} = \mathrm{LCS}(X_{m-1}, Y_{n-1}) \end{aligned}$

### **Optimal Substructure of an LCS**

- ullet Let  $X=< x1, x2, \ldots, xm>$  and  $Y=\langle y_1, y_2, \ldots, y_n
  angle$  are given
- ullet Let  $Z=\langle z_1,z_2,\ldots,z_k
  angle$  be an **LCS** of X and Y

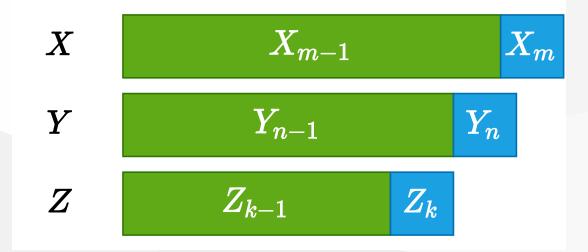


- Question 2: If  $x_m \neq y_n \text{ and } z_k \neq x_m$ , how to define the optimal substructure?
  - $\circ$  We must have  $Z=\mathrm{LCS}(X_{m-1},Y)$



### **Optimal Substructure of an LCS**

- ullet Let  $X=< x1, x2, \ldots, xm>$  and  $Y=\langle y_1, y_2, \ldots, y_n
  angle$  are given
- ullet Let  $Z=\langle z_1,z_2,\ldots,z_k
  angle$  be an **LCS** of X and Y



- Question 3: If  $x_m \neq y_n$  and  $z_k \neq y_n$ , how to define the optimal substructure?
  - $\circ$  We must have  $Z = \mathrm{LCS}(X, Y_{n-1})$



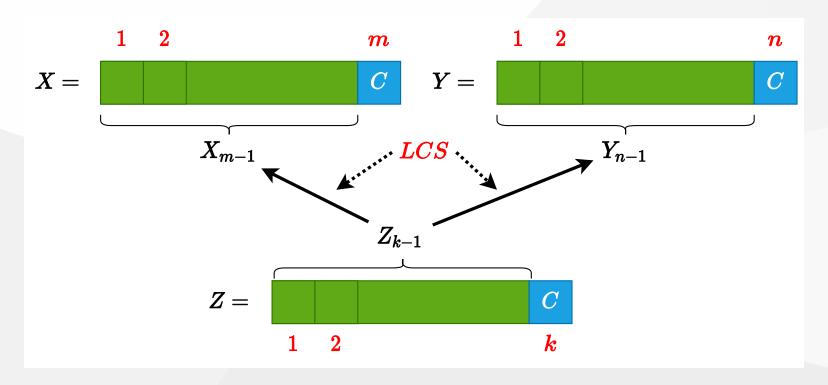
### Theorem: Optimal Substructure of an LCS

- ullet Let  $X=\langle x_1,x_2,\ldots,x_m
  angle$  and Y = <y1, y2, ..., yn> are given
- ullet Let  $Z=\langle z_1,z_2,\ldots,z_k
  angle$  be an **LCS** of X and Y
- Theorem: Optimal substructure of an LCS:
  - $\circ$  If  $x_m=y_n$ 
    - lacksquare then  $z_k=x_m=y_n$  and  $Z_{k-1}$  is an **LCS** of  $X_{m-1}$  and  $Y_{n-1}$
  - $\circ$  If  $x_m 
    eq y_n$  and  $z_k 
    eq x_m$ 
    - lacktriangle then Z is an **LCS** of  $X_{m-1}$  and Y
  - $\circ$  If  $x_m 
    eq y_n$  and  $z_k 
    eq y_n$ 
    - lacktriangle then Z is an **LCS** of X and  $Y_{n-1}$



#### **Optimal Substructure Theorem (case 1)**

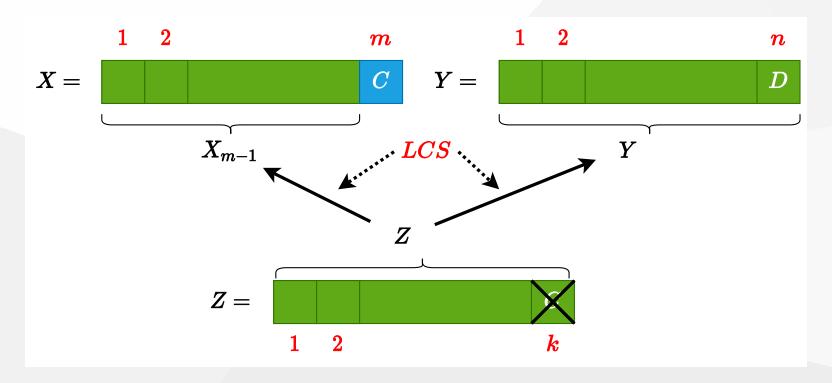
ullet If  $x_m=y_n$  then  $z_k=x_m=y_n$  and  $Z_{k-1}$  is an **LCS** of  $X_{m-1}$  and  $Y_{n-1}$ 





#### **Optimal Substructure Theorem (case 2)**

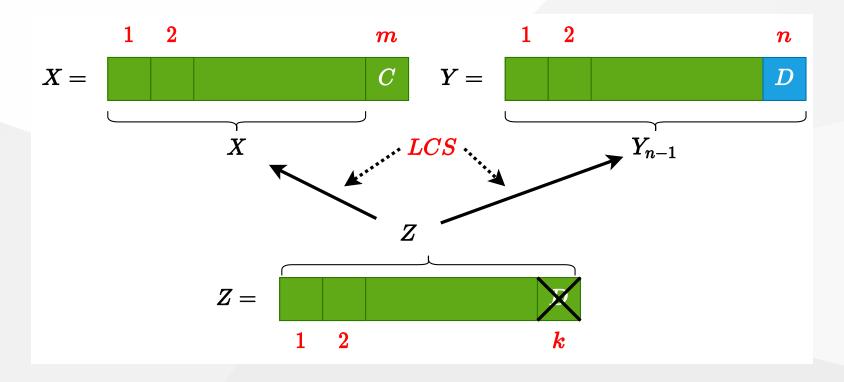
ullet If  $x_m 
eq y_n$  and  $z_k 
eq x_m$  then Z is an **LCS** of  $X_{m-1}$  and Y

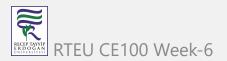




### **Optimal Substructure Theorem (case 3)**

ullet If  $x_m 
eq y_n$  and  $z_k 
eq y_n$  then Z is an **LCS** of X and  $Y_{n-1}$ 





### **Proof of Optimal Substructure Theorem (case 1)**

- ullet If  $x_m=y_n$  then  $z_k=x_m=y_n$  and  $Z_{k-1}$  is an LCS of  $X_{m-1}$  and  $Y_{n-1}$
- ullet Proof: If  $z_k 
  eq x_m = y_n$  then
  - $\circ$  we can append  $x_m=y_n$  to Z to obtain a common subsequence of length  $k+1\Longrightarrow {\sf contradiction}$
  - $\circ$  Thus, we must have  $z_k=x_m=y_n$
  - $\circ$  Hence, the prefix  $Z_{k-1}$  is a **length-(**k-1**) CS** of  $X_{m-1}$  and  $Y_{n-1}$
- ullet We have to show that  $Z_{k-1}$  is in fact an LCS of  $X_{m-1}$  and  $Y_{n-1}$
- Proof by contradiction:
  - $\circ$  Assume that  $\exists$  a CS W of  $X_{m-1}$  and  $Y_{n-1}$  with |W|=k
  - $\circ$  Then appending  $x_m=y_n$  to W produces a **CS** of length k+1



### **Proof of Optimal Substructure Theorem (case 2)**

- ullet If  $x_m 
  eq y_n$  and  $z_k 
  eq x_m$  then Z is an **LCS** of  $X_{m-1}$  and Y
- ullet Proof : If  $z_k 
  eq x_m$  then Z is a CS of  $X_{m-1}$  and  $Y_n$ 
  - $\circ$  We have to show that Z is in fact an LCS of  $X_{m-1}$  and  $Y_n$
- (Proof by contradiction)
  - $\circ$  Assume that  $\exists$  a CS W of  $X_{m-1}$  and  $Y_n$  with |W|>k
  - $\circ$  Then W would also be a CS of X and Y
  - Contradiction to the assumption that
    - lacksquare Z is an LCS of X and Y with |Z|=k
- Case 3: Dual of the proof for (case 2)



### A Recursive Solution to Subproblems

- Theorem implies that there are one or two subproblems to examine
- if  $x_m = y_n$  then
  - $\circ$  we must solve the subproblem of finding an **LCS** of  $X_{m-1}\&Y_{n-1}$
  - $\circ$  appending  $x_m=y_n$  to this **LCS** yields an **LCS** of X&Y
- else
  - we must solve two subproblems
    - finding an LCS of  $X_{m-1}\&Y$
    - finding an LCS of  $X\&Y_{n-1}$
  - $\circ$  longer of these two **LCS** s is an **LCS** of X&Y
- endif



#### Recursive Algorithm (Inefficient)

```
LCS(X,Y) {
   m \leftarrow length[X]
   n \leftarrow length[Y]
   if x_m = y_n then
       Z \leftarrow \mathrm{LCS}(X_{m-1}, Y_{n-1}) \triangleright \text{solve one subproblem}
       return \langle Z, x_m = y_n \rangle \triangleright append x_m = y_n to Z
   else
       Z^{'} \leftarrow \mathrm{LCS}(X_{m-1},Y) 	riangleright 	ext{solve two subproblems}
       Z^{''} \leftarrow \mathrm{LCS}(X, Y_{n-1})
       return longer of Z^{'} and Z^{''}
```

#### **A Recursive Solution**

ullet c[i,j] : length of an LCS of  $X_i$  and  $Y_j$ 

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i 
eq y_j \end{array}
ight.$$



- We can easily write an **exponential-time recursive algorithm** based on the given recurrence.  $\Longrightarrow$  **Inefficient!**
- How many distinct subproblems to solve?
  - $\circ~\Theta(mn)$
- Overlapping subproblems property: Many subproblems share the same subsubproblems.
  - $\circ$  e.g. Finding an LCS to  $X_{m-1}\&Y$  and an LCS to  $X\&Y_{n-1}$
  - $\circ$  has the sub-subproblem of finding an **LCS** to  $X_{m-1}\&Y_{n-1}$
- Therefore, we can use dynamic programming.



#### **Data Structures**

- Let:
  - $\circ\ c[i,j]:$  length of an LCS of  $X_i$  and  $Y_j$
  - $\circ$  b[i,j]: direction towards the table entry corresponding to the optimal subproblem solution chosen when computing c[i,j].
  - Used to simplify the construction of an optimal solution at the end.
- Maintain the following tables:
  - $\circ \ c[0 \dots m, 0 \dots n]$



#### **Bottom-up Computation**

• Reminder:

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i 
eq y_j \end{array}
ight.$$

- ullet How to choose the order in which we process c[i,j] values?
- ullet The values for c[i-1,j-1], c[i,j-1], and c[i-1,j] must be computed before computing c[i,j].



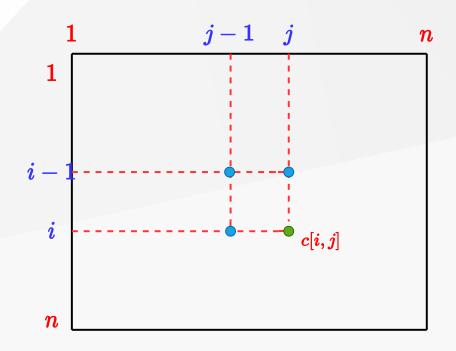
#### **Bottom-up Computation**

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i
eq y_j \end{array}
ight.$$

#### Need to process:

#### after computing:

$$egin{aligned} c[i-1,j-1],\ c[i,j-1],\ c[i-1,j] \end{aligned}$$



#### **Bottom-up Computation**

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if} & i=0 ext{ or } j=0 \ c[i-1,j-1]+1 & ext{if} & i,j>0 ext{ and } x_i=y_j \ \max\{c[i,j-1],c[i-1,j]\} & ext{if} & i,j>0 ext{ and } x_i 
eq y_j \end{array}
ight.$$

 $\Downarrow$ 

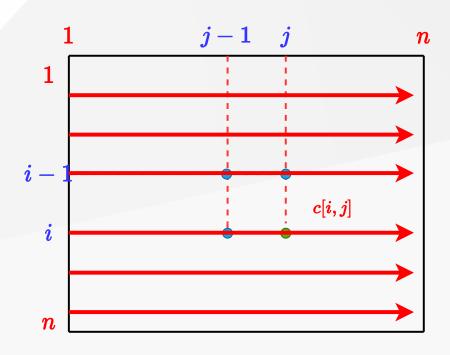
for  $i \leftarrow 1$  to m

for  $j \leftarrow 1$  to n

• •

. . .

$$c[i,j] = \cdots$$



$$rac{ ext{Total Runtime} = \Theta(mn)}{ ext{Total Space} = \Theta(mn)}$$

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

$\downarrow i/j$	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0						
2B	0						
3C	0						
4B	0						
5D	0						
6A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} \rangle$$
 $Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} \rangle$ 

1	. $i/j$ $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>†</b>	<b>†</b>	<b>†</b>	1	<del>←</del> 1	1
	2B	0						
	3~C	0						
	4 B	0						
	5 D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

<b></b>	. $i/j$ $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>†</b>	<b>†</b> 0	<b>1</b> 0	1	<del>←</del> 1	1
	2 B	0	1	<del>←</del> 1	<b>←</b> 1	<b>1</b>	2	$\leftarrow$ 2
	3 C	0						
	4 B	0						
	5D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

1	. $i/j$ $ ightarrow$	$\rightarrow 0y_{j}$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\stackrel{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>1 0</b>	<b>1 0</b>	<b>1 0</b>	<u>۲</u>	<del>←</del> 1	1
	2 B	0	1	$\leftarrow$ 1	$\leftarrow$ 1	<b>1</b>	2	$\leftarrow$ 2
	3 C	0	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	$\leftarrow 2$	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	$egin{pmatrix} igwedge \ 2 \end{matrix}$
	4 B	0						
	5D	0						
	6A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

-	$\downarrow i/j - i$	$ ightarrow 0 y_j$	1 <i>B</i>	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\stackrel{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>1</b> 0	<b>1</b> 0	<b>1</b> 0	1	<u>←</u>	1
	2 B	0	1	<del>←</del> 1	<del>←</del> 1	<b>1</b>	2	$\leftarrow$ 2
	3 C	0	<b>1</b>	<b>1</b>	2	$\leftarrow$ 2	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1					
	5D	0						
	6~A	0						
	7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

$\downarrow i/j  ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1A	0	<b>†</b> 0	<b>1</b> 0	<b>†</b> 0	<u>ر</u> 1	<del>←</del> 1	1
2 B	0	1	$\leftarrow$ 1	<u>←</u>	<b>1</b>	2	$\leftarrow$ 2
3 C	0	$egin{pmatrix} igwedge \ 1 \end{matrix}$	<b>1</b>	2	$\leftarrow$ 2	$egin{array}{c} \uparrow \ 2 \end{array}$	<b>1 2</b>
4B	0	1	<b>1</b>				
5D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

$\downarrow i/j - i$	$ ightarrow 0 y_j$	$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	<b>†</b>	<b>1</b> 0	$\uparrow$	1	<u>←</u>	1
2 B	0	1	<u>←</u>	<del>←</del> 1	<b>1</b>	2	$iggraphi_{f 2}$
3 C	0	$egin{pmatrix} igwedge \ 1 \end{matrix}$	<b>1</b>	2	$\leftarrow 2$	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	1	<b>1</b>	$egin{pmatrix} igwedge 2 \end{matrix}$			
5D	0						
6~A	0						
7 B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

$\downarrow i/j  ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	<b>†</b> 0	<b>†</b> 0	<b>†</b> 0	<u>ر</u> 1	<del>←</del> 1	1
2 B	0	1	$\leftarrow$ 1	<u>←</u>	<b>1</b>	2	$\leftarrow$ 2
3 C	0	$\uparrow$ 1	<b>1</b>	2	$\leftarrow$ 2	<b>1 2</b>	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	1	<b>1</b>	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$		
5 D	0						
6~A	0						
7B	0						
			_				

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

$\downarrow i/j  ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	<b>†</b> 0	<b>†</b> 0	<b>†</b> 0	1	<del>←</del> 1	1
2 B	0	1	$\leftarrow$ 1	<u>←</u>	<b>1</b>	2	$\leftarrow$ 2
3 C	0	$\uparrow$ 1	<b>1</b>	2	$\leftarrow$ 2	$egin{pmatrix} \uparrow & \ 2 & \ \end{matrix}$	<b>† 2</b>
4B	0	1	<b>1</b>	$egin{pmatrix} igwedge 2 \end{matrix}$	<b>1 2</b>	3	
5 D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

$\downarrow i/j  ightarrow 0 y_j$		$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 <i>A</i>	0	<b>†</b> 0	<b>†</b> 0	<b>†</b> 0	1	<u>←</u>	1
2 B	0	1	$\leftarrow$ 1	<u>←</u>	<b>1</b>	2	$\leftarrow 2$
3 C	0	$\uparrow$ 1	<b>1</b>	2	$\leftarrow$ 2	$egin{pmatrix} \uparrow & \ 2 & \ \end{matrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$
4B	0	1	<b>1</b>	<b>1 2</b>	<b>1 2</b>	3	$\frac{\leftarrow}{3}$
5 D	0						
6~A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

$\downarrow i/j$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	<b>0</b>	<b>0</b>	<b>1 0</b>	1	$\leftarrow$ 1	1
2 B	0	1	$\leftarrow$ 1	$\leftarrow$ 1	<b>1</b>	2	$iggraphi_{f 2}$
3 C	0	$\uparrow$ 1	<b>1</b>	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4 B	0	<u>۲</u>	<b>1</b>	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	† 1	2	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	<b>†</b> 3	$egin{pmatrix} \uparrow \ 3 \end{bmatrix}$
6 A	0						
7B	0						

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} 
angle \ Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} 
angle$$

1	i/j - i	$\rightarrow 0y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$_{A}^{6}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>†</b>	<b>0</b>	<b>0</b>	1	$\leftarrow$ 1	<u>ر</u> 1
	2 B	0	1	$\leftarrow$ 1	$\leftarrow$ 1	<b>1</b>	2	$\leftarrow 2$
	3 C	0	<b>1</b>	$\uparrow$ 1	2	$\leftarrow$ 2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$
	4B	0	1	<b>1</b>	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\frac{\leftarrow}{3}$
	5 D	0	<b>1</b>	2	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{pmatrix} igspace 2 \end{matrix}$	$\uparrow$ 3	<b>3</b>
	6A	0	<b>1</b>	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	<b>† 3</b>	4
	7 B	0						

Operation of LCS-LENGTH on the sequences

$$X = \langle \overset{1}{A}, \overset{2}{B}, \overset{3}{C}, \overset{4}{B}, \overset{5}{D}, \overset{6}{A}, \overset{7}{B} \rangle$$
 $Y = \langle \overset{1}{B}, \overset{2}{D}, \overset{3}{C}, \overset{4}{A}, \overset{5}{B}, \overset{6}{A} \rangle$ 

• Running-time = O(mn)since each table entry takes O(1) time to compute

<b>↓</b>	. $i/j  ightarrow$	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>1</b> 0	<b>†</b>	<b>†</b>	1	<del>←</del> 1	1
	2 B	0	1	<b>←</b> 1	<b>←</b> 1	$egin{pmatrix} \uparrow \\ 1 \end{bmatrix}$	2	$\leftarrow 2$
	3 C	0	1 1	$egin{pmatrix} lack \ 1 \end{matrix}$	2	$\leftarrow$ 2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	$egin{pmatrix} \uparrow & & \\ 1 & & \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} igwedge 2 \end{matrix}$	3	$\leftarrow 3$
	5 D	0	$egin{pmatrix} \uparrow & \ 1 & \ \end{matrix}$	2	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$	$\uparrow$ 3	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	$egin{pmatrix} \uparrow \\ 1 \end{bmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	<b>†</b> 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	$\uparrow$ 3	<b>†</b> 3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{bmatrix}$

$$X = \langle \stackrel{1}{A}, \stackrel{2}{B}, \stackrel{3}{C}, \stackrel{4}{B}, \stackrel{5}{D}, \stackrel{6}{A}, \stackrel{7}{B} \rangle$$
 $Y = \langle \stackrel{1}{B}, \stackrel{2}{D}, \stackrel{3}{C}, \stackrel{4}{A}, \stackrel{5}{B}, \stackrel{6}{A} \rangle$ 

- Running-time = O(mn)since each table entry takes O(1) time to compute
- LCS of  $X\&Y = \langle B,C,B,A \rangle$

1	. $i/j$ $ ightarrow$	$0y_j$	$\frac{1}{B}$	D = D	$\frac{3}{C}$	$\stackrel{4}{A}$	$\frac{5}{B}$	$egin{array}{c} 6 \ A \end{array}$
	$0x_i$	0	0	0	0	0	0	0
	1 <i>A</i>	0	$ \uparrow $	$ \uparrow $	<b>1</b> 0	1	<del>←</del> 1	1
	2 B	0	<u>ر</u> 1	<del>←</del> 1	<b>←</b> 1	$\uparrow$ 1	2	$iggrup rac{\leftarrow}{2}$
	3 C	0	<b>1</b>	$egin{pmatrix} lack \ 1 \end{matrix}$	2	$\overset{\longleftarrow}{2}$	$egin{array}{c} oldsymbol{\uparrow} \ oldsymbol{2} \end{array}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	<u>ر</u> 1	$egin{pmatrix} lacktriangle & lacktriangle$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} oldsymbol{\uparrow} \ oldsymbol{2} \end{array}$	3	iggraphsize
	5 D	0	$\uparrow$ 1	2	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$\stackrel{ o}{3}$	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	$\uparrow$ 1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	<b>†</b> 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	$\uparrow$ 3	$\uparrow$ 3	4	↑ <b>4</b>

#### Constructing an LCS

- ullet The b table returned by **LCS-LENGTH** can be used to quickly construct an **LCS** of X&Y
- ullet Begin at b[m,n] and trace through the table following arrows
- ullet Whenever you encounter a "widthick ullet" in entry b[i,j] it implies that  $x_i=y_j$  is an element of **LCS**
- The elements of LCS are encountered in reverse order



#### Constructing an LCS

- The recursive procedure PRINT-LCS prints out LCS in proper order
- ullet This procedure takes O(m+n) time since at least one of i and j is decremented in each stage of the recursion

```
PRINT-LCS(b, X, i, j)
  if i = 0 or j = 0 then
  return
  if b[i,j] = " \nwarrow " then
    PRINT-LCS(b, X, i-1, j-1)
    print x_i
  else if b[i,j] = " \uparrow " then
    PRINT-LCS(b, X, i - 1, j)
  else
    PRINT-LCS(b, X, i, j - 1)
```

• The initial invocation:  $\operatorname{PRINT-LCS}(b,X,length[X],length[Y])$ 

# Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- Answer: Upper-left neighbor, because X[i] = Y[j].

<b>\</b>	. $i/j  ightarrow$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\overset{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>1</b> 0	<b>0</b>	<b>1 0</b>	1	$\leftarrow$ 1	
	2 B	0	1	$\leftarrow$ 1	<b>←</b> 1	$egin{pmatrix} ightarrow \ 1 \end{matrix}$	2	$oxed{\leftarrow 2}$
	3 C	0	<b>1</b>	<b>1</b>	2	$\leftarrow$ 2	$egin{pmatrix} egin{pmatrix} egi$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	<b>1</b>	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$oxed{\leftarrow 3}$
	5 D	0	<b>1</b>	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	$egin{array}{c} \uparrow \ 3 \end{array}$	$egin{array}{c} \uparrow \ 3 \end{array}$
	6 A	0	<b>1</b>	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	<b>†</b> 3	4
	7 B	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	<b>†</b> 3	<b>†</b> 3	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{bmatrix}$

# Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- ullet Answer: Left neighbor, because X[i] 
  eq Y[j] and LCS[i,j-1] > LCS[i-1,j].

<b>↓</b>	. $i/j  ightarrow i$	$0y_j$	$\frac{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>†</b>	<b>↑ 0</b>	<b>†</b>	1	<del>←</del> 1	1
	2 B	0	1	$\leftarrow$ 1	$\leftarrow$ 1	<b>1</b>	2	$iggraphi_{f 2}$
	3 C	0	<b>1</b>	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5 D	0	<b>1</b>	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	<b>† 3</b>	$egin{pmatrix} \uparrow \ 3 \end{bmatrix}$
	6A	0	<b>1</b>	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	3	<b>† 3</b>	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	<b>† 3</b>	<b>† 3</b>	4	$egin{array}{c} \uparrow \ oldsymbol{4} \end{array}$

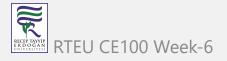
# Do we really need the b table (back-pointers)?

- Question: From which neighbor did we expand to the highlighted cell?
- ullet Answer: Upper neighbor,because X[i] 
  eq Y[j] and LCS[i,j-1] = LCS[i-1,j]. (See pseudo-code to see how ties are handled.)

<b>↓</b> 1	i/j  ightarrow	$0y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1A	0	<b>†</b>	<b>1 0</b>	<b>†</b>	1	<del>←</del> 1	
	2B	0	1	$\leftarrow$ 1	$\leftarrow$ 1	1 1	2	$oxed{\leftarrow 2}$
	3 C	0	$\uparrow$ 1	1 1	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1	1 1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	3	iggraphsize
	5D	0	$\uparrow$ 1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} egi$	<b>† 3</b>	$egin{array}{c} \uparrow \ 3 \end{array}$
	6A	0	<b>1</b>	$egin{pmatrix} egin{pmatrix} egi$	$egin{pmatrix} egin{pmatrix} egi$	3	<b>† 3</b>	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	<b>† 3</b>	<b>† 3</b>	4	$egin{array}{c} \uparrow \ 4 \end{array}$

#### Improving the Space Requirements

- We can eliminate the b table altogether
  - $\circ$  each c[i,j] entry depends only on 3 other c table entries: c[i-1,j-1], c[i-1,j] and c[i,j-1]
- Given the value of c[i,j]:
  - $\circ$  We can determine in O(1) time which of these 3 values was used to compute c[i,j] without inspecting table b
  - $\circ$  We save  $\Theta(mn)$  space by this method
  - $\circ$  However, space requirement is still  $\Theta(mn)$  since we need  $\Theta(mn)$  space for the c table anyway



- ullet To compute c[i,j], we only need c[i-1,j-1], c[i-1,j],and c[i-1,j-1]
- So, we can store only the last two rows.

$\downarrow i/j -$	$0y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\overset{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	$\uparrow$	<b>1</b> 0	<b>1</b> 0	1	<del>←</del> 1	1
2 B	0	1	<b>←</b> 1	$\stackrel{\longleftarrow}{1}$	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	2	$oxed{\leftarrow 2}$
3 C	0	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4B	0	<u>ر</u> 1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	<b>1</b>	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	<b>† 3</b>	$egin{array}{c} \uparrow \ 3 \end{array}$
6~A	0	<b>1</b>	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} egi$	3	<b>† 3</b>	4
7 B	0	1	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	<b>1</b> 3	<b>1</b> 3	4	$egin{pmatrix} \uparrow \\ 4 \end{bmatrix}$

- $oldsymbol{\circ}$  To compute c[i,j], we only need c[i-1,j-1], c[i-1,j], and c[i-1,j-1]
- So, we can store only the last two rows.

$\downarrow i/j$ $-$	$ ightarrow 0 y_j$	$\frac{1}{B}$	$\stackrel{2}{D}$	$\frac{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
$0x_i$	0	0	0	0	0	0	0
1 A	0	<b>†</b>	<b>†</b> 0	<b>†</b>	1	<b>←</b> 1	1
2 B	0	1	$\leftarrow$ 1	<b>←</b> 1	$egin{pmatrix} ightarrow \ egin{pmatrix} ightarrow \ ightarrow \ \end{bmatrix}$	2	$oxed{\leftarrow 2}$
3 C	0	<b>1</b>	<b>1</b>	2	$\leftarrow 2$	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
4 B	0	<u>ر</u> 1	† 1	$\uparrow$ 2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	3	$\leftarrow 3$
5 D	0	<b>† 1</b>	2	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} egi$	$\uparrow$ 3	↑ <b>3</b>
6 A	0	<b>†</b> 1	$egin{pmatrix} igspace 2 \end{matrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	<b>† 3</b>	4
7 B	0	<u>۲</u>	$egin{pmatrix} ightarrow{1}{2} \ \end{array}$	<b>† 3</b>	<b>† 3</b>	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

- $oldsymbol{\circ}$  To compute c[i,j], we only need c[i-1,j-1], c[i-1,j], and c[i-1,j-1]
- So, we can store only the last two rows.
- This reduces space complexity from  $\Theta(mn)$  to  $\Theta(n)$ .
- Is there a problem with this approach?

1	i/j  ightharpoonup i	$ ightarrow 0 y_j$	$\stackrel{1}{B}$	$\stackrel{ extbf{2}}{D}$	$\overset{3}{C}$	$egin{array}{c} A \ A \end{array}$	$\overset{5}{B}$	$\overset{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>†</b>	<b>0</b>	<b>†</b>	1	<del>←</del> 1	1
	2 B	0	1	$\leftarrow$ 1	$\stackrel{\longleftarrow}{1}$	<b>1</b>	2	$iggrup_{f 2}$
	3 C	0	<b>1</b>	<b>1</b>	2	$\leftarrow 2$	$egin{pmatrix} igwedge 2 \end{matrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4B	0	1	<b>1</b>	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5D	0	<b>† 1</b>	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} igwedge 2 \end{matrix}$	$\uparrow 3$	↑ <b>3</b>
	6A	0	<b>†</b> 1	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	<b>3</b>	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{matrix}$	<b>† 3</b>	<b>3</b>	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

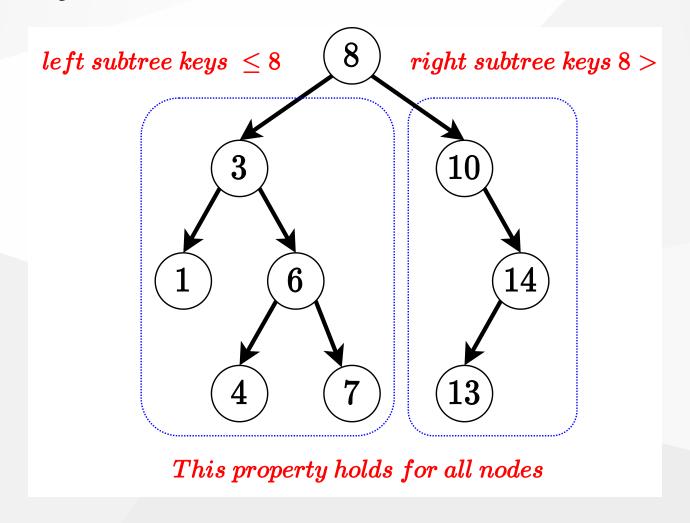
- Is there a problem with this approach?
  - We cannot construct the optimal solution because we cannot backtrace anymore.
  - This approach works if we only need the length of an LCS, not the actual LCS.

<b>↓</b>	. $i/j  ightarrow$	$0y_j$	$\overset{1}{B}$	$\overset{2}{D}$	$\overset{3}{C}$	$\stackrel{4}{A}$	$\overset{5}{B}$	$\stackrel{6}{A}$
	$0x_i$	0	0	0	0	0	0	0
	1 A	0	<b>†</b>	<b>1 0</b>	<b>†</b>	1	<b>←</b> 1	1
	2 B	0	1	$\leftarrow$ 1	<b>←</b> 1	$egin{pmatrix} igwedge \ 1 \end{matrix}$	2	iggraphi
	3 C	0	<b>1</b>	<b>1</b>	2	$\leftarrow$ 2	$egin{pmatrix} igwedge \ egin{pmatrix} igwedge \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	$egin{array}{c} \uparrow \ 2 \end{array}$
	4 B	0	1	<b>1</b>	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	3	$\leftarrow 3$
	5 D	0	<b>†</b> 1	2	$egin{pmatrix} oldsymbol{\uparrow} \ oldsymbol{2} \end{pmatrix}$	$egin{array}{c} \uparrow \ 2 \end{array}$	$egin{array}{c} \uparrow \ 3 \end{array}$	↑ 3
	6A	0	<b>† 1</b>	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	$egin{pmatrix} egin{pmatrix} \egn{pmatrix} \e$	3	<b>†</b> 3	4
	7 B	0	1	$egin{pmatrix} \uparrow \ 2 \end{bmatrix}$	<b>† 3</b>	<b>3</b>	4	$egin{pmatrix} \uparrow & \ 4 & \ \end{matrix}$

### **Problem 4 Optimal Binary Search Tree**



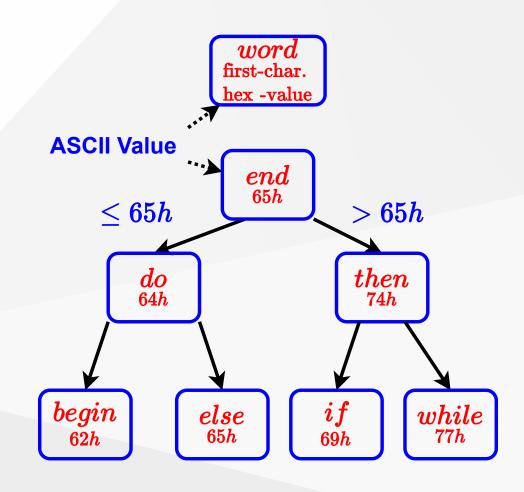
### Reminder: Binary Search Tree (BST)





### **Binary Search Tree Example**

- Example: English-to-French translation
  - Organize (English, French) word pairs in a BST
    - Keyword: English word
    - Satellite Data: French word
- We can search for an English word (node key) efficiently, and return the corresponding French word (satellite data).



# **ASCII Table**

Dec	Hex	0ct	Char	Dec	Hex	0ct	Char	Dec	Hex	0ct	Char	Dec	Hex	0ct	Char
0	0	0		32	20	40	[space]	64	40	100	@	96	60	140	`
1	1	1		33	21	41	!	65	41	101	Α	97	61	141	a
2	2	2		34	22	42	"	66	42	102	В	98	62	142	b
3	3	3		35	23	43	#	67	43	103	С	99	63	143	С
4	4	4		36	24	44	\$	68	44	104	D	100	64	144	d
5	5	5		37	25	45	%	69	45	105	E	101	65	145	e
6	6	6		38	26	46	&	70	46	106	F	102	66	146	f
7	7	7		39	27	47		71	47	107	G	103	67	147	g
8	8	10		40	28	50	(	72	48	110	Н	104	68	150	h
9	9	11		41	29	51	)	73	49	111	1	105	69	151	i
10	Α	12		42	2A	52	*	74	4A	112	J	106	6A	152	j
11	В	13		43	2B	53	+	75	4B	113	K	107	6B	153	k
12	C	14		44	2C	54	,	76	4C	114	L	108	6C	154	1
13	D	15		45	2D	55	-	77	4D	115	M	109	6D	155	m
14	Е	16		46	2E	56		78	4E	116	N	110	6E	156	n
15	F	17		47	2F	57	/	79	4F	117	Ο	111	6F	157	0
16	10	20		48	30	60	0	80	50	120	Р	112	70	160	р
17	11	21		49	31	61	1	81	51	121	Q	113	71	161	q
18	12	22		50	32	62	2	82	52	122	R	114	72	162	r
19	13	23		51	33	63	3	83	53	123	S	115	73	163	S
20	14	24		52	34	64	4	84	54	124	Т	116	74	164	t
21	15	25		53	35	65	5	85	55	125	U	117	75	165	u
22	16	26		54	36	66	6	86	56	126	V	118	76	166	V
23	17	27		55	37	67	7	87	57	127	W	119	77	167	W
24	18	30		56	38	70	8	88	58	130	X	120	78	170	X
25	19	31		57	39	71	9	89	59	131	Υ	121	79	171	У
26	1A	32		58	3A	72	:	90	5A	132	Z	122	7A	172	Z
27	1B	33		59	3B	73	;	91	5B	133	[	123	7B	173	{
28	1C	34		60	3C	74	<	92	5C	134	\	124	7C	174	
29	1D	35		61	3D	75	=	93	5D	135	]	125	7D	175	}
30	1E	36		62	3E	76	>	94	5E	136	^	126	7E	176	~
31	1F	37		63	3F	77	?	95	5F	137	_	127	7F	177	

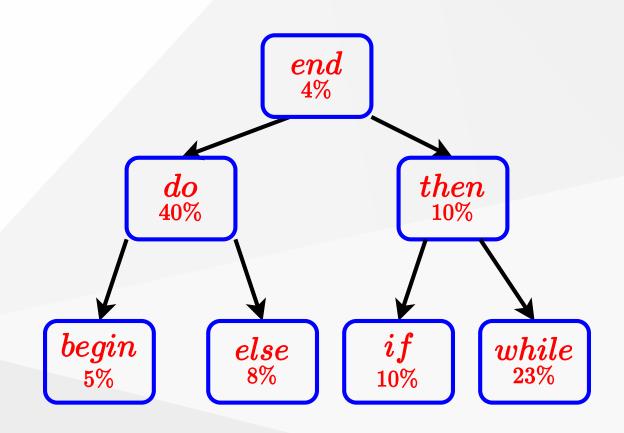


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# **Binary Search Tree Example**

Suppose we know the frequency of each keyword in texts:

$$\frac{begin}{5\%}, \frac{do}{40\%}, \frac{else}{8\%}, \frac{end}{4\%}, \frac{if}{10\%}, \frac{then}{10\%}, \frac{while}{23\%},$$



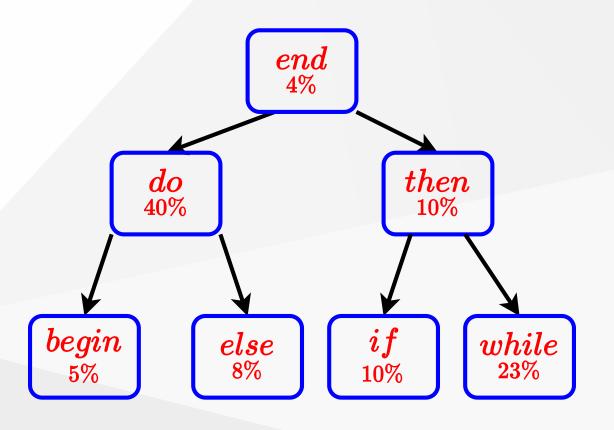


# **Cost of a Binary Search Tree**

**Example:** If we search for keyword "while", we need

to access 3 nodes. So, 23 of the queries will have cost of 3.

$$egin{aligned} ext{Total Cost} &= \sum_i ( ext{depth}(i) + 1) ext{freq}(i) \ &= 1 imes 0.04 + 2 imes 0.4 + \ 2 imes 0.1 + 3 imes 0.05 + \ 3 imes 0.08 + 3 imes 0.1 + \ 3 imes 0.23 \ &= 2.42 \end{aligned}$$





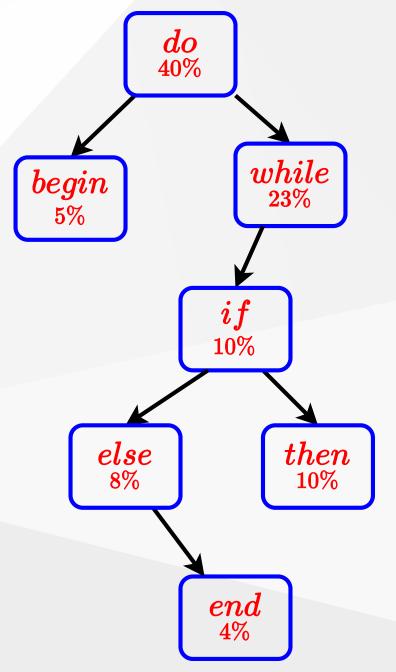
## Cost of a Binary Search Tree

**Example:** If we search for keyword "while", we need to access 3 nodes. So, 23 of the queries will have cost of 3.

$$egin{aligned} ext{Total Cost} &= \sum_i ( ext{depth}(i) + 1) ext{freq}(i) \ &= 1 imes 0.4 + 2 imes 0.05 + 2 imes 0.23 + \ &3 imes 0.1 + 4 imes 0.08 + \ &4 imes 0.1 + 5 imes 0.04 \ &= 2.18 \end{aligned}$$

This is in fact an optimal BST.





# **Optimal Binary Search Tree Problem**

- Given:
  - $\circ$  A collection of n keys  $K_1 < K_2 < \ldots K_n$  to be stored in a **BST**.
  - $\circ$  The corresponding  $p_i$  values for  $1 \leq i \leq n$ 
    - $p_i$ : probability of searching for key  $K_i$
- Find:
  - An optimal BST with minimum total cost:

$$ext{Total Cost} = \sum_i ( ext{depth}(i) + 1) ext{freq}(i)$$

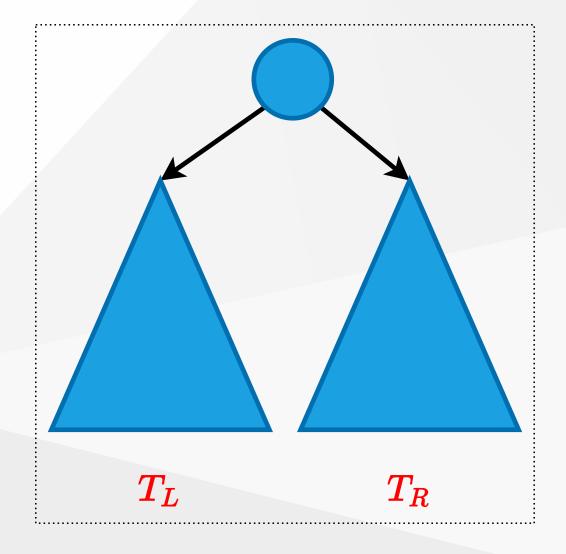
• Note: The BST will be static. Only search operations will be performed. No insert, no delete, etc.

# **Cost of a Binary Search Tree**

• Lemma 1: Let Tij be a BST containing keys  $K_i < K_{i+1} < \cdots < K_j$ . Let  $T_L$  and  $T_R$  be the left and right subtrees of T. Then we have:

$$\mathrm{cost}(T_{ij}) = \mathrm{cost}(T_L) + \mathrm{cost}(T_R) + \sum_{h=i}^{j} p_h$$

Intuition: When we add the root node, the depth of each node in  $T_L$  and  $T_R$  increases by 1. So, the cost of node h increases by  $p_h$ . In addition, the cost of root node r is  $p_r$ . That's why, we have the last term at the end of the formula above.





# **Optimal Substructure Property**

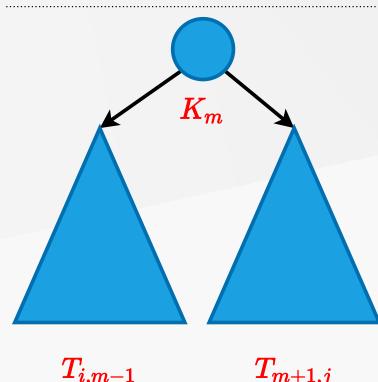
- Lemma 2: Optimal substructure property
  - $\circ$  Consider an optimal BST  $T_{ij}$  for keys  $K_i < K_{i+1} <$  $\cdots < K_i$
  - $\circ$  Let  $K_m$  be the key at the root of  $T_{ij}$
- Then:
  - $\circ T_{i,m-1}$  is an **optimal BST** for subproblem containing keys:

• 
$$K_i < \cdots < K_{m-1}$$

 $\circ T_{m+1,j}$  is an **optimal BST** for subproblem containing keys:

• 
$$K_{m+1} < \cdots < K_j$$

$$\operatorname{cost}(T_{ij}) = \operatorname{cost}(T_{i,m-1}) + \operatorname{cost}(T_{m+1,j}) + \sum_{h=i}^{j} p_h$$



#### **Recursive Formulation**

- Note: We don't know which root vertex leads to the minimum total cost. So, we need to try each vertex m, and choose the one with minimum total cost.
- ullet c[i,j]: cost of an optimal BST  $T_{ij}$  for the subproblem  $K_i < \cdots < K_j$

$$c[i,j] = \left\{egin{array}{l} 0 & ext{if } i>j \ \min_{i \leq r \leq j} \{c[i,r-1] + c[r+1,j] + P_{ij}\} \end{array}
ight. ext{otherwise} 
ight.$$
 where  $P_{ij} = \sum_{h=i}^{j} p_h$ 



### **Bottom-up computation**

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if } i>j \ \min_{i \leq r \leq j} \{c[i,r-1] + c[r+1,j] + P_{ij}\} & ext{otherwise} \end{array}
ight.$$

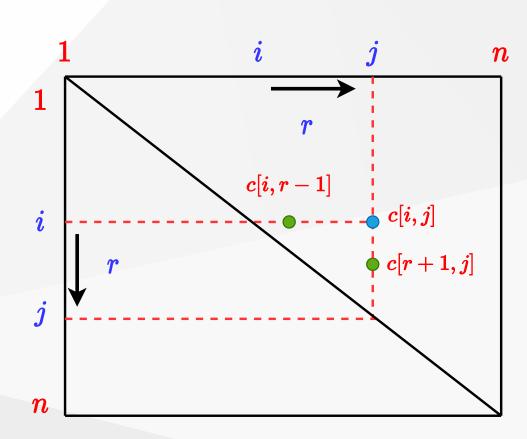
- ullet How to choose the order in which we process c[i,j] values?
- ullet Before computing c[i,j], we have to make sure that the values for c[i,r-1] and c[r+1,j] have been computed for all r.



### **Bottom-up computation**

$$c[i,j] = \left\{egin{array}{ll} 0 & ext{if } i>j \ \min_{i \leq r \leq j} \{c[i,r-1] + c[r+1,j] + P_{ij}\} \end{array}
ight. ext{otherwise}$$

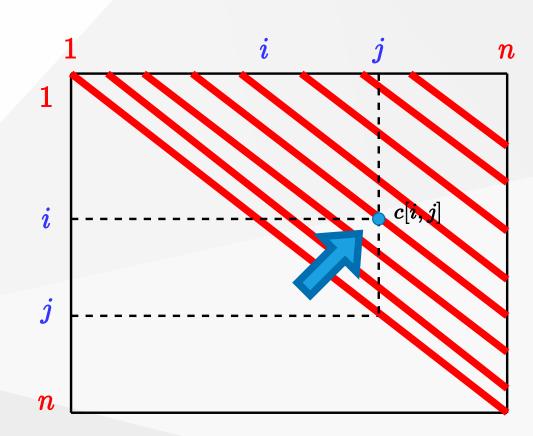
ullet c[i,j] must be processed after c[i,r-1] and c[r+1,j]



## **Bottom-up computation**

$$c[i,j] = \left\{egin{array}{l} 0 & ext{if } i>j \ \min_{i \leq r \leq j} \{c[i,r-1] + c[r+1,j] + P_{ij}\} \end{array}
ight. ext{otherwise}$$

ullet If the entries c[i,j] are computed in the shown order, then c[i,r-1] and c[r+1,j] values are guaranteed to be computed before c[i,j].





## **Computing the Optimal BST Cost**

```
OPTIMAL-BST-COST(p, n)
  for i \leftarrow 1 to n do
      c[i,i-1] \leftarrow 0
      c[i,i] \leftarrow p[i]
      R[i,j] \leftarrow i
  PS[1] \leftarrow p[1] \iff PS[i] \rightarrow \text{ prefix-sum } (i) : \text{Sum of all } p[j] \text{ values for } j \leq i
  for i \leftarrow 2 to n do
      PS[i] \leftarrow p[i] + PS[i-1] \iff \text{compute the prefix sum}
  for d \leftarrow 1 to n-1 do \iff BSTs with d+1 consecutive keys
      for i \leftarrow 1 to n-d do
        j \leftarrow i + d
         c[i,j] \leftarrow \infty
         for r \leftarrow i to j do
            q \leftarrow min\{c[i, r-1] + c[r+1, j]\} + PS[j] - PS[i-1]\}
            if q < c[i, j] then
               c[i,j] \leftarrow q
               R[i,j] \leftarrow r
  return c[1, n], R
```

#### **Note on Prefix Sum**

• We need  $P_{ij}$  values for each  $i, j (1 \le i \le n \text{ and } 1 \le j \le n)$ , where:

$$P_{ij} = \sum_{h=i}^{j} p_h$$

- If we compute the summation directly for every (i,j) pair, the runtime would be  $\Theta(n^3)$ .
- Instead, we spend O(n) time in preprocessing to compute the prefix sum array **PS**. Then we can compute each  $P_{ij}$  in O(1) time using **PS**.



#### **Note on Prefix Sum**

- In preprocessing, compute for each i:
  - $\circ \ PS[i]$ : the sum of p[j] values for  $1 \leq j \leq i$
- Then, we can compute  $P_{ij}$  in O(1) time as follows:

$$\circ \ P_{ij} = PS[i] – PS[j-1]$$

• Example:

$$p: 0.\overset{1}{05} \ 0.\overset{2}{02} \ 0.\overset{3}{06} \ 0.\overset{4}{07} \ 0.\overset{5}{20} \ 0.\overset{6}{05} \ 0.\overset{7}{08} \ 0.\overset{8}{02}$$

$$PS: 0.05 \stackrel{1}{0.07} \stackrel{2}{0.13} \stackrel{3}{0.20} \stackrel{4}{0.40} \stackrel{5}{0.45} \stackrel{6}{0.53} \stackrel{7}{0.55}$$

$$P_{27} = PS[7] - PS[1] = 0.53 - 0.05 = 0.48$$

$$P_{36} = PS[6] - PS[2] = 0.45 - 0.07 = 0.38$$



# **Most Common Dynamic Programming Interview Questions**



- Problem-1: Longest Increasing Subsequence
  - https://www.geeksforgeeks.org/longest-increasing-subsequence-dp-3/
  - https://en.wikipedia.org/wiki/Longest\_increasing\_subsequence#:~:text=In
     computer science%2C the longest,not necessarily contiguous%2C or unique.
  - https://www.youtube.com/watch?v=22s1xxRvy28&ab\_channel=StableSort



- Problem-2: Edit Distance
  - https://www.geeksforgeeks.org/edit-distance-dp-5/
  - https://www.youtube.com/watch?
     v=tU2f2JwHmfQ&feature=youtu.be&ab\_channel=PrepForTech
  - Recursive
    - https://www.youtube.com/watch?v=8Q2IEIY2pDU&ab\_channel=BenLangmead
  - o DP
    - https://www.youtube.com/watch? v=0KzWq118UNI&ab\_channel=BenLangmead
    - https://www.youtube.com/watch? v=eAVGRWSryGo&ab\_channel=BenLangmead



- Problem-3: Partition a set into two subsets such that the difference of subset sums is minimum
  - https://www.geeksforgeeks.org/partition-a-set-into-two-subsets-such-thatthe-difference-of-subset-sums-is-minimum/
- Problem-4: Count number of ways to cover a distance
  - https://www.geeksforgeeks.org/count-number-of-ways-to-cover-a-distance/
- Problem-5: Find the longest path in a matrix with given constraints
  - https://www.geeksforgeeks.org/find-the-longest-path-in-a-matrix-with-givenconstraints/



- Problem-6: Subset Sum Problem
  - https://www.geeksforgeeks.org/subset-sum-problem-dp-25/
- Problem-7: Optimal Strategy for a Game
  - https://www.geeksforgeeks.org/optimal-strategy-for-a-game-dp-31/
- Problem-8: 0-1 Knapsack Problem
  - https://www.geeksforgeeks.org/0-1-knapsack-problem-dp-10/



- Problem-9: Boolean Parenthesization Problem
  - https://www.geeksforgeeks.org/boolean-parenthesization-problem-dp-37/
- Problem-10: Shortest Common Supersequence
  - https://www.geeksforgeeks.org/shortest-common-supersequence/
  - https://en.wikipedia.org/wiki/Shortest\_common\_supersequence\_problem
- Problem-11: Partition Problem
  - https://www.geeksforgeeks.org/partition-problem-dp-18/
- Problem-12: Cutting a Rod
  - https://www.geeksforgeeks.org/cutting-a-rod-dp-13/



- Problem-13: Coin Change
- Problem-14: Word Break Problem
- Problem-15: Maximum Product Cutting

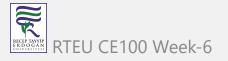


- Problem-16: Dice Throw
  - https://www.geeksforgeeks.org/dice-throw-dp-30/
- Problem-17: Box Stacking Problem
  - https://www.geeksforgeeks.org/box-stacking-problem-dp-22/
- Problem-18: Egg Dropping Puzzle
  - https://www.geeksforgeeks.org/egg-dropping-puzzle-dp-11/



### References

- Introduction to Algorithms, Third Edition | The MIT Press
- Bilkent CS473 Course Notes (new)
- Bilkent CS473 Course Notes (old)



$$-End-Of-Week-6-Course-Module-$$

