

*What **Cannot** Be Learned With Bounded Memory?*

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Limitations

Learning
Algorithm

Data

Space
Bounded



Learning with Bounded Space: Motivation

- Natural question - next step after time constraints
- We are in the middle of the big data era
- (Artificial) Neural Networks can be viewed as a bounded space algorithm
- Number of neurons in the nervous system is bounded

Plan

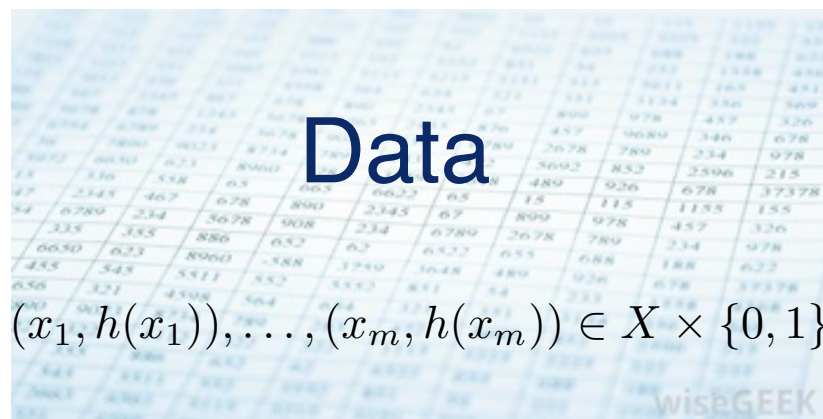
- Definitions
 - What is (PAC) learning?
 - What is online learning?
 - What is bounded memory learning?
- Problem Formulation
- Main Theorem and a Surprising Conclusion

Supervised Learning: Example



PAC Learning (Valiant, 1984)

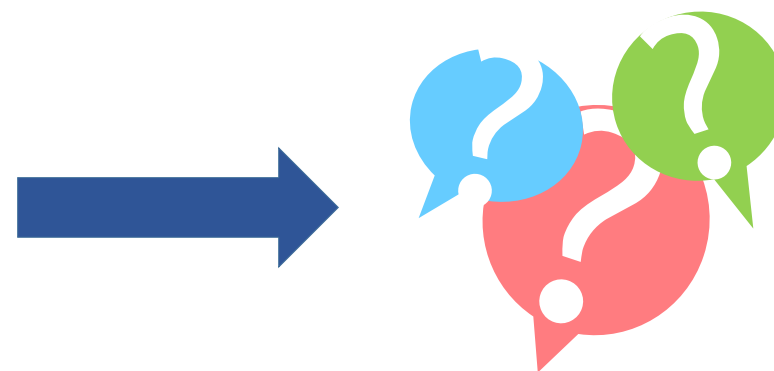
Hypothesis class $H=\{h:X\rightarrow\{0,1\}\}$ is PAC-learnable if there is a learner s.t. for any h , for any distribution over X , with probability > 0.99 , the learner will come up with an approximation h' with $P_x(h'(x)\neq h(x))<0.01$.



Hypothesis class
 $H=\{h:X\rightarrow\{0,1\}\}$

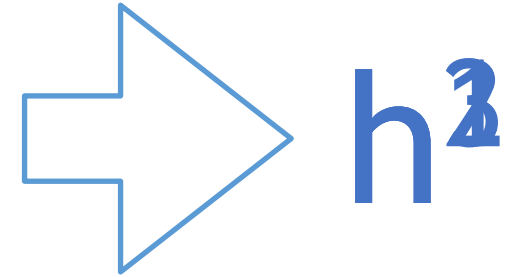
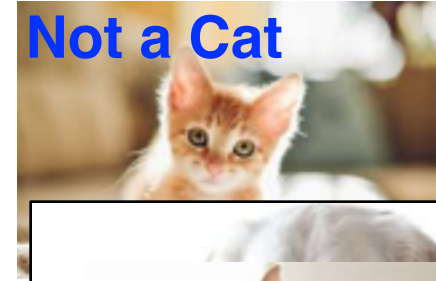


Learner



h' close to h

Online Learning: Example



The Online-Learning Framework

- For $t=1,2,\dots$
 - An example x^t is given
 - Learner predicts label y^t
 - True label y^t is revealed
- Goal: minimize number of mistakes

Online Learning with Bounded Memory: Example



learning with bounded memory is hard

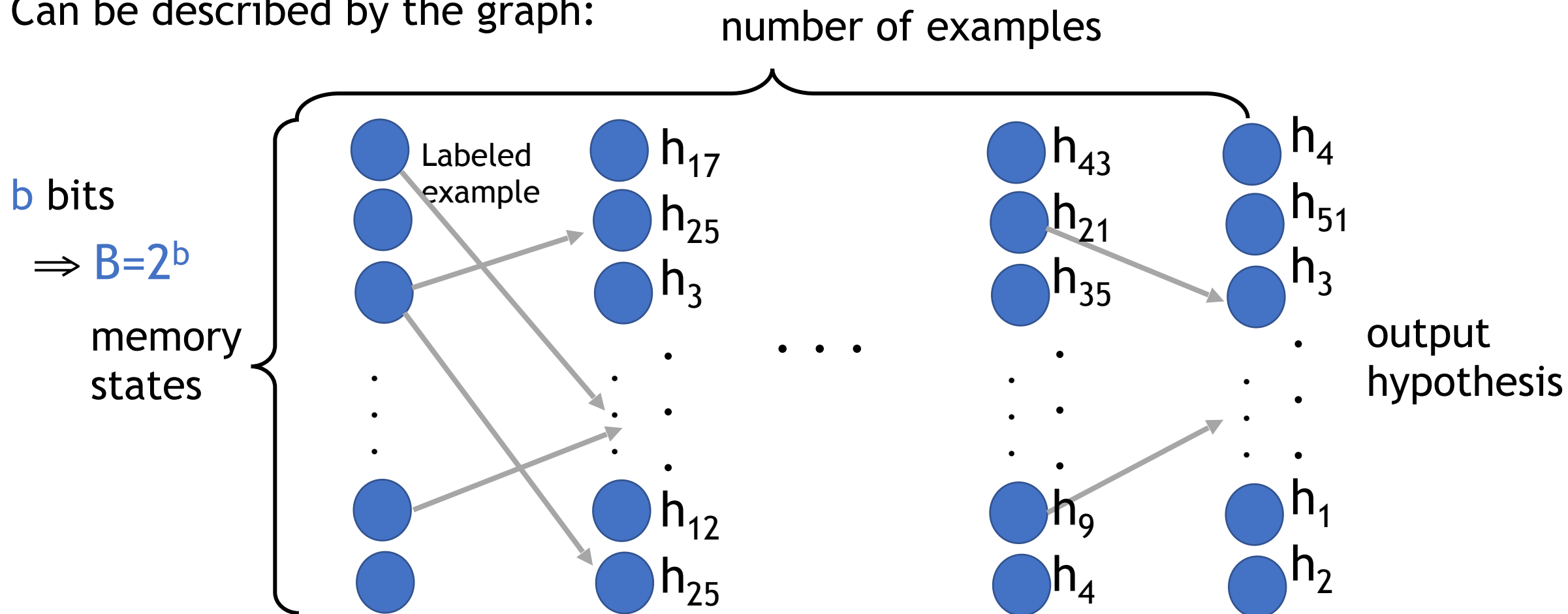


What Cannot be Learned with Bounded
Memory?

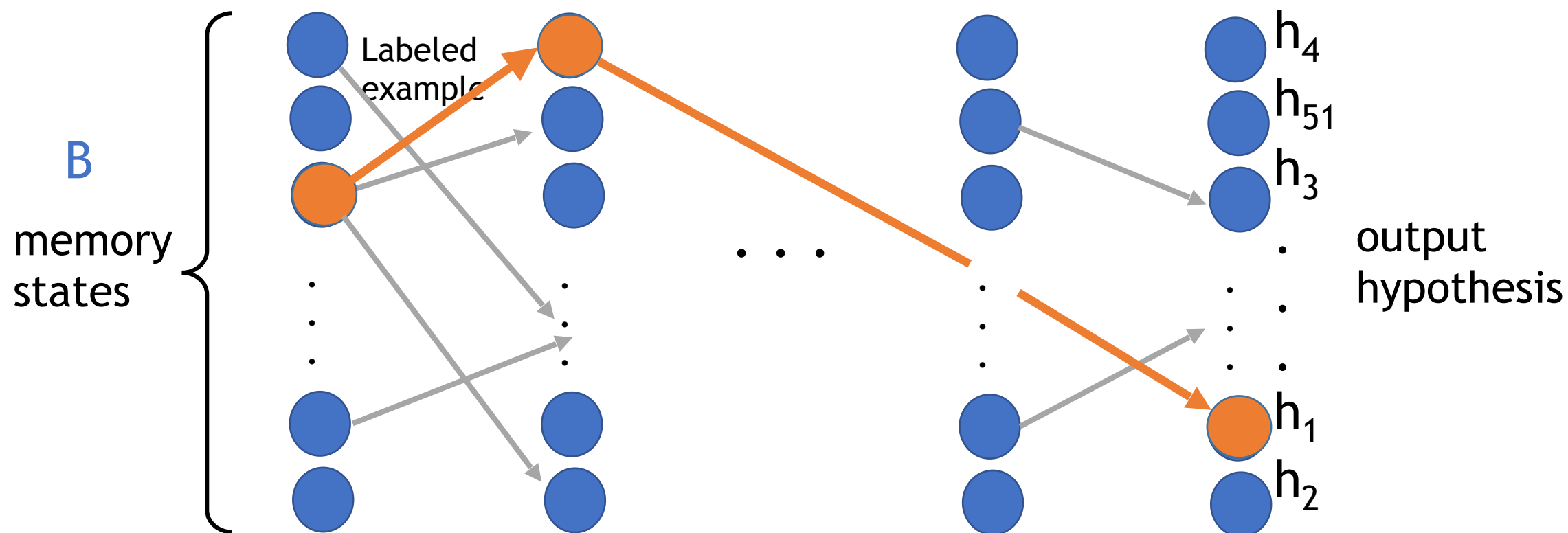
Learning with Bounded Memory

Fix an algorithm A .

Can be described by the graph:



Learning with Bounded Memory



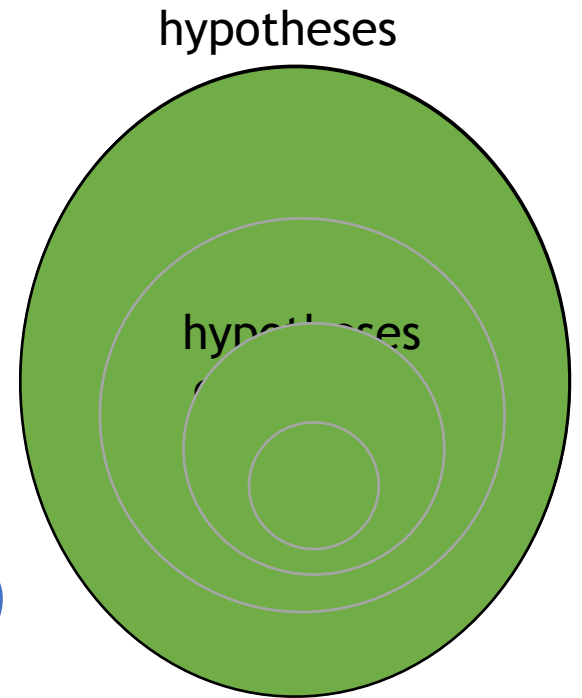
Unbounded Learner

Initially, all h in H are possible.

Repeat: Given example (x, b) , rule out h' where $h'(x) \neq b$.

Claim: With high probability, after seeing $O(\log |H|)$ random examples any h' not ruled out satisfies $P_z(h'(z) = h(z)) > 0.99$.

But this requires a lot of memory! Must store received examples in memory, which requires $\min\{\Theta(\log |H| \log |X|), |H|\}$ memory bits.



Bounded Learner

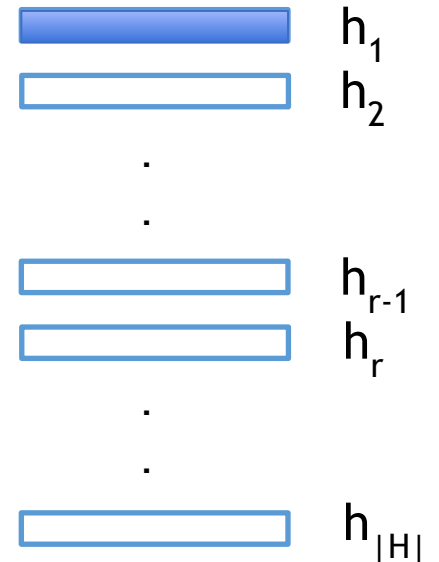


Initially, h' is the first function in H .

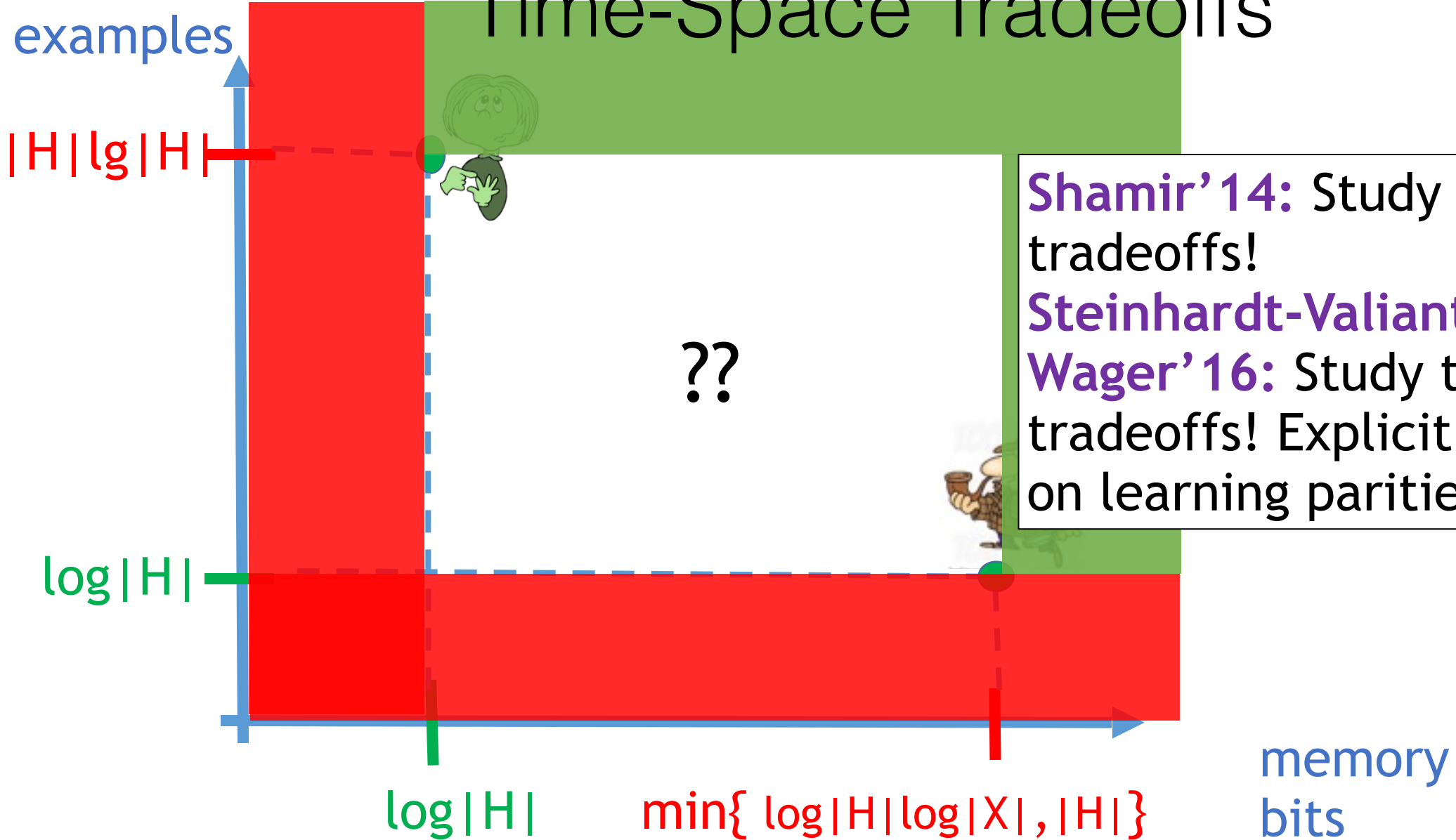
Repeat: Given example (x, b) , if $h'(x) \neq b$, then let h' be the next function in H .

Claim: With high probability, after seeing $O(|H| \log |H|)$ random examples, h' satisfies $P_z(h'(z) = h(z)) > 0.99$.

This requires only a minimal number of $\log |H|$ memory bits.



Time-Space Tradeoffs

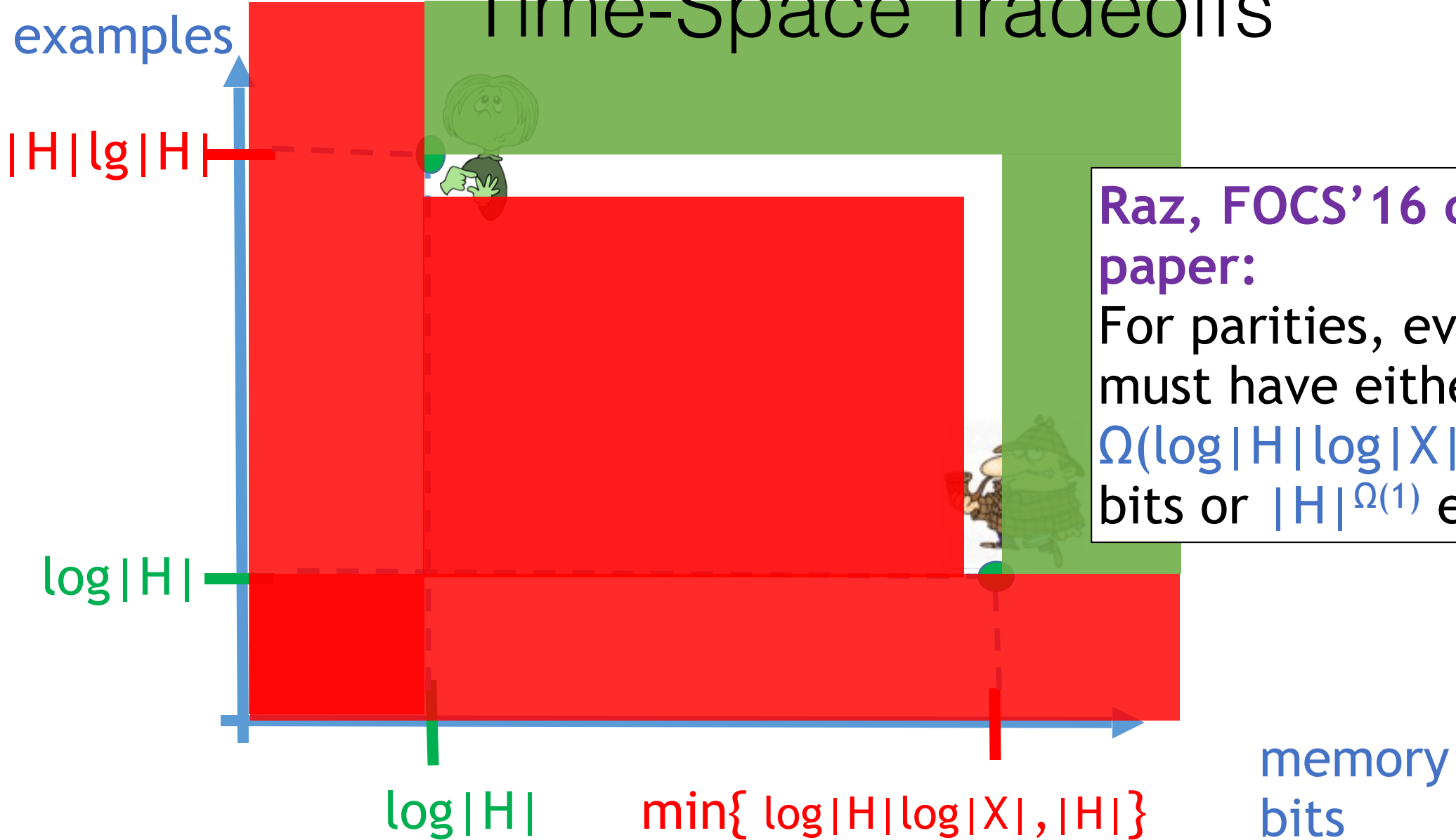


Shamir'14: Study time-space tradeoffs!

Steinhardt-Valiant-

Wager'16: Study time-space tradeoffs! Explicit conjecture on learning parities.

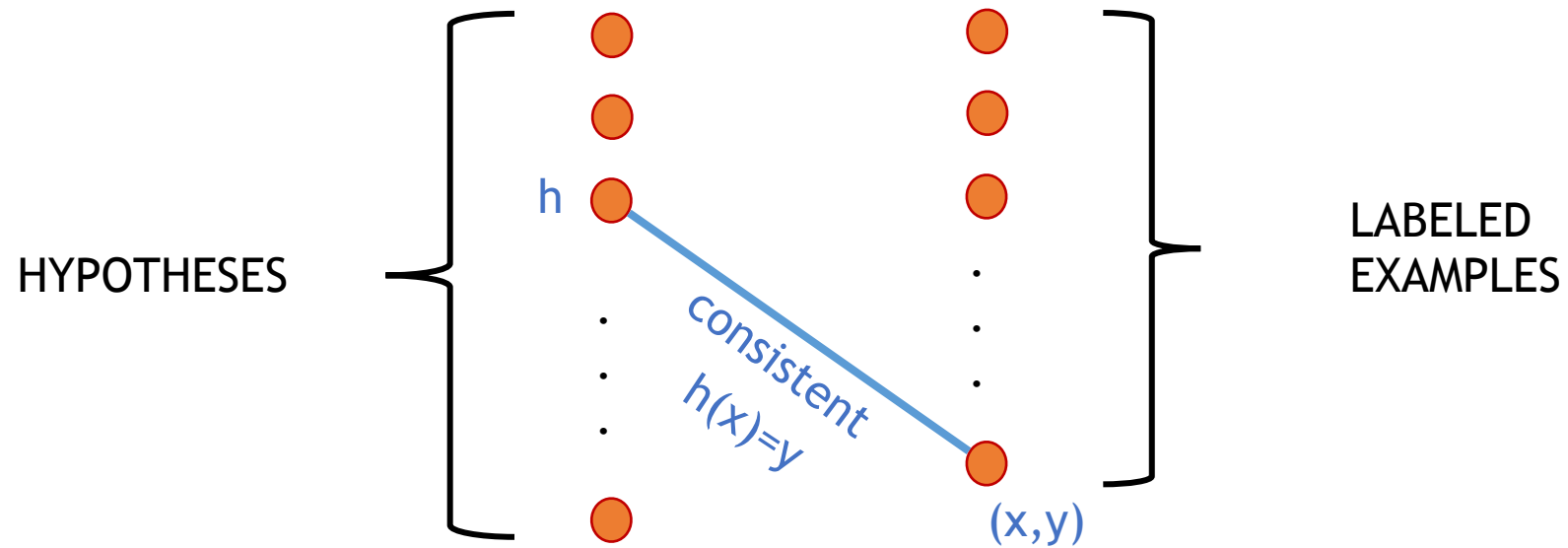
Time-Space Tradeoffs



Raz, FOCS'16 co-best paper:
For parities, every learner must have either $\Omega(\log |H| \log |X|)$ memory bits or $|H|^{\Omega(1)}$ examples.

How Can We Prove Lower Bounds For
General Hypotheses Classes?

Hypotheses Graph



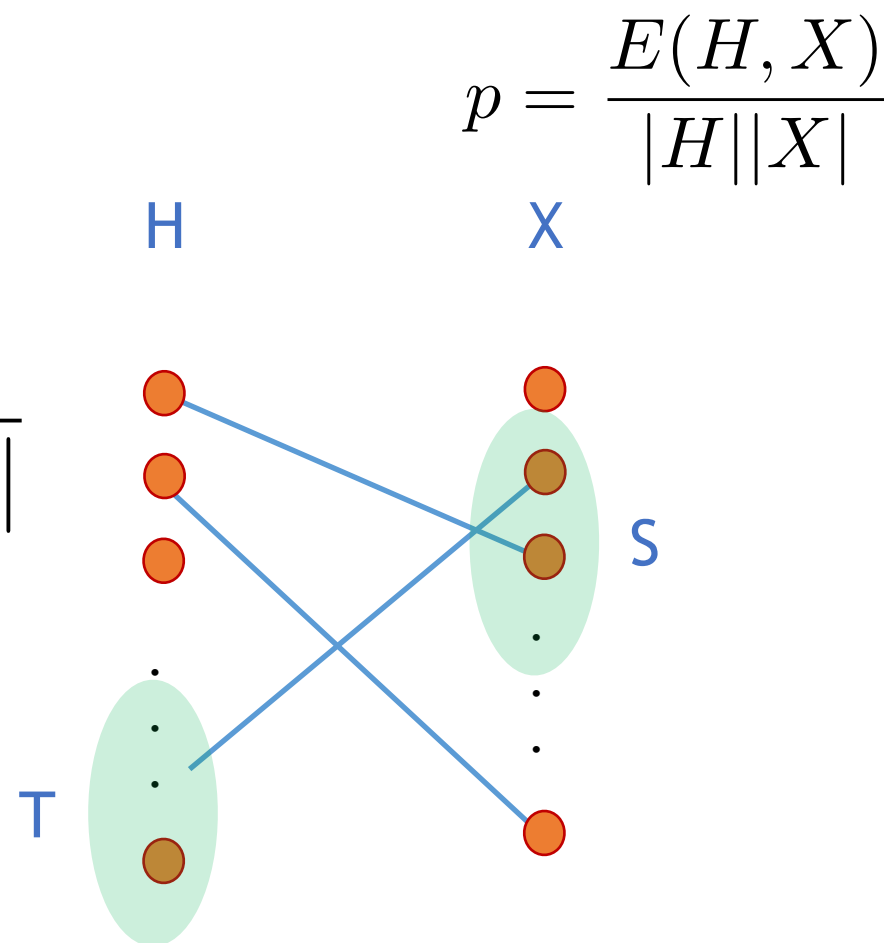
Mixing

D-Mixing: For every set S of hypotheses, every set T of labeled examples,

$$|E(S, T) - p|S||T|| \leq D\sqrt{|S||T|}$$

number of edges
between S and T

expected number of
edges between S
and T



Examples:

- Parities are $O(\sqrt{|X|})$ -mixing
- Almost surely $G(n, m, 0.5)$ is $O(\sqrt{n})$ -mixing (for $n > m$)

Our Theorem: From Mixing To Lower Bounds

Main Thm: If the hypotheses graph is $O(\sqrt{|X|})$ -mixing, then either $B = \Omega(\log^2 |H|)$ memory bits or $|H|^{\Omega(1)}$ examples are needed to learn.

- A pseudorandomness **sufficient condition** for unlearnability with bounded memory.
- A new combinatorial **framework** for proving lower bounds on space bounded learning.



Time-Space Tradeoffs

examples

$|H| \lg |H|$

$\log |H|$

$\log |H|$

$\min\{\log |H| \log |X|, |H|\}$

Moshkovitz-
Moshkovitz'17a+b;
Raz'17:

For most classes H ,
every learner must have
either $\Omega(\log^2 |H|)$
memory bits or $|H|^{\Omega(1)}$
examples.

memory
bits

The Low Certainty Framework

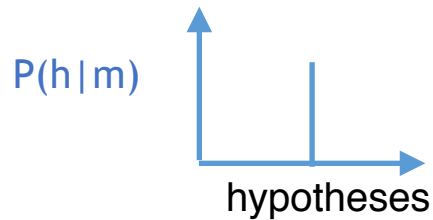
Certainty

We'll pick the underlying hypothesis at random.

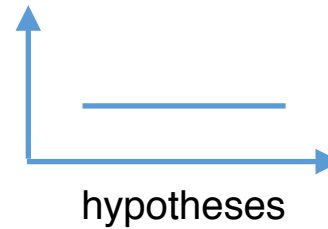
The *certainty* of a memory state m at time t :

- $P(h|m)$ - probability h correct given the algorithm in state m

high certainty:



low certainty:



- $\text{cer}^t(m) = \sum_h P(h|m)^2$.

The *average certainty* at time t is $\text{cer}^t = E_m[\text{cer}(m)]$.



Proof Outline

1. **Initially:** $\text{cer}^1 = O(1/|H|)$.
2. **Eventually:** Learning at time $T \Rightarrow \text{cer}^T \geq \Omega(1)$.
3. **We'll show:** For any learner with B memory states, for every time t , after removal of few hypotheses and examples of low total probability,
 $\text{cer}^{t+1} \leq (1 + 1/|H|^{\Theta(1)})\text{cer}^t$.

As a result: either B memory states or $|H|^{\Omega(1)}$ examples are needed.

The Intuition (The paper is 51 pages)

Given an example there are two things the learner can do:

(1) Heavy step:

- Remember only a little about the example. For mixing H , gain almost no information about h .

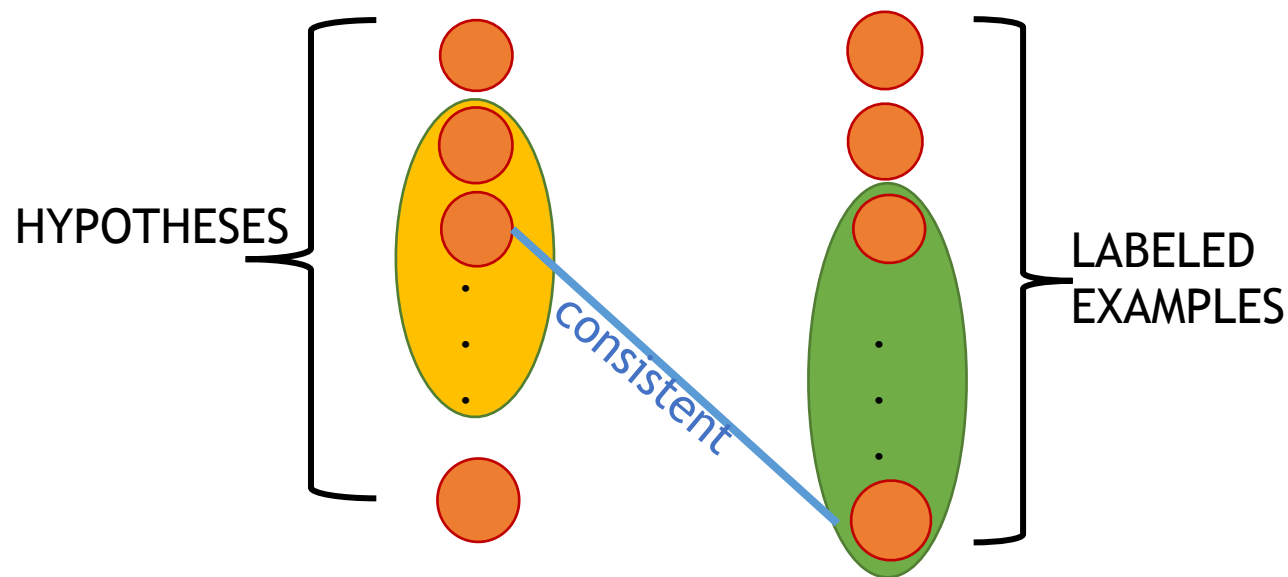
(2) Many Step:

- Remember the example in detail, but then have to erase previous memories.



Forget Some Lose All Principle

Fix a mixing hypotheses graph. Suppose that one picks uniformly at random a hypothesis h and an example x . Suppose that one stores a short string s about $(x, h(x))$. Then $h|s$ is close to uniform.



Surprising Conclusion

Most problems cannot be learned with bounded memory ...

Luckily, real-problems are not mixing
and can be learned with bounded memory

Thank you!