

# HW2 System Call & CPU Scheduling

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## 1. Motivation

### (1) System call: Sleep

現在我們的 nachos 裡面並沒有 sleep 的 system call，因此我們必須實作一個 sleep 的 system call

來讓我們的 threads 可以休息。

### (2) CPU Scheduling

原本 nachos 裡面的 scheduling 方式是 RR 的，讓不同 process 輪流執行，現在我們要加入其他的

scheduling 方法: FCFS, SJS, Priority。

同時我們要 implement 自我測試的 code，這樣可以方便且快速測是我們的 scheduling 是否是正

確的。

## 2. Implementation

### (1) System Call: Sleep

# code/userprog/syscall.h

```
32 #define SC_PrintInt 11
33 #define SC_Sleep 12
34
35 #ifndef IN_ASM
131 void PrintInt(int number); //my System Call
132
133 void Sleep(int number);
134
```

幫 sleep syscall 編號(12)，並加入 sleep 的程式碼定義。

# code/test/start.s

```
149     .global Sleep
150     .ent Sleep
151 Sleep:
152     addiu    $2,$0,SC_Sleep
153     syscall
154     j        $31
155     .end     Sleep
156
```

把 sleep 變成系統的一個 API，讓 c++ 可以以 library 的方式 call 他。

# user/exception.cc

```
64     case SC_PrintInt:
65         val=kernel->machine->ReadRegister(4);
66         cout << "Print integer:" <<val << endl;
67         return;
68     case SC_Sleep:
69         val=kernel->machine->ReadRegister(4);
70         cout << "Sleep Time:" << val << "(ms)" << endl;
71         kernel->alarm->WaitUntil(val);
72         return;
```

在 trap 到 os 之中後，會觸發 exception，接著這邊就要觸發 wait 指令。

# code/threads/alarm.h

```
25 #include <list>
26 #include "thread.h"
27 class sleepList {
28     public:
29         sleepList():_current_interrupt(0) {};
30         void PutToSleep(Thread *t, int x);
31         bool PutToReady();
32         bool IsEmpty();
33     private:
34         class sleepThread {
35             public:
36                 sleepThread(Thread *t, int x):
37                     sleeper(t), when(x) {};
38                 Thread* sleeper;
39                 int when;
40         };
41
42         int _current_interrupt;
43         std::list<sleepThread> _threadlist;
44 };
45
```

# code/threads/alarm.cc

```

49 void
50 Alarm::CallBack()
51 {
52     Interrupt *interrupt = kernel->interrupt;
53     MachineStatus status = interrupt->getStatus();
54
55     bool woken = _sleepList.PutToReady();
56     if (status == IdleMode && !woken && _sleepList.IsEmpty()) {
57         // is it time to quit?
58         if (!interrupt->AnyFutureInterrupts()) {
59             timer->Disable(); // turn off the timer
60         }
61     } else { // there's someone to preempt
62         interrupt->YieldOnReturn();
63     }
64 }
65
66 void
67 Alarm::WaitUntil(int x){
68     // 關中斷
69     IntStatus oldLevel = kernel->interrupt->SetLevel(IntOff);
70     Thread* t = kernel->currentThread;
71     //cout << "Alarm::WaitUntil go sleep" << endl;
72     _sleepList.PutToSleep(t, x);
73     // 開中斷
74     kernel->interrupt->SetLevel(oldLevel);
75 }
76
77 bool
78 sleepList::IsEmpty(){
79     return _threadlist.size() == 0;
80 }
81
82 void
83 sleepList::PutToSleep(Thread *t, int x){
84     ASSERT(kernel->interrupt->getLevel() == IntOff);
85     _threadlist.push_back(sleepThread(t, _current_interrupt + x));
86     t->Sleep(false);
87 }
88
89 bool
90 sleepList::PutToReady() {
91     bool woken=false;
92     _current_interrupt ++;
93     for(std::list<sleepThread>::iterator it = _threadlist.begin(); it!=_threadl
ist.end(); ){
94         if(_current_interrupt ≥ it->when){
95             woken=true;
96             //cout << "sleepList::PutToReady Thread woken" << endl;
97             kernel->scheduler->ReadyToRun(it->sleeper);
98             it = _threadlist.erase(it);
99         } else {
100             it++;
101         }
102     }
103     return woken;
104 }
105

```

在 os 中會有個 clock，每 tick 一次就會觸發一次中斷，並去執行該中斷該執行的 code，在 nachos 裡面執行的是 alarm，而 alarm 裡面原本就有定義好 WaitUntil，因此我們就要利用這個 function 來實作 sleep，我們實作一個 sleep list 來儲存每個 thread sleep 的時間。然後當觸發 time 的中段的時候，我們就把計數器往上加 1，然後判斷有沒有一些 thread 可以回去 ready queue 的。

# code/test/sleep1.cc

```
1 #include "syscall.h"
2
3 main() {
4     int i;
5     for(i=0; i<10; i++){
6         Sleep(500000);
7         PrintInt(1);
8     }
9     return 0;
10 }
```

# code/test/sleep2.cc

```
1 #include "syscall.h"
2
3 main() {
4     int i;
5     for(i=0; i<5; i++){
6         Sleep(1000000);
7         PrintInt(2);
8     }
9     return 0;
10 }
```

Sleep1 的 delay 是 500000(ms)，然後會顯示 1；而 Sleep2 的 delay 是 1000000(ms)，然後會顯示 2。

# code/test/Makefile

```
35
36 all: halt shell matmult sort test1 test2 sleep1 sleep2
37
75 sleep1: sleep1.o start.o
76     $(LD) $(LDFLAGS) start.o sleep1.o -o sleep1.coff
77     ../bin/coff2nooff sleep1.coff sleep1
78
79 sleep2: sleep2.o start.o
80     $(LD) $(LDFLAGS) start.o sleep2.o -o sleep2.coff
81     ../bin/coff2nooff sleep2.coff sleep2
82
```

## (2) CPU Scheduling

- Self testing:

# code/thread/thread.cc

```
440 void
441 threadBody(){
442     Thread * thread=kernel->currentThread;
443     while(thread->getBurstTime()>0){
444         thread->setBurstTime(thread->getBurstTime()-1);
445         kernel->interrupt->OneTick();
446         printf("%s: remaining %d\n", kernel->currentThread->getName(),
447             kernel->currentThread->getBurstTime());
448     }
449 }
450
451 void
452 Thread::SchedulingTest()
453 {
454     const int thread_num=4;
455     char * name[thread_num] = {"A", "B", "C", "D"};
456     int thread_priority[thread_num] = {1, 9, 8, 7};
457     int thread_burst[thread_num] = {8, 7, 4, 5};
458
459     Thread *t;
460     for(int i=0; i<thread_num; i++){
461         t = new Thread(name[i]);
462         t->setPriority(thread_priority[i]);
463         t->setBurstTime(thread_burst[i]);
464         t->Fork((VoidFunctionPtr) threadBody, (void *)NULL);
465     }
466     kernel->currentThread->Yield();
467 }
468
```

# code/thread/thread.h

## Public

```
110 void setBurstTime(int t) { burstTime=t; }
111 int getBurstTime() { return burstTime; }
112 void setStartTime(int t) { startTime=t; }
113 int getStartTime() { return startTime; }
114 void setPriority(int t) { execPriority=t; }
115 int getPriority() { return execPriority; }
116 static void SchedulingTest();
117
```

## Private

```
130
131 int burstTime;
132 int startTime;
133 int execPriority;
134
```

# code/thread/kernel.cc

```
104 void
105 ThreadedKernel::SelfTest() {
106     Semaphore *semaphore;
107     SynchList<int> *synchList;
108
109     LibSelfTest();          // test library routines
110
111     currentThread->SelfTest(); // test thread switching
112     Thread::SchedulingTest();
113
114     // test semaphore operation
115     semaphore = new Semaphore("test", 0);
116     semaphore->SelfTest();
117     delete semaphore;
118
119     // test locks, condition variables
120     // using synchronized lists
121     synchList = new SynchList<int>;
122     synchList->SelfTest(9);
123     delete synchList;
124
125     ElevatorSelfTest();
```

# code/thread/main.cc

```
75
76     DEBUG(dbgThread, "Entering main");
77
78     SchedulerType type=RR;
79     if(strcmp(argv[1], "FCFS")==0) {
80         type=FIFO;
81     }else if(strcmp(argv[1], "SJF")==0){
82         type=SJF;
83     }else if(strcmp(argv[1], "PRIORITY")==0){
84         type=Priority;
85     }else if(strcmp(argv[1], "RR")==0){
86         type=RR;
87     }
88
89     kernel = new KernelType(argc, argv);
90     kernel->Initialize(type);
91
92     CallOnUserAbort(Cleanup); // if user hits ctrl-C
```

# code/thread/scheduler.h

```
20 enum SchedulerType {
21     RR,          // Round Robin
22     SJF,
23     Priority,
24     FIFO
25 };
26
```

# code/machine/machine.h

```
30 const unsigned int PageSize = 128;    // set the page size equal to
31                                     // the disk sector size, for simplicity
32
33 const unsigned int NumPhysPages = 64;
34 const int MemorySize = (NumPhysPages * PageSize);
35 const int TLBSize = 4;                // if there is a TLB, make it small
36
```

- Scheduling:

# code/thread/scheduler.h

```
19
20 enum SchedulerType {
21     RR,    // Round Robin
22     SJF,
23     Priority,
24     FIFO
25 };
26
27 class Scheduler {
28 public:
29     Scheduler();    // Initialize list of ready threads
30     Scheduler(SchedulerType);
31     ~Scheduler();   // De-allocate ready list
32
```

# code/thread/scheduler.cc

```

32 int SJFCompare(Thread *a, Thread *b){
33     if(a->getBurstTime() == b->getBurstTime())
34         return 0;
35     return a->getBurstTime() > b->getBurstTime() ? 1:-1;
36 }
37 int PriorityCompare(Thread *a, Thread *b){
38     if(a->getPriority() == b->getPriority())
39         return 0;
40     return a->getPriority() > b->getPriority() ? 1:-1;
41 }
42 int FIFOCompare(Thread *a, Thread *b){
43     return 1;
44 }
45
46 Scheduler::Scheduler()
47 {
48     Scheduler(RR);
49     //readyList = new List<Thread *>;
50     //toBeDestroyed = NULL;
51 }
52
53 Scheduler::Scheduler(SchedulerType type){
54     schedulerType = type;
55     switch(schedulerType){
56         case RR:
57             readyList = new List<Thread *>;
58             break;
59         case SJF:
60             readyList = new SortedList<Thread *>(SJFCompare);
61             break;
62         case Priority:
63             readyList = new SortedList<Thread *>(PriorityCompare);
64             break;
65         case FIFO:
66             readyList = new SortedList<Thread *>(FIFOCompare);
67     }
68     toBeDestroyed = NULL;
69 }

```

# code/thread/alarm.cc



```

49 void
50 Alarm::CallBack()
51 {
52     Interrupt *interrupt = kernel->interrupt;
53     MachineStatus status = interrupt->getStatus();
54
55     bool woken = _sleepList.PutToReady();
56     if (status == IdleMode && !woken && _sleepList.IsEmpty()) {
57         // is it time to quit?
58         if (!interrupt->AnyFutureInterrupts()) {
59             timer->Disable(); // turn off the timer
60         }
61     } else { // there's someone to preempt
62         if (kernel->scheduler->getSchedulerType() == RR ||
63             kernel->scheduler->getSchedulerType() == Priority) {
64             cout << "≡ interrupt->YieldOnReturn ≡" << endl;
65             interrupt->YieldOnReturn();
66         }
67     }
68 }
69
70 void
71 Alarm::WaitUntil(int x){
72     // 關中斷
73     IntStatus oldLevel = kernel->interrupt->SetLevel(IntOff);
74     Thread* t = kernel->currentThread;
75
76     int worktime = kernel->stats->userTicks - t->getStartTime();
77     t->setBurstTime(t->getBurstTime()+worktime);
78     t->setStartTime(kernel->stats->userTicks);
79
80     //cout << "Alarm::WaitUntil go sleep" << endl;
81     _sleepList.PutToSleep(t, x);
82     // 開中斷
83     kernel->interrupt->SetLevel(oldLevel);
84 }

```

在運行的時候計算 burstTime。

### 3. Result

#### (1) System Call: Sleep

```
aa@aa:~/r08942087_Nachos1/nachos-4.0/code/userprog$ ./nachos -e ../test/sleep1 -e ../test/sleep2
Total threads number is 2
Thread ../test/sleep1 is executing.
Thread ../test/sleep2 is executing.
Sleep Time:500000(ms)
Sleep Time:1000000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:2
Sleep Time:1000000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:2
Sleep Time:1000000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:2
Sleep Time:1000000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:2
Sleep Time:1000000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:2
Sleep Time:1000000(ms)
Print integer:1
Sleep Time:500000(ms)
Print integer:1
return value:0
Print integer:2
return value:0
No threads ready or runnable, and no pending interrupts.
Assuming the program completed.
Machine halting!
```

Sleep1 的 delay 是 500000(ms)，然後會顯示 1；而 Sleep2 的 delay 是 1000000(ms)，然後會顯示 2。從實驗結果可以看到 sleep 真的有起作用，我們畫面中會看到兩個 1 後才看到一個 2，代表 systemcall sleep 有起到作用。

#### (2) CPU Scheduling

- FCFS

```

aa@aa:~/r08942087_Nachos1/nachos-4.0/code/userprog$ ./nachos FCFS -e ../
test/test1 -e ../test/test2
cpu scheduling type:3
Total threads number is 2
Thread ../test/test1 is executing.
Thread ../test/test2 is executing.
Print integer:9
Print integer:8
Print integer:7
Print integer:6
return value:0
Print integer:20
Print integer:21
Print integer:22
Print integer:23
Print integer:24
Print integer:25
return value:0
No threads ready or runnable, and no pending interrupts.
Assuming the program completed.
Machine halting!

```

(case 1)

```

A: remaining 5
A: remaining 4
A: remaining 3
A: remaining 2
A: remaining 1
A: remaining 0
B: remaining 6
B: remaining 5
B: remaining 4
B: remaining 3
B: remaining 2
B: remaining 1
B: remaining 0
C: remaining 3
C: remaining 2
C: remaining 1
C: remaining 0
D: remaining 4
D: remaining 3
D: remaining 2
D: remaining 1
D: remaining 0
No threads ready or runnable, and no pending interrupts.
Assuming the program completed.
Machine halting!

```

(case 2)

再 First Come First Serve 裡面，先到的會先完成，所以會有個類似 fifo 的感覺，因此順序是 A->B->C->D。

- SJF

```

aa@aa:~/r08942087_Nachos1/nachos-4.0/code/userprog$ ./nachos SJF -e ../t
est/test1 -e ../test/test2
cpu scheduling type:1
Total threads number is 2
Thread ../test/test1 is executing.
Thread ../test/test2 is executing.
Print integer:9
Print integer:8
Print integer:7
Print integer:6
return value:0
Print integer:20
Print integer:21
Print integer:22
Print integer:23
Print integer:24
Print integer:25
return value:0
No threads ready or runnable, and no pending interrupts.
Assuming the program completed.
Machine halting!

```

(case 1)

```

C: remaining 3
C: remaining 2
C: remaining 1
C: remaining 0
D: remaining 4
D: remaining 3
D: remaining 2
D: remaining 1
D: remaining 0
B: remaining 6
B: remaining 5
B: remaining 4
B: remaining 3
B: remaining 2
B: remaining 1
B: remaining 0
A: remaining 7
A: remaining 6
A: remaining 5
A: remaining 4
A: remaining 3
A: remaining 2
A: remaining 1
A: remaining 0
No threads ready or runnable, and no pending interrupts.
Assuming the program completed.
Machine halting!

```

(case 2)

T Name	A	B	C	D
T burst	8	7	4	5

# Case2:

Burst time: C < D < B < A

因此如果用 Short Job First 的話，會照著 Burst time 小的先執行，因此完成順序會是

C->D->B->A，結果也跟預期的依樣。

- Priority

```
aa@aa:~/r08942087_Nachos1/nachos-4.0/code/userprog$ ./nachos Priority -e
../test/test1 -e ../test/test2
cpu scheduling type:0
Total threads number is 2
Thread ../test/test1 is executing.
Thread ../test/test2 is executing.
Print integer:9
Print integer:8
Print integer:7
=== interrupt->YieldOnReturn ===
Print integer:20
Print integer:21
Print integer:22
Print integer:23
Print integer:24
=== interrupt->YieldOnReturn ===
Print integer:6
return value:0
Print integer:25
return value:0
No threads ready or runnable, and no pending interrupts.
Assuming the program completed.
```

```
B: remaining 6
B: remaining 5
B: remaining 4
B: remaining 3
B: remaining 2
B: remaining 1
B: remaining 0
=== interrupt->YieldOnReturn ===
D: remaining 4
D: remaining 3
D: remaining 2
D: remaining 1
D: remaining 0
=== interrupt->YieldOnReturn ===
C: remaining 3
C: remaining 2
C: remaining 1
C: remaining 0
A: remaining 7
A: remaining 6
=== interrupt->YieldOnReturn ===
A: remaining 5
A: remaining 4
A: remaining 3
A: remaining 2
A: remaining 1
A: remaining 0
=== interrupt->YieldOnReturn ===
```

(case 1)

(case 2)

T Name	A	B	C	D
T Priority	1	9	7	8

### # Case 1:

因為兩個 thread 他們的 priority 相同，所以他們是輪流在執行，這便變成是 Round Robin 的感覺。

### # Case 2:

Priority: B>D>C>A

如果是 Priority 的話，會照著她們重要的優先順序跑，因此會是照著 B->D->C->A 的順序完成。