

## IPPR Lab 4-B

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**Aim: Apply Median Filter To Reduce The Effect Of Salt & Pepper Noise On The Given Image**

```
#Importing Libraries
from skimage import io
import matplotlib.pyplot as plt
from skimage.color import rgb2gray
import numpy as np
from scipy import signal
from random import randint

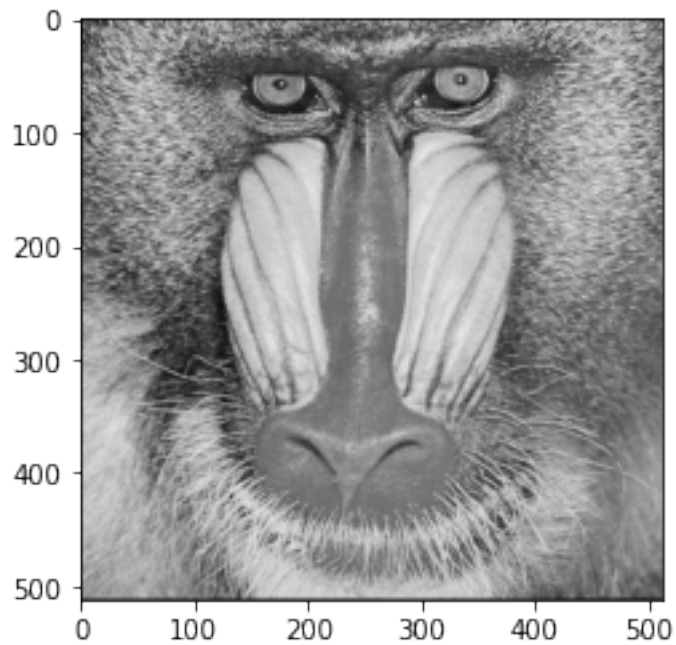
#Import Image
image_color=io.imread('baboon.png')

image_color.shape
(512, 512, 3)

image = rgb2gray(image_color)

image=255*image

plt.imshow(image, cmap = 'gray')
<matplotlib.image.AxesImage at 0x12e2fe25a08>
```



```

image.shape
(512, 512)
sh = image.shape
rows = sh[0]
cols = sh[1]

no_pixels = rows*cols
no_pixels
262144

# % of pixels corrupted by noise
a = 0.1
no_rp = int(a * no_pixels)

no_rp
26214

sp = 255

image_sp = image.copy()

# Take random row and column and change the pixel value. Alternate pixels assumed as salt and pepper
for i in range(no_rp):
    temp1 = randint(0,rows-1)

```

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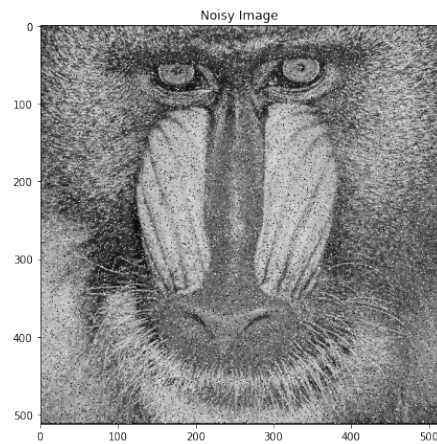
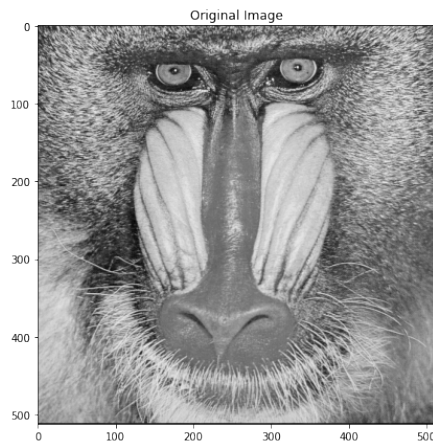
temp2 = randint(0,cols-1)
image_sp[temp1][temp2] = sp
if sp == 255:
    sp = 0
else:
    sp = 255

#Display original and noisy image
plt.figure(figsize=(15,15))
plt.subplot(1,2,1)
plt.imshow(image, cmap = 'gray')
plt.title('Original Image')

plt.subplot(1,2,2)
plt.imshow(image_sp, cmap = 'gray')
plt.title('Noisy Image')

Text(0.5, 1.0, 'Noisy Image')

```



```

image_sp_filt = image_sp.copy()

sz = 3
# central value
cent = int((sz-1)/2)
med = int(((sz*sz)-1)/2) # getting the fifth value which is the middle value in a 3x3 matrix

print(cent)
print(med)

1
4

for r in range(0,rows-sz):
    for c in range(0,cols-sz):

```

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temp1 = image_sp[r:r+sz,c:c+sz] # 0,1,2 rows and cols values extracted
temp2 = np.reshape(temp1, (1,sz*sz)) # Reshaped to single vector
temp3 = np.sort(temp2)
image_sp_filt[r+cent][c+cent] = temp3[0][med]

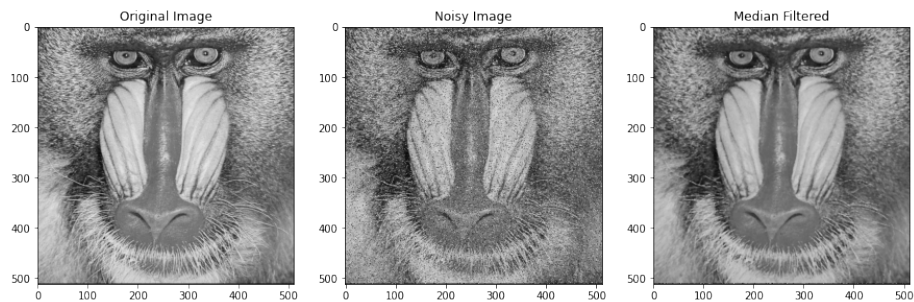
plt.figure(figsize=(15,15))
plt.subplot(1,3,1)
plt.imshow(image,cmap='gray')
plt.title('Original Image')

plt.subplot(1,3,2)
plt.imshow(image_sp,cmap='gray')
plt.title('Noisy Image')

plt.subplot(1,3,3)
plt.imshow(image_sp_filt, cmap = 'gray')
plt.title('Median Filtered')

Text(0.5, 1.0, 'Median Filtered')

```



```

# Increasing Noise
# % of pixels corrupted by noise
a = 0.3
no_rp = int(a * no_pixels)

no_rp
78643

sp =255

image_sp1 = image.copy()

# Take random row and column and change the pixel value. Alternate pixels assumed as salt and pepper
for i in range(no_rp):
    temp1 = randint(0,rows-1)
    temp2 = randint(0,cols-1)
    image_sp1[temp1][temp2] = sp
    if sp == 255:

```

```

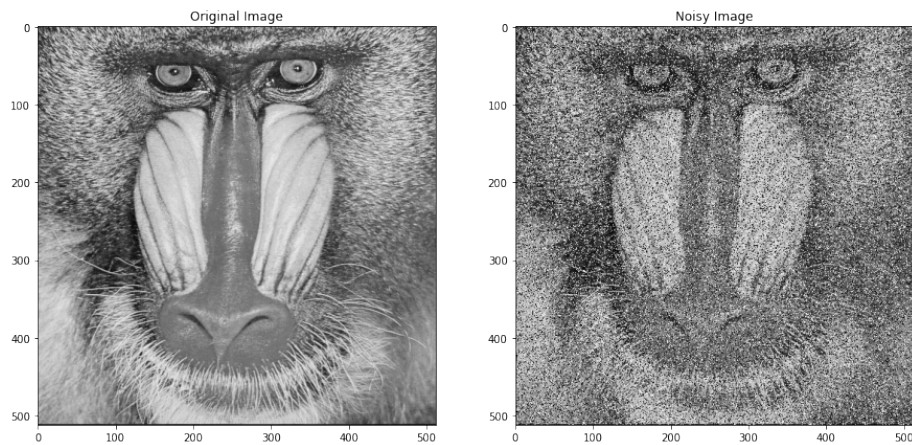
        sp = 0
    else:
        sp = 255

#Display origina and noisy image
plt.figure(figsize=(15,15))
plt.subplot(1,2,1)
plt.imshow(image, cmap = 'gray')
plt.title('Original Image')

plt.subplot(1,2,2)
plt.imshow(image_sp1, cmap = 'gray')
plt.title('Noisy Image')

Text(0.5, 1.0, 'Noisy Image')

```



```

image_sp_filt1 = image_sp1.copy()

sz = 3
# central value
cent = int((sz-1)/2)
med = int(((sz*sz)-1)/2) # getting the fifth value which is the middle value in a 3x3 matrix

for r in range(0,rows-sz):
    for c in range(0,cols-sz):
        temp1 = image_sp1[r:r+sz,c:c+sz] # 0,1,2 rows and cols values extracted
        temp2 = np.reshape(temp1, (1,sz*sz)) # Reshaped to single vector
        temp3 = np.sort(temp2)
        image_sp_filt[r+cent][c+cent] = temp3[0][med]

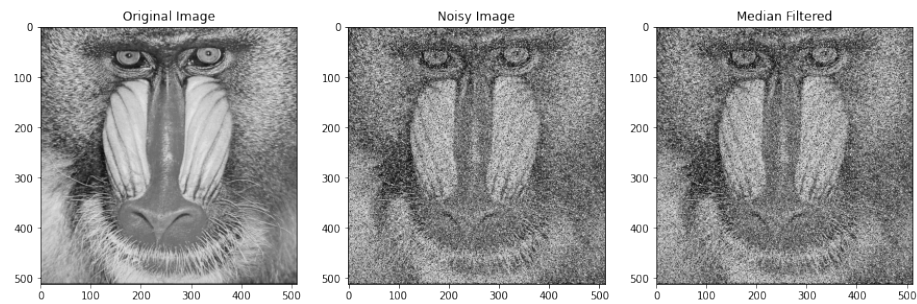
plt.figure(figsize=(15,15))
plt.subplot(1,3,1)
plt.imshow(image,cmap='gray')
plt.title('Original Image')

```

```
plt.subplot(1,3,2)
plt.imshow(image_sp1,cmap='gray')
plt.title('Noisy Image')

plt.subplot(1,3,3)
plt.imshow(image_sp_filt1, cmap = 'gray')
plt.title('Median Filtered')

Text(0.5, 1.0, 'Median Filtered')
```



```
# Taking 5x5 mask and a=0.4
# Increasing Noise
# % of pixels corrupted by noise
a = 0.4
no_rp = int(a * no_pixels)

no_rp
104857

sp=255

image_sp2 = image.copy()

# Take random row and column and change the pixel value. Alternate pixels assumed as salt and pepper
for i in range(no_rp):
    temp1 = randint(0,rows-1)
    temp2 = randint(0,cols-1)
    image_sp2[temp1][temp2] = sp
    if sp == 255:
        sp = 0
    else:
        sp = 255

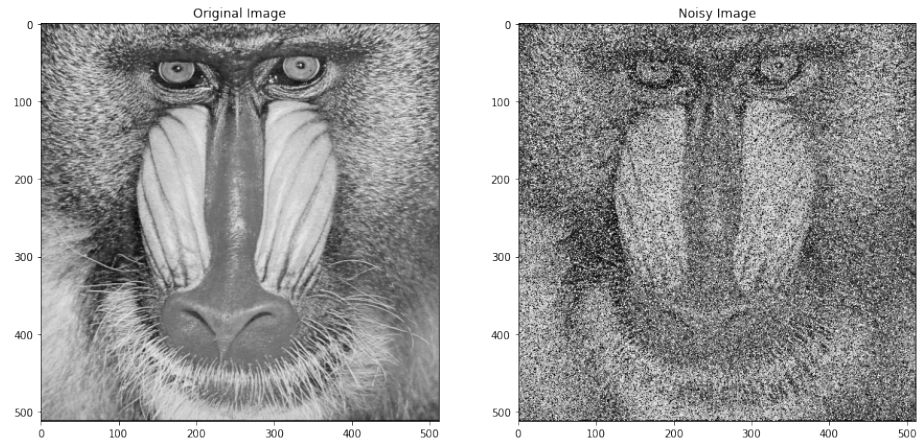
#Display original and noisy image
plt.figure(figsize=(15,15))
plt.subplot(1,2,1)
plt.imshow(image, cmap = 'gray')
```



```
plt.title('Original Image')

plt.subplot(1,2,2)
plt.imshow(image_sp2, cmap = 'gray')
plt.title('Noisy Image')

Text(0.5, 1.0, 'Noisy Image')
```



```
image_sp_filt2 = image_sp2.copy()

sz = 5
# central value
cent = int((sz-1)/2)
med = int(((sz*sz)-1)/2) # getting the fifth value which is the middle value in a 3x3 matrix

print(cent)
print(med)

2
12

for r in range(0,rows-sz):
    for c in range(0,cols-sz):
        temp1 = image_sp2[r:r+sz,c:c+sz] # 0,1,2 rows and cols values extracted
        temp2 = np.reshape(temp1, (1,sz*sz)) # Reshaped to single vector
        temp3 = np.sort(temp2)
        image_sp_filt2[r+cent][c+cent] = temp3[0][med]

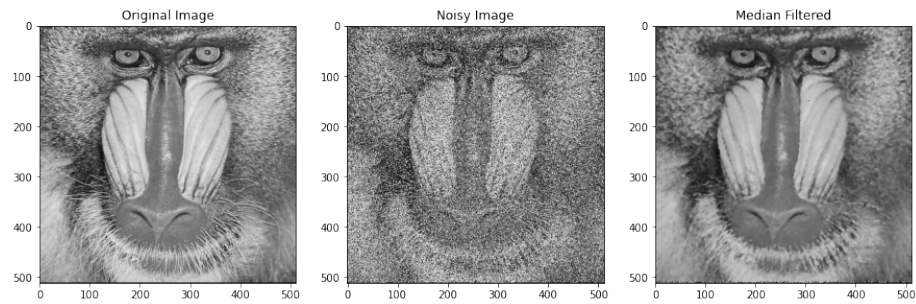
plt.figure(figsize=(15,15))
plt.subplot(1,3,1)
plt.imshow(image,cmap='gray')
plt.title('Original Image')

plt.subplot(1,3,2)
```

```
plt.imshow(image_sp2,cmap='gray')
plt.title('Noisy Image')

plt.subplot(1,3,3)
plt.imshow(image_sp_filt2, cmap = 'gray')
plt.title('Median Filtered')

Text(0.5, 1.0, 'Median Filtered')
```



## Conclusion

- The given image is corrupted with salt and pepper noise.
- If 10% of the pixels are corrupted by the noise then median filter of size 3x3 is effective in reducing the noise to almost negligible value.
- If 40% of the image is corrupted by the noise, then the size of the median filter is to be increased to get the significant effect of the filter.
- However if the size of the filter is increased, then the sharpness of the edges reduces. This is because size of the filter is more than the size of the object.