Notes for ECE 30100 - Signals and Systems Zeke Ulrich January 13, 2025

## Contents

Course Description 1
Introduction 2
Reference 4

## Course Description

Classification, analysis and design of systems in both the time- and frequency-domains. Continuous-time linear systems: Fourier Series, Fourier Transform, bilateral Laplace Transform. Discrete-time linear systems: difference equations, Discrete-Time Fourier Transform, bilateral z-Transform. Sampling, quantization, and discrete-time processing of continuous-time signals. Discrete-time nonlinear systems: median-type filters, threshold decomposition. System design examples such as the compact disc player and AM radio.

## Introduction

As this course studies signals and systems, it behooves us to understand what signals and systems are. A signal is a quantity that varies over time. Examples include voltage waveform on a circuit, height as a function of age, or pulses of light through fiber optic.

We distinguish between continuous time (CT) and discrete time (DT) signals. CT signals have a continuous independent variable, such as time. DT signals have a discrete independent variable, such as the date. The indices are a set of integers.

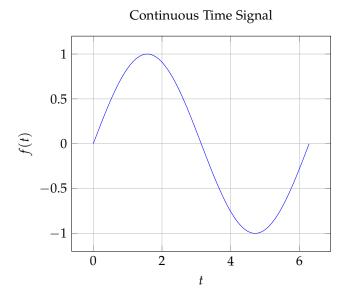


Figure 1: Continuous Time Signal

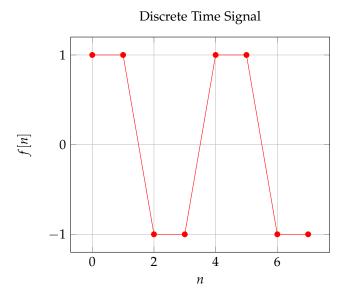


Figure 2: Discrete Time Signal

In the most general terms, a systems transform inputs to outputs. They're interconnections of subsystems. Examples of systems include, topically, circuits.

Similarly to signals, there are continuous time systems and discrete time systems. In a CT system, the input and output are continuous. Conversely, DT systems have discrete inputs and outputs.

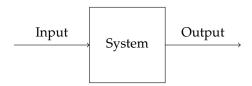


Figure 3: System Diagram

The astute reader will notice systems operate much like functions. We use function notation to describe systems. For a CT system, we write y(t) = S(x(t)) with parentheses to show it's CT. For DT, we use brackets like y[t] = S(x[t]).

It's easy to imagine a system with continuous input and discrete output, or vice versa. These are called samplers and reconstructors respectively. We'll mostly be looking at linear time-invariant discrete systems, since they have the greatest analogy to ECE.

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$$E = mc^2$$