

EECS 442 F17 Images as Functions : Operations

3 Types

① Range Operation

② Range Maps

③ Domain Operations

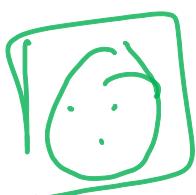
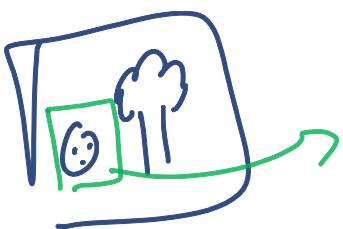
$$I: \mathbb{R}^2 \rightarrow \mathbb{R}$$
$$\mathbb{Z}^2 \rightarrow \mathbb{Z}$$

Range Operations

Λ is the lattice of pixel locations

A region $W \subseteq \Lambda \subseteq \mathbb{Z}^2$
↳ windows

$I[W]$ → a new image where we save
only the subset of Λ on W .



Binary W

$I \rightarrow \Lambda$

$B_W: \Lambda \rightarrow \{0, 1\}$

$I \cdot * B_W \doteq I[W]$

Def : Range Operation

A function $f : W \times \underline{\mathbb{Z}^2 \rightarrow \mathbb{Z}} \rightarrow \mathbb{R}$
in the discrete case.

or $f : W \times I \rightarrow \mathbb{R}$

↑ can include parameters
to f as well

Def Linearity : A R.O. f is said to be
linear if

$$f_w(\alpha_i I_i + \alpha_j I_j) = \alpha_i f_w(I_i) + \alpha_j f_w(I_j)$$

where $\alpha_i, \alpha_j \in \mathbb{R}$.

Example of Composition

Haar Operator

$$\xrightarrow{\text{haar}} \text{haar}(I, \{W\}_i^N, \{\mathcal{Z}\}_i^N) = \sum_{i=1}^N \alpha_i \text{sum}(I, W_i)$$
$$\alpha_1, \alpha_2, \dots, \alpha_N \in \{-1, +1\}$$

Range Map

Def. A range map operation

$$g : (\underbrace{W \times I \rightarrow \mathbb{R}}) \times I \rightarrow J$$

for image J .

The range operation "kernel"

A kernel k is a matrix the same size as W whose values are real numbers : $k \in \mathbb{R}^{|W|}$.

Kernel operations are element-wise products over W followed by sums.

$$k \in \mathbb{R}^{n \times n} \quad I[W] \in \mathbb{R}^{n \times n}$$

$$\text{sum}(k \cdot * I[W])$$

Vectorize k and $I[w]$:

$$\overrightarrow{k} \in \mathbb{R}^{(n \times n) \times 1}, \quad \overrightarrow{I[w]}$$

$\overrightarrow{k^T} \overrightarrow{I[w]}$

Kernel operation as dot-product.

Det. Kernel range map is classically called convolution, \otimes

$$J(s,t) = K \otimes I[w] = \sum_{k=-m}^m \sum_{l=-n}^n k(k,l) I(s-k, t-l)$$
$$= \overrightarrow{k^T} \overrightarrow{I[w]}$$

write $K \otimes I$ means we apply this as a map.

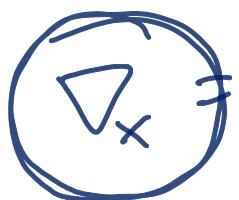
Ex. KRM : Discrete Image Derivatives

$I(x,y)$

$$\text{def. } \frac{\partial I(x,y)}{\partial x} = \lim_{h \rightarrow 0} \frac{I(x+h,y) - I(x,y)}{h}$$

$$\text{discrete } \frac{dI(x,y)}{dx} = \frac{I(x+h,y) - I(x,y)}{h}$$

when $h = 1$



$$\frac{dI(x,y)}{dx} = \frac{I(x+1,y) - I(x,y)}{1}$$

1	2	20
3	3	3
0	0	0

1	18	
0	8	

I

J



$$K = [-1, 1]$$

