

# 1 Experimental Methods and Signal Processing (CEE 5984)

## 2 FINAL PROJECT PROPOSAL – MUSICAL INSTRUMENT TUNING APP

3 V0.1: 2018-11-10

4 Martin Scavone

### 5 Background and project problem statement

6 Chord musical instruments rely on a set of tense strings to produce sound. When put to vibrate by the  
7 player, these will emit sound at certain predefined frequencies – those of the musical notes. However, in a  
8 similar manner to any material subject to constant tension over a long period of time, the instrument's  
9 strings will tend to creep, releasing themselves of such tensile stress (stretching themselves) and so they  
10 would lose their tuning to the note they were meant to vibrate at (Lynch-Aird and Woodhouse, 2017). That  
11 is why such instruments must be periodically checked and tuned before playing, and even the reason  
12 why automatic tuning devices exist.

13 The task of tuning consists of applying or releasing tension to the instrument's strings so that, when  
14 operated by the player, they will produce sound at the frequency of certain musical notes. A variety of  
15 professional-level tuning aids are available for musicians – even smartphone applications that use the  
16 phone's built-in microphone to listen to a musical instrument and evaluate whether the instrument is  
17 tuned or not<sup>1</sup>.

18 Voice range for human singers, however, cannot be tuned, but the classification of voices is similarly  
19 frequency-based<sup>2</sup> - a lyric singer must be able to cover a predefined frequency range with their voice to be  
20 entitled to any voice range. Nevertheless, both tuning a chord instrument and recognizing a singer's voice  
21 range involve analyzing the frequencies at which both subjects' sounds are emitted – a task that can be  
22 performed with the aid of a computer.

23 On that grounds, this document will present the work plan towards the implementation of a Matlab-  
24 based musical instrument and voice range recognition app, to be run on any personal computer. Besides,  
25 an ancillary experiment will be conducted to test how microphones with different frequency ranges  
26 would perform when put to listen to sounds on the fringe and out of such ranges.

### 27 Project proposal.

28 This project will consist of two main experiments – namely *Experiment 01*, the development of the  
29 musical instrument tuner app, and *Experiment 02*, the comparison of the signals produced by different  
30 microphones after a sound on the verge or off their declared frequency range. This chapter is divided into  
31 three subsections: firstly, the statements that will be assumed true throughout the development of the  
32 project will be pointed out. This 'assumptions' section will be followed by the two experiments' objective  
33 statement, and finally, discussion will be brought on the applicability of these experiments' outcome.

### 34 Assumptions

35 The development of the musical instrument tuner will rely on the following axioms. These have been  
36 written referring to musical instruments, but they also will be assumed true for the human voice:

1 <sup>1</sup> An example of such an app is "Guitar Tuna", both available for Android, Windows, and iOS mobile phones

2 <sup>2</sup> Refer to the following archived music-school course entry for definitions on the most widespread male and female voice  
3 categories: <https://web.archive.org/web/20080605192215/http://pioneer2.aaps.k12.mi.us:80/choir/voiceclass.html>

- 1) The sound signals produced by both a subject instrument<sup>3</sup> can be processed by frequency analysis and will have peaks at certain frequencies, namely its fundamental frequency and its harmonics.
- 2) The fundamental frequency of the sensed sound (i.e. lowest frequency value at which an outstanding peak in magnitude is observed) is that of its matching musical note; whereas all the harmonics will define the instrument's timbre.
- 3) The sounds of the subject instruments will not contain sub-harmonics. In other words, no outstanding peaks will be expected at frequencies lower than the fundamental frequency. This assumption is based on what stated in the work by Berg and Stork (2005), where it is implied that very few instruments actually have sub-harmonics (the only example of such an instrument provided therein is a percussion instrument, and these will be disregarded in the proposed implementation for Experiment 01)
- 4) All the instruments will be tuned to the equally-tempered scale with the A<sub>4</sub> set at 440.00Hz. The equally-tempered scale features a fixed value to increase the frequency of any given note and its successor. In other words, the ratio of the frequencies of the two notes that define a semitone is constant – an equal to  $^{12}\sqrt{2}$ . This scale has been selected since it is the most widespread tuning scale (Hartmann, 2013) However, that is not the case of pianos, which are purposefully tuned with an offset from the equally-tempered scale – each note's offset from the scale is given by the Rainsback curve (Fletcher and Rossling, 1991). The inclusion of the Rainsback curve in the tuner's programming can nevertheless be achieved with ease.

### **Experiment 01 – Development of a Matlab-based musical instrument tuning app**

The goal of this Experiment 01 is to implement a Matlab-based application for tuning string instruments. Tuning will be based on real-time frequency analysis of incoming sounds; the player must play the instrument in the manner needed for tuning while the app is running so that the instrument's sounds could be recorded and processed. The app will report the player whether the note he or she is playing with the subject instrument matches a tuning note or not.

The proposed tuning application will also be able to compute the frequency range of any person's voice, by sampling their lowest and highest singing frequencies. Further details on how the frequency analysis of the input signals will be conducted are provided in the *Materials and Methods* chapter.

The instrument tuning application will be programmed in Matlab yet full compatibility with GNU-Octave will be sought.

### **Experiment 02 – Assessment of different microphones for musical instrument tuning purposes.**

Not all microphones for PCs operate in the entire range of human hearing (20-20,000 Hz). In fact, there are commercially available microphones which operate in the 100-16,000Hz frequency band – designed for voice recording only and intended for Voice-over-IP [VoIP] applications. An end-user may wish to try the final product of Experiment 01 using a non-full-range microphone to tune any instrument, yet no accurate tuning could be guaranteed when the attempt is made of tuning notes beyond the microphone's frequency range.

---

<sup>3</sup>The term "subject instrument" will refer to the musical instrument that whose sounds are to be analyzed by the tuner

1 On such grounds, experiment 02 will consist of recording the sounds produced by a properly-tuned bass  
2 guitar when playing its tuning notes with full-range and wideband microphones and comparing the  
3 signals retrieved in terms of frequency content and attenuation.

#### 4 **Applicability**

5 For the sake of this Project, the instrument tuning app will be developed to assist in the tuning of guitars,  
6 violins, bass guitars [4-string and 5-string], and pianos<sup>4</sup>. However, its analysis capabilities can easily be  
7 extended to other instruments -provided the notes these are tuned against are known – or even human  
8 voices: by performing frequency analysis on a person’s voice, the application may solve the singer’s vocal  
9 range.

## 10 **Materials and Methods**

### 11 **Microphones**

12 As it has been mentioned in previous paragraphs, Experiment 02 will consist of comparing how  
13 responsive different microphones are to the tuning notes of certain instruments – most particularly the  
14 lower tuning notes in guitars and bass guitars, whose frequencies are below 100Hz. The following  
15 microphones will be used to record the sounds of a tuned bass guitar while playing its tuning notes:

- 16 1. Laptop’s built-in omnidirectional microphone array. (Specifications not available)
- 17 2. Typical wide-band plug-in microphone for VoIP applications. Frequency range 100-16000Hz.  
18 Sensitivity 60dB.
- 19 3. Full-bandwidth plug-in PC microphone. Frequency range 20-20000 Hz. Sensitivity 58dB.
- 20 4. Professional-level condenser microphone. Frequency range 20-20000Hz. Sensitivity 37dB

21 Aside from that, microphones 1 and 3 from the above list will be used throughout the beta-testing of the  
22 musical instrument tuning app (Experiment 01).

### 23 **Computer software**

24 Experiment 02 is not by any means overly demanding in terms of computing requirements – Matlab’s  
25 built-in audio recording and frequency analysis functions are the most sophisticated software  
26 requirements for this experiment.

27 That, nonetheless, is not the case for Experiment 01, in which the programming of the instrument tuner  
28 -which will also rely on Matlab’s built-in commands to operate- is the core challenge. That is the reason  
29 why this chapter will mostly deal with Experiment 01’s software requirements. For the sake of simplicity,  
30 however, the sampling time, length and frequency resolution constraints that may be set for Experiment  
31 01 will also be kept for Experiment 02.

### 32 **Frequency range, frequency resolution, and time of sampling**

33 Each of the compatible instruments has predefined tuning frequencies (see Table 1 for the case of guitars,  
34 4 and 5-string bass guitars, and violins, and Table 2 for the frequency ranges defining each male and  
35 female voice category). Such would be the frequency range of each tuning process. In other words, that

---

<sup>4</sup>One of the project’s key assumptions must be highlighted once again here: the musical instrument tuning app will assume that all instruments are tuned to an equally-tempered scale, whereas in fact the lower and higher octaves in pianos are “stretched” beyond the target frequency values of the equally-tempered scale (as pointed out for instance in Fletcher and Rossling (1991)).

- 1 would be the frequency range to be adopted each time the instrument tuner is called to tune one of such
- 2 instruments.

Table 1: Frequencies of tuning notes of selected musical instruments

	ID	Freq [Hz]	Note Id
Guitar	1	82.41	E2
	2	110	A2
	3	146.83	D3
	4	196	G3
	5	246.94	B3
	6	329.63	E4
Violin	1	196	G3
	2	293.66	D4
	3	440	A4
	4	659.26	E5
4-string Bass guitar	1	41.204	E1
	2	55	A1
	3	73.416	E2
	4	97.999	G2
5-string Bass guitar	1	30.868	B0
	2	41.204	E1
	3	55	A1
	4	73.416	E2
	5	97.999	G2

Table 2: Frequency limits for male and female voice ranges

	Freq. Low	Freq. High	Note low	Note high	Range
Male adult voices	82.41	329.63	E2	E4	Bass
	110	440	A2	A4	Baritone
	130.81	523.25	C3	C5	Tenor
	164.81	659.25	E3	E5	Countertenor
Female adult voices	174.61	698.46	F3	F5	contralto
	220	880	A3	A5	Mezzo-soprano
	261.63	1046.5	C4	C6	soprano

3

4 All in all, the most demanding case scenario is the tuning of a piano, in which sounds with a frequency  
5 ranging between 27.50Hz and 4186.01Hz (disregarding the additional offset plotted in the Railsback  
6 curve) will be produced. This maximum expected frequency constrains the tuner's sampling frequency ( $f_s$ )  
7 must at the very least be twice larger than 4186Hz. So, a  $f_s$  of **16 kHz** will be used on every execution of  
8 Experiment 01.

9 Concerns about frequency range notwithstanding, the most crucial parameter to proper recognition of  
10 musical notes is the tuner's frequency resolution. In an attempt to resemble the most an experienced  
11 musician tuning a musical instrument, Experiment 01's tuner will aim at a frequency resolution ( $\delta f$ ) of  
12  $1/230$  of an octave – the frequency resolution of the human ear (Rebillard and Pujol, 2016). In terms of  
13 semitones (interval between two consecutive notes),  **$\delta f$  equals 5 cents** ( $5/100$  of the difference in  
14 frequency of two consecutive notes). In the equally-tempered scale, the “size” of a semitone depends on  
15 the frequency of the two defining notes, and the smallest  $\delta f$  would be required when tuning the deepest

1 note of pianos and five-string bass guitars (27.5 and 30.87 Hz respectively; leading to a **target  $\delta f$  of 1.72**  
2 **and 1.53 Hz**).

3 A frequency resolution target in signal processing is only achieved by manipulating the length of the  
4 input signal in the time domain (Figliola and Beasley, 2015). That being said, the target  $\delta f$  would require a  
5 **sample time of 0.58 / 0.65 seconds**, in which the instrument's sound must be clearly noticeable. The  
6 implementation of Experiment 01 tuner will take samples at **0.7-second** intervals.

### 7 **Fundamental frequency recognition and feedback to end-user**

8 Experiment 01's tuner will conduct a fast Fourier transform of samples of the digitalized sound signals  
9 covering segments 0.7 seconds long. The note being played by the instrument (or in the case of voice  
10 recognition, the note at which the subject is singing) will be identified by the software as the smallest  
11 frequency value which produces a peak in the signal amplitude versus frequency plot. The tuner's peak  
12 recognition software will distinguish actual peaks in the frequency domain plot from peaks due to  
13 background noise or lesser frequency components by relying on the signal's mean and standard  
14 deviation, and the amplitude difference between the potential peak and the signal's mean amplitude.

15 Once the played note is identified by the tuning software, it will print this result on screen, along with the  
16 closest target tuning note and an indication of whether to tighten or release tension on the instrument's  
17 strings to achieve the target note.

## 18 **References**

- 19 • Berg, R. E., Stork, D. G. (2005): "The Physics of Sound". Third Edition. Pearson. ISBN: 013-145789-6
- 20 • Hartmann, W. M. (2013): "Principles of Musical Acoustics". Springer. ISBN: 978-1-4614-6786-1
- 21 • Fletcher, N. H., Rossling, T. D. (1991): "The Physics of Musical Instruments". Springer-Verlag. ISBN:  
22 978-0-387-94151-6
- 23 • Figliola, R. S., Beasley, D. E (2015): "Theory and Design for Mechanical Measurements". Sixth  
24 Edition. Wiley. ISBN 978-1-118-88127-9
- 25 • Rebillard, G.; Pujol, R. (2016): "The Transfer OF Airborne Sound Vibration to the Structures and  
26 Fluid of the Cochlea". Web article, available at <http://www.cochlea.eu/en/cochlea/function>. Last  
27 accessed 2018-11-07.
- 28 • Lynch-Aird, N.; Woodhouse, J (2017): "Mechanical Properties of Nylon Harp Strings". Materials,  
29 2017, 10, 497. Pp. 1-32

30