

Recall that $\alpha_i = \bar{\mu}_{i.} - \bar{\mu}$, $i=1, \dots, a$; $\beta_j = \bar{\mu}_{.j} - \bar{\mu}$, $j=1, \dots, b$, and $\mu = \bar{\mu}$. (4.03.14) (19)

Then

$$\mu_{ij} = \mu + \alpha_i + \beta_j + \gamma_{ij}$$

where $\sum_{i=1}^a \alpha_i = 0$, $\sum_{j=1}^b \beta_j = 0$, and $\sum_{i=1}^a \gamma_{ij} = \sum_{j=1}^b \gamma_{ij} = 0$.

This model is called a two-way model with interactions.

Example 2

For $a=2$, $b=3$, $\mu=5$, $\alpha_1=1$, $\alpha_2=-1$, $\beta_1=1$, $\beta_2=0$, $\beta_3=-1$,

$\gamma_{11}=1$, $\gamma_{12}=1$, $\gamma_{13}=-2$, $\gamma_{21}=-1$, $\gamma_{22}=-1$, and $\gamma_{23}=2$,

we have

		Factor B		
		1	2	3
Factor A	1	$\mu_{11}=8$	$\mu_{12}=7$	$\mu_{13}=3$
	2	$\mu_{21}=4$	$\mu_{22}=3$	$\mu_{23}=5$

8	.	.
7	.	.
6	.	.
5	.	x
4	x	.
3	.	x

First,
we consider ^{the} testing problem

$H_{0AB}: \gamma_{ij} = 0$ for all ij versus $H_{1AB}: \gamma_{ij} \neq 0$, for some ij .

We have

$$\begin{aligned} \sum_{i=1}^a \sum_{j=1}^b \sum_{k=1}^c (X_{ijk} - \bar{X}_{...})^2 &= \underbrace{bc \sum_{i=1}^a (\bar{X}_{i..} - \bar{X}_{...})^2}_{\text{row differences}} + \underbrace{ac \sum_{j=1}^b (\bar{X}_{.j.} - \bar{X}_{...})^2}_{\text{column differences}} \\ &+ c \sum_{i=1}^a \sum_{j=1}^b (\bar{X}_{ij.} - \bar{X}_{i..} - \bar{X}_{.j.} + \bar{X}_{...})^2 + \left. \begin{aligned} &+ \sum_{i=1}^a \sum_{j=1}^b \sum_{k=1}^c (X_{ijk} - \bar{X}_{ij.})^2 \end{aligned} \right\} \begin{array}{l} \text{interaction} \\ \text{within cells} \end{array} \end{aligned}$$

$$\begin{aligned} a-1, b-1, (a-1)(b-1) & \quad ab(c-1) \\ a-1, b-1, ab-b-a+1 & \quad abc-ab \\ & \quad ab-1 \end{aligned}$$

$$\begin{aligned} abc-1-(ab-1) & \\ abc-ab &= ab(c-1) \end{aligned}$$

has, under H_{0AB} , an F -distribution with $(a-1)(b-1)$ and $ab(c-1)$ degrees of freedom.

$$C = \frac{\sum \sum x_{ij}^2}{6^2}$$

on the basis of

which, under H_{0A} , has an F -distribution with $(a-1)$ and $ab(c-1)$ degrees of freedom.

on the basis of

which, under H_{0B} , has an F-distribution with $b-1$ and $ab(c-1)$ degrees of freedom.

$$(a-1) + (b-1) + (a-1)(b-1) + ab(c-1) = \cancel{a-1} + \cancel{b-1} + \cancel{a-1}\cancel{b-1} + \cancel{a}\cancel{b} - \cancel{a} + 1 + \cancel{a}b\cancel{c} - \cancel{a}b$$

4. LS Estimation for Linear Model

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6.05.14

We have p predictors x_1, \dots, x_p and a response variable Y .

We consider the model of the form

$$Y = h(x_1, \dots, x_p) + \epsilon,$$

where ϵ is a random variable (a random error), and h is a specified function. We will restrict our attention to the case where h is linear in the β -coefficients. Our data consists of n vectors of the form

$(Y_i, x_{i1}, \dots, x_{ip})$, for $i=1, \dots, n$. We will center the x 's, i.e., $x_{cij} = x_{ij} - \bar{x}_j$, where $\bar{x}_j = \frac{1}{n} \sum_{i=1}^n x_{ij}$. The linear model is

$$Y_i = \alpha + x_{ci1}\beta_1 + x_{ci2}\beta_2 + \dots + x_{cip}\beta_p + \epsilon_i, \quad i=1, \dots, n,$$

where $\alpha, \beta_1, \dots, \beta_p$ are unknown parameters (regression coefficients).

We assume that the random errors $\epsilon_1, \dots, \epsilon_n$ are iid.

The matrix formulation of the model is as follows.

$$\begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \alpha + \begin{bmatrix} x_{c11} & \dots & x_{c1p} \\ \vdots & & \vdots \\ x_{cn1} & \dots & x_{cnp} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_p \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix},$$

or equivalently as

$$\underline{Y} = \underline{1} \alpha + \underline{X}_c \underline{\beta} + \underline{\epsilon},$$

or in a more compact form

$$\underline{Y} = \underline{X} \underline{b} + \underline{\epsilon}, \quad \text{where } \underline{X} = [\underline{1} \ \underline{X}_c] \text{ and } \underline{b} = (\alpha, \underline{\beta}')'.$$

We will assume that the $n \times (p+1)$ matrix \underline{X} has full column rank $p+1$.

Let V be the space spanned by the columns of \underline{X} .

Then V is $(p+1)$ -dimensional vector space of \mathbb{R}^n .

Put $\underline{\eta} = \underline{X} \underline{b}$. Then

$$\underline{Y} = \underline{\eta} + \underline{\epsilon}, \quad \text{for } \underline{\eta} \in V.$$

Reading: Except for random error, \underline{Y} would lie in the subspace V . So, to estimate $\underline{\eta}$, find a vector in V which lies "closest" to \underline{Y} (if a given \underline{Y} is known).

4.1 Least Squares

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6.05.14

The LS estimator of η has a form

$$\hat{\eta} = \arg \min_{\eta \in V} \|Y - \eta\|^2, \quad \text{where } \|v\|^2 = \sum_{i=1}^n v_i^2.$$

Let V^\perp be the subspace which consists of all vectors in \mathbb{R}^n which are orthogonal to all vectors in V , that is,

$$V^\perp = \{w \in \mathbb{R}^n : w'v = 0, \text{ for all } v \in V\}.$$

The dimension of V^\perp is $n - (p+1)$.

Definition 1

Let v be a vector in \mathbb{R}^n and let V be a subspace of \mathbb{R}^n . We say that \hat{v} is the projection of v onto V if

- (i) $\hat{v} \in V$,
- (ii) $v - \hat{v} \in V^\perp$.

Theorem 1

Projections are unique.

Proof

1. Let \hat{v}_1 and \hat{v}_2 be projections of v onto V .
2. Since V is a subspace, from (i) $\hat{v}_1 - \hat{v}_2 \in V$.
3. But $\hat{v}_1 - \hat{v}_2 = (v - \hat{v}_2) - (v - \hat{v}_1) \in V^\perp$.
4. Thus $\|\hat{v}_1 - \hat{v}_2\|^2 = 0$.
5. Finally $\hat{v}_1 = \hat{v}_2$. \square

The columns of \underline{X} form a basis for the subspace V .

Therefore, we will say that \underline{X} is a basis matrix for V and that \underline{X} has full column rank, which implies that $(\underline{X}'\underline{X})^{-1}$ exists

Theorem 2

Let \underline{X} be a basis matrix for a subspace V , let $\underline{H} = \underline{X}(\underline{X}'\underline{X})^{-1}\underline{X}'$, and let \underline{v} be a vector in \mathbb{R}^n . Then the projection of \underline{v} onto V is $\underline{H}\underline{v}$.