

IPPR Lab 6

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Aim: To Apply Otsu Thresholding Technique To Segment The Objects And To Apply Canny Edge Detection Algorithm To Detect The Edges To Segment The Object

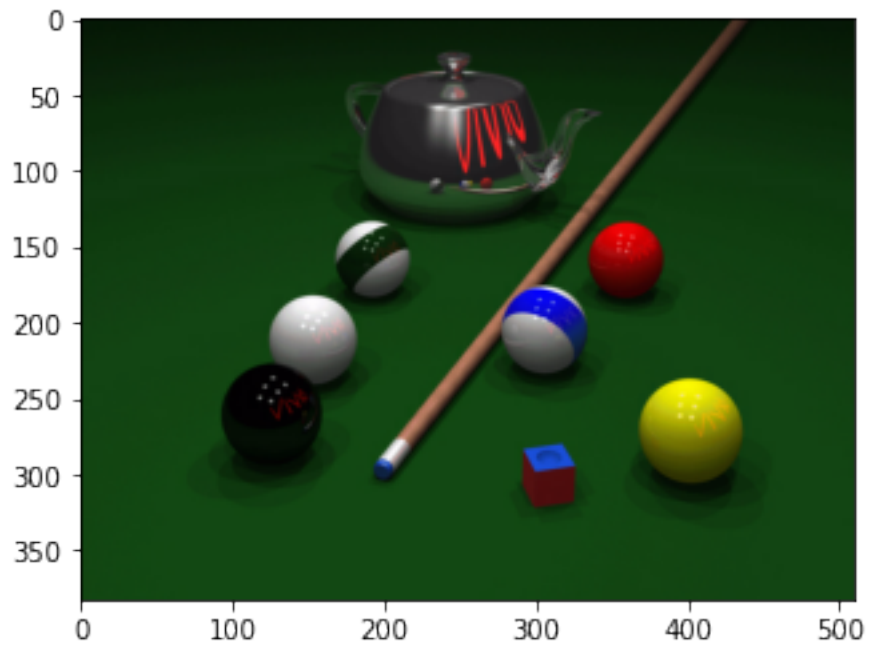
```
from skimage import io
import matplotlib.pyplot as plt
from skimage.color import rgb2gray
import numpy as np
from scipy import signal
from random import randint
import cv2

#Import Image
image=io.imread('pool.png')

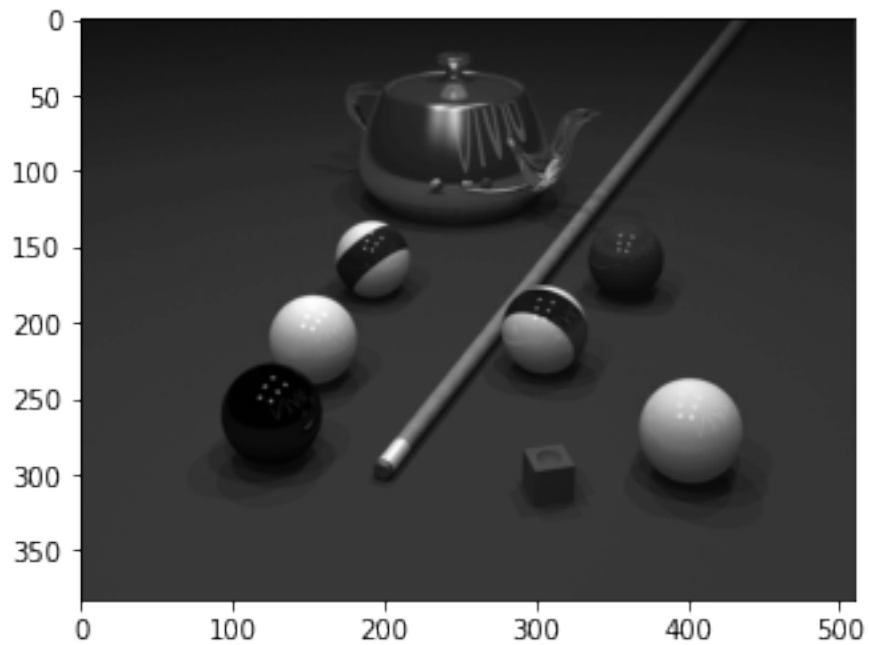
image.shape

(383, 510, 3)

plt.imshow(image, cmap = 'gray')
<matplotlib.image.AxesImage at 0x209fb257c88>
```



```
#Convert rgb to gray  
image=rgb2gray(image)  
image=image*255  
plt.imshow(image, cmap = 'gray')  
<matplotlib.image.AxesImage at 0x209fb4b3c08>
```

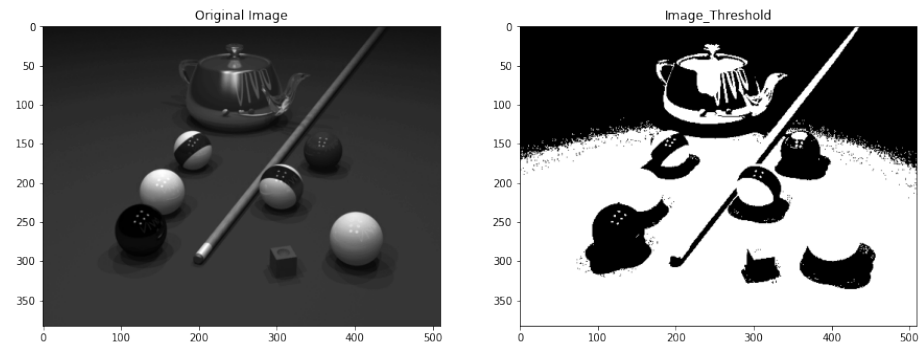


```
# All pixels more than 150 become 255 and rest 0
# Given image made binary to segment the balls in the pool image
```

```
image_s=image.copy()
T=50
thresh,image_s = cv2.threshold(image,T,200,cv2.THRESH_BINARY)

#Display original and sobel image
plt.figure(figsize=(15,15))
plt.subplot(1,2,1)
plt.imshow(image, cmap = 'gray')
plt.title('Original Image')

plt.subplot(1,2,2)
plt.imshow(image_s, cmap = 'gray')
plt.title('Image_Threshold = 50')
Text(0.5, 1.0, 'Image_Threshold')
```



```

image_s[0:10,0:10]
array([[0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.],
       [0., 0., 0., 0., 0., 0., 0., 0., 0., 0.]])

image_s[380:398,440:450]
array([[200., 200., 200., 200., 200., 200., 200., 200., 200., 200.],
       [200., 200., 200., 200., 200., 200., 200., 200., 200., 200.],
       [200., 200., 200., 200., 200., 200., 200., 200., 200., 200.]])

# Increase/Decrease Threshold Value
T1 = 30

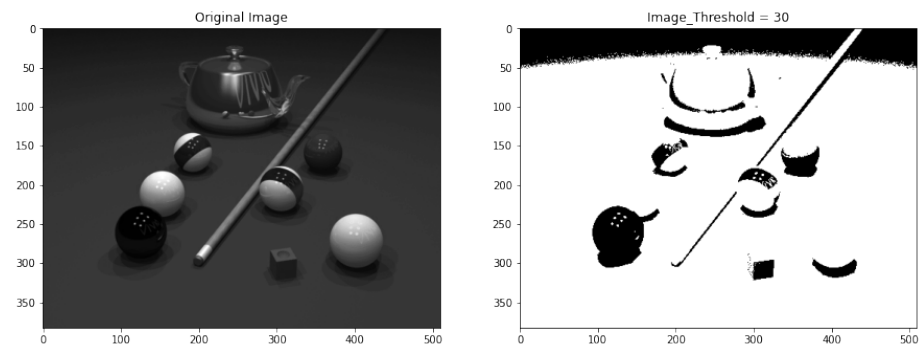
thresh,image_s = cv2.threshold(image,T1,200,cv2.THRESH_BINARY)

#Display original and sobel image
plt.figure(figsize=(15,15))
plt.subplot(1,2,1)
plt.imshow(image, cmap = 'gray')
plt.title('Original Image')

plt.subplot(1,2,2)
plt.imshow(image_s, cmap = 'gray')
plt.title('Image_Threshold = 30')

Text(0.5, 1.0, 'Image_Threshold = 30')

```



Conclusion

- For image threshold using threshold = 50 to segment the objects of the given image
- To segment more objects with little darker intensity than the original objects, threshold should be reduced further

(Initially threshold is 50, Reducing threshold to 30,)

```

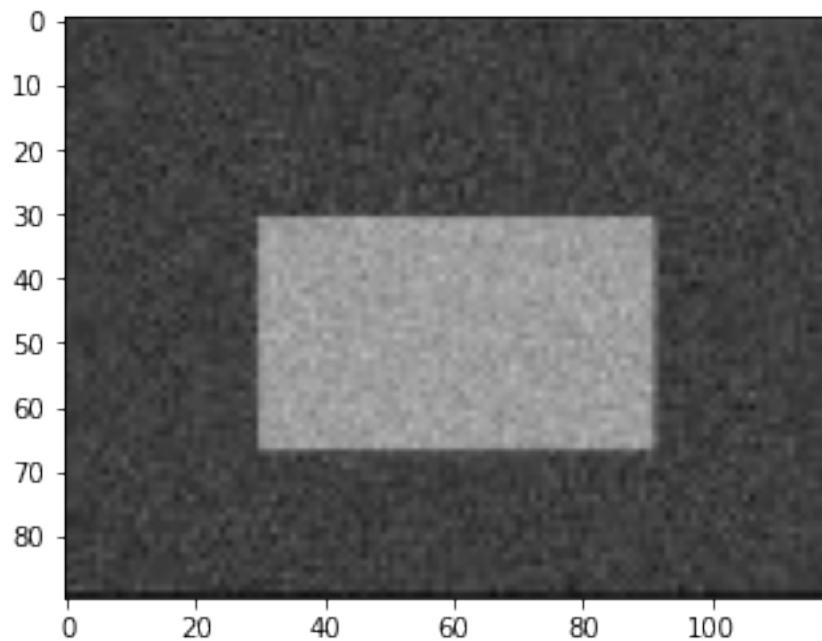
from skimage import io
import matplotlib.pyplot as plt
from skimage.color import rgb2gray
import numpy as np
from scipy import signal
from random import randint
import cv2

#Import Image
image=io.imread('noisy_image.png')

image.shape
(90, 119, 4)

plt.imshow(image, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156c805de88>

```



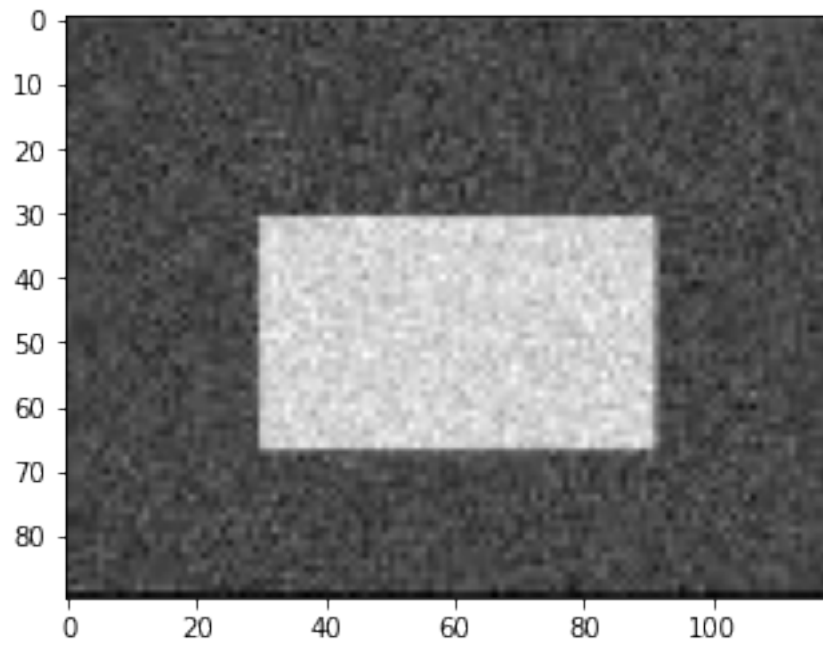
```

#Convert rgb to gray
from skimage.color import rgba2rgb
image = rgb2gray(rgba2rgb(image))

image=image*255

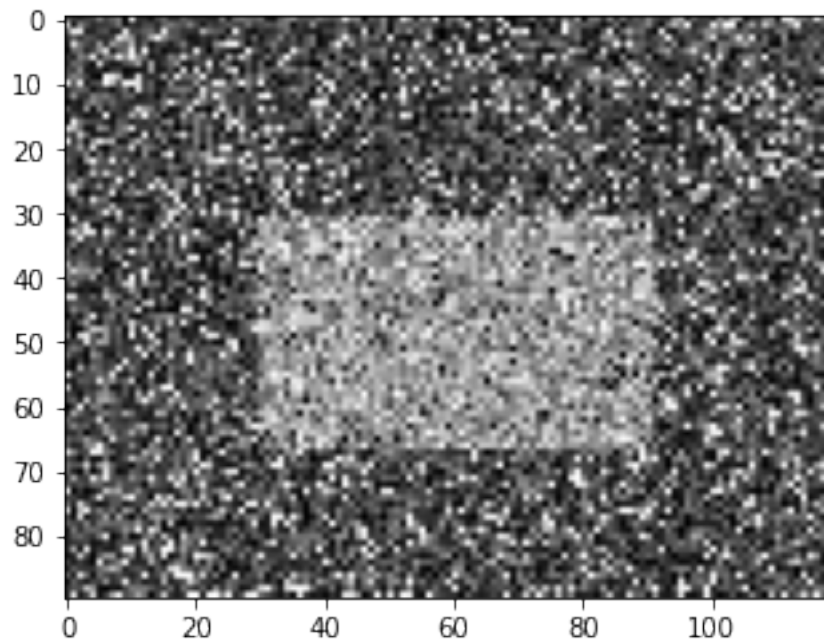
plt.imshow(image, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156c8143c88>

```

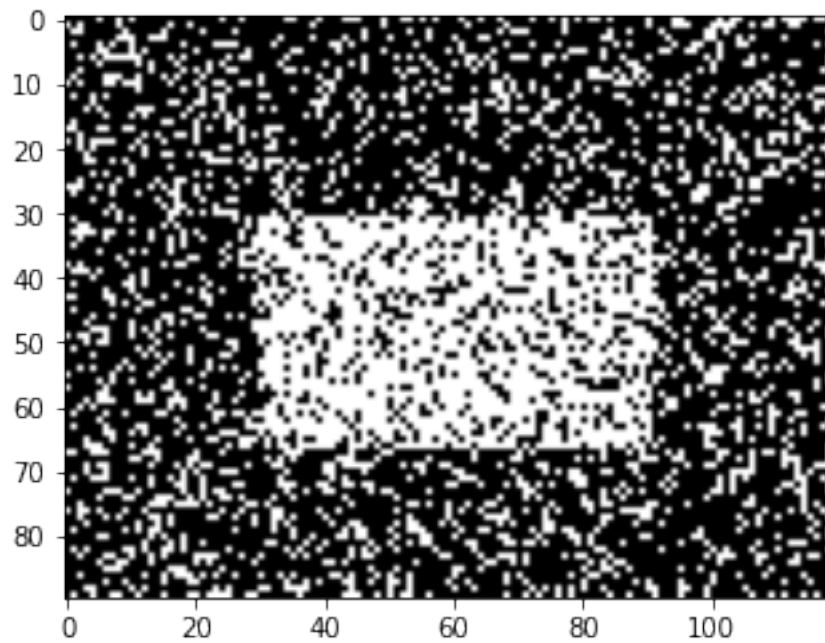


```
sh = image.shape
rows = sh[0]
cols = sh[1]

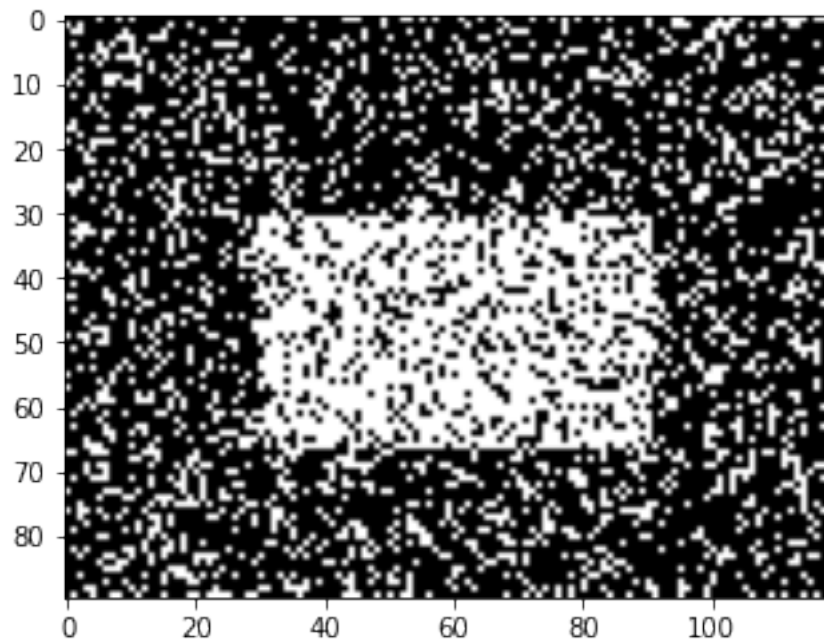
gn = np.random.normal(0,50,(rows,cols))
img1 = image+gn
img1 = np.uint8(img1)
plt.imshow(img1, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156c81e1488>
```



```
# Threshold and the Image it will be generating
th1,img1_th1 = cv2.threshold(img1,120,255,cv2.THRESH_BINARY)
th1
120.0
plt.imshow(img1_th1, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156c826a608>
```

```
th2,img1_th2 = cv2.threshold(img1,100,255,cv2.THRESH_BINARY+cv2.THRESH_OTSU)
th2
121.0
plt.imshow(img1_th2, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156c82e7c08>
```



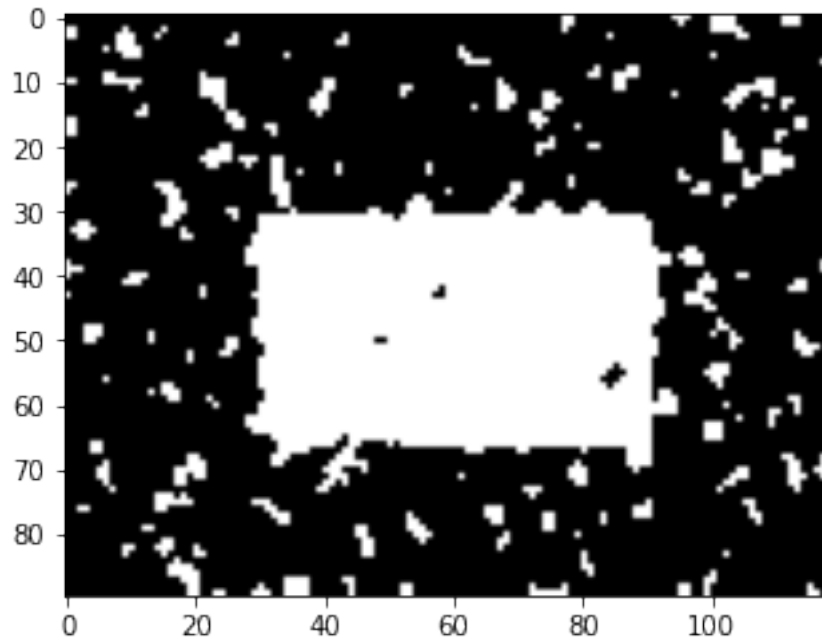
```
# Change 100 to 50
th2, img1_th2 = cv2.threshold(img1, 50, 255, cv2.THRESH_BINARY+cv2.THRESH_OTSU)

th2 # Getting the same threshold value
121.0

img_blur = cv2.GaussianBlur(img1, (5, 5), 0)
th3, img1_th3 = cv2.threshold(img_blur, 100, 255, cv2.THRESH_BINARY+cv2.THRESH_OTSU)

th3
115.0

plt.imshow(img1_th3, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156c836af48>
```



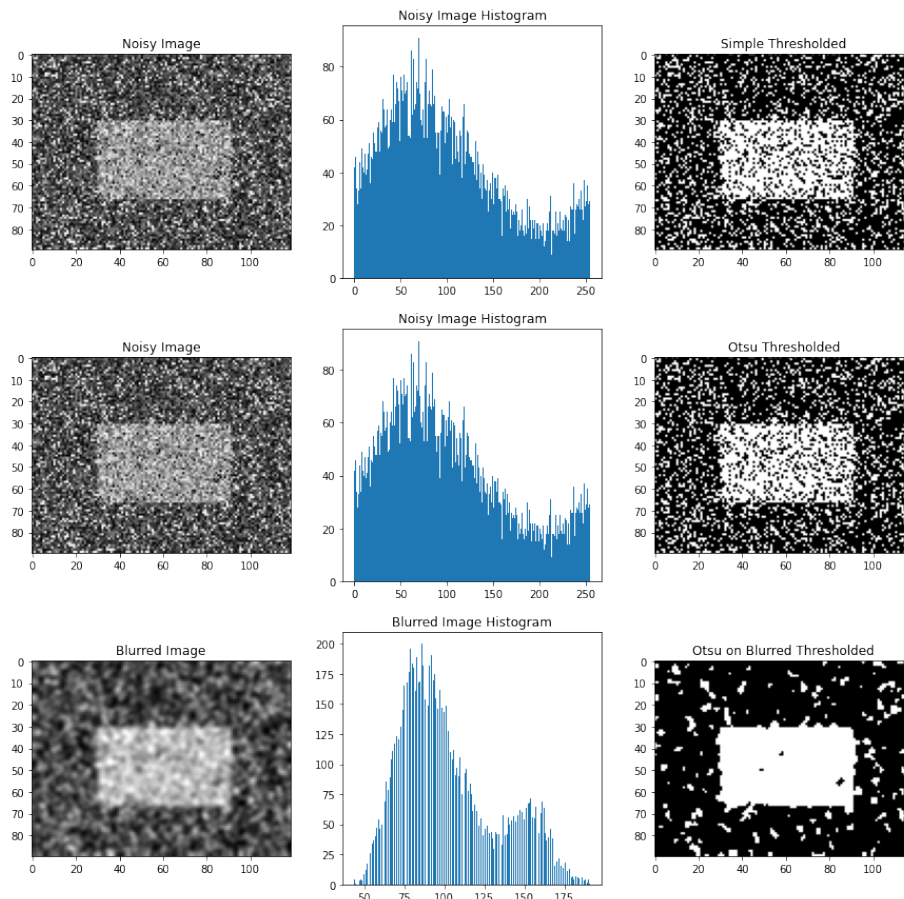
```
plt.figure(figsize=(15,15))
plt.subplot(3,3,1)
plt.imshow(img1, cmap = 'gray')
plt.title("Noisy Image")
plt.subplot(3,3,2)
plt.hist(img1.ravel(),256)
plt.title("Noisy Image Histogram")
plt.subplot(3,3,3)
plt.imshow(img1_th1, cmap = 'gray')
plt.title("Simple Thresholded")

plt.subplot(3,3,4)
plt.imshow(img1, cmap = 'gray')
plt.title("Noisy Image")
plt.subplot(3,3,5)
plt.hist(img1.ravel(),256)
plt.title("Noisy Image Histogram")
plt.subplot(3,3,6)
plt.imshow(img1_th2, cmap = 'gray')
plt.title("Otsu Thresholded")

plt.subplot(3,3,7)
plt.imshow(img_blur, cmap = 'gray')
plt.title("Blurred Image")
```

```
plt.subplot(3,3,8)
plt.hist(img_blur.ravel(),256)
plt.title("Blurred Image Histogram")
plt.subplot(3,3,9)
plt.imshow(img1_th3, cmap = 'gray')
plt.title("Otsu on Blurred Thresholded")

Text(0.5, 1.0, 'Otsu on Blurred Thresholded')
```



Exam Q: Level of standard deviation till which the threshold is working
Increased the gaussian noise std deviation
Originally it was 20 made it 50

Conclusion

- If Image is corrupted with the noise with standard deviation of 20, the simple & Otsu method of thresholding show some noisy dots in the segmented

image.

- To reduce the effect of noise, the given image is blurred by using Gaussian Filter before applying Otsu's Thresholding
- It is observed that Otsu's method is effective on the blurred image.
- If standard deviation of noise is increased to 50, Otsu method is not effective in segmenting the object

Canny Edge Detection

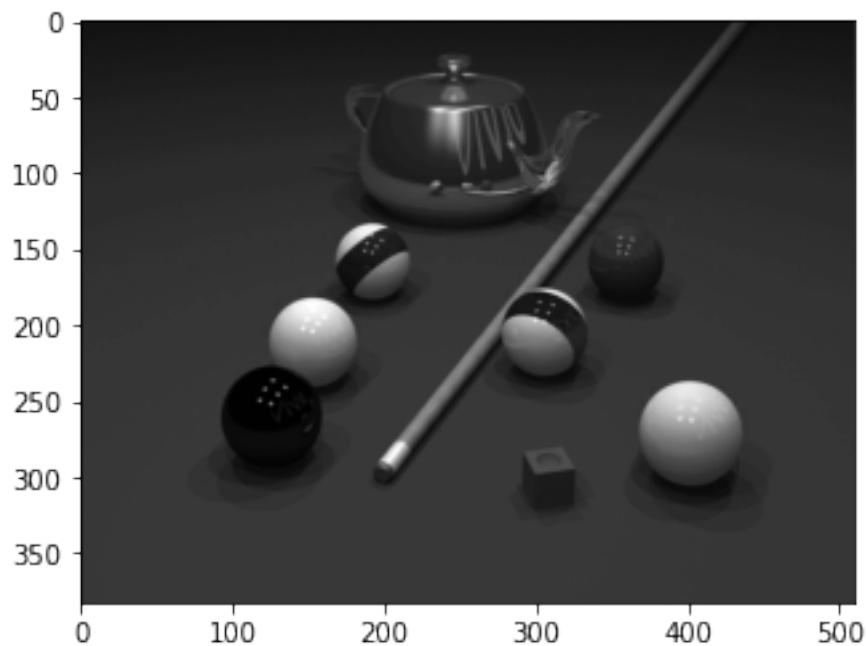
```
#Import Image
img=io.imread('pool.png')

img.shape
(383, 510, 3)

#Convert rgb to gray
img=rgb2gray(img)

img=img*255

plt.imshow(img, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156c93f5ec8>
```



```
'''
If gradient more than threshold, they are all strong edge points
```

```

If gradient less than threshold, no edge point
In between is unsure
Canny edge decides which goes to which part of the threshold
'''

```

```

'\nIf gradient more than threshold, they are all strong edge points\nIf gradient less than t

```

```

# Above 150 strong edge points, below 100 no edge points

```

```

th_l = 100

```

```

th_h = 150

```

```

img = np.uint8(img)

```

```

img_canny = cv2.Canny(img,th_l,th_h)

```

```

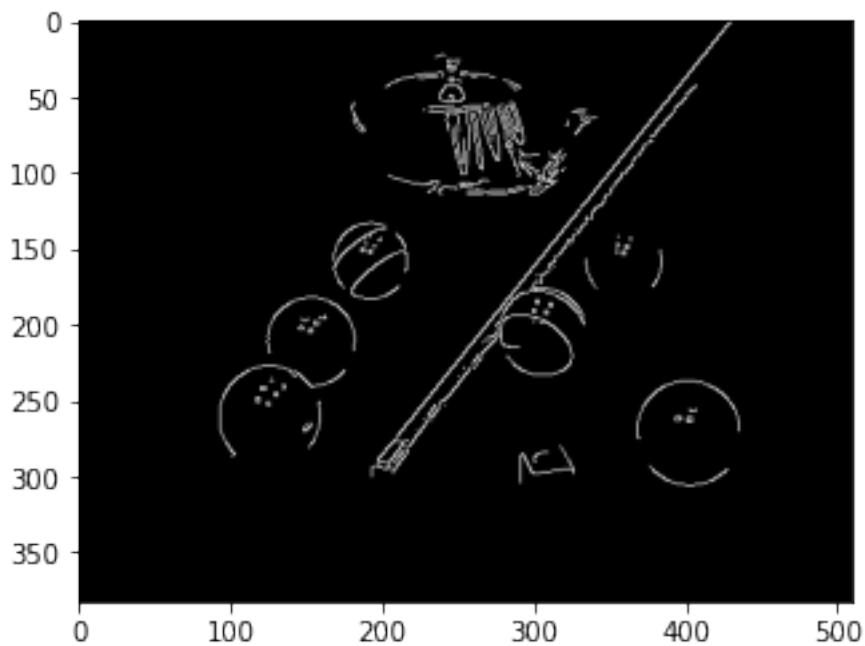
plt.imshow(img_canny, cmap = 'gray')

```

```

<matplotlib.image.AxesImage at 0x156c93c9c88>

```



```

#Display original and segmented image

```

```

plt.figure(figsize=(15,15))

```

```

plt.subplot(1,2,1)

```

```

plt.imshow(img, cmap = 'gray')

```

```

plt.title('Original Image')

```

```

plt.subplot(1,2,2)

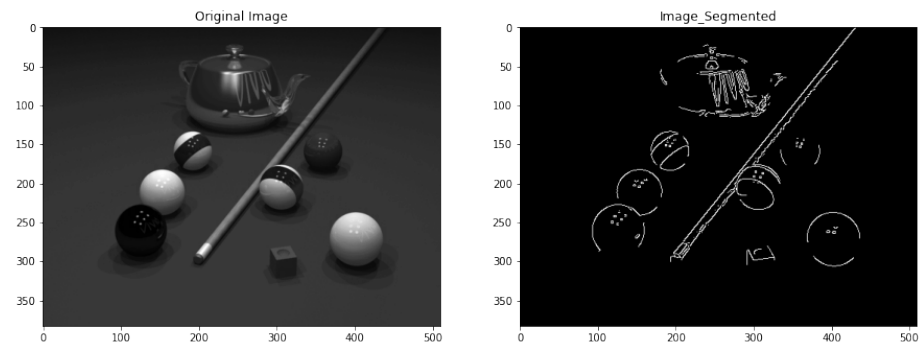
```

```

plt.imshow(img_canny, cmap = 'gray')

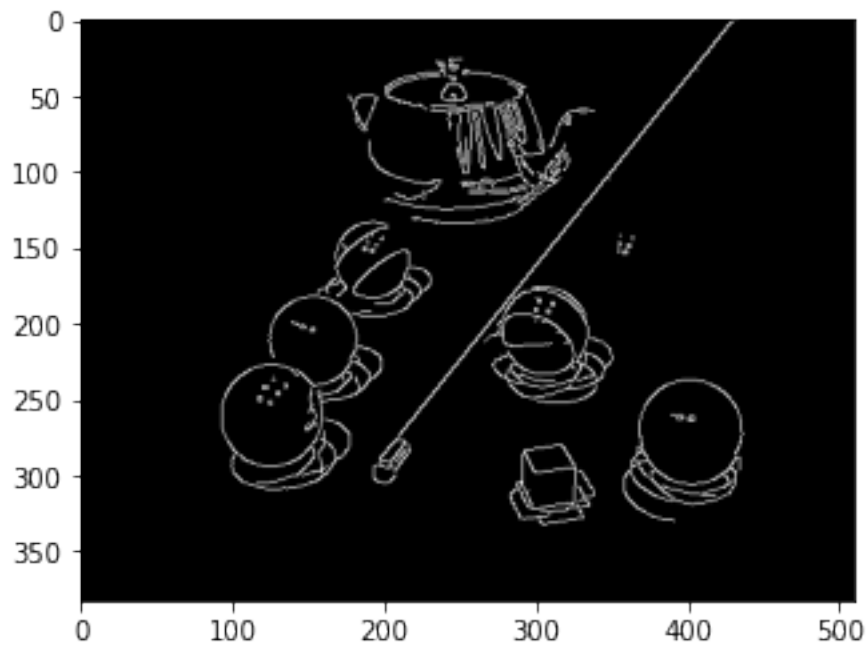
```

```
plt.title('Image_Segmented')
Text(0.5, 1.0, 'Image_Segmented')
```



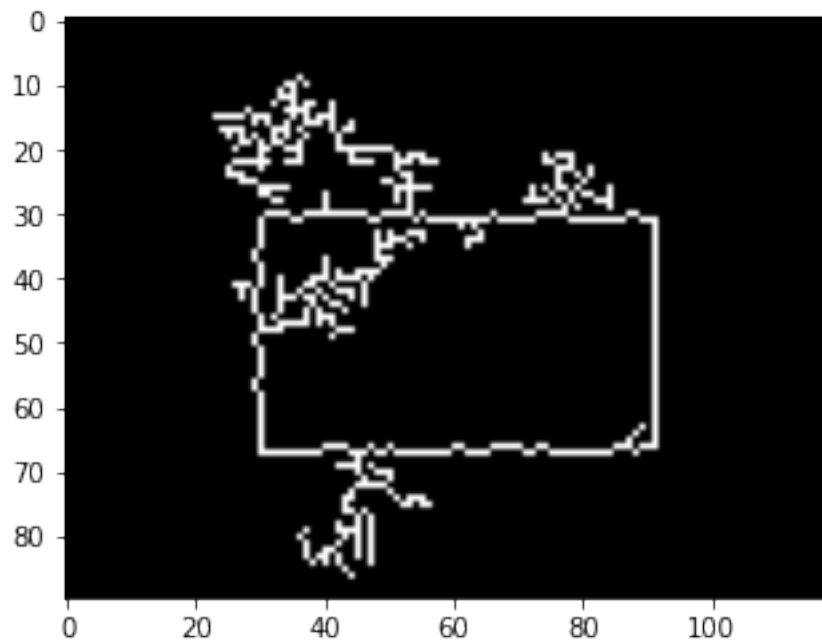
```
# Try Changing Threshold
th_l = 10
th_h = 250

img_canny = cv2.Canny(img,th_l,th_h)
plt.imshow(img_canny, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156ca737988>
```



```
image = np.uint8(image)
```

```
img_canny1 = cv2.Canny(image,th_l,th_h)
plt.imshow(img_canny1, cmap = 'gray')
<matplotlib.image.AxesImage at 0x156ca878048>
```



Conclusion

- Canny Edge Detection is applied on the image with the hysteresis range of 100 to 150.
- It is observed that not all the objects are segmented using this range.
- If this range is increased to 50 to 200, more objects can be segmented