



Machine Learning: Yoshinari Fujinuma University of Colorado Boulder

Slides adapted from Jordan Boyd-Graber, Chris Ketelsen

## Logistics

- Homework 3 is due today
- Homework 4 is available
- Project proposal is due on Friday

## Overview

Kernels

Examples

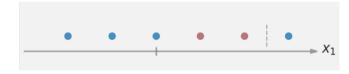
## **Outline**

Kernels

Examples

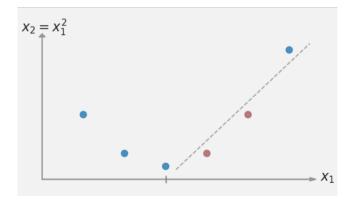
## Can you solve this with linear separator?

What can we do if the data is clearly not linearly separable?



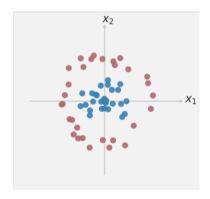
# Can you solve this with linear separator?

## Add a dimension.



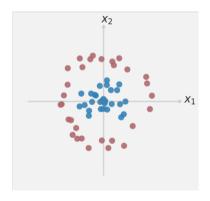
## What about this?

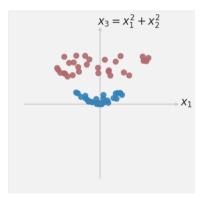
Definitely not separable in two dimensions.



#### What about this?

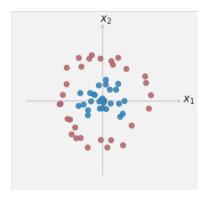
Definitely not separable in two dimensions. But in three dimensions, it becomes easily separable.

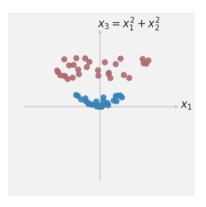




#### **Derived features**

We started with the original feature vector,  $\mathbf{x} = (x_1, x_2)$ , and we created a new derived feature vector,  $\phi(\mathbf{x}) = (x_1, x_2, x_1^2 + x_2^2)$ .





### What's special about SVMs?

$$\max_{\alpha} \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{i=1}^{m} \alpha_i \alpha_j y_i y_j (\boldsymbol{x_i}^T \boldsymbol{x_j})$$

### What's special about SVMs?

$$\max_{\alpha} \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{i=1}^{m} \alpha_i \alpha_j y_i y_j (\mathbf{x_i}^T \mathbf{x_j})$$

- This dot product is basically just how much  $x_i$  looks like  $x_j$ . Can we generalize that?
- Kernels!

## What's special about SVMs?

# Soft-margin SVM

$$\max_{\alpha} \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{i=1}^{m} \alpha_i \alpha_j y_i y_j (\mathbf{x_i}^T \mathbf{x_j})$$

Soft-margin SVM with feature mapping 
$$\phi$$
 
$$\max_{\alpha} \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{i=1}^{m} \alpha_i \alpha_j y_i y_j (\phi(\mathbf{x_i})^T \phi(\mathbf{x_j}))$$

Soft-margin SVM with a kernel K

$$\max_{\alpha} \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{i=1}^{m} \alpha_i \alpha_j y_i y_j K(\mathbf{x}_i, \mathbf{x}_j)$$

Kernel is a generalization of dot product

- Dot product tells us about the similarity of the two vectors
- Kernel can be viewed as a similarity measure but with non-linear combination of features

$$K(\mathbf{x}, \mathbf{x}') = \phi(\mathbf{x})^T \phi(\mathbf{x}')$$

So why do we want kernels instead of just defining a projection  $\phi$ ?

Assume d-dimensional feature vectors x and z Example of a kernel:

$$K(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^{T} \mathbf{z})^{2}$$

$$= (\sum_{i=1}^{p} x_{i} z_{i})^{2}$$

$$= (\sum_{i=1}^{p} x_{i} z_{i}) (\sum_{j=1}^{p} x_{j} z_{j})$$

$$= \sum_{i=1}^{p} \sum_{j=1}^{p} x_{i} z_{i} x_{j} z_{j}$$

$$= \sum_{i=1}^{p} \sum_{j=1}^{p} x_{i} x_{j} z_{i} z_{j}$$

$$= \phi(\mathbf{x})^{T} \phi(\mathbf{z})$$

Suppose 
$$d=3$$
. Then  ${\pmb x}=(x_1,x_2,x_3)$  and  ${\pmb z}=(z_1,z_2,z_3)$ . Using  ${\pmb K}({\pmb x},{\pmb z})=({\pmb x}^T{\pmb z})^2=\sum_{i=1}^p\sum_{j=1}^px_ix_jz_iz_j=\phi({\pmb x})^T\phi({\pmb z})$ , where  $\phi({\pmb x})$  is

$$\phi(\mathbf{x}) = \begin{bmatrix} x_1 x_1 \\ x_1 x_2 \\ x_1 x_3 \\ x_2 x_1 \\ x_2 x_2 \\ x_2 x_3 \\ x_3 x_1 \\ x_3 x_2 \\ x_3 x_3 \end{bmatrix}$$

So we need to keep track of  $d^2 = 9$  features if we explicitly use  $\phi$ .

If we use the kernel  $K(x,z)=(x^Tz)^2$  where  $x,z\in\mathbb{R}^d$ , then

- computation of  $\phi$  requires  $O(p^2)$  in time and space
- computation of  $(x^Tz)^2$  requires O(p) in time

Evaluating using kernels is lot cheaper especially when d is large.

#### What's a kernel?

- A function  $K: \mathcal{X} \times \mathcal{X} \mapsto R$  is a kernel over  $\mathcal{X}$ .
- This is equivalent to taking the dot product  $\phi(x)^T \phi(x')$  for some mapping
- Mercer's Theorem: So long as the function is continuous and symmetric, then K admits an expansion of the form

$$K(\mathbf{x}, \mathbf{x}') = \sum_{n} a_n \phi_n(\mathbf{x}) \phi_n(\mathbf{x}')$$

The computational cost is just in computing the kernel

#### **Kernel Matrix**

The important property of the kernel matrix  $K = [K(x_i, x_j)]_{ij} \in \mathbb{R}^{m \times m}$  is symmetric positive semidefinite.

$$\mathbf{K}^T = \mathbf{K}$$
 (symmetric)

$$\forall x, x^T K x \ge 0$$
 (positive semidefinite)

Also known as Gram matrix.

## **Example of Kernels**

# **Polynomial Kernel**

$$K(\mathbf{x}, \mathbf{x}') = (\mathbf{x}^T \mathbf{x}' + c)^d$$

where c is a constant, d is the degree of polynomial

# (Gaussian) Radial Basis Kernel (RBF Kernel)

$$K(\mathbf{x}, \mathbf{x}') = \exp\left(-\gamma \|\mathbf{x}' - \mathbf{x}\|^2\right)$$

where  $\gamma$  is a hyperparameter.

- if x = x', then K(x, x') = 1
- if x is very different from x', then  $K(x, x') \approx 0$

### How does it affect optimization

$$\max_{\alpha} \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{i=1}^{m} \alpha_i \alpha_j y_i y_j (\boldsymbol{x_i}^T \boldsymbol{x_j}) \qquad \max_{\alpha} \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{i=1}^{m} \alpha_i \alpha_j y_i y_j K(\boldsymbol{x_i}, \boldsymbol{x_j})$$

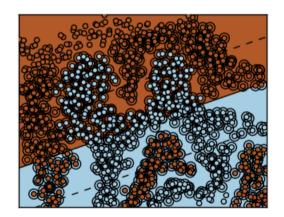
- Replace all dot product with kernel evaluations  $K(x_1, x_2)$
- Makes computation more expensive, overall structure is the same

## **Outline**

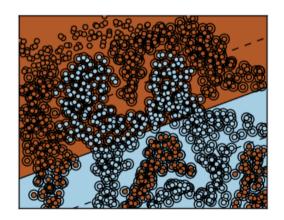
Kernels

Examples

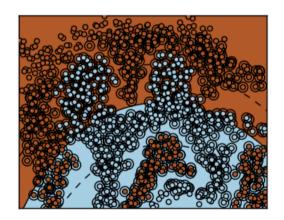
## **Linear Decision Boundary Doesn't Work**



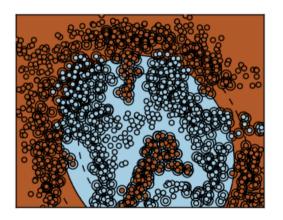
## Polynomial Kernel d = 1, c = 5

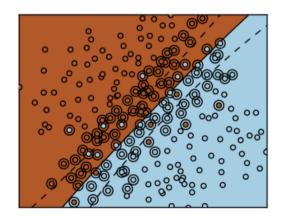


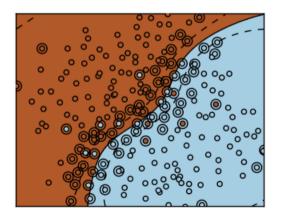
## Polynomial Kernel d = 2, c = 5

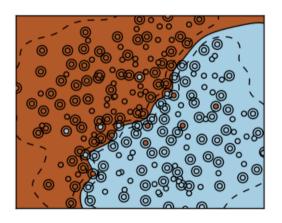


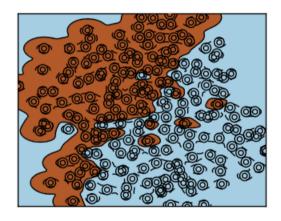
## Polynomial Kernel d = 3, c = 5











## Recap

 Kernels: applicable to wide range of data, inner product trick keeps method simple