Problem 1 Lagrangian and Duality

(35 points)

We are given N samples: $\{(\mathbf{x}_1, y_1) \dots (\mathbf{x}_N, y_N)\}$, $\mathbf{x}_i \in \mathcal{X}$, $y_i \in \{-1, 1\} \ \forall i \in \{1 \dots N\}$. We say input \mathbf{x}_i belongs to class C_1 if its label y_i is 1 and it belongs to class C_{-1} if its label is -1. Mathematically, $C_1 = \{(\mathbf{x}_i, y_i) : y_i = 1\}$ and $C_{-1} = \{(\mathbf{x}_i, y_i) : y_i = -1\}$. Now, consider a two class classification problem formulation as follows: We want to find a separating hyper-plane w such that if input x_i belongs to C_1 then $w^Tx_i \geq 0$ and if it belongs to C_{-1} then $\mathbf{w}^T \mathbf{x}_i \leq 0$. Therefore, we can find the optimal weights \mathbf{w}^* by maximizing the objective

$$f(\mathbf{w}) = \sum_{i=1}^{N} y_i \mathbf{w}^T \mathbf{x}_i$$

Note that $f(\mathbf{w})$ can be arbitrarily maximized by increasing the magnitude of \mathbf{w} once we have found a vector **w** such that $f(\mathbf{w}) > 0$. Therefore, we add an additional constraint that $\mathbf{w}^T \mathbf{w} = \|\mathbf{w}\|^2 \le 1$.

1.1 Write the down the constraint minimization problem. Solve it and find the explicit form the optimal weights \mathbf{w}^* . (10 points)

 $max \sum y_i W^T x_i = min - \sum y_i W^T x_i$

subject to

 $||w||^2 - 1 \le 0$

Lagrange

 $L = -\sum y_i W^T x_i + \lambda (W^T W - 1)$

solve

$$\frac{dL}{dW} = -\sum y_i x_i + 2\lambda W = 0$$

$$\lambda(W^TW - 1) = 0$$

$$\lambda^* = \frac{1}{2}||\sum y_i x_i||$$

$$W^* = \frac{\sum y_i x_i}{||\sum y_i x_i||}$$
 1.2 Suppose we use a transformation function $\phi: \mathcal{X} \to^K$ to transform inputs and the corresponding kernel

function is $k(\mathbf{x}, \mathbf{x}') = \phi(\mathbf{x})^T \phi(\mathbf{x}')$. Analogus to problem 1.1, write down the constraint minimization problem for this setup. (4 points) $max \sum y_i W^T \phi(x_i) = min - \sum y_i W^T \phi(x_i)$

$$\left|\left|w\right|\right|^2-1\leq 0$$

subject to

 $L = -\sum_i y_i W^T \phi(x_i) + \lambda (W^T W - 1)$

Lagrange

(15 points)

$$egin{aligned} rac{d\,L}{d\,W} &= -\sum y_i \phi(x_i) + 2\lambda W = 0 \ W &= rac{\sum y_i \phi(x_i)}{2\lambda} \ L &= -\sum y_j [rac{\sum y_i \phi(x_i)}{2\lambda}]^T \phi(x_j) + \lambda ([rac{\sum y_i \phi(x_i)}{2\lambda}]^T [rac{\sum y_i \phi(x_i)}{2\lambda}] - 1) \ L &= -rac{1}{2\lambda} \sum_i \sum_j y_i y_j \phi(x_i)^T \phi(x_j) + \lambda ([rac{1}{4\lambda^2} \sum_i \sum_j y_i y_j \phi(x_i)^T \phi(x_j) - 1) \ L &= -rac{1}{4\lambda} \sum_i \sum_j y_i y_j \phi(x_i)^T \phi(x_j) - \lambda \ max - rac{1}{4\lambda} \sum_i \sum_j y_i y_j \phi(x_i)^T \phi(x_j) - \lambda \ \end{array}$$

why or why not.

$$||W||^2-1\leq 0$$

$$\lambda\geq 0$$
 1.4 Can the optimization problem in **1.2** be kernelized? Also, can you kernelize the prediction rule? Explain why or why not. (6 points)

By above equation, it can be kernalized by replacing $\phi(x_i)^T\phi(x_j)$ with $K(x_i,x_j)$ **Problem 2 Support Vector Machines** (40 points)

Consider the dataset consisting of points (x, y), where x is a real value, and $y \in \{-1, 1\}$ is the class label.

Let's start with three points $(x_1, y_1) = (-1, -1), (x_2, y_2) = (1, -1), (x_3, y_3) = (0, 1).$

(2 points)

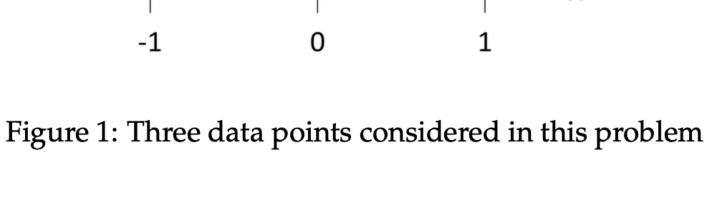
(2 points)

(6 points)

(15 points)

(6 points)

label = -1 label = +1 label = -1



2.1 Can three points shown in Figure 1, in their current one-dimensional feature space, be perfectly separated with a linear separator? Explain why or why not.

Since in 1D space, to be linear separable, the linear separator is a point but obviously, there is no such point existing. **2.2** Now we define a simple feature mapping $\phi(x) = [x, x^2]^T$ to transform the three points from one- to two-dimensional feature space. Plot the transformed points in the new two-dimensional feature space. Is

there a linear decision boundary that can separate the points in this new feature space? Explain why or

else:

plt.show()

1.0

0.8

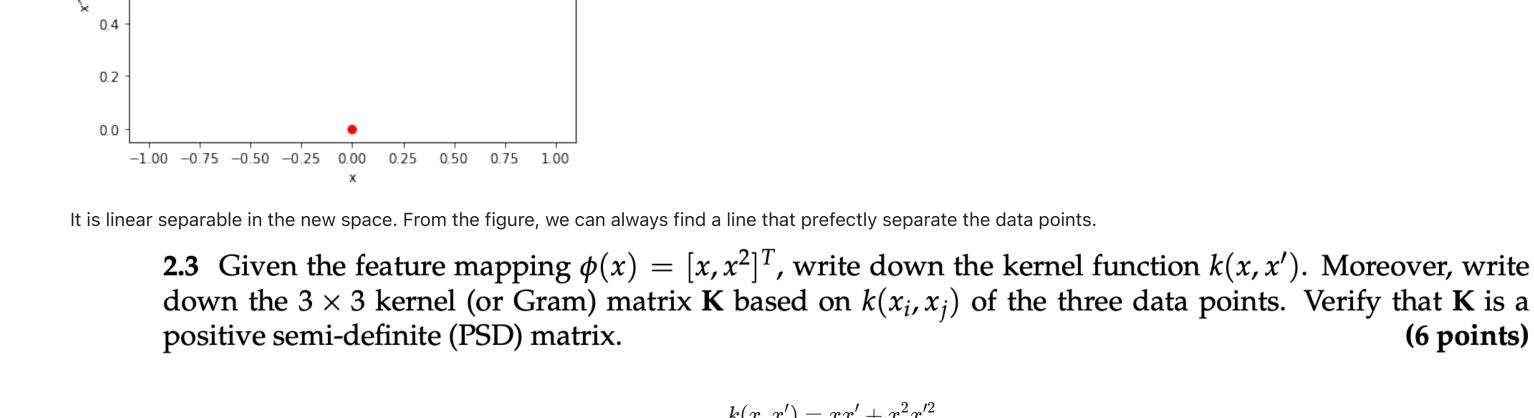
0.6

plt.xlabel('x') plt.ylabel('x^2')

No

why not.

import numpy as np import matplotlib.pyplot as plt x = np.array([-1, 0, 1]).reshape(-1,1)y = np.array([-1, 1, -1])phi x = np.concatenate([x, np.square(x)], axis=1)for i in range(x.shape[0]): **if** y[i] == 1: plt.scatter(phi_x[i, 0], phi_x[i, 1], c='r')



the e-vaulue is 0 and 1, so it is PSD

Problem 3 PCA

(PCA).

corresponding eigen-vector

Transformed

Show your work.

subject to

plt.scatter(phi_x[i, 0], phi_x[i, 1], c='b')

- $k(x,x') = xx' + x^2x'^2$ $\lceil k(x1,x1) \quad k(x1,x2) \quad k(x1,x3) \rceil$
 - k(x2, x1) k(x2, x2) k(x2, x3)k(x3, x1) k(x3, x2) k(x3, x3)0 0 0

2.4 Write down the dual formulation of this problem by plugging in the specific data points.
$$\max_{\alpha} \sum \alpha_i - \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j \phi(x_i) \phi(x_j)$$

$$\alpha_i \geq 0$$

$$\sum_i \alpha_i y_i = 0$$

2.5 Solve the above dual form analytically and obtain primal solutions \mathbf{w}^* and b^* . (15 points)

 $w^st = [0,-2]^T$

 $b^* = 1$

$$\mathbf{X} = \begin{bmatrix} 4 & 1 \\ 2 & 3 \\ 5 & 4 \\ 1 & 0 \end{bmatrix}$$

Consider the following design matrix, representing four sample points $X_i \in \mathbb{R}$

We want to represent the data in only one dimension, so we turn to principal components analysis

(15 points)

(25 points)

directions would the PCA algorithm choose if you request just one principal component to be returned. Please provide an exact answer, without approximation. (You will need to use the square root symbol.)

3.1 Compute the unit-length principal component directions of X, and state which one of the component

 $X_{cov} = rac{1}{4-1}(X-mean(X))^T(X-mean(X)) =$

Perform SVD get the $eigen-value = \{\frac{16}{3}, \frac{4}{3}\}$

$$[0,0,2\sqrt{2},-2\sqrt{2}]^T$$
 3.2 The plot below (Fig. 3.2) depicts the sample points from X . We want a one-dimensional representation

of the data, so draw the principal component direction (as a line) and the projections of all four sample

 $[\frac{1}{\sqrt(2)}, -\frac{1}{\sqrt(2)}]^T, \ [\frac{1}{\sqrt(2)}, \frac{1}{\sqrt(2)}]^T$

points onto the principal direction. Label each projected point with its principal coordinate value (where the origin's principal coordinate is zero). Give the principal coordinate values exactly.

(10 points) The red line is the new 1D axis, the 4 red points (two at 0) are the projected coordinates

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