
%%Ex 3 task 2b

```
A= [ 2 1 1 0;
     1 3 0 1];
c_t= [-3/2 -1 0 0];
b= [8;
     15];
x = linspace(0,10, 100);
y = linspace(0,10, 100);
[X,Y] = meshgrid(x, y);

Z = 3/2 * X + Y;
c1 = 2*X + Y;
c2 = 1*X + 3*Y;

x0= [0 0 8 15]';
[x, fval, iterates] = simplex(c_t',A,b,x0,'report');

[px,py]= gradient(Z);
figure(1);
hold on;
contour(X, Y, Z, 'Levelstep', 1)
contour(X, Y, c1, 'LevelList', 8)
contour(X, Y, c2, 'LevelList', 15)
stem(0,0);
stem(1.8, 4.4);
stem(4,0);
```

```
Iteration number: 1
Basic index set:      {3, 4}
Nonbasic index set:  {1, 2}
x_B =      [      8.0000,      15.0000]'
x_N =      [      0.0000,      0.0000]'
lambda = [      0.0000,      0.0000]'
s_N =      [     -1.5000,     -1.0000]'
x =      [      0.0000,      0.0000,      8.0000,      15.0000]'
c'x =      0.00000000
x_1 will enter the basis (q = 1)
d =      [      2.0000,      1.0000]'
x_q+ = x_1+ =      4.0000 (value of entering variable/step length)
x_3 will leave the basis (p = 1)
x_B+ =      [      0.0000,      11.0000]' (Current basic vector at new
point)
x_N+ =      [      4.0000,      0.0000]' (Current nonbasic vector at new
point)
```

```
Iteration number: 2
Basic index set:      {1, 4}
```

```

Nonbasic index set: {3, 2}
x_B = [ 4.0000, 11.0000]'
x_N = [ 0.0000, 0.0000]'
lambda = [ -0.7500, 0.0000]'
s_N = [ 0.7500, -0.2500]'
x = [ 4.0000, 0.0000, 0.0000, 11.0000]'
c'x = -6.00000000
x_2 will enter the basis (q = 2)
d = [ 0.5000, 2.5000]'
x_q+ = x_2+ = 4.4000 (value of entering variable/step length)
x_4 will leave the basis (p = 2)
x_B+ = [ 1.8000, 0.0000]' (Current basic vector at new
point)
x_N+ = [ 0.0000, 4.4000]' (Current nonbasic vector at new
point)

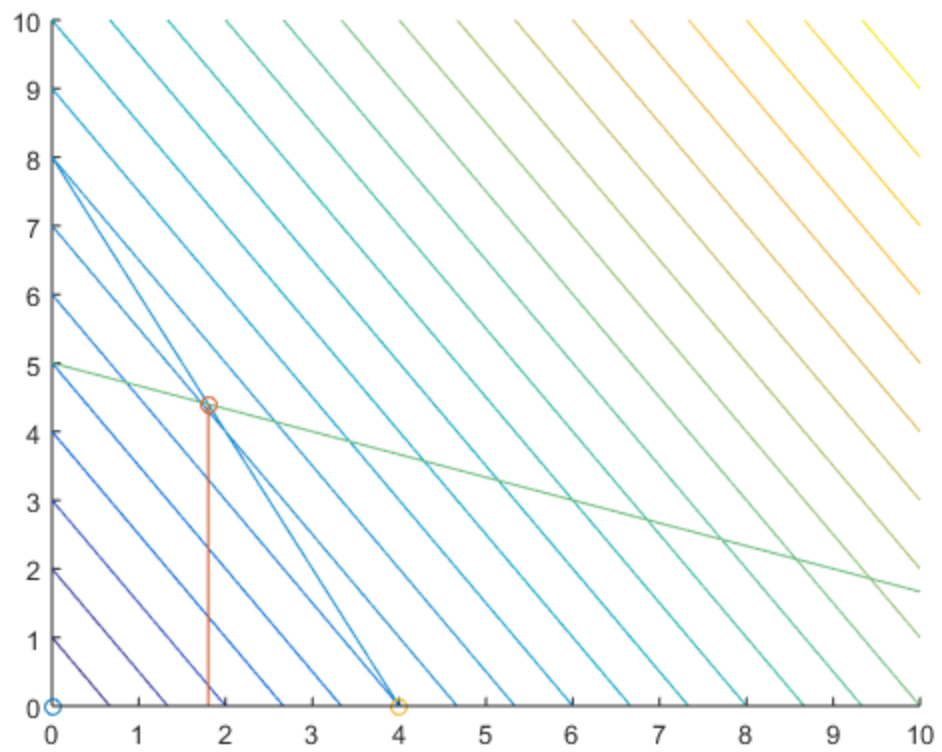
```

```

Iteration number: 3
Basic index set: {1, 2}
Nonbasic index set: {3, 4}
x_B = [ 1.8000, 4.4000]'
x_N = [ 0.0000, 0.0000]'
lambda = [ -0.7000, -0.1000]'
s_N = [ 0.7000, 0.1000]'

OPTIMAL POINT FOUND
x^* = [ 1.8000, 4.4000, 0.0000, 0.0000]'
c'x^* = -7.10000000

```



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