D-optimal design

The most widely used scalarization is called D-optimal design, in which we minimize the determinant of the error covariance matrix E. This corresponds to designing the experiment to minimize the volume of the resulting confidence ellipsoid (for a fixed confidence level). Ignoring the constant factor 1/m in E, and taking the logarithm of the objective, we can pose this problem as

minimize
$$\log \det \left(\sum_{i=1}^{p} \lambda_i v_i v_i^T \right)^{-1}$$

subject to $\lambda \succeq 0$, $\mathbf{1}^T \lambda = 1$, (7.26)

which is a convex optimization problem

E-optimal design

In E-optimal design, we minimize the norm of the error covariance matrix, i.e., the maximum eigenvalue of E. Since the diameter (twice the longest semi-axis) of the confidence ellipsoid \mathcal{E} is proportional to $||E||_2^{1/2}$, minimizing $||E||_2$ can be interpreted geometrically as minimizing the diameter of the confidence ellipsoid. E-optimal design can also be interpreted as minimizing the maximum variance of $q^T e$, over all q with $||q||_2 = 1$.

The E-optimal experiment design problem is

minimize
$$\left\| \left(\sum_{i=1}^{p} \lambda_i v_i v_i^T \right)^{-1} \right\|_2$$

subject to $\lambda \succeq 0$, $\mathbf{1}^T \lambda = 1$.

The objective is a convex function of λ , so this is a convex problem.

The E-optimal experiment design problem can be cast as an SDP

maximize
$$t$$

subject to $\sum_{i=1}^{p} \lambda_i v_i v_i^T \succeq tI$ $\lambda \succeq 0$, $\mathbf{1}^T \lambda = 1$, (7.27)

with variables $\lambda \in \mathbf{R}^p$ and $t \in \mathbf{R}$.

A-optimal design

In A-optimal experiment design, we minimize $\operatorname{tr} E$, the trace of the covariance matrix. This objective is simply the mean of the norm of the error squared:

$$\mathbf{E} \|e\|_2^2 = \mathbf{E} \operatorname{tr}(ee^T) = \operatorname{tr} E.$$

The A-optimal experiment design problem is

minimize
$$\operatorname{tr}\left(\sum_{i=1}^{p} \lambda_{i} v_{i} v_{i}^{T}\right)^{-1}$$

subject to $\lambda \succeq 0$, $\mathbf{1}^{T} \lambda = 1$. (7.28)

This, too, is a convex problem. Like the E-optimal experiment design problem, it can be cast as an SDP:

minimize
$$\mathbf{1}^T u$$

subject to $\begin{bmatrix} \sum_{i=1}^p \lambda_i v_i v_i^T & e_k \\ e_k^T & u_k \end{bmatrix} \succeq 0, \quad k = 1, \dots, n$
 $\lambda \succeq 0, \quad \mathbf{1}^T \lambda = 1,$