W1 Graph-Based Path Planning

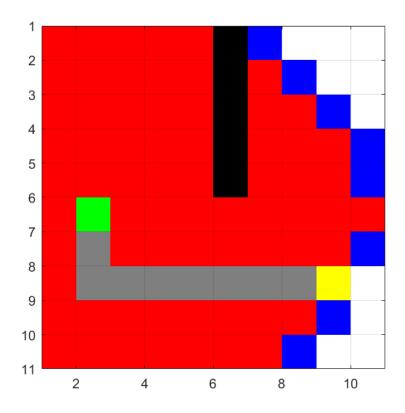
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```
clear;
clc;
```

Occupancy Grid Map

Dijkstra Algorithm

```
[dijRoute, dijNumExpanded] = DijkstraGrid(map, start_coords, dest_coords);
```



A* Algorithm

