```
void trig rept task() {
  #if EBOARD NANO == OxO|
   | defined(DOC) if ( pwm
      Value!=_OpwmValue) { ana
        logWrite(PIN MOTOR SPE,
          pwmValue); OpwmValue =
            pwmValue;}#endif #ifde
              f REPT TASK rept task(
                ); #endif} int timer cou
                  nt = 0; bool timer ofl=
                    false; ISR (TIMER2 OVF v
                      ect) { timer count++; i
                        f(timer count >= EBOARD
                        PWM SPE*1000 && EBOARD
                      PWM SPE >? 0 && !timer
                    _ofl) { timer_ofl = true
                  ; timer count -= EBOARD
                _PWM_SPE * 1000; trig_r
              ept task(); timer ofl =
            false: } TCNT2 = 256 -
          (int)((float)F CPU * 0.
        001 / 64); } struct LCD
      { #if EBOARD NANO == 0
                                          d=0x3C); #endif bool changeID(optVAL t new
    LCD (SoccerBoard & soccer
                                          ID = 0x3C); bool clear(void); void print(co
  Board, optVAL t id=0x3C
                                          nst char* data); void print(int data); void
); #else LCD(optVAL_t i
                                           print(optVAL_t line, optVAL_t cols, const
```