Dodowhile





Machine Learning: Yoshinari Fujinuma University of Colorado Boulder LECTURE 15

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Logistics

- Quiz 1 grades are available
- Homework 3 will be available today
- Project team formulation deadline is today

Overview

Forward propagation recap

Back propagation
Chain rule
Back propagat

Back propagation

Full algorithm

Outline

Forward propagation recap

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Forward propagation algorithm

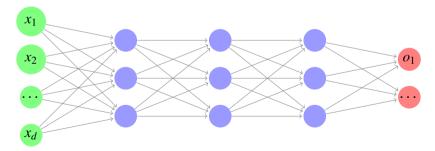
How do we make predictions based on a multi-layer neural network? Store the biases for layer l in b^l , weight matrix in W^l

$$W^{1}, b^{1}$$

$$W^2, b^2$$

$$W^1, b^1$$
 W^2, b^2 W^3, b^3 W^4, b^4

$$\pmb{W}^4, \pmb{b}^4$$



Forward propagation algorithm

Suppose your network has L layers Make prediction for an instance x

- 1: Initialize $a^0 = x$
- 2: **for** l = 1 to L **do**
- 3: $\mathbf{z}^l = \mathbf{W}^l \mathbf{a}^{l-1} + \mathbf{b}^l$
- 4: $a^l = g(z^l) // g$ represents the nonlinear activation
- 5: end for
- 6: The prediction \hat{y} is simply a^L

Neural networks in a nutshell

- Training data $S_{\text{train}} = \{(x, y)\}$
- Network architecture (model)

$$\hat{y} = f_w(x)$$

 $\mathbf{W}^l, \mathbf{b}^l, l = 1, \dots, L$

Loss function (objective function)

$$\mathcal{L}(y,\hat{y})$$

• How do we learn the parameters?

Neural networks in a nutshell

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How do we learn the parameters?
 Stochastic gradient descent,

$$m{W}^l \leftarrow m{W}^l - \eta rac{\partial \mathscr{L}(y, \hat{y})}{\partial m{W}^l}$$

Challenge

- Challenge: How do we compute derivatives of the loss function with respect to weights and biases?
- Solution: Back propagation

Outline

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Back propagation
Chain rule
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Full algorithm

The chain rule allows us to take derivatives of nested functions.

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Univariate chain rule:

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Example:

$$\frac{d}{dx} \, \frac{1}{1 + \exp(-x)}$$

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Univariate chain rule:

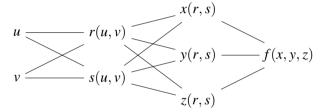
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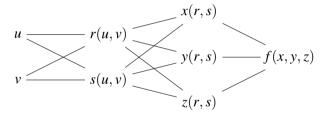
$$\frac{d}{dx} \frac{1}{1 + \exp(-x)} = -\frac{1}{(1 + \exp(-x))^2} \cdot \exp(-x) \cdot -1$$

$$\frac{d\sigma(x)}{dx} = \sigma(x)(1 - \sigma(x))$$

Multivariate chain rule:

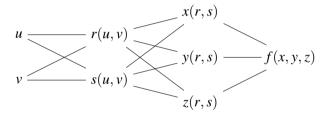


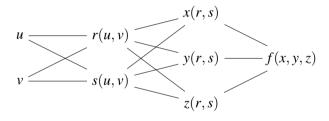
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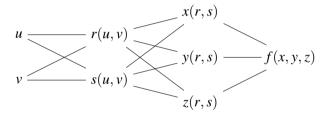
Derivative of $\mathscr L$ with respect to x is straightforward. e.g., f=xyz, then:

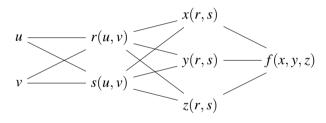
$$\frac{\partial f}{\partial x} = yz$$



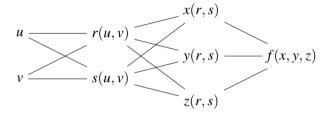


$$\frac{\partial f}{\partial r} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial r} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial r}$$



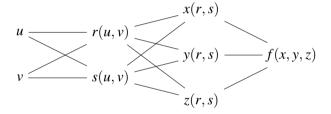


$$\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial s}$$



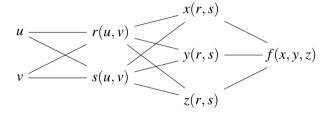
Example: Let
$$f = xyz$$
, $x = r$, $y = rs$, and $z = s$. Find $\partial f/\partial s$

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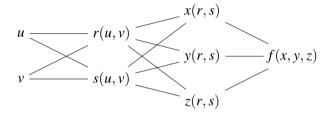
Example: Let
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$$\frac{\partial f}{\partial s} = yz \cdot 0 + xz \cdot r + xy \cdot 1$$



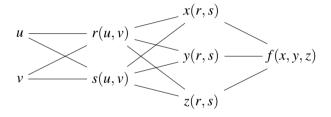
Example: Let
$$f=xyz$$
, $x=r$, $y=rs$, and $z=s$. Find $\partial f/\partial s$
$$\frac{\partial f}{\partial s}=rs^2\cdot 0+rs\cdot r+r^2s\cdot 1$$

What is the derivative of *f* with respect to *s*?



Example: Let f = xyz, x = r, y = rs, and z = s. Find $\partial f/\partial s$

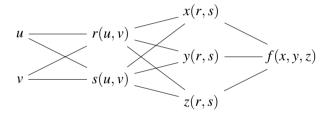
$$\frac{\partial f}{\partial s} = 2r^2s$$

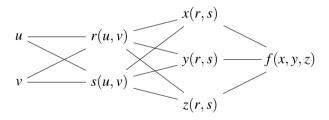


Example: Let f = xyz, x = r, y = rs, and z = s. Find $\partial f/\partial s$

$$f(r,s) = r \cdot rs \cdot s = r^2 s^2 \quad \Rightarrow \quad \frac{\partial f}{\partial s} = 2r^2 s \checkmark$$

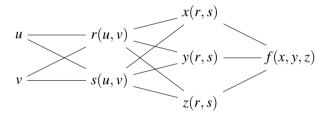
Machine Learning: Yoshinari Fujinuma





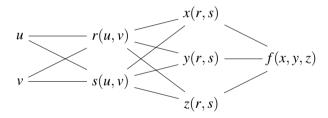
$$\frac{\partial f}{\partial u} = \frac{\partial f}{\partial r} \frac{\partial r}{\partial u} + \frac{\partial f}{\partial s} \frac{\partial s}{\partial u}$$

What is the derivative of f with respect to u?



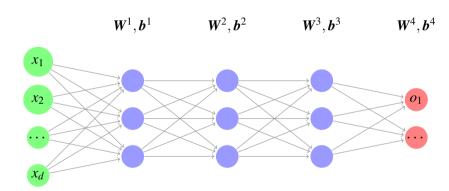
If you know the derivative of objective w.r.t. intermediate value in the chain, you don't need to now the following values in the chain.

What is the derivative of f with respect to u?

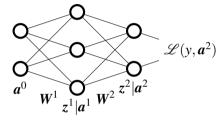


If you know the derivative of objective w.r.t. intermediate value in the chain, you don't need to now the following values in the chain.

This is the cornerstone of the *back propagation* algorithm.



For the derivation, we'll consider a simplified network

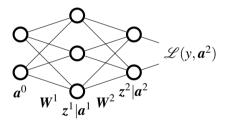


Remind that $a^L=g(z^L)$ where g is the activation function. Use back propagation to compute partial derivative of $\mathscr L$ w.r.t. the weights

$$\frac{\partial \mathcal{L}}{\partial w_{ij}^2}$$
, for $l = 1, 2$

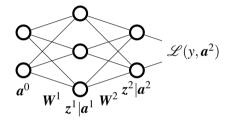
 w_{ii}^l is the weight from node j in layer l-1 to node i in layer l.

For the derivation, we'll consider a simplified network



Choose an intermediate term so that we can easily compute derivatives.

For the derivation, we'll consider a simplified network

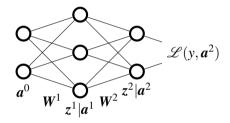


Define the derivative w.r.t. the z's by δ :

$$\delta_j^l = \frac{\partial \mathscr{L}}{\partial z_j^l}$$

Note that δ^l has the same size as z^l and a^l .

For the derivation, we'll consider a simplified network



Let's compute δ^L for output layer L:

$$\delta_j^L = \frac{\partial \mathcal{L}}{\partial z_j^L} = \frac{\partial \mathcal{L}}{\partial a_j^L} \frac{da_j^L}{dz_j^L}$$

$$\delta_j^L = \frac{\partial \mathscr{L}}{\partial z_j^L} = \frac{\partial \mathscr{L}}{\partial a_j^L} \frac{da_j^L}{dz_j^L}$$
 We know that $a_j^L = g(z_j^L)$, so $\frac{da_j^L}{dz_i^L} = g'(z_j^L)$

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$$a_j^L=g(z_j^L),~~$$
 so $\dfrac{du_j}{dz_j^L}=g'(z_j^L)$
$$\delta_j^L=\dfrac{\partial \mathscr{L}}{\partial a_i^L}g'(z_j^L)$$

Note: The first term is j^{th} entry of gradient of \mathcal{L} .

$$\delta_j^L = \frac{\partial \mathcal{L}}{\partial a_j^L} g'(z_j^L)$$

We can combine all of these into a vector operation

$$oldsymbol{\delta}^L = rac{\partial \mathscr{L}}{\partial oldsymbol{a}^L} \odot g'(oldsymbol{z}^L)$$

Where $g'(z^L)$ is the activation function applied elementwise to z^L .

The symbol \odot indicates element-wise multiplication of vectors.

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Notice that computing δ^L requires knowing activations. This means that before we can compute derivatives for SGD through back propagation, we first run forward propagation through the network.

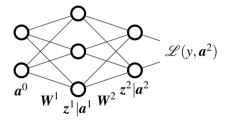
Example: Suppose we're in regression setting and choose a sigmoid activation function:

$$\mathcal{L} = \frac{1}{2} \sum_{j} (y_j - a_j^L)^2 \quad \text{and} \quad a_j^L = \sigma(z)$$

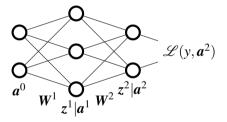
$$\frac{\partial \mathcal{L}}{\partial a_j^L} = (a_j^L - y_j), \quad \frac{da_j^L}{dz_j^L} = \sigma'(z_j^L) = \sigma(z_j^L)(1 - \sigma(z_j^L))$$

So
$$\delta^L = (a^L - y) \odot \sigma(z^L) \odot (1 - \sigma(z^L))$$

Now we can easily-ish compute the δ 's for the output layer. But really we're after partials w.r.t. to weights and biases.

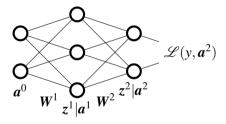


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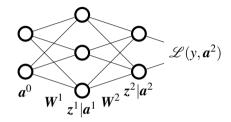


Question: What do you notice?

We want to find derivative $\mathscr L$ w.r.t. to weights and biases



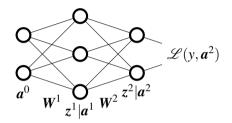
Every weight connected to a node in layer L depends on a single δ_j^L



So we have
$$\frac{\partial \mathscr{L}}{\partial w_{jk}^L} = \frac{\partial \mathscr{L}}{\partial z_j^L} \frac{\partial z_j^L}{\partial w_{jk}^L} = \delta_j^L \frac{\partial z_j^L}{\partial w_{jk}^L}$$
Need to compute $\frac{\partial z_j^L}{\partial w_{jk}^L}$. Recall $\mathbf{z}^L = W^L \mathbf{a}^{L-1} + \mathbf{b}^L$

$$rac{\partial \mathcal{L}_j}{\partial w_{jk}^L}$$
. Recall $\mathbf{z}^L = W^L \mathbf{a}^{L-1} + \mathbf{b}^L$

$$j^{\text{th}}$$
 entry in vector \Rightarrow $z_j^L = \sum_i w_{ji}^L a_i^{L-1} + b_j^L$

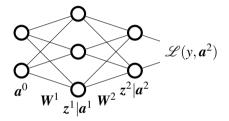


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Taking derivative w.r.t. w_{ik}^L gives

$$\Rightarrow \quad \frac{\partial z_{j}^{L}}{\partial w_{jk}^{L}} = a_{k}^{L-1} \quad \Rightarrow \quad \frac{\partial \mathcal{L}}{\partial w_{jk}^{L}} = a_{k}^{L-1} \delta_{j}^{L}$$



So we have
$$\frac{\partial \mathcal{L}}{\partial w_{jk}^L} = a_k^{L-1} \delta_j^L$$

Easy expression for derivative w.r.t. every weight leading into layer L.

Let's make the notation a little more practical.

$$\mathbf{W}^2 = \begin{bmatrix} w_{11}^2 & w_{12}^2 & w_{13}^2 \\ w_{21}^2 & w_{22}^2 & w_{23}^2 \end{bmatrix}$$

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$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}^2} = \begin{bmatrix} \frac{\partial \mathcal{L}}{\partial w_{11}^2} & \frac{\partial \mathcal{L}}{\partial w_{12}^2} & \frac{\partial \mathcal{L}}{\partial w_{13}^2} \\ \frac{\partial \mathcal{L}}{\partial w_{21}^2} & \frac{\partial \mathcal{L}}{\partial w_{22}^2} & \frac{\partial \mathcal{L}}{\partial w_{23}^2} \end{bmatrix} = \begin{bmatrix} \delta_1^2 a_1^1 & \delta_1^2 a_2^1 & \delta_1^2 a_3^1 \\ \delta_2^2 a_1^1 & \delta_2^2 a_2^1 & \delta_2^2 a_3^1 \end{bmatrix}$$

Now we can write this as an outer-product of δ^2 and a^1 .

$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}^2} = \boldsymbol{\delta}^2 (\mathbf{a}^1)^T$$

Intermediate summary

For a giving training example x, perform forward propagation to get z^l and a^l on each layer.

Then to get the partial derivatives for W^2 or W^L :

- 1. Compute $\delta^L = \frac{\partial \mathscr{L}}{\partial a_j^L} \odot g'(z^L)$
- 2. Compute $\frac{\partial \mathscr{L}}{\partial \pmb{w}^L} = \pmb{\delta}^L (\pmb{a}^{L-1})^T$ and $\frac{\partial \mathscr{L}}{\partial \pmb{b}^L} = \pmb{\delta}^L$

We found very simple expressions for the derivatives with respect to the weights in the last hidden layer!

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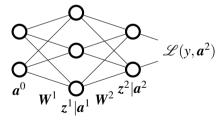
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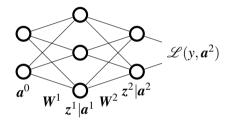
Once we knew the adjacent δ^l , we can easily compute the δ^l 's on earlier layers.

But the relationship between \mathcal{L} and z^1 is really complicated because of multiple passes through the activation functions.

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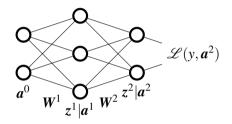
Notice that δ^1 depends on δ^2 .



By multivariate chain rule,

$$\frac{\partial \mathcal{L}}{\partial z_k^{l-1}} = \sum_j \frac{\partial \mathcal{L}}{\partial z_j^l} \frac{\partial z_j^l}{\partial z_k^{l-1}}$$

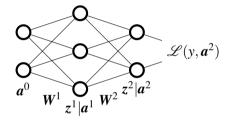
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Notice that δ^1 depends on δ^2 .



By multivariate chain rule,

$$\delta_2^1 = \frac{\partial \mathcal{L}}{\partial z_2^1} = \delta_1^2 \frac{\partial z_1^2}{\partial z_2^1} + \delta_2^2 \frac{\partial z_2^2}{\partial z_2^1}$$

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Recall that $z^2 = W^2 a^1 + b^2$, it follows that

$$z_i^2 = w_{i1}^2 a_1^1 + w_{i2}^2 a_2^1 + w_{i3}^2 a_3^1 + b_i^2$$

Taking the derivative $\frac{\partial z_1^2}{\partial z_2^1}=w_{i2}^2g'(z_2^1)$, and plugging in gives

$$\delta_2^1 = \frac{\partial \mathcal{L}}{\partial z_2^1} = \delta_1^2 w_{12}^2 g'(z_2^1) + \delta_2^2 w_{22}^2 g'(z_2^1)$$

If we do this for each of the 3 δ_i^1 's, something nice happens:

$$\delta_1^1 = \delta_1^2 w_{11}^2 g'(z_1^1) + \delta_2^2 w_{21}^2 g'(z_1^1)
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Notice that each row of the system gets multiplied by $g'(z_i^1)$, so let's factor those out.

If we do this for each of the 3 δ_i^2 's, something nice happens:

$$\delta_1^1 = (\delta_1^2 w_{11}^2 + \delta_2^2 w_{21}^2) \cdot g'(z_1^1)
\delta_2^1 = (\delta_1^2 w_{12}^2 + \delta_2^2 w_{22}^2) \cdot g'(z_2^1)
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Remember
$$\delta^2 = \begin{bmatrix} \delta_1^2 \\ \delta_2^2 \end{bmatrix}$$
, $W^2 = \begin{bmatrix} w_{11}^2 & w_{12}^2 & w_{13}^2 \\ w_{21}^2 & w_{22}^2 & w_{23}^2 \end{bmatrix}$

If we do this for each of the 3 δ_i^2 's, something nice happens:

$$\delta_1^1 = (\delta_1^2 w_{11}^2 + \delta_2^2 w_{21}^2) \cdot g'(z_1^1)
\delta_2^2 = (\delta_1^2 w_{12}^2 + \delta_2^2 w_{22}^2) \cdot g'(z_2^1)
\delta_3^2 = (\delta_1^2 w_{13}^2 + \delta_2^2 w_{23}^2) \cdot g'(z_3^1)$$

$$(\mathbf{W}^2)^T = egin{bmatrix} w_{11}^2 & w_{21}^2 \ w_{12}^2 & w_{23}^2 \ w_{13}^2 & w_{23}^2 \end{bmatrix}, \, oldsymbol{\delta}^2 = egin{bmatrix} \delta_1^2 \ \delta_2^2 \end{bmatrix}.$$

If we do this for each of the 3 δ_i^2 's, something nice happens:

$$\delta_1^1 = (\delta_1^2 w_{11}^2 + \delta_2^2 w_{21}^2) \cdot g'(z_1^1)
\delta_2^1 = (\delta_1^2 w_{12}^2 + \delta_2^2 w_{22}^2) \cdot g'(z_2^1)
\delta_3^1 = (\delta_1^2 w_{13}^2 + \delta_2^2 w_{23}^2) \cdot g'(z_3^1)
\delta^1 = (\mathbf{W}^2)^T \delta^2 \odot g'(z^1)$$

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We can easily compute δ^1 from δ^2 Then we can compute derivatives of \mathcal{L} w.r.t. weights \mathbf{W}^1 and biases \mathbf{b}^1 exactly the way we did for \mathbf{W}^2 and biases \mathbf{b}^2

- 1. Compute $\delta^1 = (\mathbf{W}^2)^T \delta^2 \odot g'(z^1)$
- 2. Compute $\frac{\partial \mathscr{L}}{\partial \pmb{w}^1} = \pmb{\delta}^1 (\pmb{a}^0)^T$ and $\frac{\partial \mathscr{L}}{\partial \pmb{b}^1} = \pmb{\delta}^1$

We can easily compute δ^1 from δ^2

Then we can compute derivatives of \mathcal{L} w.r.t. weights W^1 and biases b^1 exactly the way we did for W^2 and biases b^2

- 1. Compute $\delta^1 = (\mathbf{W}^2)^T \delta^2 \odot g'(z^1)$
- 2. Compute $\frac{\partial \mathscr{L}}{\partial \pmb{w}^1} = \pmb{\delta}^1 (\pmb{a}^0)^T$ and $\frac{\partial \mathscr{L}}{\partial \pmb{b}^1} = \pmb{\delta}^1$

We've worked this out for a simple network with one hidden layer.

Nothing we've done assumed anything about the number of layers, so we can apply the same procedure recursively with any number of layers.

$$\begin{split} \delta^L &= \frac{\partial \mathscr{L}}{\partial a_j^L} \odot g'(\mathbf{z}^L) \quad \text{\# Compute δ's on output layer} \\ \text{For $\ell = L, \dots, 1$} \\ &\frac{\partial \mathscr{L}}{\partial \mathbf{w}^\ell} = \boldsymbol{\delta}^\ell (\boldsymbol{a}^{l-1})^T \quad \text{\# Compute weight derivatives} \\ &\frac{\partial \mathscr{L}}{\partial \boldsymbol{b}^\ell} = \boldsymbol{\delta}^\ell \qquad \text{\# Compute bias derivatives} \\ &\boldsymbol{\delta}^{\ell-1} = \left(W^\ell\right)^T \boldsymbol{\delta}^\ell \odot g'(\mathbf{z}^{\ell-1}) \quad \text{\# Back prop δ's to previous layer} \\ \text{(After this, ready to do a SGD update on weights/biases)} \end{split}$$

Training a Feed-Forward Neural Network

Given initial guess for weights and biases. Loop over each training example in random order:

- 1. Forward propagate to get activations on each layer
- Back propagate to get derivatives
- 3. Update weights and biases via stochastic gradient descent
- 4. Repeat