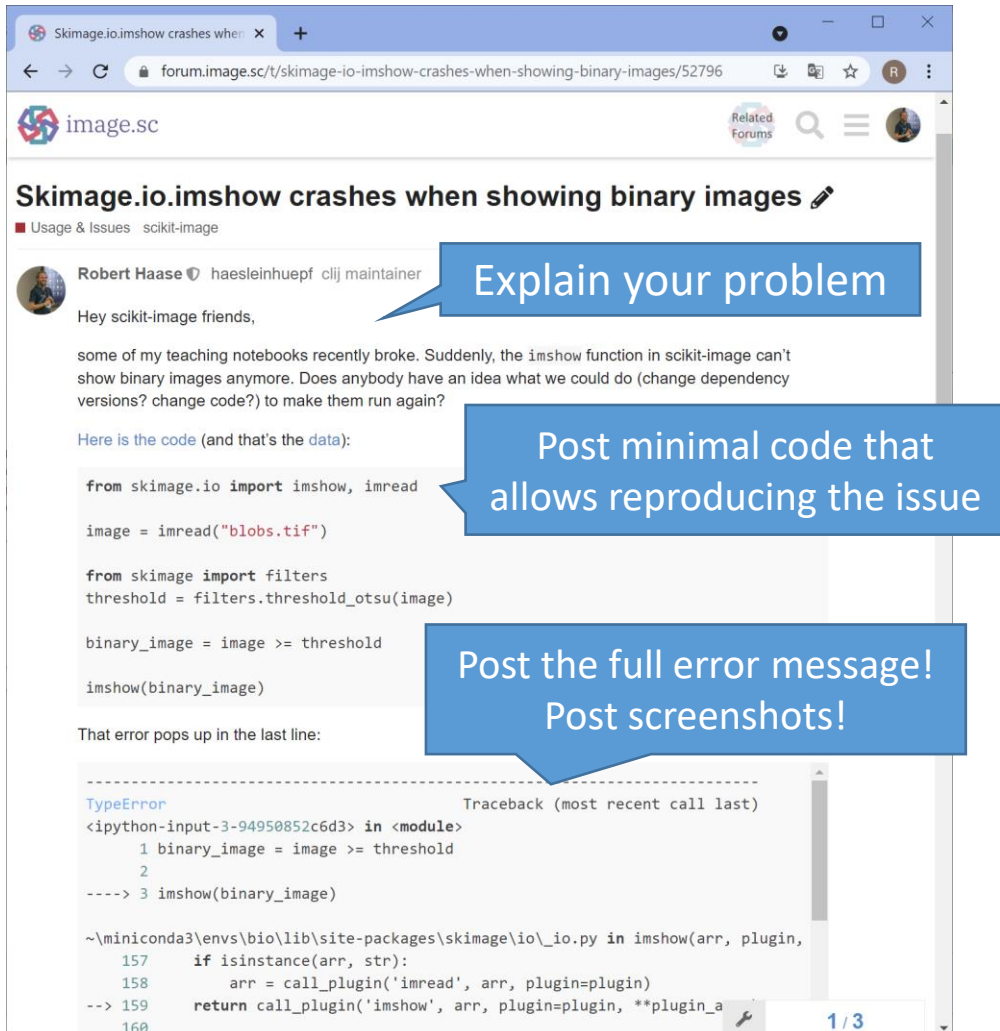


GPU-accelerated image processing

Robert Haase

May 2021

- In case you run in trouble with image analysis, observe bugs in open-source software or want to know how to analyze your image data: Ask experts!



Skimage.io.imshow crashes when showing binary images

Usage & Issues skikit-image

Robert Haase haesleinhuepf clij maintainer

Hey scikit-image friends,

some of my teaching notebooks recently broke. Suddenly, the `imshow` function in `scikit-image` can't show binary images anymore. Does anybody have an idea what we could do (change dependency versions? change code?) to make them run again?

Here is the code (and that's the data):

```
from skimage.io import imread, imread

image = imread("blobs.tif")

from skimage import filters
threshold = filters.threshold_otsu(image)

binary_image = image >= threshold

imshow(binary_image)
```

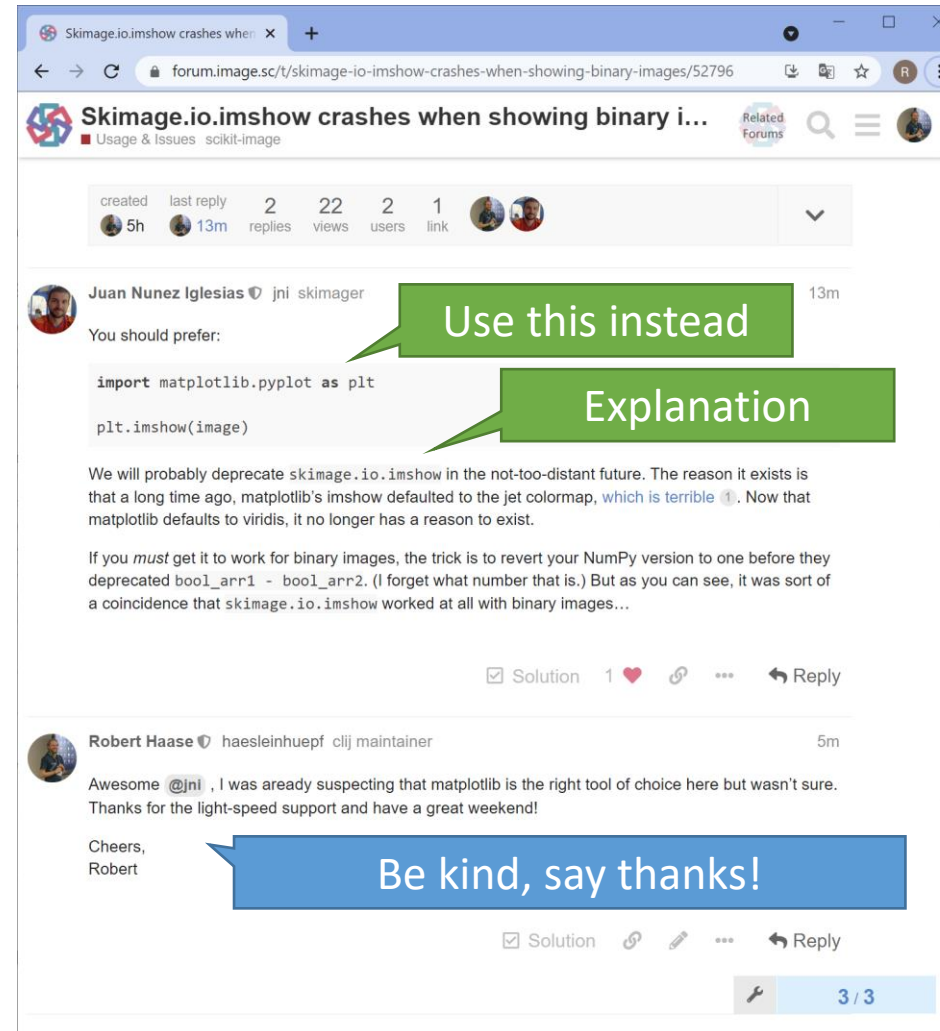
That error pops up in the last line:

```
-----
TypeError                                Traceback (most recent call last)
<ipython-input-3-94950852c6d3> in <module>
      1 binary_image = image >= threshold
      2
----> 3 imshow(binary_image)

~\miniconda3\envs\bio\lib\site-packages\skimage\io\io.py in imshow(arr, plugin,
    157     if isinstance(arr, str):
    158         arr = call_plugin('imread', arr, plugin=plugin)
--> 159     return call_plugin('imshow', arr, plugin=plugin, **plugin_a
    160
```

Callout boxes:

- Explain your problem
- Post minimal code that allows reproducing the issue
- Post the full error message! Post screenshots!



Skimage.io.imshow crashes when showing binary i...

Usage & Issues skikit-image

created 5h last reply 13m 2 replies 22 views 2 users 1 link

Juan Nunez-Iglesias jni skimagier

You should prefer:

```
import matplotlib.pyplot as plt

plt.imshow(image)
```

We will probably deprecate `skimage.io.imshow` in the not-too-distant future. The reason it exists is that a long time ago, `matplotlib`'s `imshow` defaulted to the `jet` colormap, which is terrible. Now that `matplotlib` defaults to `viridis`, it no longer has a reason to exist.

If you *must* get it to work for binary images, the trick is to revert your NumPy version to one before they deprecated `bool_arr1 - bool_arr2`. (I forget what number that is.) But as you can see, it was sort of a coincidence that `skimage.io.imshow` worked at all with binary images...

Callout boxes:

- Use this instead
- Explanation



Juan Nunez-Iglesias

jni

Biomedicine Discovery Institute, Monas...

Melbourne, VIC, Australia

juan.nunez-iglesias@monash.edu

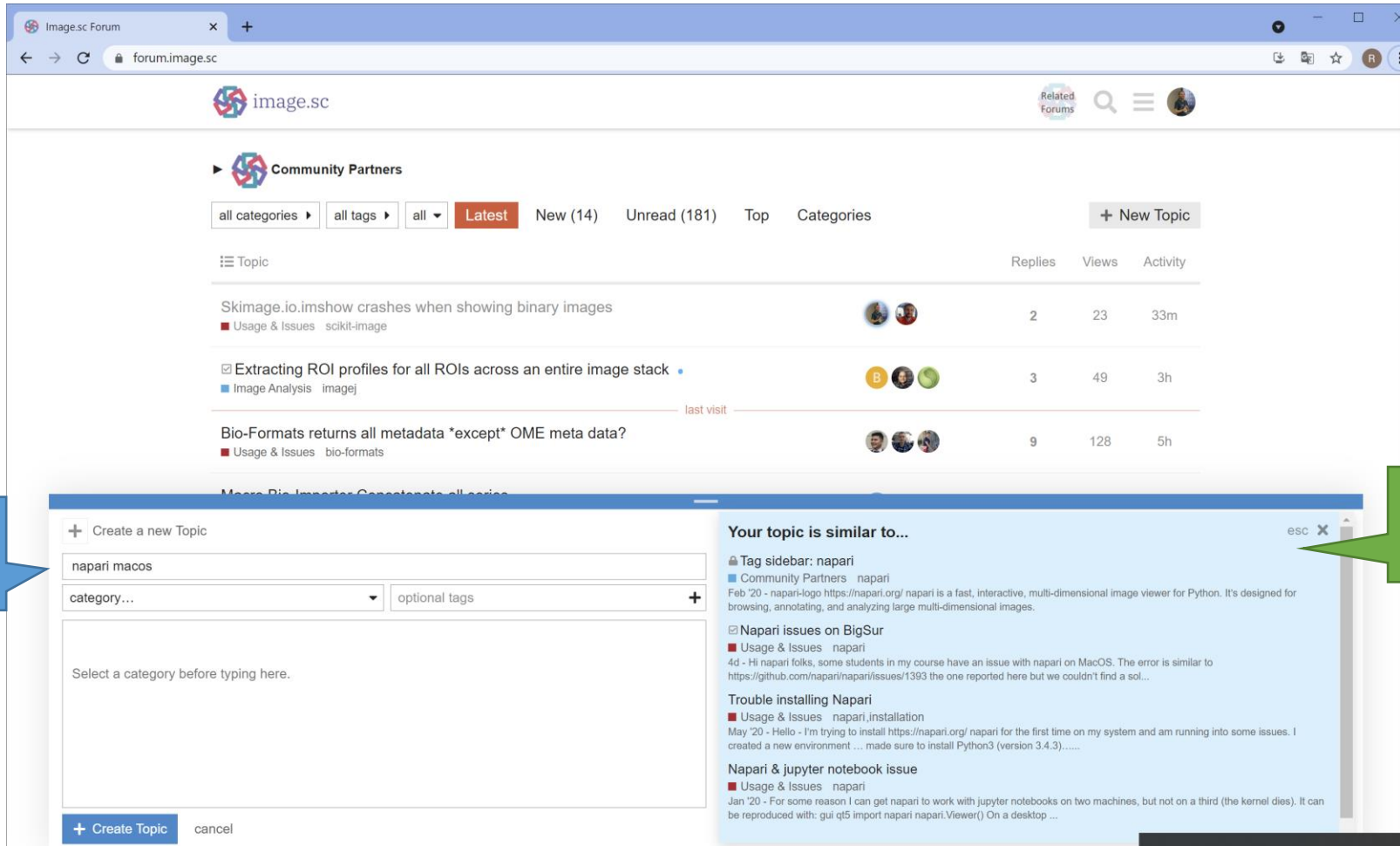
<http://ilovesymposia.com>

[@jnuneziglesias](https://twitter.com/jnuneziglesias)

Tell a friend!

Be kind, say thanks!

- In case you run in trouble with image analysis, observe bugs in open-source software or want to know how to analyze your image data: Ask experts!
- Plus: discover other's people similar questions



The screenshot shows the image.sc forum interface. At the top, there's a navigation bar with the image.sc logo and search icons. Below it, a 'Community Partners' section is visible. The main content area displays a list of forum topics with columns for Topic, Replies, Views, and Activity. The topics listed are:

Topic	Replies	Views	Activity
Skimage.io.imshow crashes when showing binary images ■ Usage & Issues scikit-image	2	23	33m
☑ Extracting ROI profiles for all ROIs across an entire image stack ■ Image Analysis imagej	3	49	3h
Bio-Formats returns all metadata *except* OME meta data? ■ Usage & Issues bio-formats	9	128	5h

Below the list, a 'Create a new Topic' modal is open. It has a text input field containing 'napari macos', a 'category...' dropdown, and an 'optional tags' field. A button '+ Create Topic' is at the bottom left of the modal. On the right side of the modal, there's a section titled 'Your topic is similar to...' which lists related topics:

- Tag sidebar: napari
- Community Partners: napari
- Feb '20 - napari-logo <https://napari.org/> napari is a fast, interactive, multi-dimensional image viewer for Python. It's designed for browsing, annotating, and analyzing large multi-dimensional images.
- ☑ Napari issues on BigSur
- Usage & Issues: napari
- 4d - Hi napari folks, some students in my course have an issue with napari on MacOS. The error is similar to <https://github.com/napari/napari/issues/1393> the one reported here but we couldn't find a sol...
- Trouble installing Napari
- Usage & Issues: napari.installation
- May '20 - Hello - I'm trying to install <https://napari.org/> napari for the first time on my system and am running into some issues. I created a new environment ... made sure to install Python3 (version 3.4.3).....
- Napari & jupyter notebook issue
- Usage & Issues: napari
- Jan '20 - For some reason I can get napari to work with jupyter notebooks on two machines, but not on a third (the kernel dies). It can be reproduced with: `gui qt5 import napari napari.Viewer()` On a desktop ...

Name your problem

Discover similar problems

- State-of-the-art software for more than 20 years: ImageJ / Fiji



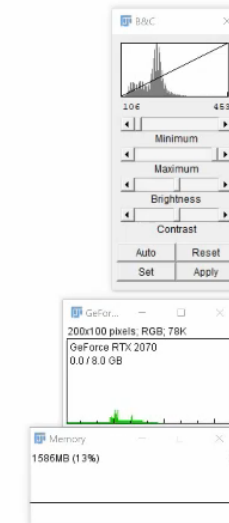
2x

<https://imagej.nih.gov/ij/> <https://fiji.sc>

- The dawn of graphics processing units changes how we interact with image data



2x



<https://clij.github.io/assistant>

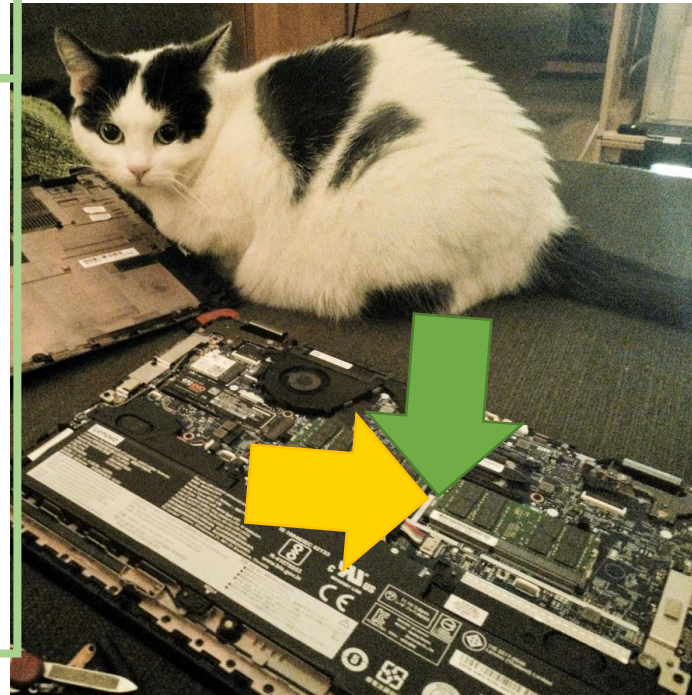
- Every computer that has a screen also has a GPU.

Central Processing Unit (CPU)

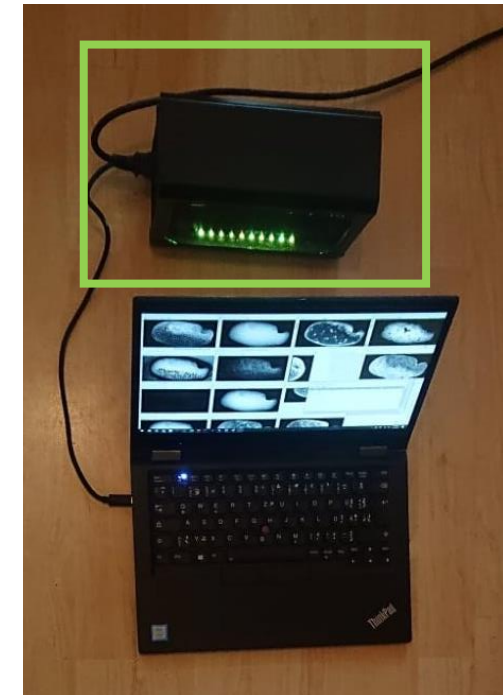
Graphics Processing Unit (GPU)



dedicated GPUs



integrated GPUs



external "eGPUs"

Why GPU-acceleration?

- 1-2 orders of magnitude speedup are possible



vs.



 Workstation CPU

2x Intel Xeon Silver 4110

 Workstation GPU

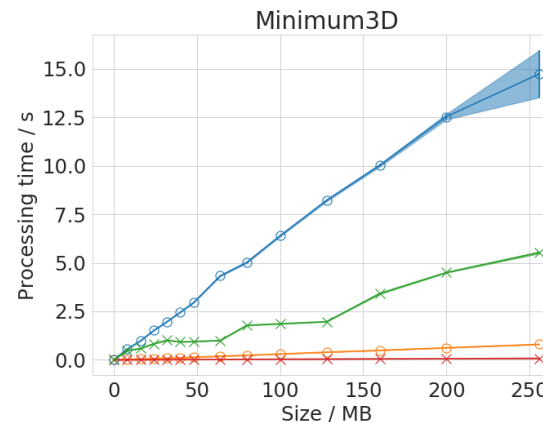
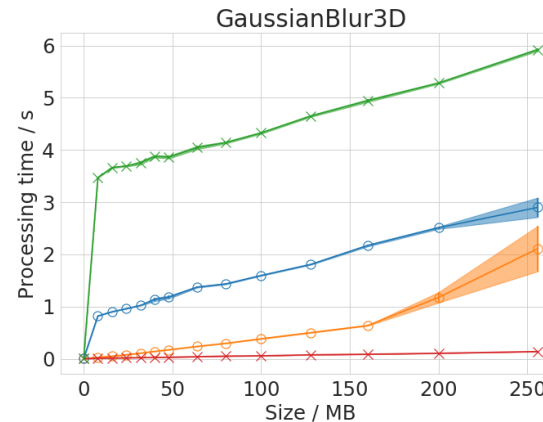
Nvidia Quadro P6000

 Laptop CPU

Intel Core i7-8650U

 Laptop GPU

Intel UHD 620 GPU



Speedup factor compared to Laptop CPU

8 MB (2D)	AddImagesWeighted2D	3	8
	AddScalar2D	7	14
	AutoThreshold2D	2	2
	BinaryAnd2D	2	4
	Erode2D	11	20
	FixedThreshold2D	2	5
	Flip2D	16	37
	GaussianBlur2D	3	9
	Mean2D	3	10
	Median2D	2	35
	Minimum2D	7	22
	MultiplyScalar2D	10	21
	Rotate2D	3	22
	AddImagesWeighted3D	3	26
	AddScalar3D	3	23
64 MB (3D)	AutoThreshold3D	3	5
	BinaryAnd3D	3	24
	Erode3D	2	13
	FixedThreshold3D	4	30
	Flip3D	15	119
	GaussianBlur3D	6	35
	MaximumZProjection	7	46
	Mean3D	18	150
	Median3D	3	43
	Minimum3D	23	188
	MultiplyScalar3D	4	28
	RadialReslice	14	42
	Rotate3D	0.1	2
		Laptop GPU	Workstation GPU

For 3D data worthwhile!

Why GPU-acceleration?

- 1-2 orders of magnitude speedup are possible

```
# convolve with skimage-image
result_image = None

for i in range(0, 10):
    start_time = time.time()
    result_image = filters.gaussian(test_image, output=result_image, sigma=sigma)
    print("skimage Gaussian duration: " + str(time.time() - start_time))
```

scikit-image

```
skimage Gaussian duration: 0.644662618637085
skimage Gaussian duration: 0.63631272315979
skimage Gaussian duration: 0.6193966865539551
skimage Gaussian duration: 0.6499156951904297
skimage Gaussian duration: 0.6301307678222656
skimage Gaussian duration: 0.6531178951263428
skimage Gaussian duration: 0.6489198207855225
skimage Gaussian duration: 0.6308994293212891
skimage Gaussian duration: 0.7410404682159424
skimage Gaussian duration: 0.8148434162139893
```

clesperanto

```
# convolve with pyclesperanto
result_image_gpu = None

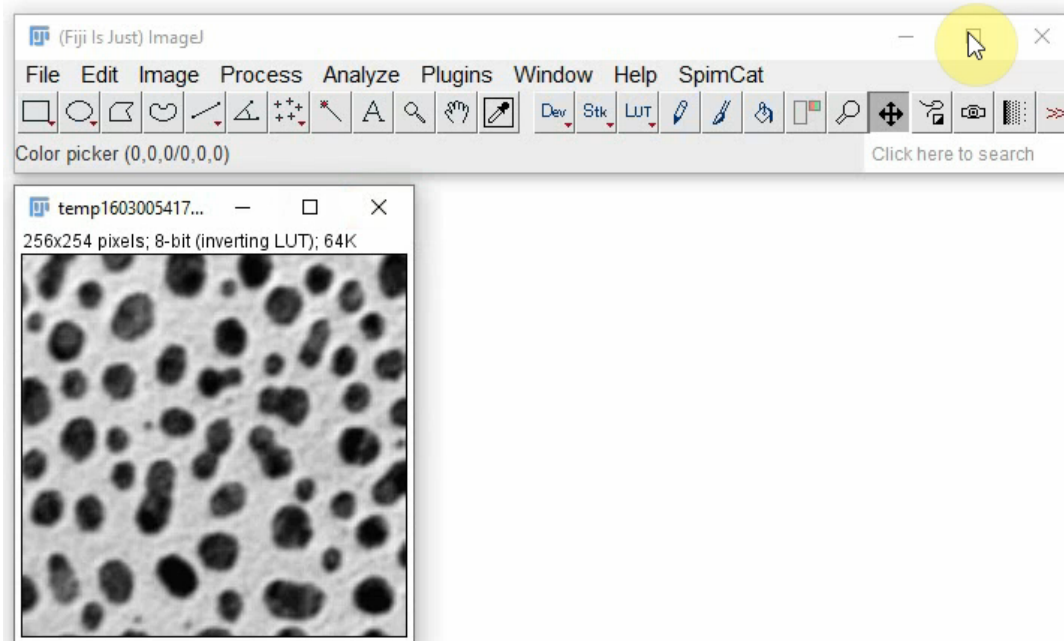
test_image_gpu = cle.push(test_image)

for i in range(0, 10):
    start_time = time.time()
    result_image_gpu = cle.gaussian_blur(test_image_gpu, result_image_gpu, sigma_x=sigma, sigma_y=sigma, sigma_z=sigma)
    print("pyclesperanto Gaussian duration: " + str(time.time() - start_time))
```

```
pyclesperanto Gaussian duration: 0.026170730590820312
pyclesperanto Gaussian duration: 0.002056121826171875
pyclesperanto Gaussian duration: 0.015659093856811523
pyclesperanto Gaussian duration: 0.019225597381591797
pyclesperanto Gaussian duration: 0.01566314697265625
pyclesperanto Gaussian duration: 0.015616178512573242
pyclesperanto Gaussian duration: 0.01566910743713379
pyclesperanto Gaussian duration: 0.015576839447021484
pyclesperanto Gaussian duration: 0.01562190055847168
pyclesperanto Gaussian duration: 0.023794889450073242
```

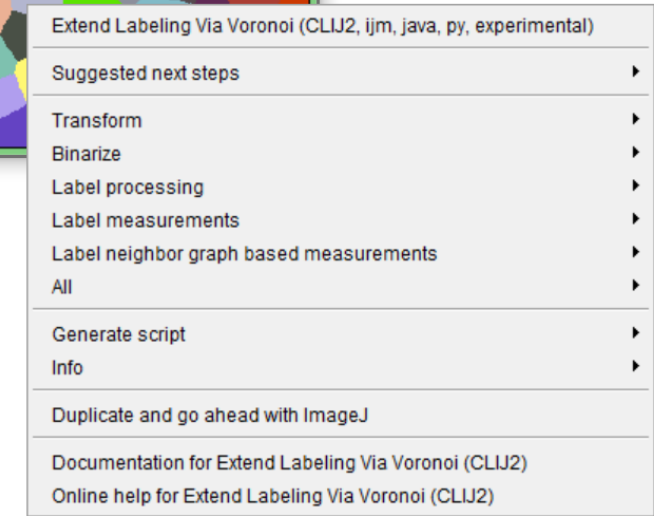
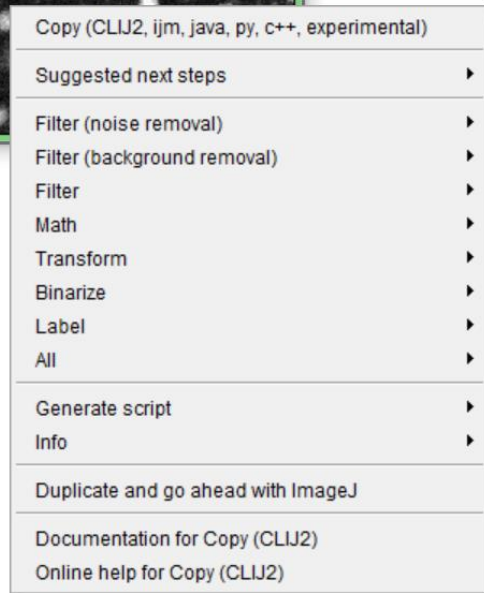
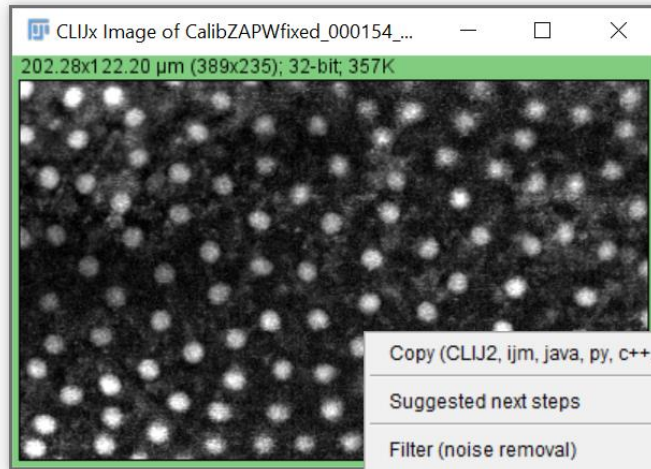
https://nbviewer.jupyter.org/github/BiAPoL/Bio-image-Analysis-with-Python/blob/main/gpu_acceleration/03_why_GPU_acceleration.ipynb

- In ImageJ / Fiji: CLIJ

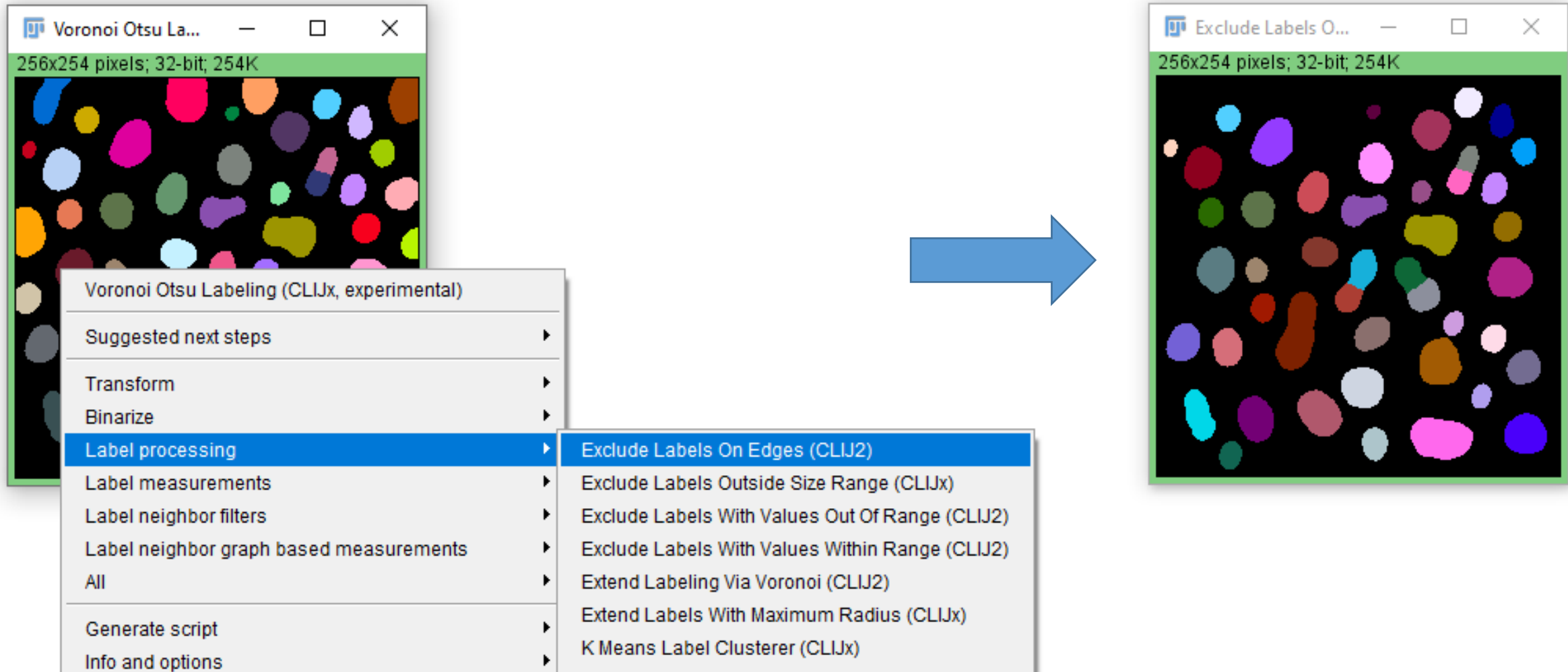


The right-click menu in CLIJ

- The menu order is intentional: From preprocessing to analysis

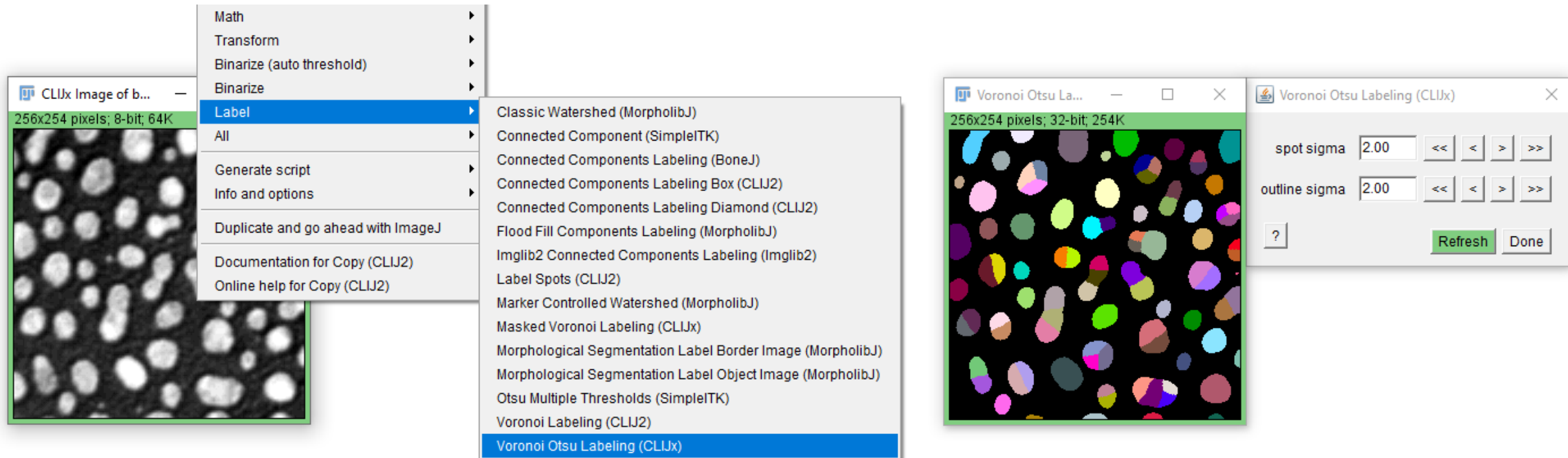


- [Right-click menu]: Label processing

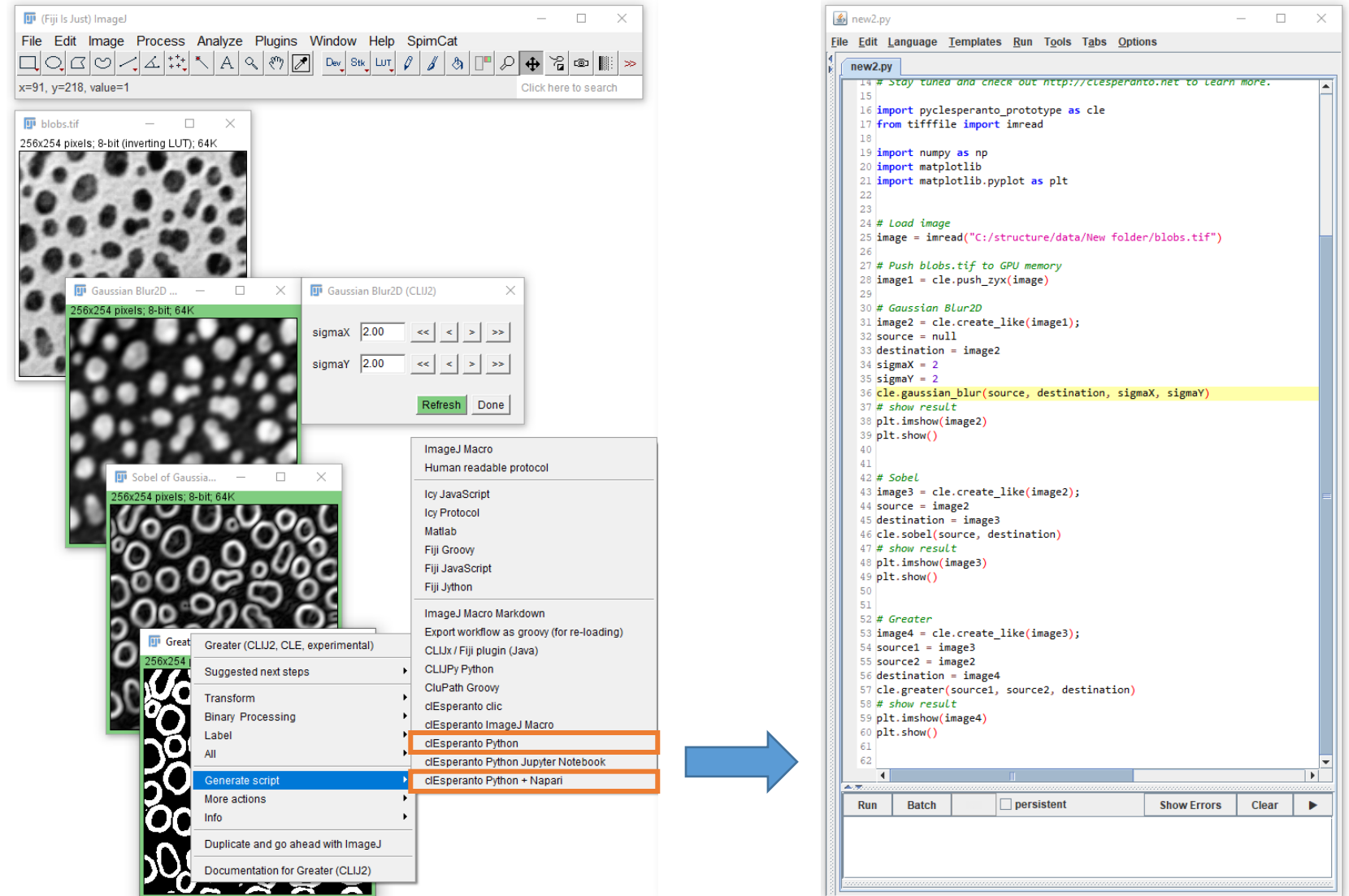


- GPU-accelerated image processing...

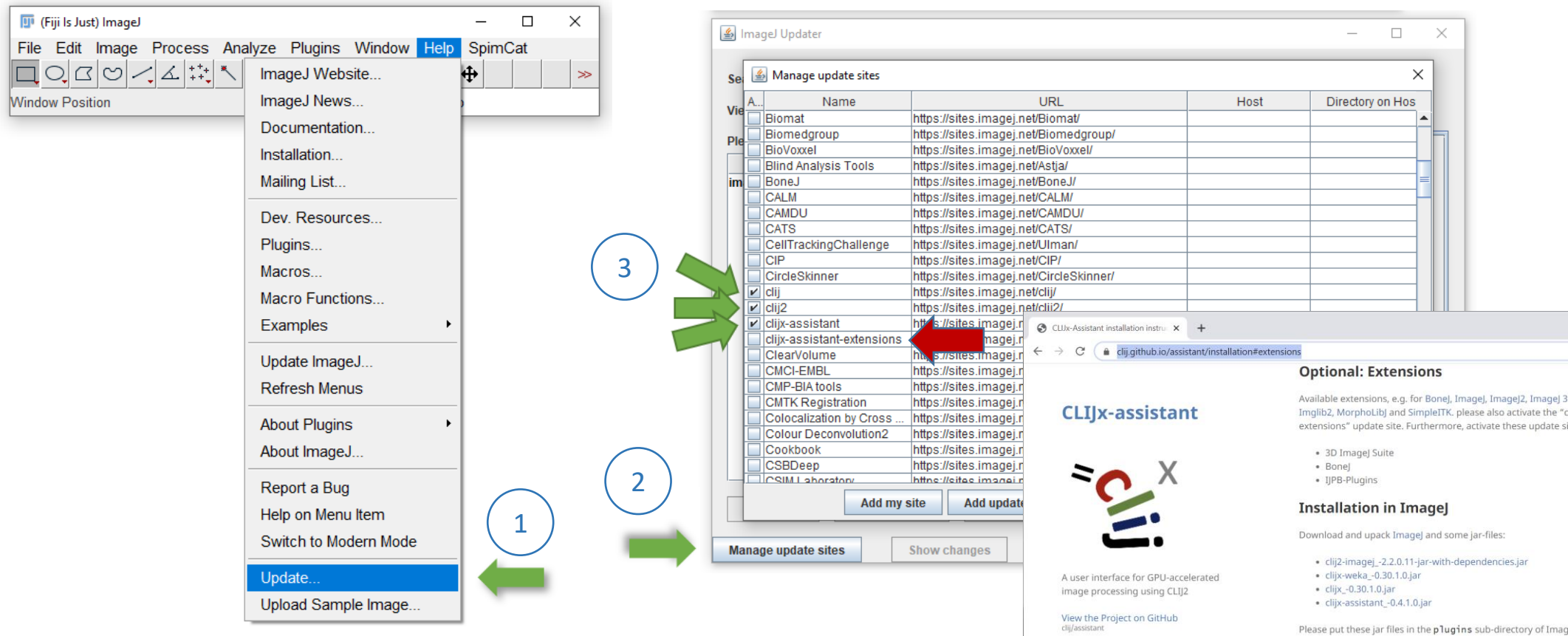
... is also just image processing



- Right-click > Generate Script > cLEsperanto Python
- Copy & Paste it to your Jupyter Notebook
- *If* you want to run it from Fiji, follow these instructions:
https://clij.github.io/assistant/installation#te_oki



- Just activate the CLIJ update sites, in menu Help > Update...
- Linux users: you may need to install OpenCL, e.g. `apt-get install ocl-icd-devel`



The screenshot illustrates the installation process for CLIJ in ImageJ. It shows the 'Help' menu being opened, the 'Update...' option being selected, and the 'Manage update sites' dialog box where the 'clij', 'clij2', and 'clijx-assistant' update sites are checked. A red arrow highlights the 'clijx-assistant' checkbox. Below the dialog, a browser window displays the CLIJx-assistant installation instructions page, which includes a list of optional extensions and the installation steps for ImageJ.

Name	URL	Host	Directory on Host
Biomat	https://sites.imagej.net/Biomat/		
Biomedgroup	https://sites.imagej.net/Biomedgroup/		
BioVoxel	https://sites.imagej.net/BioVoxel/		
Blind Analysis Tools	https://sites.imagej.net/Astja/		
BoneJ	https://sites.imagej.net/BoneJ/		
CALM	https://sites.imagej.net/CALM/		
CAMDU	https://sites.imagej.net/CAMDU/		
CATS	https://sites.imagej.net/CATS/		
CellTrackingChallenge	https://sites.imagej.net/Ulman/		
CIP	https://sites.imagej.net/CIP/		
CircleSkinner	https://sites.imagej.net/CircleSkinner/		
clij	https://sites.imagej.net/clij/		
clij2	https://sites.imagej.net/clij2/		
clijx-assistant	https://sites.imagej.net/clijx-assistant/		
clijx-assistant-extensions	https://sites.imagej.net/clijx-assistant-extensions/		
ClearVolume	https://sites.imagej.net/ClearVolume/		
CMCI-EMBL	https://sites.imagej.net/CMCI-EMBL/		
CMP-BIA tools	https://sites.imagej.net/CMP-BIA tools/		
CMTK Registration	https://sites.imagej.net/CMTK Registration/		
Colocalization by Cross ...	https://sites.imagej.net/Colocalization by Cross .../		
Colour Deconvolution2	https://sites.imagej.net/Colour Deconvolution2/		
Cookbook	https://sites.imagej.net/Cookbook/		
CSBDeep	https://sites.imagej.net/CSBDeep/		
CSM Laboratory	https://sites.imagej.net/CSM Laboratory/		

Optional: Extensions

Available extensions, e.g. for BoneJ, ImageJ, ImageJ2, ImageJ 3 Imglb2, MorphoLibJ and SimpleITK, please also activate the "c extensions" update site. Furthermore, activate these update si

- 3D Image Suite
- BoneJ
- IJPB-Plugins

Installation in ImageJ

Download and unpack ImageJ and some jar-files:

- clij2-imagej_-2.2.0.11-jar-with-dependencies.jar
- clijx-weka_-0.30.1.0.jar
- clijx_-0.30.1.0.jar
- clijx-assistant_-0.4.1.0.jar

Please put these jar files in the **plugins** sub-directory of Imag

- The CLIJ/Fiji counter-part in python/napari

```
conda install -c conda-forge pyopencl
```

```
pip install pyclesperanto-prototype
```

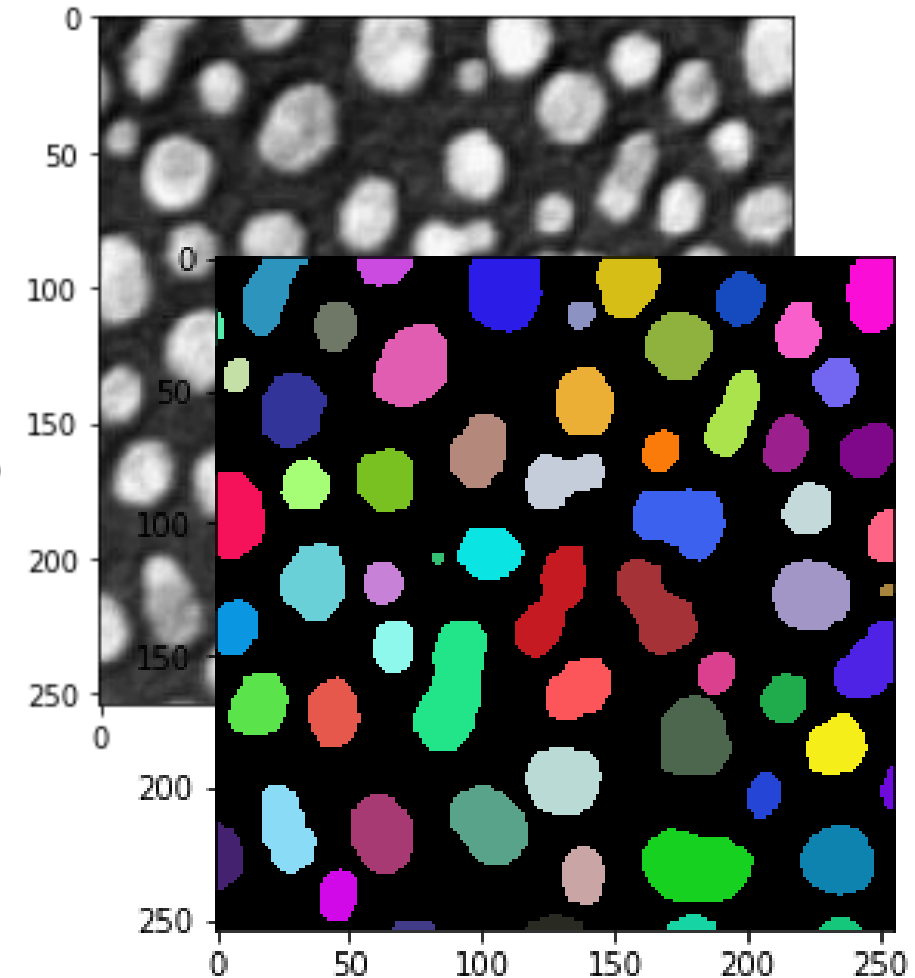
- Napari user interface

```
pip install napari-pyclesperanto-assistant
```

```
from skimage.io import imread, imshow
image = imread("blobs.tif")
imshow(image)
```

```
import pyclesperanto_prototype as cle

# noise removal
blurred = cle.gaussian_blur(image, sigma_x=1, sigma_y=1)
# binarization
binary = cle.threshold_otsu(blurred)
# labeling
labels = cle.connected_components_labeling_box(binary)
# visualize results
cle.imshow(labels, labels=True)
```



- ... allows you to explore available functions for given purposes

```
cle.operations('denoise').keys()
```

```
dict_keys(['gaussian_blur', 'mean_box', 'mean_sphere'])
```

```
cle.operations('background removal').keys()
```

```
dict_keys(['bottom_hat_box', 'bottom_hat_sphere', 'difference_of_gaussian', 'divide_by_gaussian_background', 'subtract_gaussian_background', 'top_hat_box', 'top_hat_sphere'])
```

```
cle.operations('binarize').keys()
```

```
dict_keys(['detect_label_edges', 'detect_maxima_box', 'detect_minima_box', 'equal', 'equal_constant', 'greater', 'greater_constant', 'greater_or_equal', 'greater_or_equal_constant', 'label_to_mask', 'local_threshold', 'not_equal', 'not_equal_constant', 'smaller', 'smaller_constant', 'smaller_or_equal', 'smaller_or_equal_constant', 'threshold', 'threshold_otsu'])
```

```
cle.operations('label').keys()
```

```
dict_keys(['connected_components_labeling_box', 'connected_components_labeling_diamond', 'label_spots', 'masked_voronoi_labeling', 'voronoi_labeling', 'voronoi_otsu_labeling'])
```

- ... allows you to read the documentation

```
▶ print(cle.voronoi_otsu_labeling.__doc__)
```

Applies two Gaussian blurs, spot detection, Otsu-thresholding and Voronoi-labeling.

The thresholded binary image is flooded using the Voronoi approach starting from the found local maxima. Noise-removal sigma for spot detection and thresholding can be configured separately.

Parameters

source : Image
label_image_destination : Image
spot_sigma : float

outline_sigma : float

Returns

label_image_destination

Examples

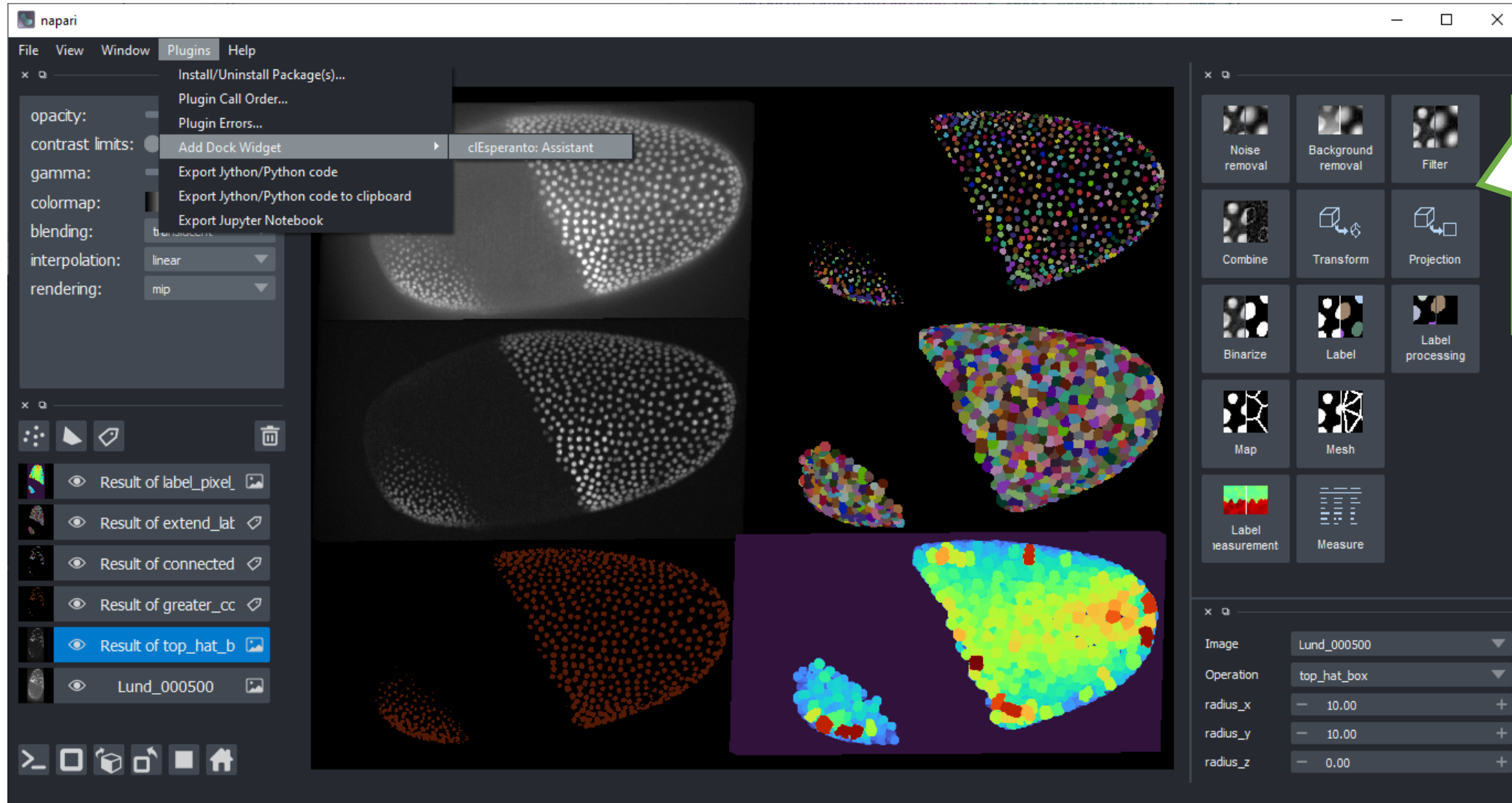
```
>>> import pyclesperanto_prototype as cle  
>>> cle.voronoi_otsu_labeling(source, label_image_destination, 10, 2)
```

References

.. [1] https://clij.github.io/clij2-docs/reference_voronoiOtsuLabeling

Why GPU-acceleration?

- ... because it renders projects feasible which were not without GPUs



Lab / Bachelor /
Master Projects
available here.
Get in touch!

Quantitative measurements

Robert Haase

With material from

Daniela Vorkel (Myers lab MPI CBG)

Cyrus Jin (Dana-Farber Cancer Institute - Harvard BCMP)

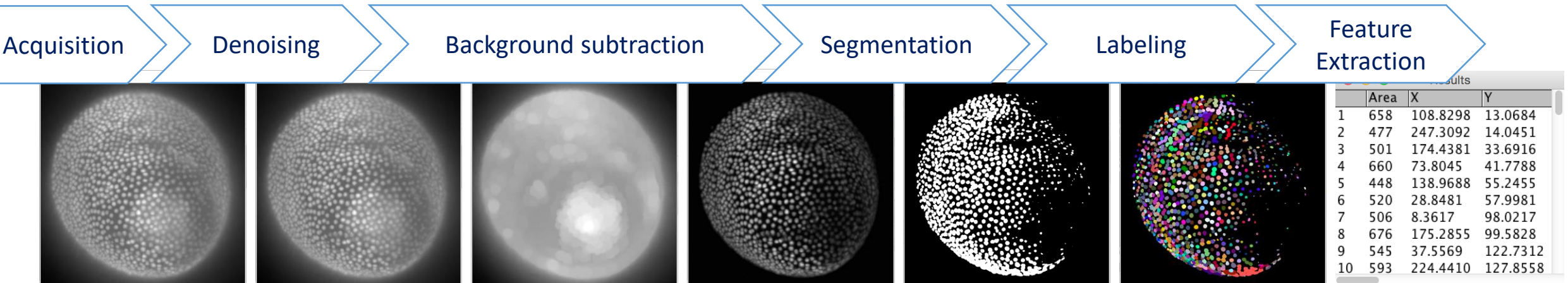
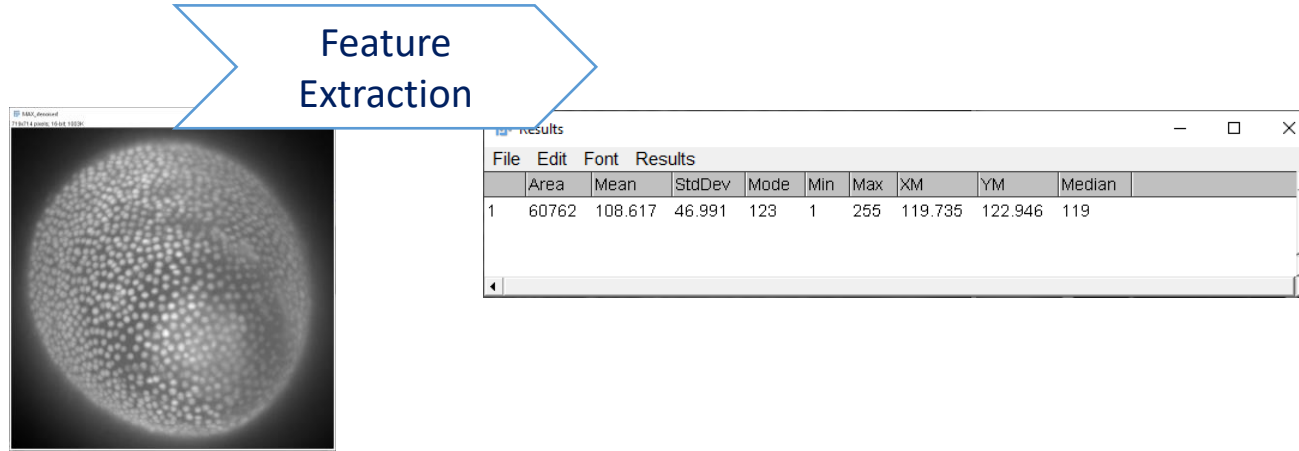
Federico M. Gasparoli (NIC@HMS)

Mauricio Rocha Martins, Norden Lab MPI CBG

David Legland (INRAE)

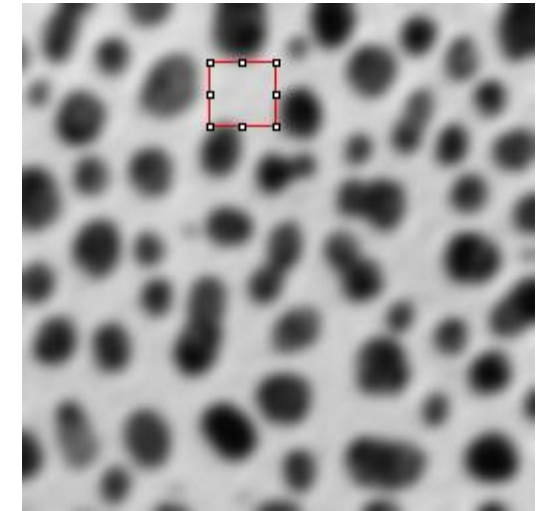
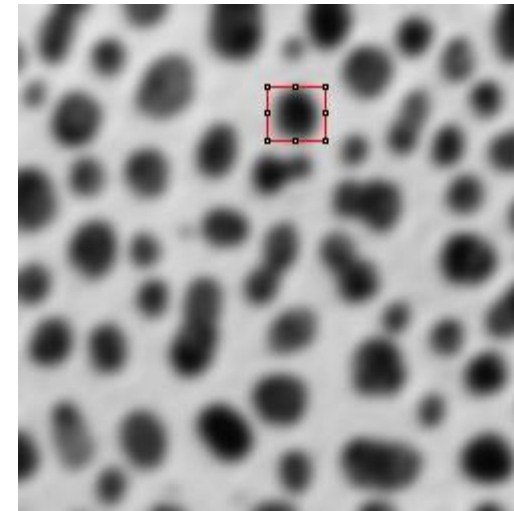
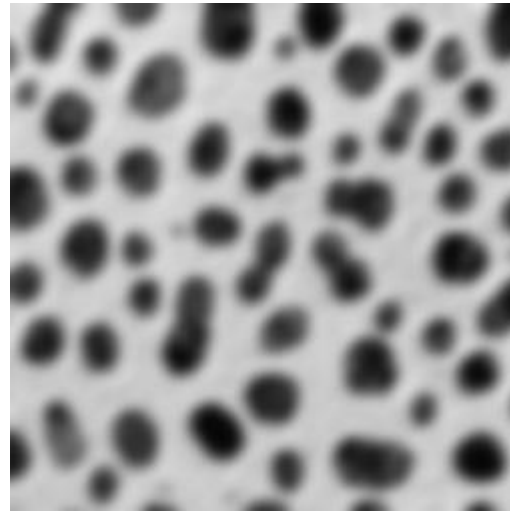
May 2021

- Feature extraction a *late* processing step in image analysis.
- It can be used for images, or segmented/labelled images

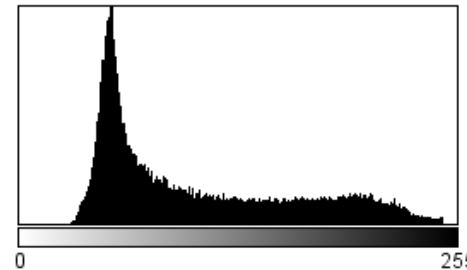


- A *feature* is a countable or measurable property of an image or object.
- Goal of feature extraction is finding a minimal set of features to describe an object well enough to differentiate it from other objects.
- Intensity based features
 - **Mean intensity**
 - **Standard deviation**
 - **Total intensity**
 - Textures
 - ...
- Shape based / spatial features
 - Area / Volume
 - **Roundness**
 - **Solidity**
 - **Circularity** / Sphericity
 - Elongation
 - **Centroid**
 - **Bounding box**
 - ...
- Spatio-temporal features
 - Displacement,
 - Speed,
 - Acceleration,
 - ...
- Others
 - Overlap
 - Colocalisation
 - Network-analysis
 - ...
- Mixed features
 - **Center of mass**
 - Local minima / maxima
 - ...

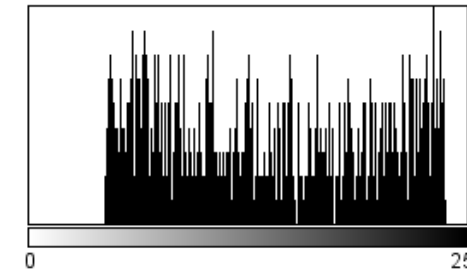
- Min / max
- Median
- Mean
- Mode
- Variance
- Standard deviation



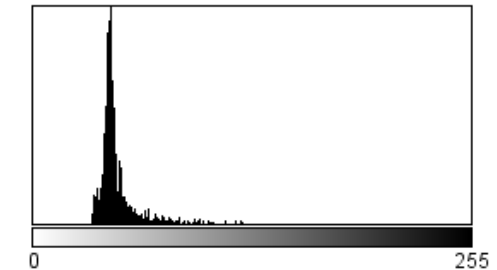
- Can be derived from pixel values
- Don't take spatial relationship of pixels into account
- See also:
 - descriptive statistics
 - histogram



Count: 65024 Min: 29
Mean: 103.301 Max: 248
StdDev: 57.991 Mode: 53 (1663)



Count: 783 Min: 44
Mean: 141.308 Max: 243
StdDev: 61.876 Mode: 236 (9)



Count: 1056 Min: 34
Mean: 49.016 Max: 122
StdDev: 12.685 Mode: 45 (120)

- Relative position in an image weighted by pixel intensities

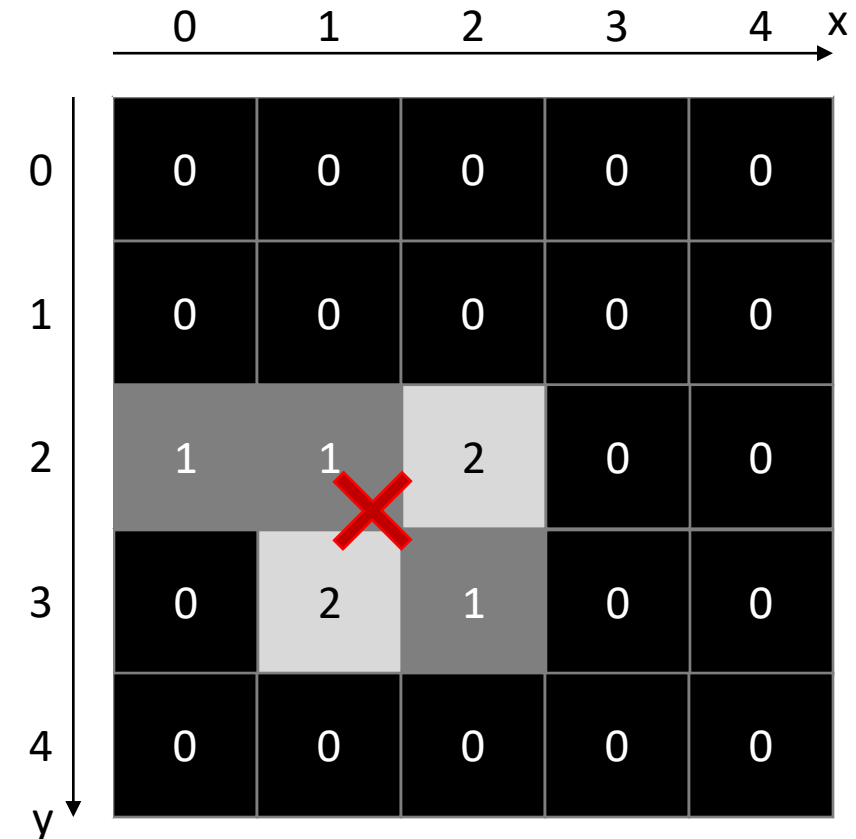
- x, y ... pixel coordinates
- w ... image width
- h ... image height
- μ ... mean intensity
- $g_{x,y}$... pixel grey value
- x_m, y_m ... center of mass coordinates

$$\mu = \frac{1}{wh} \sum_{y=0}^{h-1} \sum_{x=0}^{w-1} g_{x,y}$$

$$x_m = \frac{1}{wh\mu} \sum_{y=0}^{h-1} \sum_{x=0}^{w-1} x g_{x,y}$$

$$y_m = \frac{1}{wh\mu} \sum_{y=0}^{h-1} \sum_{x=0}^{w-1} y g_{x,y}$$

“sum intensity”
“total intensity”



$$x_m = 1/7 (1 \cdot 0 + 1 \cdot 1 + 2 \cdot 2 + 2 \cdot 1 + 1 \cdot 2) = 1.3$$

$$y_m = 1/7 (1 \cdot 2 + 1 \cdot 2 + 2 \cdot 3 + 2 \cdot 2 + 1 \cdot 3) = 2.4$$

- Relative position in an image weighted by pixel intensities
- Special case of center of mass for binary images
 - x, y ... pixel coordinates
 - w ... image width
 - h ... image height
 - μ ... mean intensity
 - $g_{x,y}$... pixel grey value, integer in range [0;1]
 - x_m, y_m ... center of mass coordinates

$$\mu = \frac{1}{wh} \sum_{y=0}^{h-1} \sum_{x=0}^{w-1} g_{x,y}$$

$$x_m = \frac{1}{wh\mu} \sum_{y=0}^{h-1} \sum_{x=0}^{w-1} x g_{x,y}$$

$$y_m = \frac{1}{wh\mu} \sum_{y=0}^{h-1} \sum_{x=0}^{w-1} y g_{x,y}$$

Number of white pixels

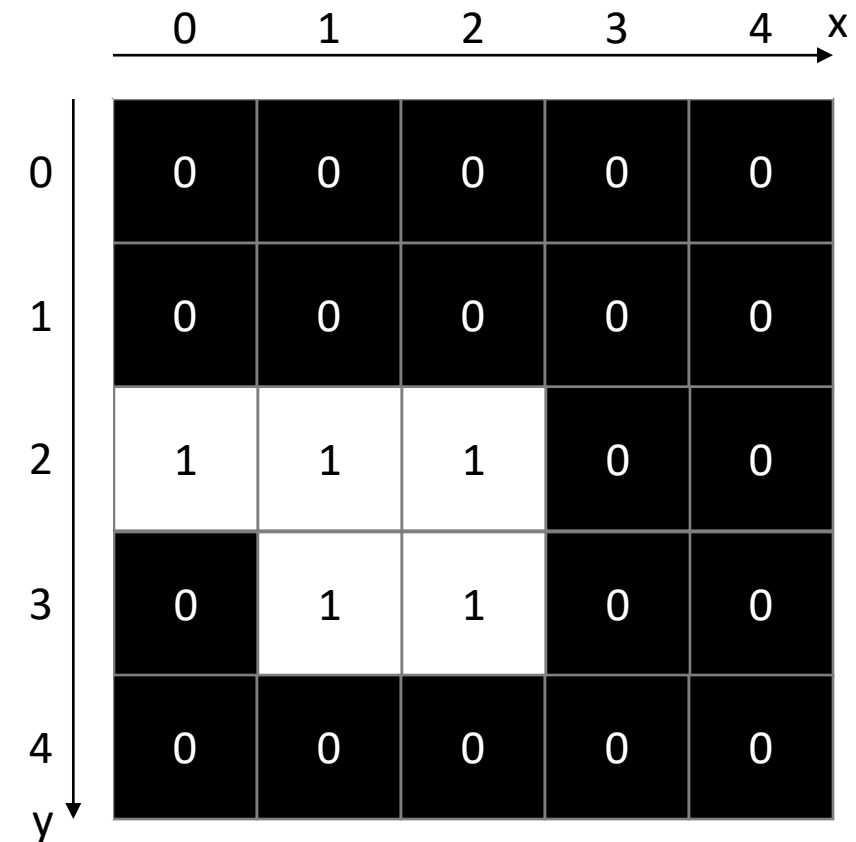
	0	1	2	3	4	x
0	0	0	0	0	0	
1	0	0	0	0	0	
2	1	1	1	0	0	
3	0	1	1	0	0	
4	0	0	0	0	0	
y						

$$x_m = 1/5 (1 \cdot 0 + 1 \cdot 1 + 1 \cdot 2 + 1 \cdot 1 + 1 \cdot 2) = 1.2$$

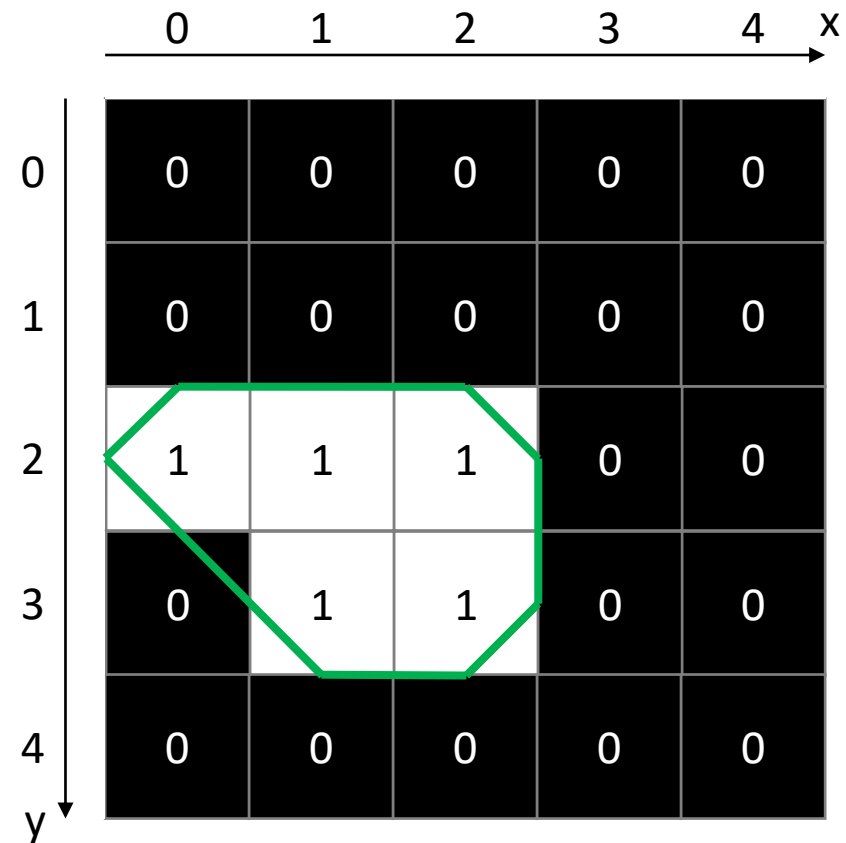
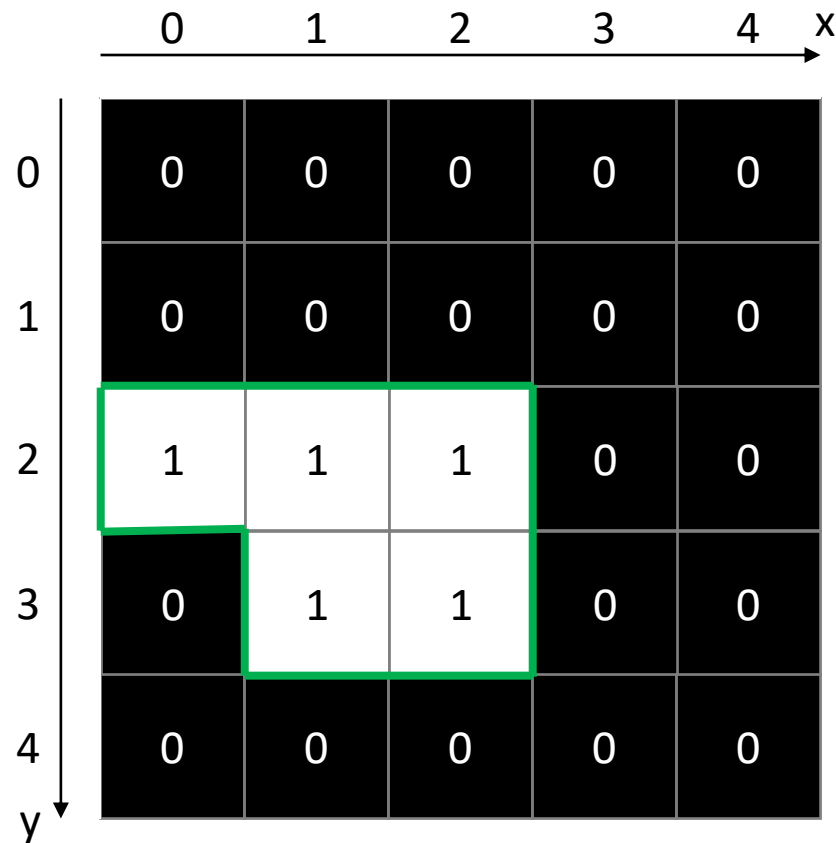
$$y_m = 1/5 (1 \cdot 2 + 1 \cdot 2 + 1 \cdot 3 + 1 \cdot 2 + 1 \cdot 3) = 2.4$$

- Position and size of the smallest rectangle containing all pixels of an object
 - x_b, y_b ... position of the bounding box
 - w_b ... width of the bounding box
 - h_b ... height of the bounding box

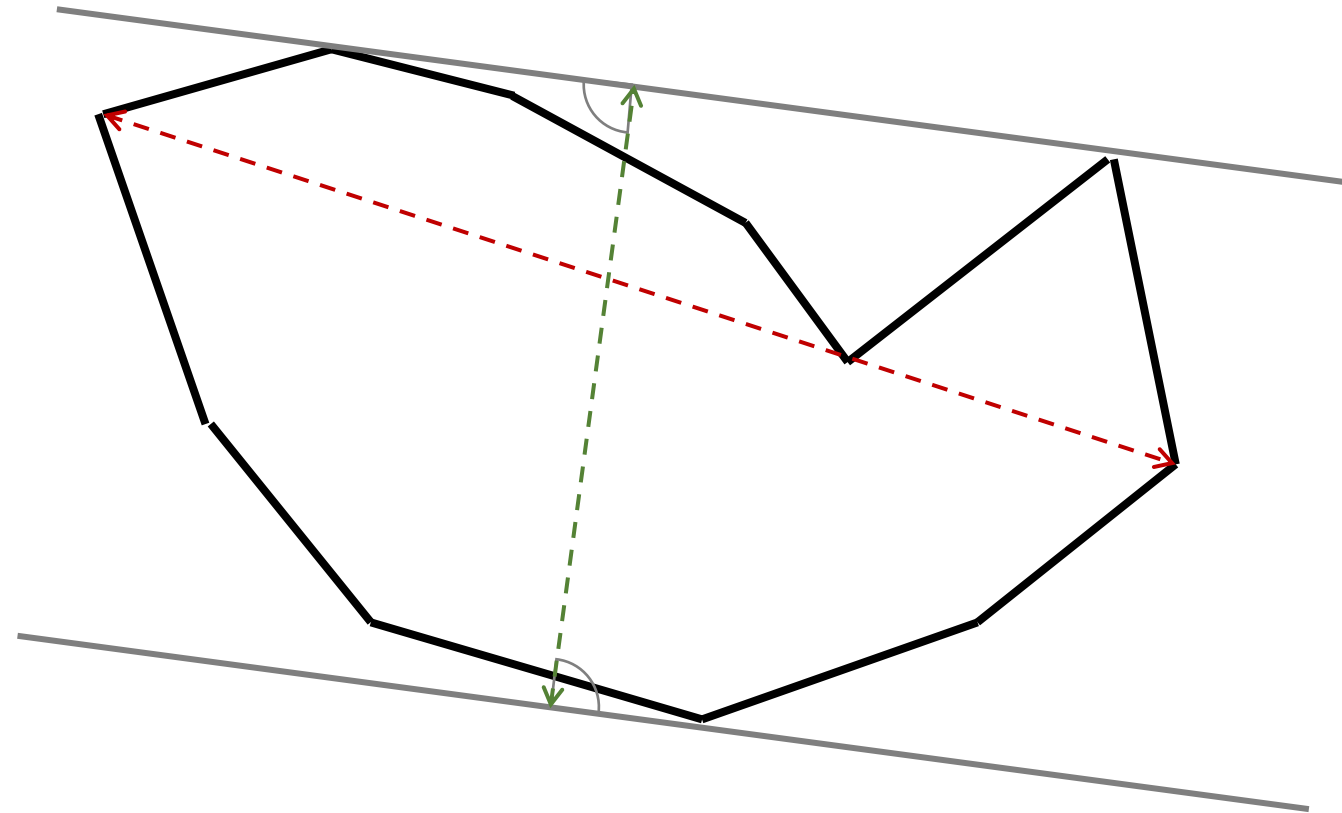
variable	value
x_b	0
y_b	2
w_b	3
h_b	2



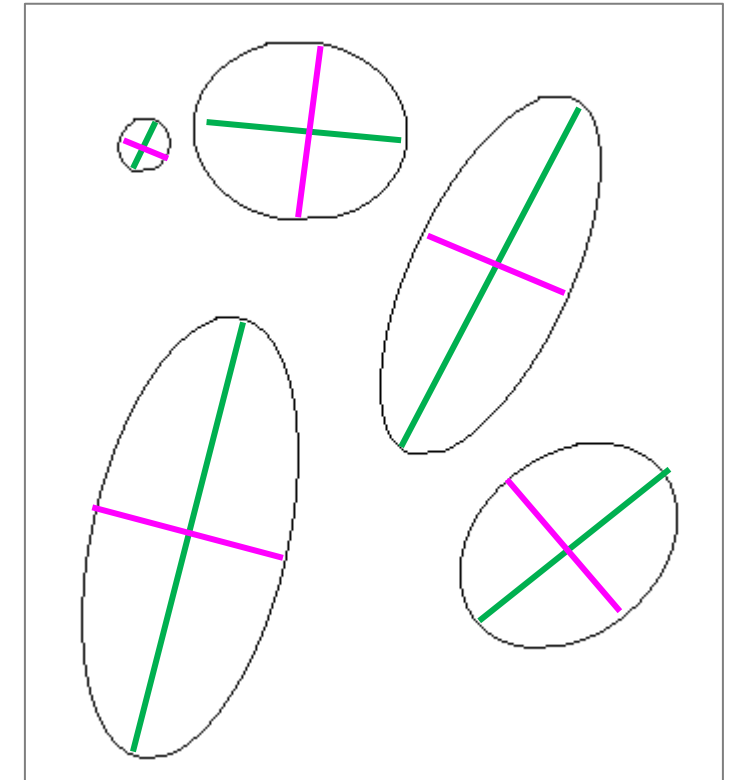
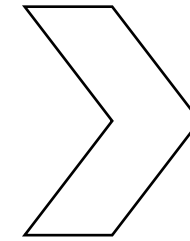
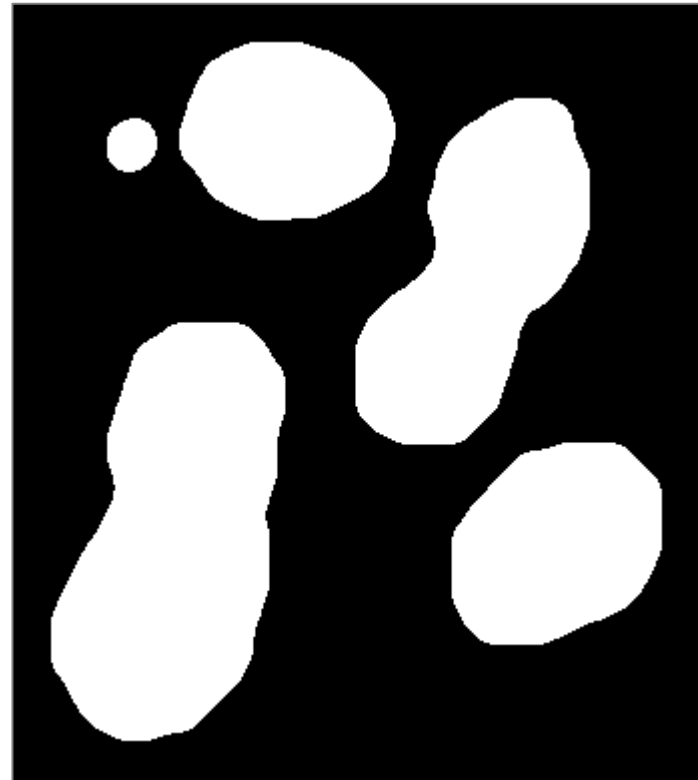
- Length of the outline around an object
- Depends on the actual implementation



- **Feret's diameter** describes the maximum distance between any two points of an outline.
- The **minimum caliper** ("Minimum Feret") describes the shortest distance, the object would fit through.
- Feret and Minimum Feret do not need to be perpendicular to each other!

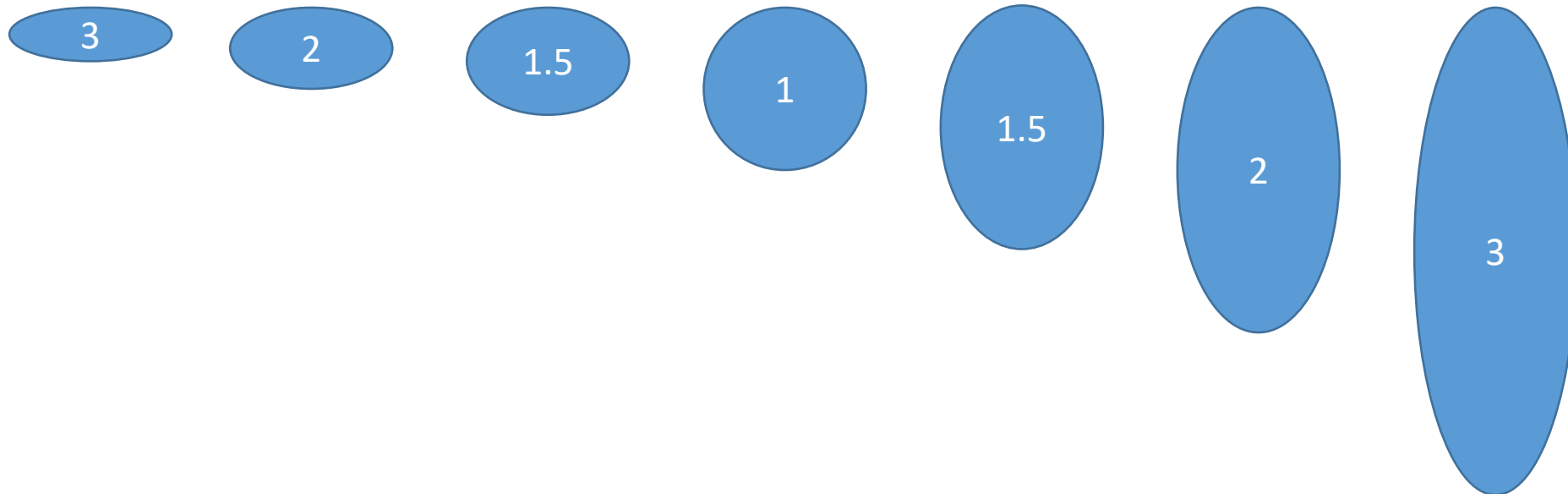


- For every object, find the optimal ellipse simplifying the object.
- Major axis ... long diameter
- Minor axis ... short diameter
- Major and minor axis are perpendicular to each other



- The aspect ratio describes the elongation of an object.

$$AR = \text{major} / \text{minor}$$



- The definition of a circle leads us to measurements of circularity and roundness.
- In case you use these measures, define them correctly. They are not standardized!

Diameter

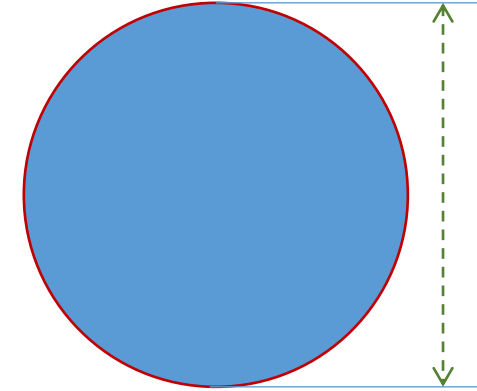
d

Circumference

$$C = \pi d$$

Area

$$A = \frac{\pi d^2}{4}$$



$$roundness = \frac{4 * A}{\pi major^2}$$

$$circularity = \frac{4\pi * A}{perimeter^2}$$

Roundness = 1
Circularity = 1

Roundness \approx 1
Circularity \approx 1

Roundness < 1
Circularity < 1

- In 3D: Circularity -> Sphericity

$$sphericity = 36\pi \frac{V^2}{S^3}$$

Volume

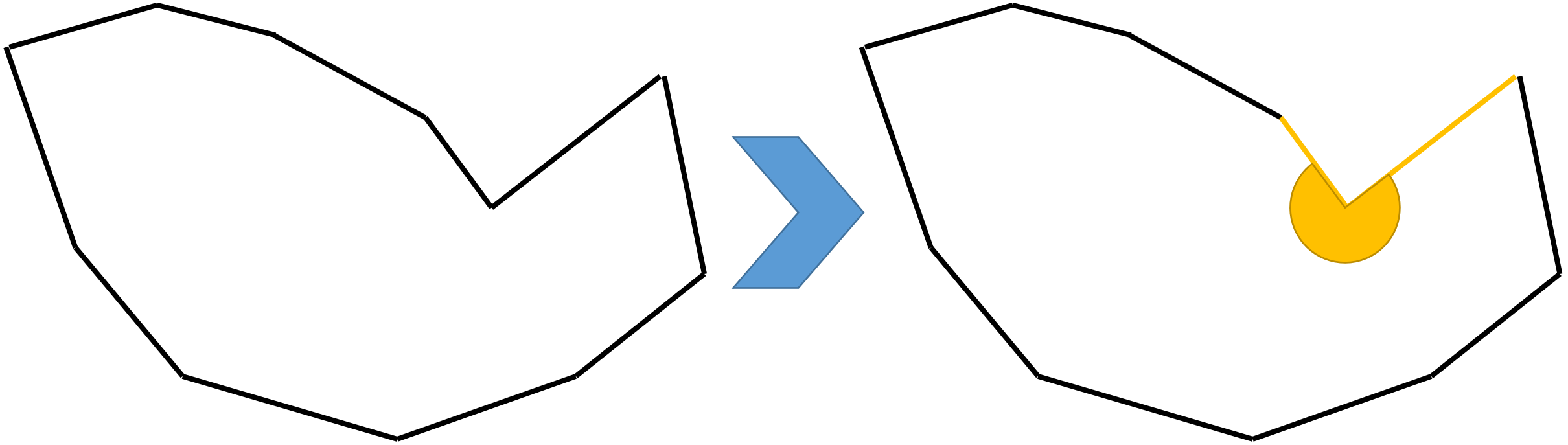
Surface area

What's the difference between circularity and roundness?

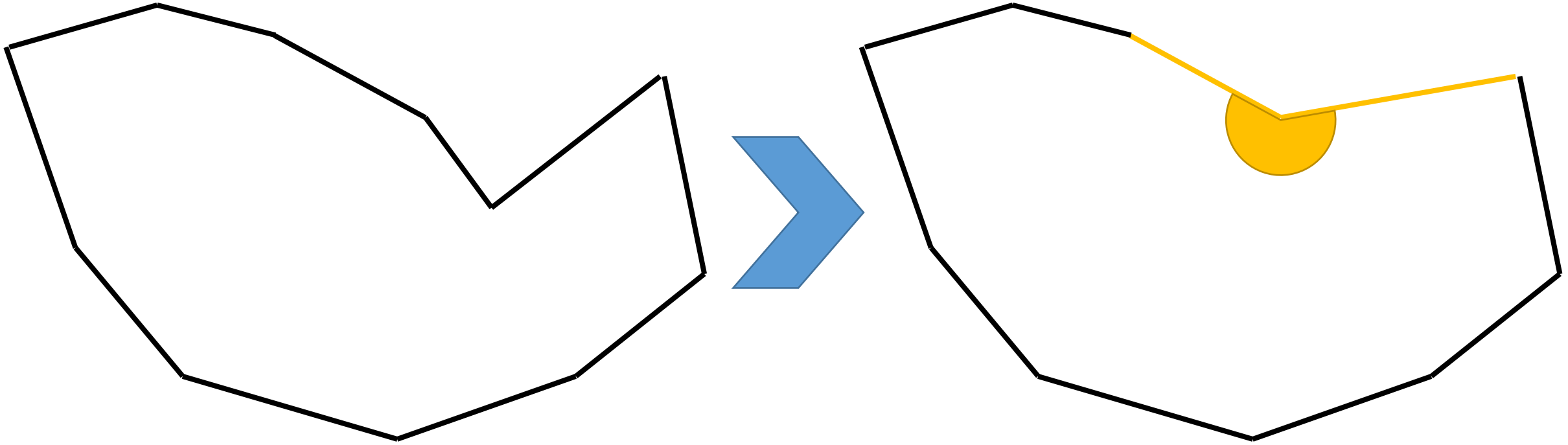
$$roundness = \frac{4 * A}{\pi major^2}$$

$$circularity = \frac{4\pi * A}{perimeter^2}$$

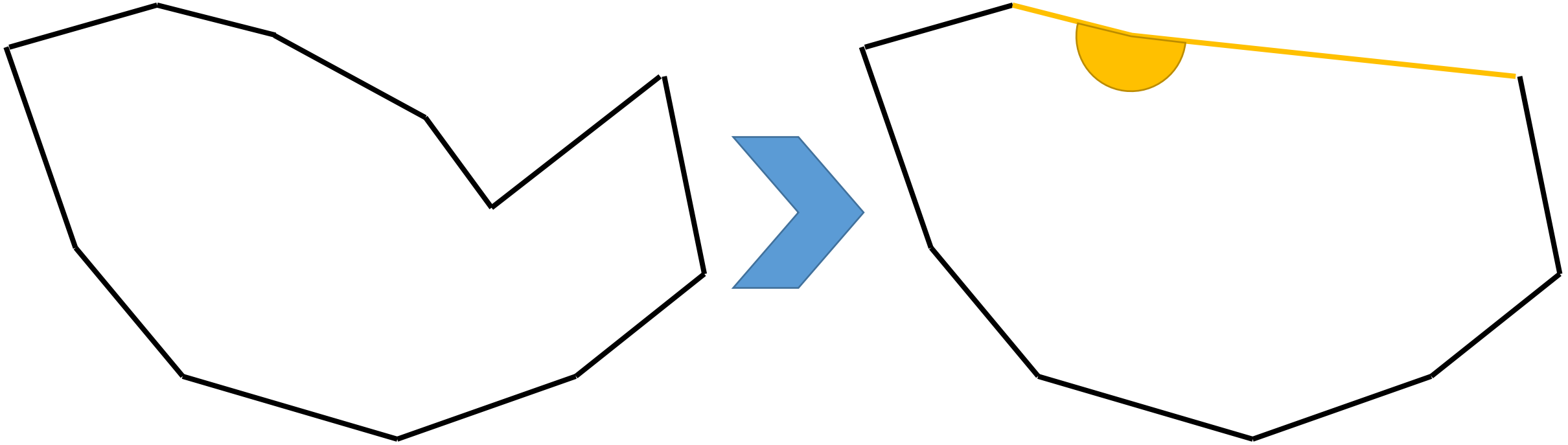
- By removing all concave corners of an object, we retrieve its **convex hull**.



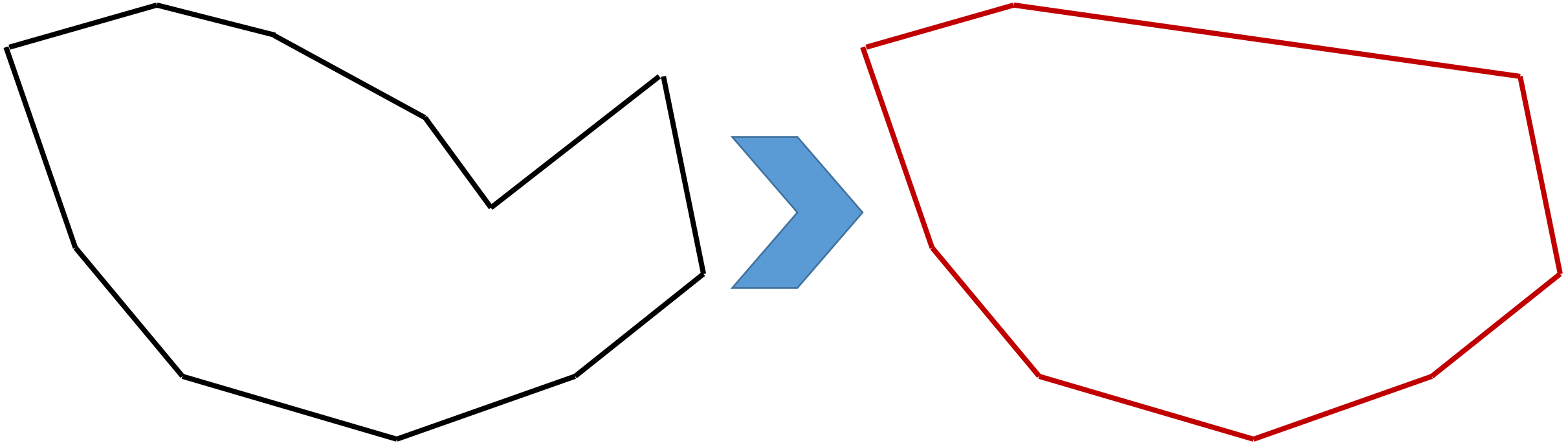
- By removing all concave corners of an object, we retrieve its **convex hull**.



- By removing all concave corners of an object, we retrieve its **convex hull**.

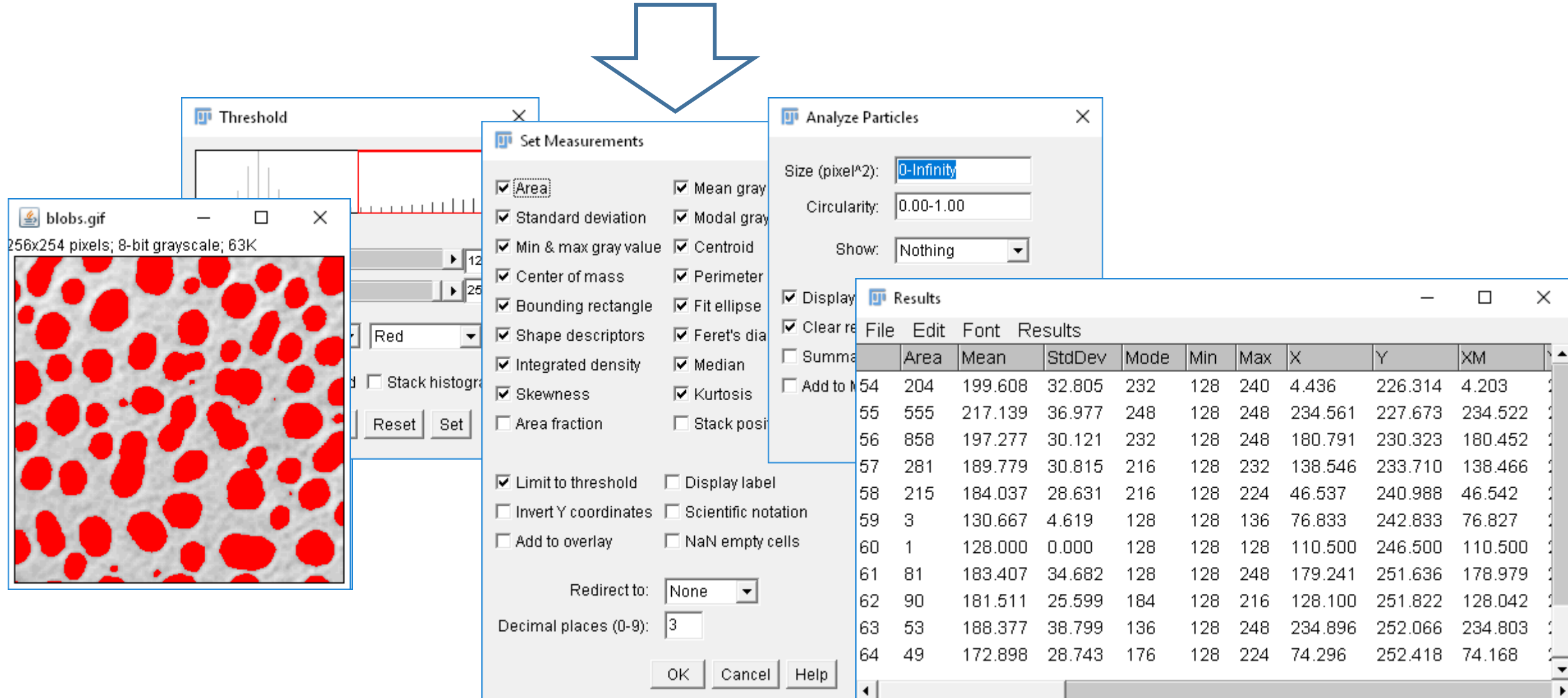


- By removing all concave corners of an object, we retrieve its **convex hull**.



$$solidity = \frac{A}{A_{convexHull}}$$

- Tell Fiji what to measure with *Analyze > Set Measurements*



The screenshot shows the Fiji software interface with several windows open. The 'blobs.gif' window displays a grayscale image of red particles. The 'Threshold' window shows a histogram and a threshold line. The 'Set Measurements' dialog box is open, showing various measurement options. The 'Analyze Particles' dialog box is also open, showing the Size (pixel²) and Circularity settings. The 'Results' window is visible in the background, displaying a table of measurement data.

Set Measurements Dialog Box:

- ☒ Area
- ☒ Standard deviation
- ☒ Min & max gray value
- ☒ Center of mass
- ☒ Bounding rectangle
- ☒ Shape descriptors
- ☒ Integrated density
- ☒ Skewness
- ☐ Area fraction
- ☒ Mean gray
- ☒ Modal gray
- ☒ Centroid
- ☒ Perimeter
- ☒ Fit ellipse
- ☒ Feret's dia
- ☒ Median
- ☒ Kurtosis
- ☐ Stack position
- ☒ Limit to threshold
- ☐ Invert Y coordinates
- ☐ Add to overlay
- ☐ Display label
- ☐ Scientific notation
- ☐ NaN empty cells

Redirect to:

Decimal places (0-9):

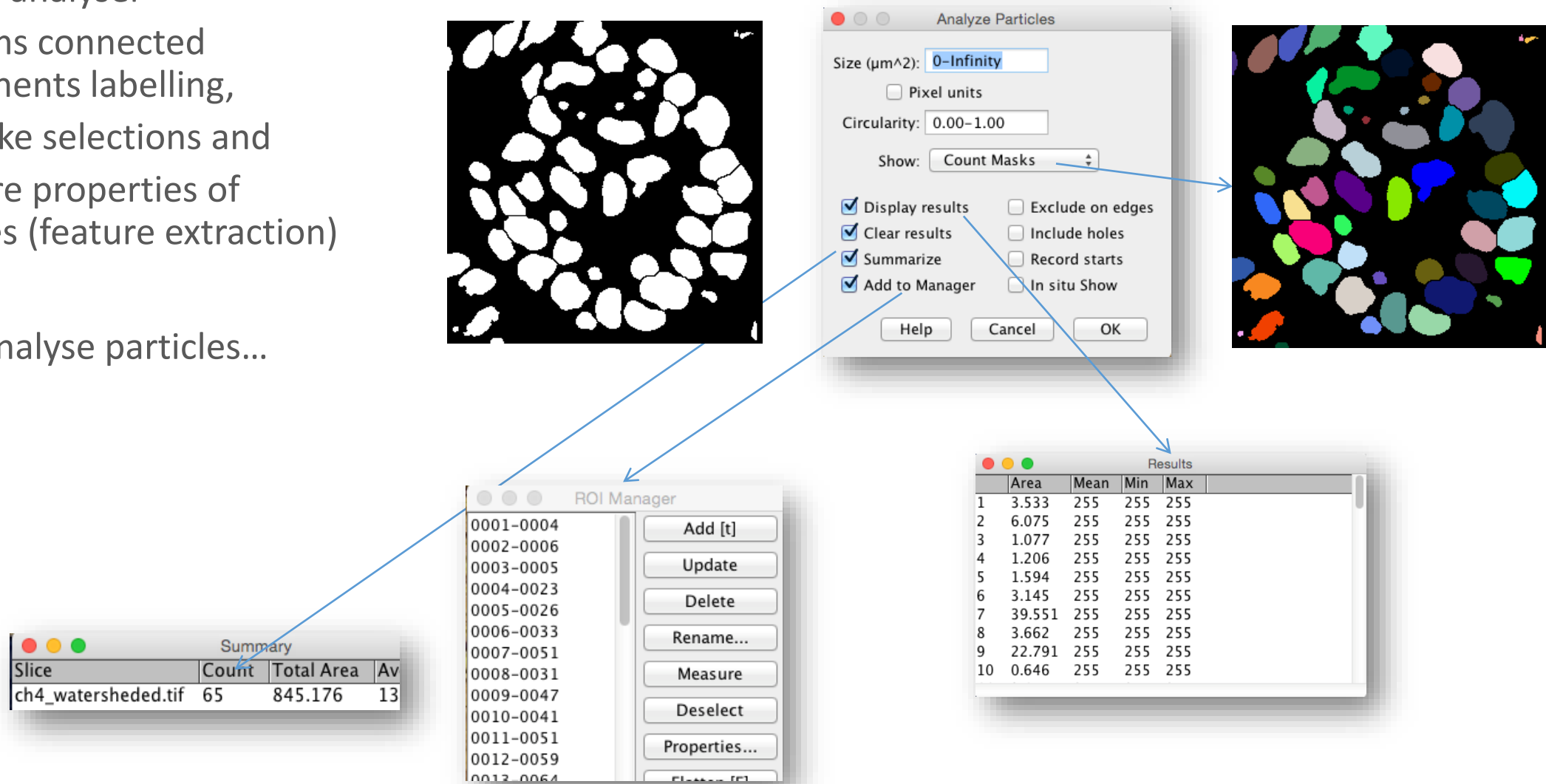
Analyze Particles Dialog Box:

- Size (pixel²):
- Circularity:
- Show:
- ☒ Display
- ☒ Clear results
- ☐ Summarize
- ☐ Add to Manager

Results Window:

File	Edit	Font	Results						
	Area	Mean	StdDev	Mode	Min	Max	X	Y	XM
54	204	199.608	32.805	232	128	240	4.436	226.314	4.203
55	555	217.139	36.977	248	128	248	234.561	227.673	234.522
56	858	197.277	30.121	232	128	248	180.791	230.323	180.452
57	281	189.779	30.815	216	128	232	138.546	233.710	138.466
58	215	184.037	28.631	216	128	224	46.537	240.988	46.542
59	3	130.667	4.619	128	128	136	76.833	242.833	76.827
60	1	128.000	0.000	128	128	128	110.500	246.500	110.500
61	81	183.407	34.682	128	128	248	179.241	251.636	178.979
62	90	181.511	25.599	184	128	216	128.100	251.822	128.042
63	53	188.377	38.799	136	128	248	234.896	252.066	234.803
64	49	172.898	28.743	176	128	224	74.296	252.418	74.168

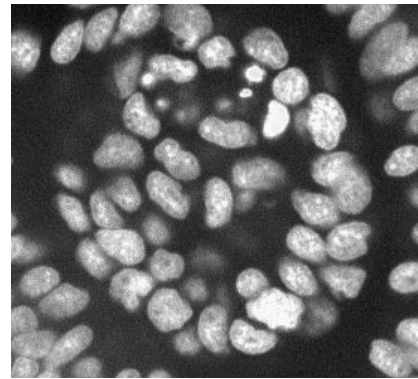
- The particle analyser
 - performs connected components labelling,
 - can make selections and
 - Measure properties of particles (feature extraction)
- Analyze > Analyse particles...



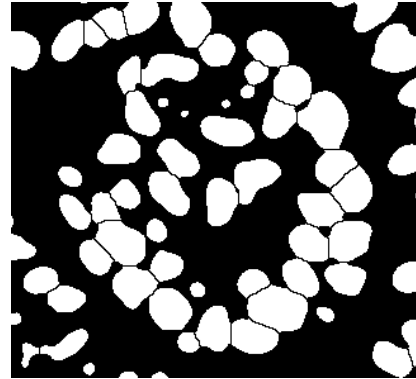
The workflow consists of the following steps and components:

- Analyze Particles Dialog:** Shows settings for Size (μm^2): 0-Infinity, Circularity: 0.00-1.00, and Show: Count Masks. Checkboxes for Display results, Clear results, Summarize, and Add to Manager are selected.
- Count Masks:** A visualization of the particles as white shapes on a black background.
- ROI Manager:** A list of regions of interest (ROIs) with labels like 0001-0004, 0002-0006, etc. Buttons for Add [t], Update, Delete, Rename..., Measure, Deselect, and Properties... are visible.
- Results Table:** A table with columns Area, Mean, Min, and Max, showing 10 rows of data.
- Summary Table:** A small table with columns Slice, Count, Total Area, and Av, showing data for ch4_watershed.tif.

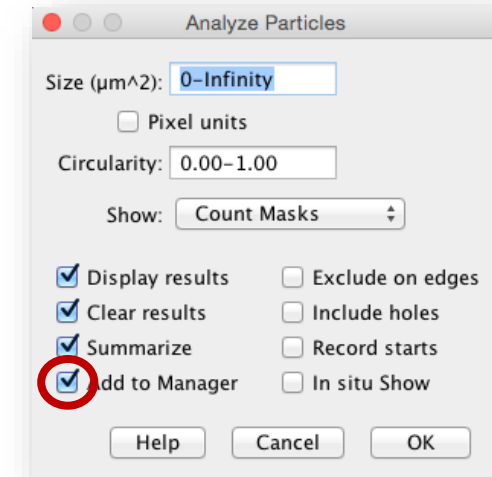
- Suggested workflow



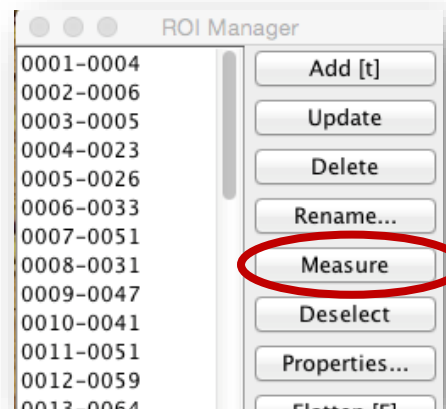
Threshold,
refine masks



Particle
analysis (CCA)

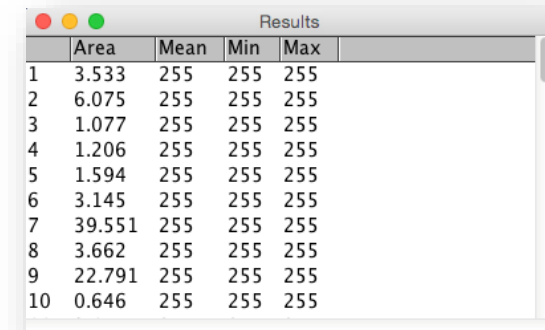


Select original
image



Measure

Add to
manager



	Area	Mean	Min	Max
1	3.533	255	255	255
2	6.075	255	255	255
3	1.077	255	255	255
4	1.206	255	255	255
5	1.594	255	255	255
6	3.145	255	255	255
7	39.551	255	255	255
8	3.662	255	255	255
9	22.791	255	255	255
10	0.646	255	255	255

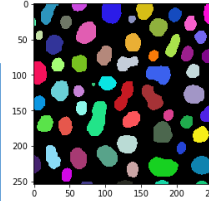
- **Regionprops** to collect measurements

```
from skimage import measure
```

```
# analyse objects
```

```
properties = measure.regionprops(label_image, intensity_image=image)
```

We start with a label image



- Reorganize in a dictionary of lists

```
statistics = {  
    'area': [p.area for p in properties],  
    'mean': [p.mean_intensity for p in properties],  
    'major_axis': [p.major_axis_length for p in properties]  
}
```

- Visualize as table, a.k.a. pandas **DataFrame**

```
import pandas as pd
```

```
dataframe = pd.DataFrame(statistics)
```

	area	mean	major_axis	aspect_ratio
0	429	191.440559	34.779230	2.088249
1	183	179.846995	20.950530	1.782168
2	658	205.604863	30.198484	1.067734
3	433	217.515012	24.508791	1.061942
4	472	213.033898	31.084766	1.579415
...
57	213	184.525822	18.753879	1.296143
58	79	184.810127	18.287489	3.173540
59	88	182.727273	21.673692	4.021193
60	52	189.538462	14.335104	2.839825
61	48	173.833333	16.925660	4.417297

- Save to disk

```
dataframe.to_csv("blobs_analysis.csv")
```

<https://pandas.pydata.org/>

Today, you learned

- GPU-acceleration
- Quantitative measurements

Coming up next:

- Introduction to Biostatistics with Anna Poetsch

