```
void trig_rept_task() {
  #if EBOARD_NANO == 0x0|
    | defined(DOC) if (_pwm
      Value!=_OpwmValue){ ana
        logWrite(PIN_MOTOR_SPE,
          _pwmValue);_OpwmValue =
            _pwmValue;}#endif #ifde
              f REPT_TASK  rept_task(
                );#endif} int timer_cou
                  nt = 0; bool timer_ofl=
                    false; ISR(TIMER2_OVF_v
                      ect) { timer_count++; i
                        f(timer_count >= EBOARD
                        _PWM_SPE*1000 && EBOARD
                      _PWM_SPE >? 0 && !timer
                    _ofl){ timer_ofl = true
                  ; timer_count -= EBOARD
                _PWM_SPE * 1000; trig_r
              ept_task(); timer_ofl =
            false; } TCNT2 =  256 -
          (int)((float)F_CPU * 0.
        001 / 64); } struct LCD
      {  #if EBOARD_NANO == 0                d=0x3C);#endif bool changeID(optVAL_t new
    LCD(SoccerBoard &soccer                ID = 0x3C); bool clear(void); void print(co
  Board, optVAL_t id=0x3C                  nst char* data); void print(int data); void
); #else LCD(optVAL_t i                     print(optVAL_t line, optVAL_t cols, const
```