Design and analysis of algorithm

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Topics

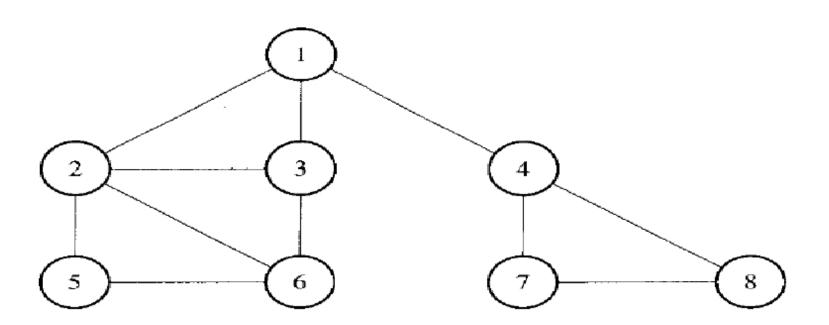
- Depth First Search (DFS)
- Breadth First Search (BFS)

DEPTH-FIRST SEARCH: UNDIRECTED GRAPHS

- Let G = (N, A) be an undirected graph all of whose nodes we wish to visit.
- Suppose it is somehow possible to mark a node to show it has already been visited.
- To carry out a depth-first traversal of the graph, choose any node $\mathbf{v} \in \mathbf{N}$ as the starting point.
- Mark this node to show it has been visited. Next, if there is a node adjacent to v that has not yet been visited, choose this node as a new starting point and call the depth-first search procedure recursively.

- On return from the recursive call, if there is another node adjacent to v that has not been visited, choose this node as the next starting point, call the procedure recursively once again, and so on.
- When all the nodes adjacent to v are marked, the search starting at v is finished.
- If there remain any nodes of G that have not been visited, choose any one of them as a new starting point, and call the procedure yet again.
- Continue thus until all the nodes of G are marked. Here is the recursive algorithm

EXAMPLE:



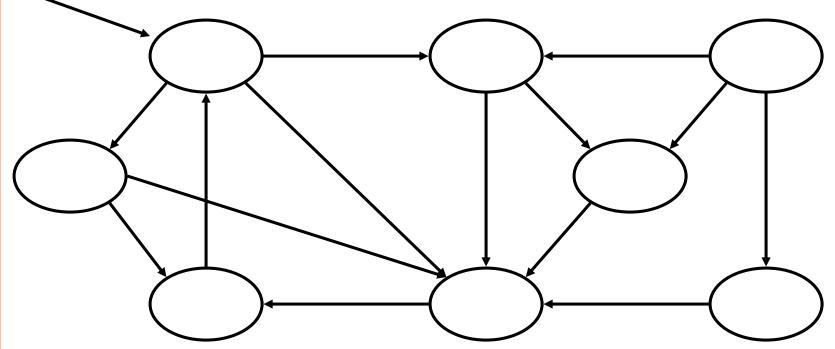
```
    dfs(1) initial call
    dfs(2) recursive call
    dfs(3) recursive call
    dfs(6) recursive call
    dfs(5) recursive call; progress is blocked
    dfs(4) a neighbour of node 1 has not been visited recursive call
    dfs(7) recursive call
    dfs(8) recursive call; progress is blocked
    there are no more nodes to visit
```

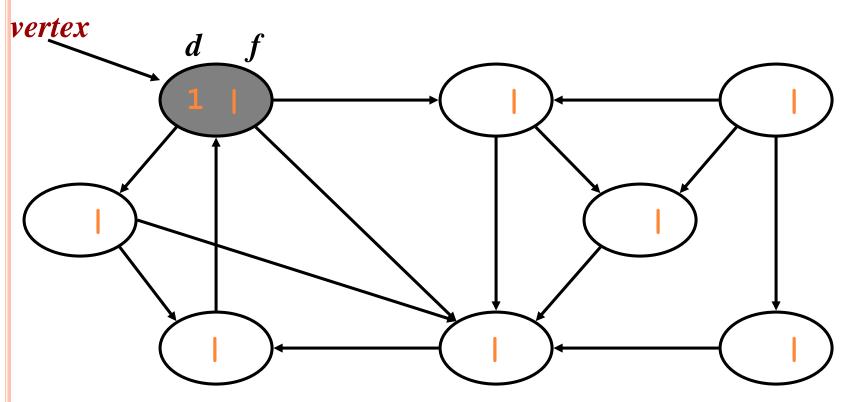
```
procedure dfsearch(G)
    for each v \in N do mark[v] \leftarrow not-visited
    for each v \in N do
        if mark[v] \neq visited then <math>dfs(v)
procedure dfs(v)
    {Node \nu has not previously been visited}
    mark[v] - visited
    for each node w adjacent to v do
        if mark[w] \neq visited then <math>dfs(w)
```

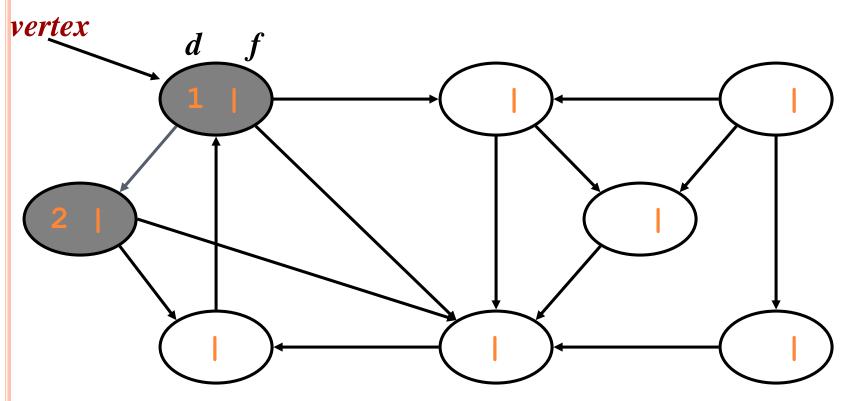
DEPTH-FIRST SEARCH: DIRECTED GRAPHS

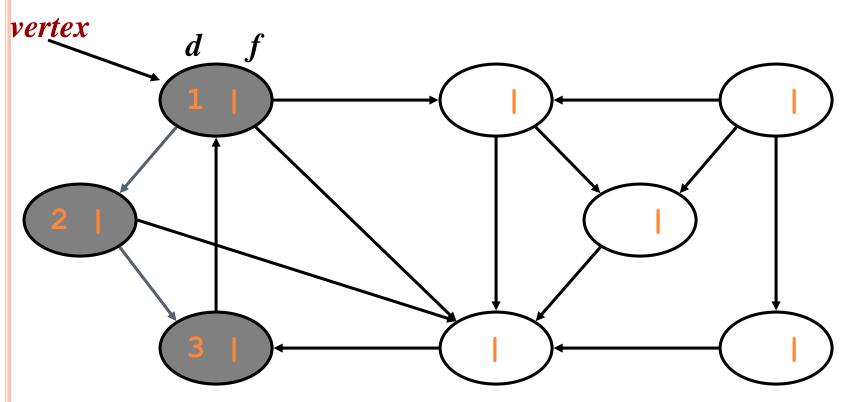
- The algorithm is essentially the same as for undirected graphs, the difference residing in the interpretation of the word "adjacent".
- In a directed graph, node w is adjacent to node v if the directed edge (v, w) exists.
- If (v, w) exists but (w, v) does not, then w is adjacent to v but v is not adjacent to w.
- With this change of interpretation the procedures dfs and search apply equally well in the case of a directed graph.

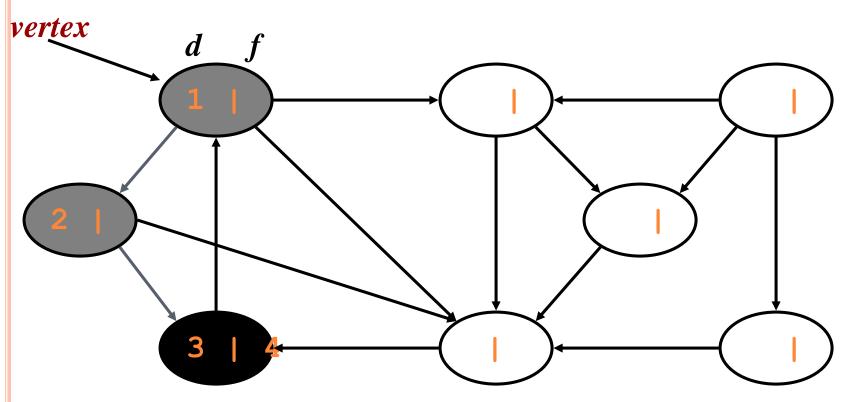


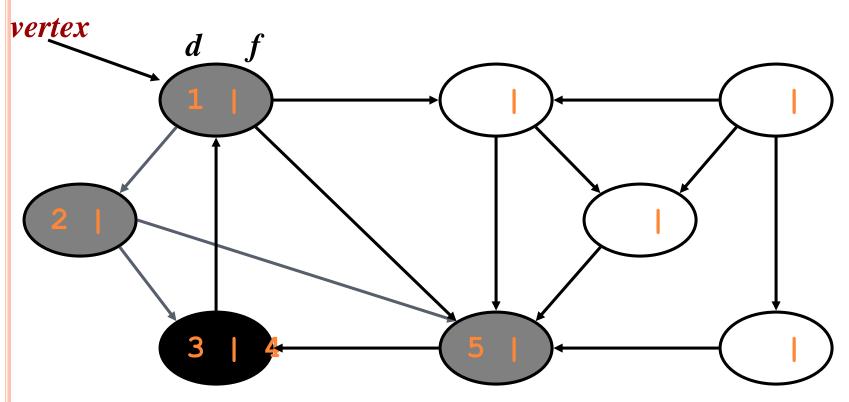


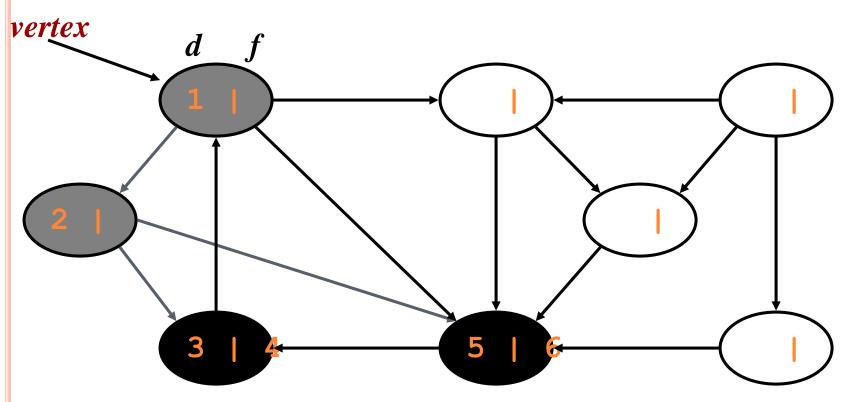


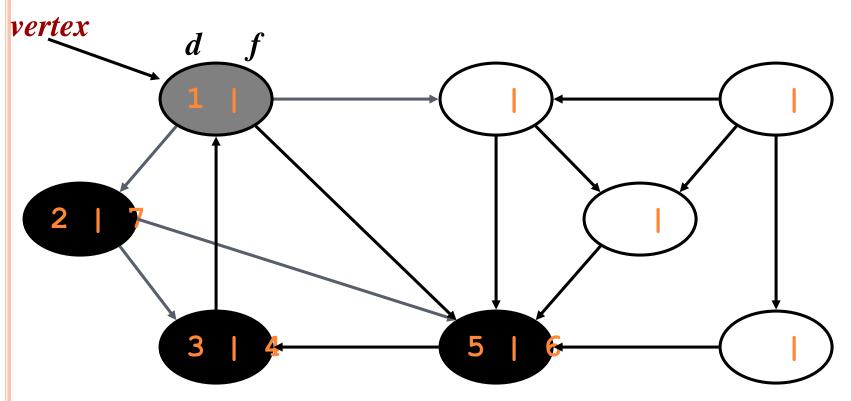


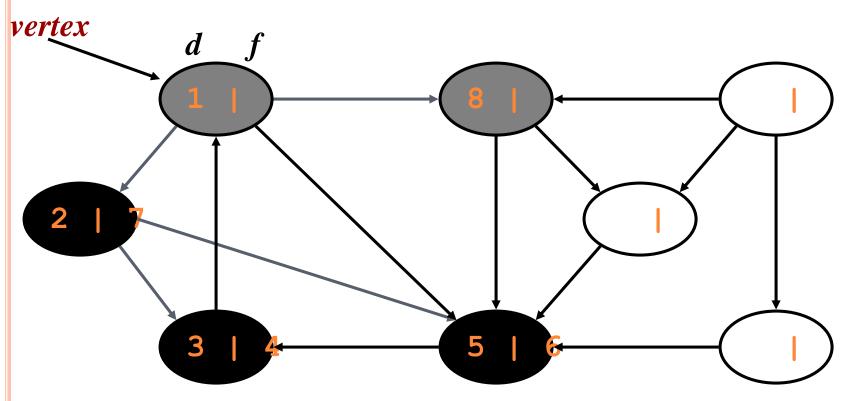


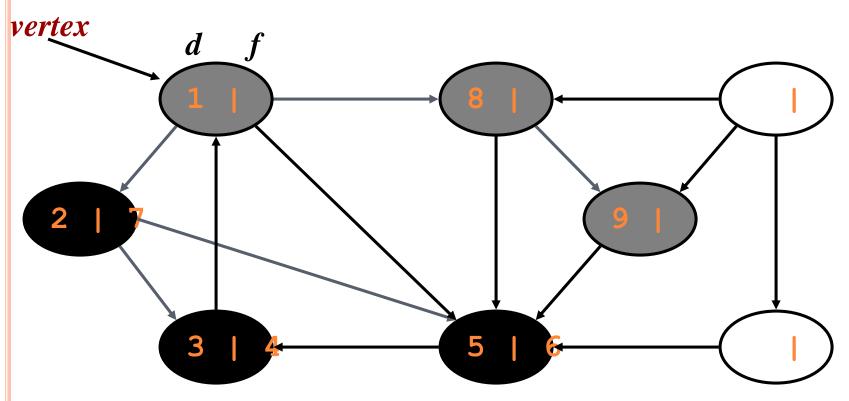


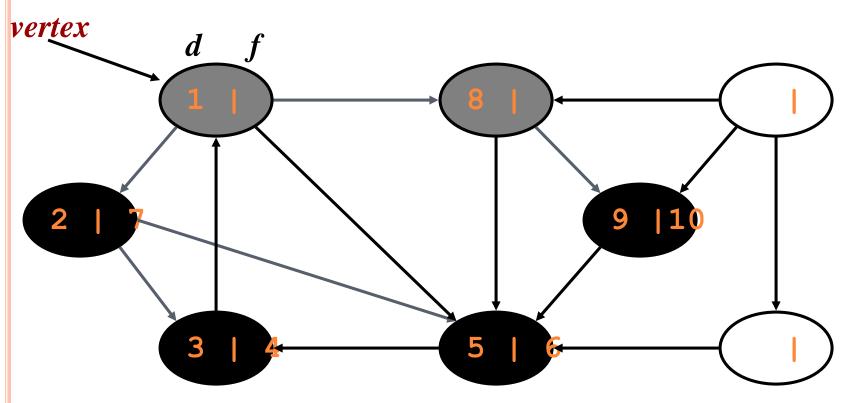


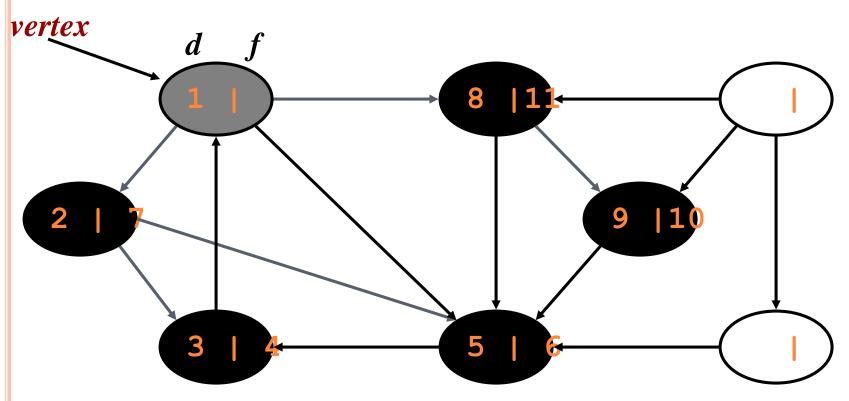


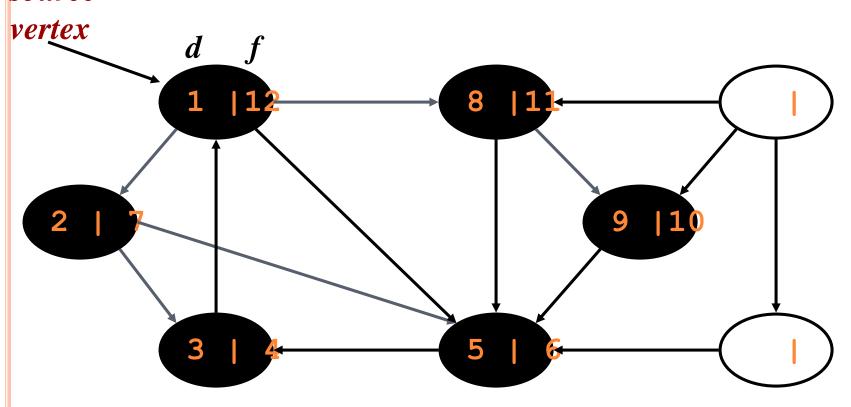


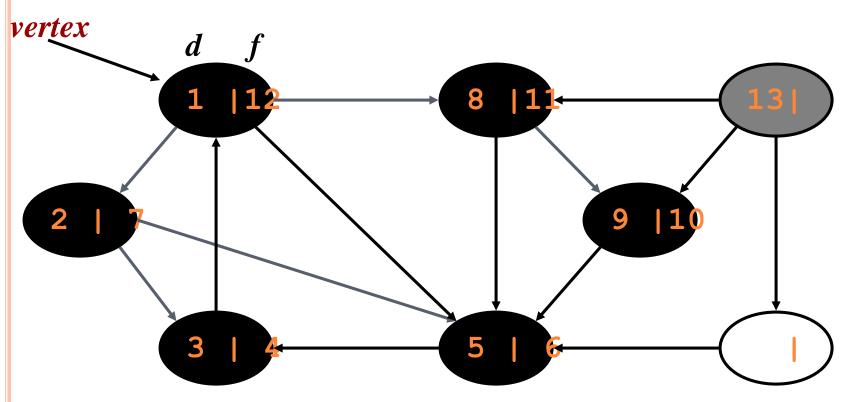


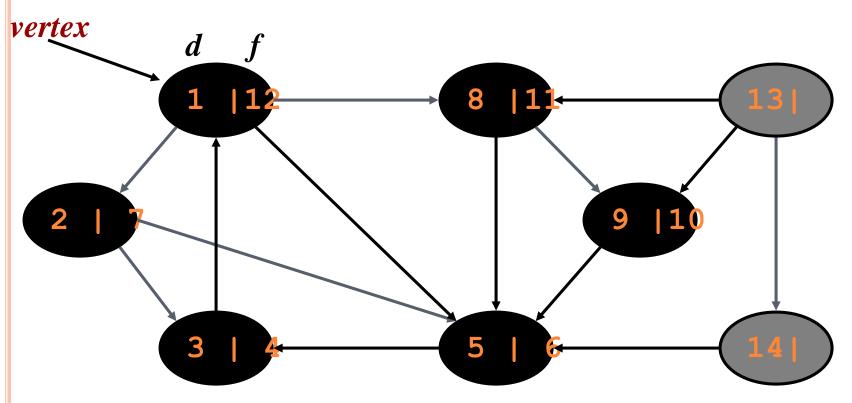


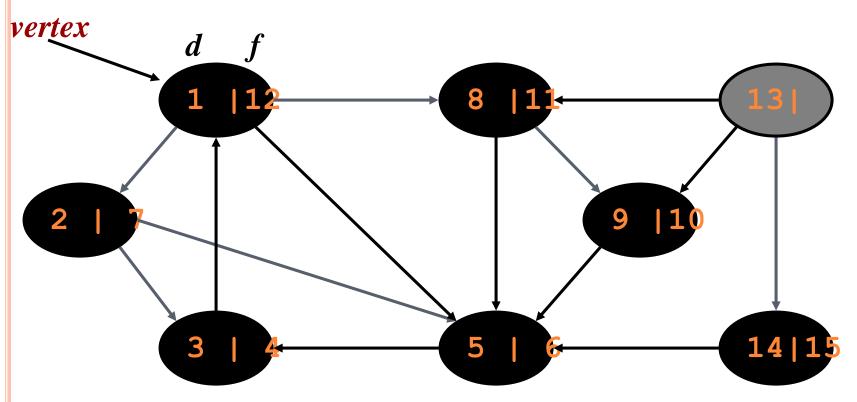


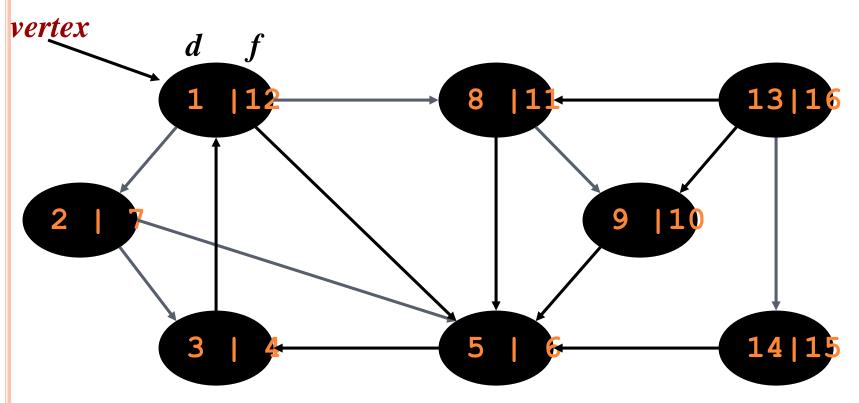












BREADTH-FIRST SEARCH (BFS)

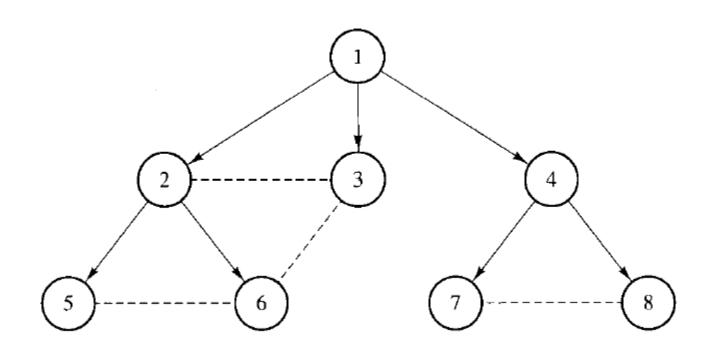
- Search for all vertices that are directly reachable from the root (called level 1 vertices)
- After mark all these vertices, visit all vertices that are directly reachable from any level 1 vertices (called level 2 vertices), and so on.
- In general, level k vertices are directly reachable from a level k 1 vertices

```
procedure bfs(v)
Q \leftarrow empty-queue
mark[v] \leftarrow visited
enqueue v into Q
while Q is not empty do
u \leftarrow first(Q)
dequeue u from Q
for each node w adjacent to u do
if mark[w] \neq visited then mark[w] \leftarrow visited
enqueue w into Q
```

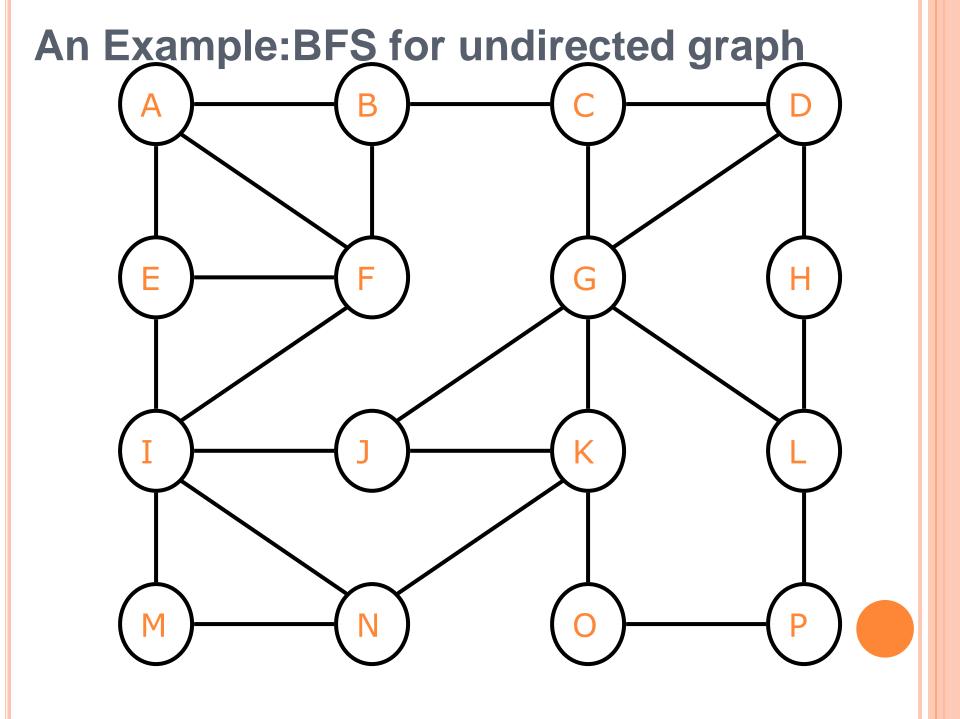
In both cases we need a main program to start the search.

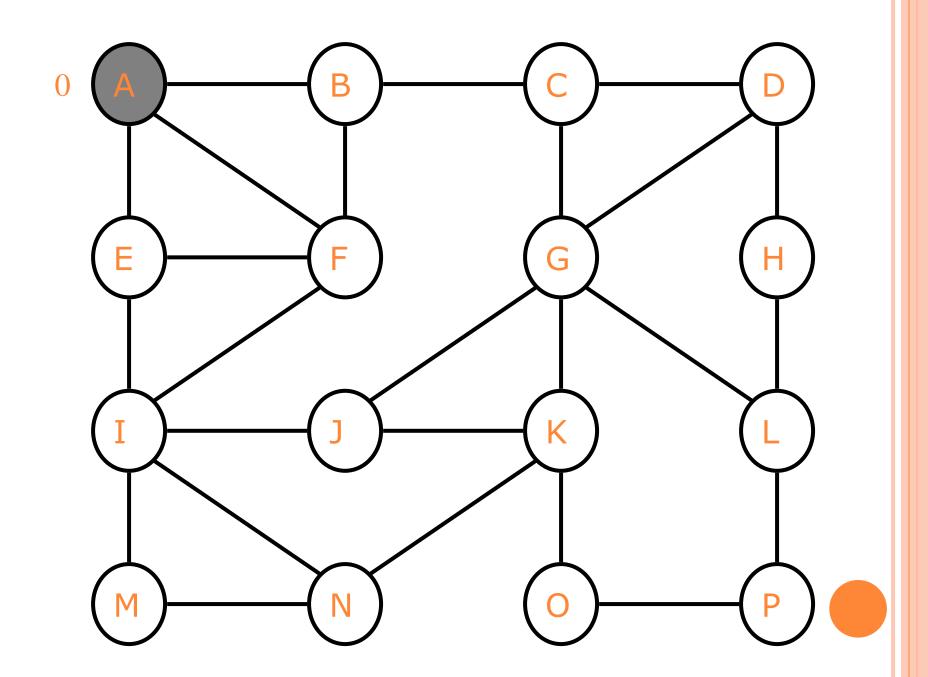
```
procedure search(G)
for each v \in N do mark[v] \leftarrow not\text{-}visited
for each v \in N do
if mark[v] \neq visited then \{dfs2 \text{ or } bfs\} (v)
```

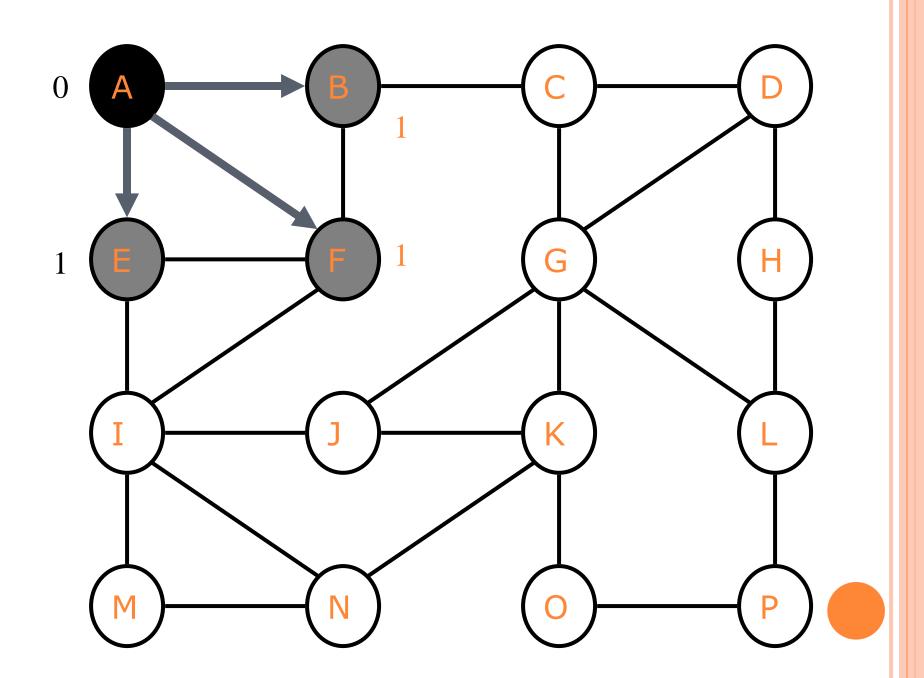
EXAMPLE:BFS FOR DIRECTED GRAPH

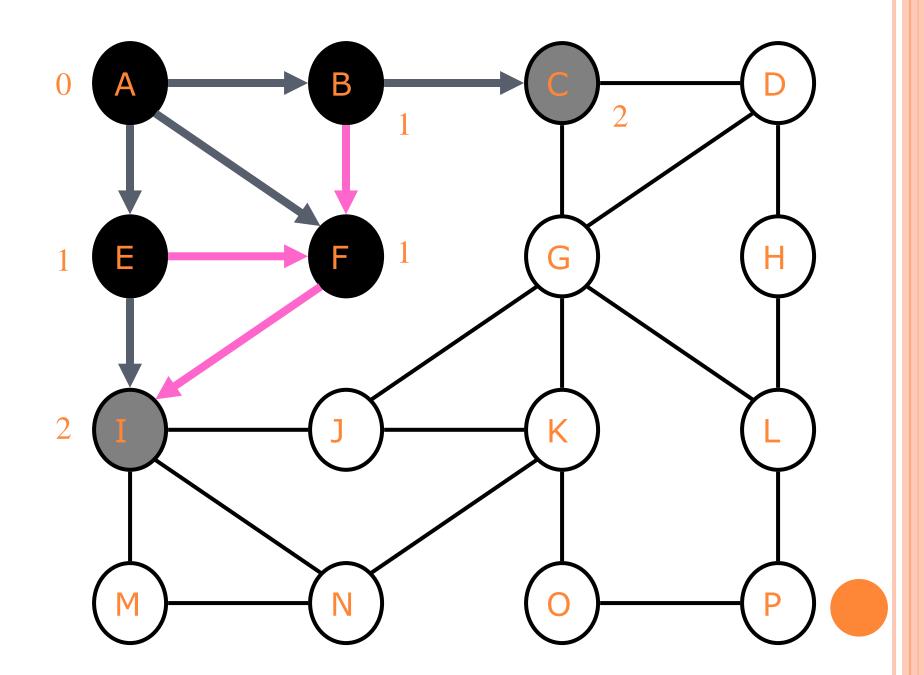


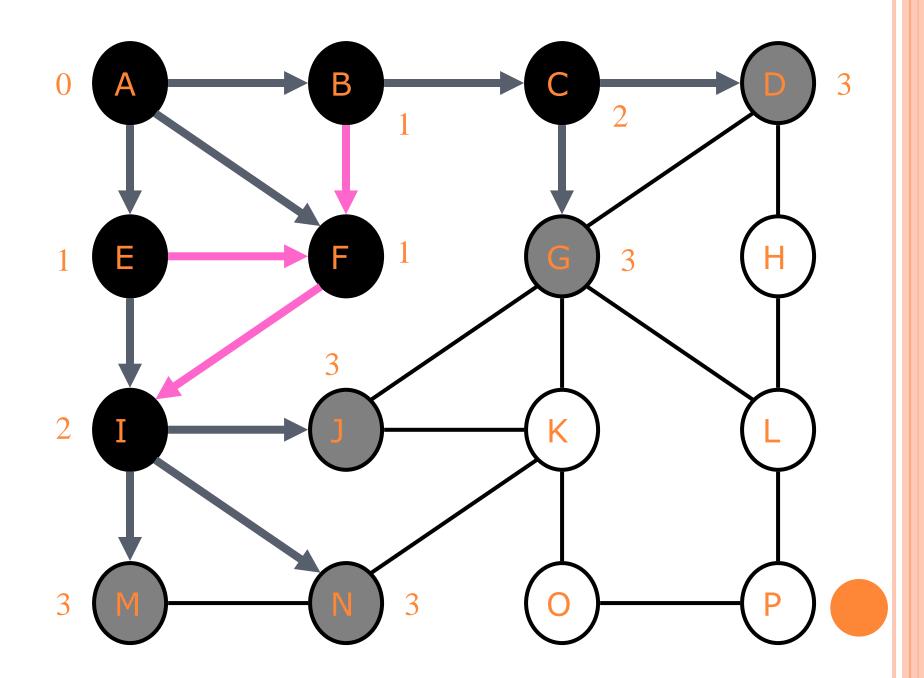
	Node visited	Q
1.	1	2,3,4
2.	2	3,4,5,6
3.	3	4,5,6
4.	4	5,6,7,8
5.	5	6,7,8
6.	6	7,8
7.	7	8
8.	8	

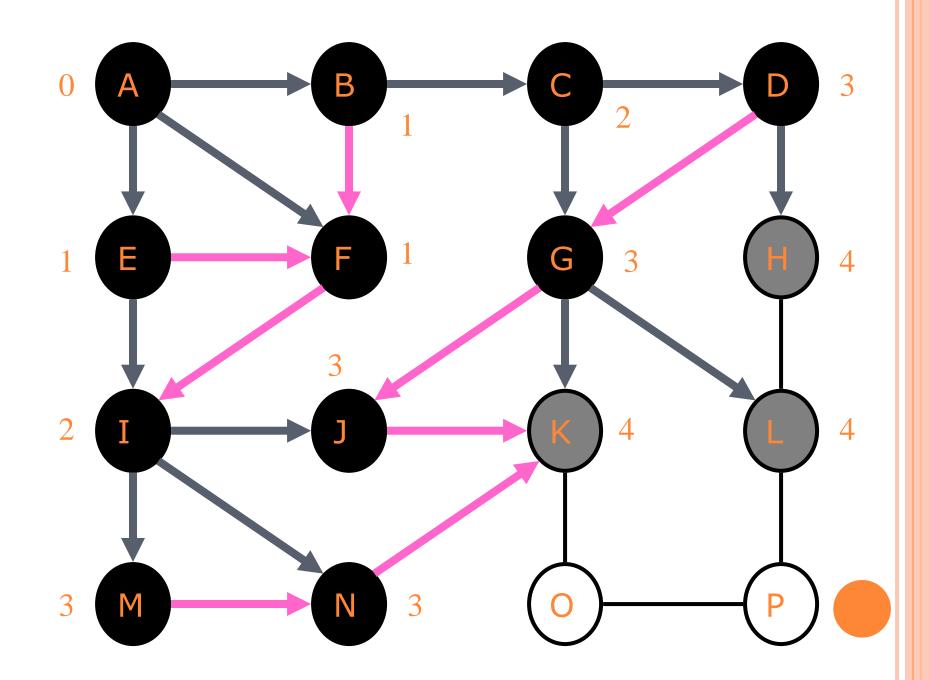


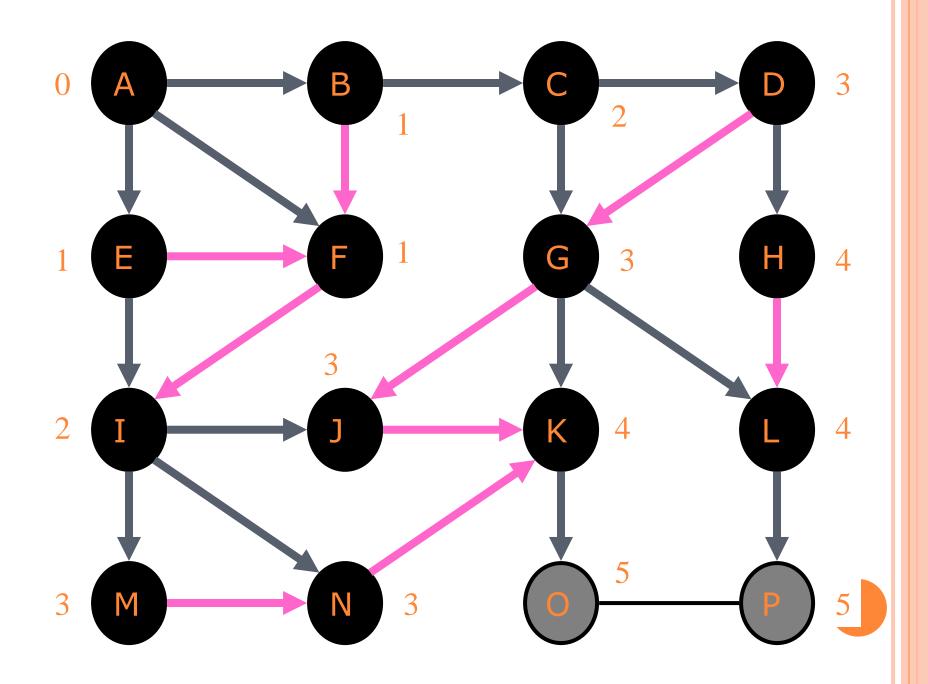


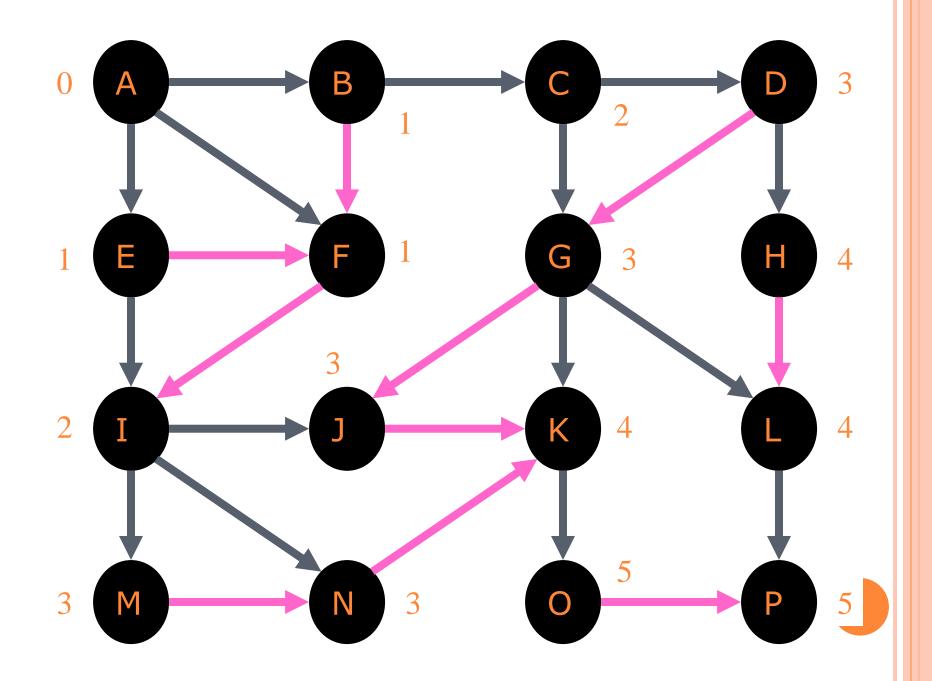


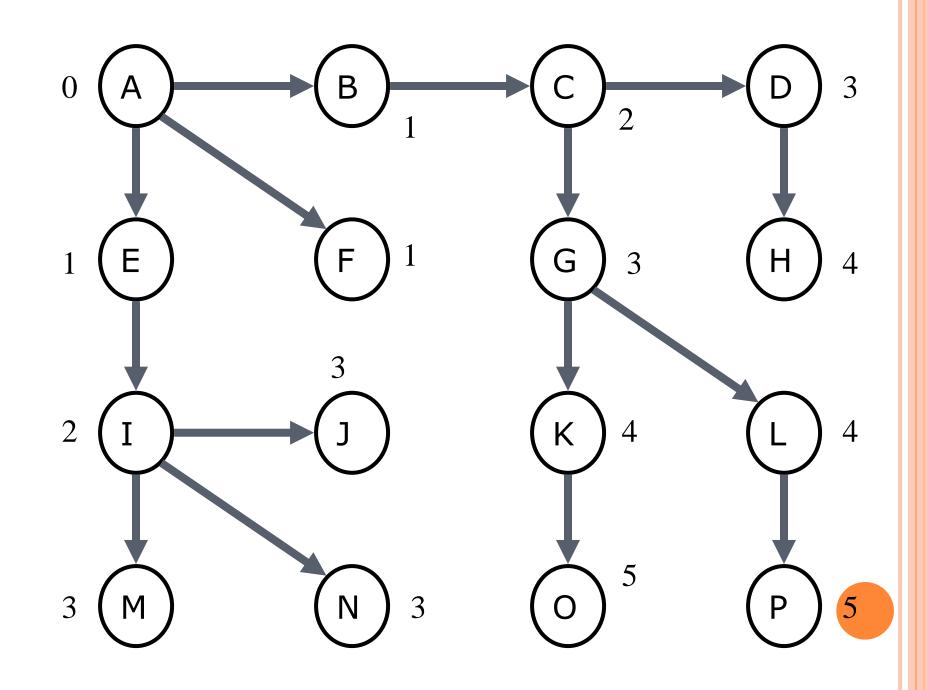












Thnk u...very much..