

Fitting implicit models

$$\text{model} \Rightarrow \bar{f}(\bar{d}, \bar{p}) = \bar{0}$$

$\bar{f} = L \times 1$ relations

$\bar{d} = N \times 1$ data

$\bar{p} = M \times 1$ model parameters

Goal function

$$\Gamma(\bar{d}, \bar{p}, \bar{\lambda}) = \phi(\bar{d}) + \psi(\bar{p}) + \bar{\lambda}^T f(\bar{d}, \bar{p})$$

\nearrow Lagrange multipliers
 \nwarrow data misfit data constraints \nwarrow regularization model constraints \nwarrow forward model

$$\bar{u} = \begin{bmatrix} \bar{d} \\ \bar{\lambda} \\ \bar{p} \end{bmatrix}$$

$$\hat{\bar{u}} = \min \Gamma(\bar{u})$$

Newton's method for optimization

$$\text{Taylor series: } \Gamma'(\bar{u}) = \Gamma'(\bar{u}^0) + \underbrace{\bar{\nabla}_{\bar{u}} \Gamma'(\bar{u}^0)^T}_{\text{gradient}} \Delta \bar{u} + \frac{1}{2} \Delta \bar{u}^T \underbrace{\bar{\nabla}_{\bar{u}}^2 \Gamma'(\bar{u}^0)}_{\text{Hessian}} \Delta \bar{u} + \underbrace{O(3)}_{\text{ignore}}$$

$$\min \Gamma'(\bar{u}) \Rightarrow \bar{\nabla}_{\bar{u}} \Gamma' = \bar{0} \Rightarrow \bar{\nabla}_{\bar{u}} \Gamma'(\bar{u}^0) + \bar{\nabla}_{\bar{u}}^2 \Gamma'(\bar{u}^0) \Delta \bar{u} = \bar{0}$$

$$\bar{\nabla}_{\bar{u}}^2 \Gamma'(\bar{u}^0) \Delta \bar{u} = - \bar{\nabla}_{\bar{u}} \Gamma'(\bar{u}^0)$$

Normal equations

Repeat iteratively until convergence

Calculating the gradient

$$\bar{\nabla}_0 \Gamma = \begin{bmatrix} \bar{\nabla}_d \Gamma \\ \bar{\nabla}_\lambda \Gamma \\ \bar{\nabla}_p \Gamma \end{bmatrix}$$

$$\bar{\nabla}_\lambda \Gamma = \bar{f}(\bar{d}, \bar{p}) \Rightarrow \bar{\nabla}_\lambda \Gamma(\bar{u}^0) = \bar{f}^0$$

$$\bar{\nabla}_d \Gamma = \bar{\nabla}_d \phi + \bar{\nabla}_d \psi + \bar{\nabla}_d \bar{\lambda}^T \bar{f}(\bar{d}, \bar{p}) \Rightarrow \bar{\nabla}_d \Gamma(\bar{u}^0) = \bar{\nabla}_d \phi(\bar{u}^0) + \bar{B}(\bar{u}^0)^T \bar{\lambda}$$

$$\bar{\nabla}_d \bar{\lambda}^T \bar{f} = \bar{\nabla}_d \bar{f}^T \bar{\lambda} = \begin{bmatrix} \frac{\partial \bar{f}}{\partial d_1} \\ \frac{\partial \bar{f}}{\partial d_2} \\ \vdots \\ \frac{\partial \bar{f}}{\partial d_N} \end{bmatrix}^T \bar{\lambda} = \bar{B}^T \bar{\lambda}$$

Data Jacobian

$$\bar{\nabla}_p \Gamma = \bar{\nabla}_p \phi + \bar{\nabla}_p \psi + \bar{\nabla}_p \bar{\lambda}^T \bar{f}(\bar{d}, \bar{p}) \Rightarrow \bar{\nabla}_p \Gamma(\bar{u}^0) = \bar{\nabla}_p \psi(\bar{u}^0) + \bar{A}(\bar{u}^0)^T \bar{\lambda}$$

parameter Jacobian

Calculating the Hessian

$$\bar{\nabla}_0^2 \Gamma = \bar{H}_0$$

$$\bar{H}_0 = \begin{bmatrix} \bar{H}_d & \bar{H}_{d\lambda} & \bar{H}_{dp} \\ \bar{H}_{\lambda d} & \bar{H}_\lambda & \bar{H}_{\lambda p} \\ \bar{H}_{pd} & \bar{H}_{p\lambda} & \bar{H}_p \end{bmatrix} \Rightarrow \bar{H}_{dp}^T = \bar{H}_{pd} \Rightarrow \begin{bmatrix} \bar{H}_d & \bar{H}_{d\lambda} & \bar{H}_{dp} \\ \bar{H}_{d\lambda}^T & \bar{H}_\lambda & \bar{H}_{\lambda p} \\ \bar{H}_{dp}^T & \bar{H}_{\lambda p}^T & \bar{H}_p \end{bmatrix}$$

$$\bar{H}_d \Rightarrow N \times N$$

$$\bar{H}_{d\lambda} \Rightarrow N \times L$$

$$\bar{H}_p \Rightarrow M \times M$$

$$\bar{H}_{dp} \Rightarrow N \times M$$

$$\bar{H}_\lambda \Rightarrow L \times L$$

$$\bar{H}_{\lambda p} \Rightarrow L \times M$$

$$\bar{H}_\lambda = \bar{0} \quad \text{since } \Gamma \text{ is linear with } \bar{\lambda}$$

$$\bar{H}_{d\lambda} = \bar{\nabla}_d [\bar{\nabla}_\lambda \Gamma^T] = \bar{\nabla}_d \bar{F}^T = \begin{bmatrix} \frac{\partial \bar{F}^T}{\partial d_1} \\ \vdots \\ \frac{\partial \bar{F}^T}{\partial d_n} \end{bmatrix} = \bar{B}^T$$

$$\bar{H}_{p\lambda} = \bar{\nabla}_p [\bar{\nabla}_\lambda \Gamma^T] = \bar{\nabla}_p \bar{F}^T = \bar{A}^T$$

$$\bar{H}_{d\phi} = \bar{\nabla}_d [\bar{\nabla}_\phi \Gamma^T] = \bar{\nabla}_d \cancel{\bar{\nabla}_\phi \psi^T}^0 + \bar{\nabla}_d [\bar{A}^T \bar{\lambda}]^T \approx \bar{0}$$

2nd derivatives
of $\bar{F} \Rightarrow 0$
GAUSS-Newton

$$\bar{H}_d = \bar{\nabla}_d [\bar{\nabla}_d \Gamma^T] = \bar{\nabla}_d [\bar{\nabla}_d \phi^T] + \bar{\nabla}_d \cancel{[\bar{B}^T \bar{\lambda}]^T}^0 \approx \bar{\nabla}_d \phi$$

$$\bar{H}_p = \bar{\nabla}_p [\bar{\nabla}_p \Gamma^T] = \bar{\nabla}_p [\bar{\nabla}_p \psi^T] + \bar{\nabla}_p \cancel{[\bar{A}^T \bar{\lambda}]^T}^0 \approx \bar{\nabla}_p \psi$$

Normal equations

system 1

$$\begin{bmatrix} \bar{H}_d & \bar{B}^T & \bar{0} \\ \bar{B} & \bar{0} & \bar{A} \\ \bar{0} & \bar{A}^T & \bar{H}_p \end{bmatrix} \begin{bmatrix} \Delta d \\ \Delta \lambda \\ \Delta p \end{bmatrix} + \begin{bmatrix} \bar{\nabla}_d \phi + \bar{B}^T \bar{\lambda} \\ \bar{F} \\ \bar{\nabla}_p \psi + \bar{A}^T \bar{\lambda} \end{bmatrix} = \begin{bmatrix} \bar{0} \\ \bar{0} \\ \bar{0} \end{bmatrix}$$

$$\hookrightarrow \begin{bmatrix} \bar{A} & \bar{B} \\ \bar{C} & \bar{D} \end{bmatrix} \begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix} + \begin{bmatrix} \bar{u} \\ \bar{v} \end{bmatrix} = \begin{bmatrix} \bar{o} \\ \bar{o} \end{bmatrix} \Rightarrow [\bar{D} - \bar{C} \bar{A}^{-1} \bar{B}] \bar{y} + \bar{v} - \bar{C} \bar{A}^{-1} \bar{u} = \bar{o}$$

$$\begin{bmatrix} \bar{0} & \bar{A} \\ \bar{A}^T & \bar{H}_p \end{bmatrix} - \begin{bmatrix} \bar{B} \\ \bar{0} \end{bmatrix} \bar{H}_d^{-1} \begin{bmatrix} \bar{B}^T & \bar{0} \end{bmatrix} \begin{bmatrix} \Delta \bar{\lambda} \\ \Delta \bar{p} \end{bmatrix} + \begin{bmatrix} \bar{f} \\ \bar{\nabla}_p \psi + \bar{A}^T \bar{\lambda} \end{bmatrix} - \begin{bmatrix} \bar{B} \\ \bar{0} \end{bmatrix} \bar{H}_d^{-1} (\bar{\nabla}_d \phi + \bar{B}^T \bar{\lambda}) = \begin{bmatrix} \bar{0} \\ \bar{0} \end{bmatrix}$$

system 2

$$\left[\begin{array}{c|c} -\bar{B} \bar{H}_d^{-1} \bar{B}^T & \bar{A} \\ \hline \bar{A}^T & \bar{H}_p \end{array} \right] \begin{bmatrix} \Delta \bar{\lambda} \\ \Delta \bar{p} \end{bmatrix} + \begin{bmatrix} \bar{f} - \bar{B} \bar{H}_d^{-1} \bar{\nabla}_d \phi - \bar{B} \bar{H}_d^{-1} \bar{B}^T \bar{\lambda} \\ \bar{\nabla}_p \psi + \bar{A}^T \bar{\lambda} \end{bmatrix} = \begin{bmatrix} \bar{0} \\ \bar{0} \end{bmatrix}$$

$$\left[\bar{H}_p + \bar{A}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} \bar{A} \right] \Delta \bar{p} + \bar{\nabla}_p \psi + \bar{A}^T \bar{\lambda} + \bar{A}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} [\bar{f} - \bar{B} \bar{H}_d^{-1} \bar{\nabla}_d \phi - \bar{B} \bar{H}_d^{-1} \bar{B}^T \bar{\lambda}] = \bar{0}$$

$$\left[\bar{H}_p + \bar{A}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} \bar{A} \right] \Delta \bar{p} + \bar{\nabla}_p \psi + \cancel{\bar{A}^T \bar{\lambda}} + \bar{A}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} [\bar{f} - \bar{B} \bar{H}_d^{-1} \bar{\nabla}_d \phi] - \cancel{\bar{A}^T \bar{\lambda}} = \bar{0}$$

$$\left[\bar{H}_p + \bar{A}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} \bar{A} \right] \Delta \bar{p} = \bar{A}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} [\bar{B} \bar{H}_d^{-1} \bar{\nabla}_d \phi - \bar{f}] - \bar{\nabla}_p \psi$$

solution for $\Delta \bar{p}$

Go back to system 2 to solve for $\Delta \bar{\lambda}$

$$-\bar{B} \bar{H}_d^{-1} \bar{B}^T \Delta \bar{\lambda} + \bar{A} \Delta \bar{p} + \bar{f} - \bar{B} \bar{H}_d^{-1} \bar{\nabla}_d \phi - \bar{B} \bar{H}_d^{-1} \bar{B}^T \bar{\lambda} = \bar{0}$$

$$\Delta \bar{\lambda} = [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} [\bar{A} \Delta \bar{p} + \bar{f} - \bar{B} \bar{H}_d^{-1} \bar{\nabla}_d \phi] - \bar{\lambda}$$

Go back to system 1 to solve for $\Delta \bar{d}$

$$\bar{H}_d \Delta \bar{d} + \bar{B}^T \Delta \bar{\lambda} + \bar{0} \Delta \bar{p} + \bar{\nabla}_d \phi + \bar{B}^T \bar{\lambda} = \bar{0}$$

$$\bar{H}_d \Delta \bar{d} + \bar{B}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} [\bar{A} \Delta \bar{p} + \bar{f} - \bar{B} \bar{H}_d^{-1} \bar{\nabla}_d \phi] - \cancel{\bar{B}^T \bar{\lambda}} + \bar{\nabla}_d \phi + \cancel{\bar{B}^T \bar{\lambda}} = \bar{0}$$

$$\bar{H}_d \Delta \bar{d} + \bar{B}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} [\bar{A} \Delta \bar{p} + \bar{f}] + [\bar{I} - \bar{B}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} \bar{B} \bar{H}_d^{-1}] \bar{\nabla}_d \phi = \bar{0}$$

$$\Delta \bar{d} = \bar{H}_d^{-1} \left[[\bar{B}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} \bar{B} \bar{H}_d^{-1} - \bar{I}] \bar{\nabla}_d \phi - \bar{B}^T [\bar{B} \bar{H}_d^{-1} \bar{B}^T]^{-1} [\bar{A} \Delta \bar{p} + \bar{f}] \right]$$