Distributed Tasking in Python with Legion

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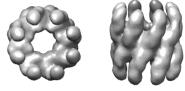


A Brave New World of Distributed Python Programming

MHz Science







Up to 1 MHz repetition rate
Up to 100 Gb/s data rate
Diverse, unique science
Experiment in the loop
Users are not HPC experts

Scalable Software

Unmodified Python code



import numpy, scipy, pandas



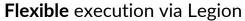
numpy.fft.fft(...)

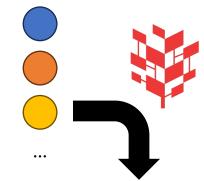


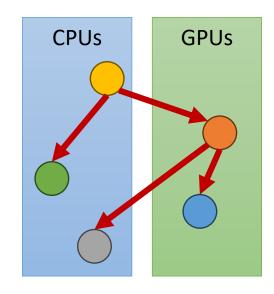
scipy.optimize.curve_fit(...)



pandas.DataFrame(...)







Diverse Hardware









Distributed Tasking in Python: It's Already Here

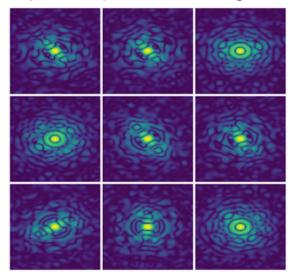
An (Incomplete) List of Python Tasking Frameworks for HPC

- Pygion (https://legion.stanford.edu/pygion/)
 - Legion programming model in Python
- cuPyNumeric / Legate (https://developer.nvidia.com/cupynumeric)
 - Write NumPy, run automatically on clusters of CPUs and GPUs
- FlexFlow (https://flexflow.ai/)
 - Drop-in PyTorch, Keras, ONNX interface with additional optimizations
- Charm4py (https://charm4py.readthedocs.io/)
 - Charm++ programming model in Python
- PyCOMPS (https://docs.idmod.org/projects/pycomps/)
 - Workflow orchestration in Python
- And others....

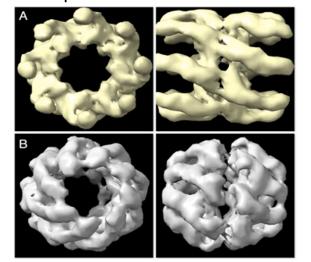


SpiniFEL: Single Particle Imaging for XFEL

Input: X-ray diffraction images



Output: 3D reconstruction of each protein conformation

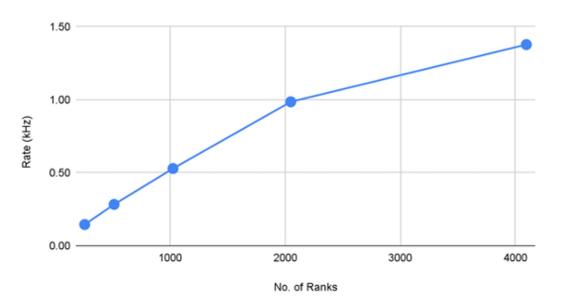


Design Principles

- Kitchen sink software design
 - If it exists, and it works, use it
 - NumPy, CuPy, Numba, hand-written
 CUDA, third-party CUDA libraries
- Pygion tasking as the orchestration layer

Lessons Learned

- Tasking layer was a non-issue
 - No production issues due to Pygion
- Kitchen sink approach caused porting issues



Weak scaling on up to 4096 GPUs on Frontier

[Mirchandaney et al.,

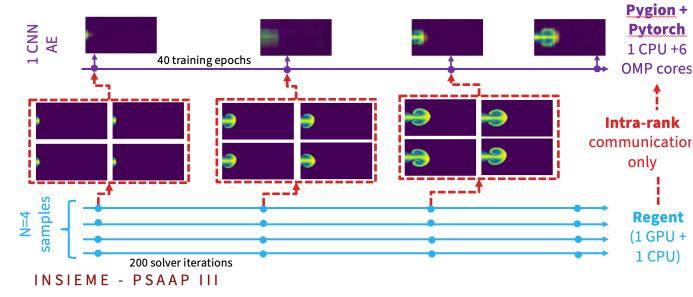
WAMTA 2024]

nHTR: Sidecar Python Analysis

Pygion as an Interface for Fast Scripting

- nHTR runs main simulation in high fidelity on GPU using Regent
- Simultaneously using PyTorch (via Pygion) for online training of ML models during the ensemble run on free CPU cores
 - Otherwise unused by the main application
 - Runs asynchronously without slowing down the main simulation
 - Can return results asynchronously to the main simulation to drive simulation parameters

Case Study: online PyTorch training in nHTR



[Laurent and Maeda, APS 2022]



Thoughts, Challenges, Provocations

- Distributed tasking systems for Python already exist
 - Maybe not marketed widely enough?
- Need to be better integrated across frameworks/libraries
 - Even when backed by the same runtime system
- Python's existing ecosystem doesn't necessarily lead to portability or distributed support
 - Easy to get "stuck" if you make the wrong bet
- Need better modular Python code analysis and code generation tools
 - Numba is overfitted to the problem it solves, code generation is not flexible enough

