## Fitting implicit models

model=) 
$$f(\bar{d}, \bar{p}) = \bar{0}$$
  $f = L \times l$  relations  $\bar{d} = N \times l$  data  $\bar{p} = M \times l$  model parameters

Agrange multipliers

$$\Gamma(\bar{a},\bar{p},\bar{\lambda}) = \phi(\bar{a}) + \psi(\bar{p}) + \bar{\lambda}^{T} f(\bar{a},\bar{p})$$

Resubstitation forward model constraints model

$$\bar{U} = \begin{bmatrix} \bar{d} \\ \bar{\lambda} \\ \bar{\gamma} \end{bmatrix} \qquad \hat{C} = \min \Gamma(\bar{z})$$

Newton's method for optimization

Taylor servics: 
$$\Gamma(\bar{v}) = \Gamma(\bar{v}) + V_0 \Gamma(\bar{v}) \Delta v + 1 \Delta v^{T} = 0$$

Hessian

 $\min \Gamma'(5) \Rightarrow \overline{\nabla}_0 \Gamma' = \overline{0} \Rightarrow \overline{\nabla}_0 \Gamma(\overline{0}^\circ) + \overline{\overline{\nabla}}_0 \Gamma(\overline{0}^\circ) \overline{\Delta 0} = \overline{0}$ 

Repeat iteratively until

$$\underline{\triangle}^{\lambda} L = \underline{f}(\underline{q},\underline{b}) \Rightarrow \underline{\underline{b}}^{\lambda} L(\underline{o},\underline{o}) = \underline{f},$$

$$\overline{\mathbb{V}}_{d} \Gamma = \overline{\mathbb{V}}_{d} \phi + \overline{\mathbb{V}}_{d} \phi + \overline{\mathbb{V}}_{d} \overline{\lambda}^{\dagger} \overline{F}(\overline{a}_{i}\overline{p}) = \overline{\mathbb{V}}_{d} \Gamma(\overline{v}^{\circ}) = \overline{\mathbb{V}}_{d} \phi(\overline{v}^{\circ}) + \overline{\mathbb{B}}(\overline{v}^{\circ})^{\dagger} \overline{\lambda}$$

$$\overline{V}_{d} \overline{\lambda}^{T} = \overline{V}_{d} f^{T} \overline{\lambda} = \begin{bmatrix} \overline{\partial f} \\ \overline{\partial d} \\ \overline{\partial f} \\ \overline{\partial d} \\ \overline{\partial f} \end{bmatrix} = \overline{B}^{T} \overline{\lambda}$$

Data Jacobi an

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Jacobia

Calculating the Hessian

$$\nabla = \bar{\bar{H}}$$

$$\frac{1}{H_{0}} = \begin{bmatrix} \frac{1}{H_{0}} & \frac{1}{H_{0}} & \frac{1}{H_{0}} \\ \frac{1}{H_{0}} & \frac{1}{H_{0}} & \frac{1}{H_{0}} \\ \frac{1}{H_{0}} & \frac{1}{H_{0}} & \frac{1}{H_{0}} \end{bmatrix} \Rightarrow \frac{1}{H_{0}} = \frac{1}{H_{0}} \Rightarrow \begin{bmatrix} \frac{1}{H_{0}} & \frac{1}{H_{0}} & \frac{1}{H_{0}} \\ \frac{1}{H_{0}} & \frac{1}{H_{0}} & \frac{1}{H_{0}} \\ \frac{1}{H_{0}} & \frac{1}{H_{0}} & \frac{1}{H_{0}} \end{bmatrix}$$

$$\frac{1}{H_{A}} = 0 \quad \text{since} \quad \nabla_{1} \text{ Incore with } \lambda$$

$$\frac{1}{H_{A}} = \nabla_{1} \left[ \nabla_{1} \nabla_{1} \nabla_{1} \right] = \nabla_{1} \left[ \nabla_{1} \nabla_{1} \nabla_{1} \right] = 0$$

$$\frac{1}{H_{A}} = \nabla_{2} \left[ \nabla_{1} \nabla_{1} \nabla_{1} \nabla_{1} \right] = 0$$

$$\frac{1}{H_{A}} = \nabla_{2} \left[ \nabla_{1} \nabla_{1} \nabla_{1} \nabla_{1} \nabla_{1} \nabla_{2} \nabla_{1} \nabla_{2} \nabla_{1} \nabla_{2} \nabla_{1} \nabla_{2} \nabla_$$

$$\overline{H}_{dp} = \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{q} \overline{\mathbb{A}}_{p} \right]^{+} \approx \overline{\underline{\mathbb{Q}}}_{d}$$
of  $\overline{\mathbb{A}}_{p} = \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{q} \overline{\mathbb{A}}_{p} \right]^{+} \approx \overline{\underline{\mathbb{Q}}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{q} \overline{\mathbb{A}}_{p} \right]^{+} \approx \overline{\underline{\mathbb{Q}}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{q} \overline{\mathbb{A}}_{p} \right]^{+} \approx \overline{\underline{\mathbb{Q}}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{A}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}}_{d} \left[ \overline{\mathbb{Q}}_{p} \Gamma^{+} \right] = \overline{\mathbb{Q}}_{d} \overline{\mathbb{Q}}_{p} \psi^{+} + \overline{\mathbb{Q}$ 

$$\overline{H}_{d} = \overline{\nabla}_{d} \left[ \overline{\nabla}_{d} \nabla^{T} \right] = \overline{\nabla}_{d} \left[ \overline{\nabla}_{d} \phi^{T} \right] + \overline{\nabla}_{d} \left[ \overline{E}^{T} \overline{\lambda} \right]^{T} \approx \overline{\nabla}_{d} \phi$$

$$\bar{H}_{p} = \bar{\nabla}_{p} \left[ \bar{\nabla}_{p} \Gamma^{T} \right] = \bar{\nabla}_{p} \left[ \bar{\nabla}_{p} \Psi^{T} + \bar{\nabla}_{p} \chi^{A} \bar{\lambda} \right]^{T} \approx \bar{\nabla}_{p} \Psi$$

Normal equations

system 1

$$\begin{bmatrix}
\bar{A}d & \bar{B}^{\dagger} & \bar{0} \\
\bar{B} & \bar{0} & \bar{A}
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 $\Delta_d = \overline{H}_a \left[ \left[ \overline{B}^T \left[ \overline{B} \, \overline{H}_a \, \overline{B}^T \right] \, \overline{B} \, \overline{H}_a \, \overline{B}^T \right] \, \overline{B} \, \overline{H}_a \, \overline{B}^T \left[ \overline{B} \, \overline{H}_a \, \overline{B}^T \right] \left[ \overline{A} \, \overline{A}_P + \overline{F} \right] \right]$ 

Regulating the step size 
$$\Delta \bar{v}$$
 $\Gamma(\bar{v}) = \Gamma(\bar{v}_0) + \bar{V}_0 \Gamma(\bar{v}_0) \Delta \bar{v} + \Delta \bar{v}^T \bar{V}_0 \Gamma(\bar{v}_0) \Delta \bar{v} + \Delta \bar{v}^T \bar{V}_0 \bar{V}_0 \Delta \bar{v}$ 
 $\Delta \bar{v}$ 

Regulating the step size  $\Delta \bar{v}$ 
 $\Delta \bar{v}$ 
 $\Delta \bar{v}$ 

$$\overline{\nabla}_{0} \overline{\Gamma} = \overline{\nabla} \Gamma(\overline{0}_{0}) + \overline{\overline{\nabla}} \Gamma(\overline{0}_{0}) \delta u + \alpha \overline{W}_{0} \delta \overline{0} = \overline{\overline{\nabla}} \Gamma(\overline{0}_{0}) + \overline{\overline{\nabla}} \Gamma(\overline{0}_{0}) + \alpha \overline{W}_{0} \overline{\overline{\Delta}} \overline{0} = \overline{0}$$

Normal equations

$$\begin{bmatrix}
\ddot{H}_{al} & \ddot{B}^{T} & \ddot{O} \\
\ddot{B} & \ddot{O} & \ddot{A}
\end{bmatrix} + \begin{bmatrix}
\alpha \ddot{W}_{al} & \ddot{O} & \ddot{O} \\
\ddot{O} & \ddot{O} & \ddot{O}
\end{bmatrix} \begin{bmatrix}
\Delta d \\
\ddot{D}\lambda
\end{bmatrix} + \begin{bmatrix}
\nabla_{a}\phi + \ddot{B}^{T}\lambda \\
\ddot{F}
\end{bmatrix} = \begin{bmatrix}
\ddot{O} \\
\ddot{O}
\end{bmatrix}$$

$$\begin{bmatrix}
\ddot{A}\phi + \ddot{B}^{T}\lambda \\
\ddot{F}
\end{bmatrix} = \begin{bmatrix}
\ddot{O} \\
\ddot{O}
\end{bmatrix}$$

$$\left[\bar{A}^{T}\left[\bar{B}\left[\bar{H}_{d}+\alpha\bar{W}_{d}\right]\bar{B}^{T}\right]\bar{A}+\bar{H}_{p}+\alpha\bar{W}_{p}\right]\Delta_{p}=\bar{A}^{T}\left[\bar{B}\left[\bar{H}_{d}+\alpha\bar{W}_{d}\right]\bar{B}^{T}\right]\left[\bar{B}\left[\bar{H}_{d}+\alpha\bar{W}_{d}\right]\bar{\nabla}_{q}\phi-\bar{F}\right]-\bar{\nabla}_{p}\phi$$

$$\left[ \bar{\bar{B}} \left[ \bar{\bar{H}}_{d} + \alpha \bar{\bar{W}}_{d} \right] \bar{\bar{B}}^{\dagger} \right]^{-1} = \bar{\bar{Q}} \Rightarrow \left[ \bar{\bar{A}}^{\dagger} \bar{\bar{Q}} \bar{\bar{A}} + \bar{\bar{H}}_{p} + \alpha \bar{\bar{W}}_{p} \right] \bar{\Delta p} = \bar{\bar{A}}^{\dagger} \bar{\bar{Q}} \left[ \bar{\bar{B}} \left[ \bar{\bar{H}}_{d} + \alpha \bar{\bar{W}}_{d} \right] \bar{\bar{V}}_{d} \phi - \bar{\bar{F}} \right] - \bar{\bar{V}}_{p} \Psi$$