```
void trig_rept_task() {
  #if EBOARD_NANO == OxO|
   | defined(DOC) if (_pwm
      Value!=_OpwmValue) { ana
        logWrite(PIN_MOTOR_SPE,
          _pwmValue);_OpwmValue =
            _pwmValue; } # endif # ifde
              f REPT_TASK rept_task(
                ); #endif } int timer_cou
                 nt = 0: bool timer ofl=
                    false; ISR(TIMER2_OVF_v
                      ect) { timer_count++; i
                        f(timer_count >= EBOARD
                        _PWM_SPE*1000 && EBOARD
                      _PWM_SPE >? 0 && !timer
                    _ofl){ timer_ofl = true
                  ; timer_count -= EBOARD
                _PWM_SPE * 1000; trig_r
              ept_task(); timer_ofl =
            (int)((float)F_CPU * 0.
        001 / 64); } struct LCD
      { #if EBOARD_NANO == 0
                                         d=0x3C); #endif bool changeID(optVAL_t new
   LCD (SoccerBoard & soccer
                                          ID = 0x3C); bool clear(void); void print(co
  Board, optVAL_t id=0x3C
                                          nst char* data); void print(int data); void
); #else LCD(optVAL_t i
                                           print(optVAL_t line, optVAL_t cols, const
```