Mini-SymEx – Weakest-Precondition Engine

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vc(v=e;P)=vc(P)[v/e] vc(\text{if } c \text{ then } b_1 \text{ else } b_2 ; P)=(c \to vc(b_1;P)) \land (\neg c \to vc(b_2;P)) vc(\text{choose } v:e;P)=\exists v.\ e \land vc(P) vc(\text{havoc } v;P)=\forall v.\ vc(P) vc(\text{assume } e;P)=e \to vc(P) vc(\text{assert } e;P)=e \land (e \to vc(P)) vc(\text{assert } e;P)=e \land (e \to vc(P)) vc(e)=true
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Definition 1. A program P is valid w.r.t. to its specification iff vc(P) is valid.

Example 1. Let us consider the following program P_0 :

```
int x = 0; choose x : x > 0; assert x == 2; vc(P_0) = vc(x = 0; (\text{choose } x : x > 0; (\text{assert } x == 2; \epsilon))) \\ = vc((\text{choose } x : x > 0; (\text{assert } x == 2; \epsilon)))[x/0] \\ = (\exists x. \ x > 0 \land vc(\text{assert } x == 2; \epsilon))[x/0] \\ = (\exists x. \ x > 0 \land x = 2 \land vc(\epsilon))[x/0] \\ = (\exists x. \ x > 0 \land x = 2 \land true)[x/0] \\ = (\exists x. \ x > 0 \land x = 2 \land true)
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