<pre>// AUTONOMOUS CODE FOR BLUE BOT - RED double redBackAuton[] = {</pre>	TILE
0,	// START FACING 0°
INTAKE_FLIP, FLIP, WRISTSEEK,WRIST_VERTICAL_POS,	// START INTAKE IN REVERSE // FLIP SO FORKS DON'T DRIFT // RAISE WRIST
DRIVE,70,0,DISTANCE,0.3,1, PAUSE,0.25, DRIVE,-70,0,DISTANCE,0.7,2, PAUSE,0.25, TURN,265,2, INTAKE_ON, WRISTSEEK,WRIST_FORWARD_POS,	// DRIVE TO DELIVER BALL // PAUSE TO LET BALL LEAVE // DRIVE BACKWARDS TO LINE UP // SHORT PAUSE // TURN TO FACE CAP // TURN INTAKE ON // LOWER FORKS
DRIVE, 100, 265, DISTANCE, 1.75, 2, PAUSE, 0.25, DRIVE, -100, 260, DISTANCE, 0.75, 1,	// DRIVE TO GET BALL // PAUSE TO LET BALL IN // DRIVE AWAY FROM CAP
TURN,0,0.5, TURN,80,2, TURN,80,2,	// START CCW TURN // TURN TURN TO FACE CAP // TURN TO FACE CAP
DRIVE, -50,80, DISTANCE, 0.75,3, WRISTSEEK, WRIST_VERTICAL_POS, PAUSE, 0.5,	// DRIVE TO GET CAP // PICK UP CAP // SHORT PAUSE
TURN,300,2, DRIVE,-100,300,DISTANCE,0.6,2, TURN,250,2, ARMSEEK,ARM_POS_LOW, PAUSE,1, DRIVE,-70,250,DISTANCE,1.85,4, DRIVE,40,250,0.2, PAUSE,2,	<pre>// TURN TO LINE UP WITH POLE // DRIVE NEAR TO POLE // TURN TO FACE POLE // RAISE ARM // WAIT FOR ARM TO RAISE // DRIVE TO POLE // DRIVE BACK A LITTLE // WAIT TO DECREASE WOBBLE</pre>
WRISTSEEK, WRIST_FORWARD_DROP_POS, PAUSE, 0.5, DRIVE, 70, 270, DISTANCE, 0.5, 2, WRISTSEEK, WRIST_FORWARD_POS, ARMSEEK, 1,	// DROP CAP #1 // PAUSE TO LET IT SCORE // DRIVE AWAY FROM POLE // LOWER WRIST // LOWER ARM
TURN, 155, 2, DRIVE, 100, 155, 0.75, PAUSE, 0.25, SET_GYRO, 180, PAUSE, 0.25,	// TURN TO FACE WALL // DRIVE AGAINST WALL // SHORT PAUSE // RESET GYRO // SHORT PAUSE
DRIVE,-100,180,DISTANCE,0.2,1,	// DRIVE TO LINE UP WITH CAP

```
TURN, 80, 2,
                                          // TURN TO FACE CAP
    DRIVE, -60, 80, DISTANCE, 1.1, 3,
                                          // DRIVE TO CAP
    WRISTSEEK, WRIST_VERTICAL_POS,
                                          // PICK UP CAP
    PAUSE, 0.5,
                                          // SHORT PAUSE
    DRIVE, 60, 80, DISTANCE, 0.3, 1,
                                          // DRIVE LINE UP
    TURN, 0, 2,
                                          // TURN TO LINE UP WITH POLE
    DRIVE, 100, 0, DISTANCE, 0.5, 2,
                                          // DRIVE NEAR POLE
    TURN, 340, 2,
                                          // TURN TO FACE POLE
    ARMSEEK, ARM_POS_LOW,
                                          // RAISE ARM
    PAUSE, 1,
                                          // PAUSE TO LET ARM LIFT
                                          // FLIP CAP
    FLIP,
    PAUSE, 0.5,
                                          // LET CAP FLIP
    DRIVE, -100, 340, DISTANCE, 0.75, 2,
                                          // DRIVE TO POLE
    DRIVE, 40, 340, 0.2,
                                          // DRIVE BACK A LITTLE
    PAUSE, 1,
                                          // PAUSE TO DECREASE WOBBLE
    WRISTSEEK, WRIST_FORWARD_DROP_POS,
                                          // DROP CAP #2
                                          // PAUSE TO LET CAP DROP
    PAUSE, 0.5,
    START_COAST,
                                          // ACTIVATE FLYWHEEL
    DRIVE, 70, 0, DISTANCE, 0.5, 2,
                                          // DRIVE AWAY FROM POLE
    WRISTSEEK, WRIST_FORWARD_POS,
                                          // LOWER WRIST
    ARMSEEK, 1,
                                          // LOWER ARM
                                          // TURN TO FACE OPPONENT FLAG
    TURN, 310, 2,
                                          // SHOOT BALL AT OPPONENT FLAG
    FIRE, LEFT, 540,
    PAUSE, FIRED, 5,
                                          // PAUSE UNTIL FIRED
    END
                                          // END OF ROUTINE
};
```