# Nicholas **Nadeau**

PROFESSIONAL ENGINEER (P.ENG.), DOCTOR OF PHILOSOPHY (PH.D.)

Montréal, Canada

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## **Education**

#### École de technologie supérieure

Montréal, Canada

PhD - Precision and Collaborative Robotics

2014 - 2019

- Thesis: Towards the Development of Safe, Collaborative Robotic Freehand Ultrasound
- Created machine learning models and genetic algorithms for physical human-robot interaction.
- Invented a novel, robust, low-cost robot calibration platform.

McGill University

Montréal, Canada

B.Eng. - Mechanical Engineering, Biomedical Engineering Minor

2010 - 2014

**Dawson College** 

Montréal, Canada

**DEC - HONOURS HEALTH SCIENCE** 

2008 - 2010

### Work

AON3D Montréal, Canada

ENGINEERING MANAGER 2019 -

- · Head of software and hardware engineering, and member of executive team.
- · Oversee the design, development, testing, and deployment of innovative solutions for challenging problems in the additive manufacturing domain.
- Ensure robust, scalable, reusable, efficient, production-quality software and hardware is being delivered to the organization.
- Usher and evangelize adoption of engineering best-practices and agile methodologies.
- Set the roadmap and budgets, drive detailed planning, and ensure execution of deliverables for a medium sized team.
- Manage the company-wide SR&ED program.
- · Mentor and help bringing up of new team members, interviewing and hiring of new team members, ensure technical development of team.

AON3D Montréal, Canada

SENIOR R&D ENGINEER 2018 - 2019

- Responsible for innovation and technology development to drive 10x revenue.
- Introduced automated data collection framework to help drive business and engineering decisions.
- Engineering ScrumMaster, responsible for ensuring the team has everything they need to deliver value.

YPC Technologies Montréal, Canada

TECHNOLOGY ADVISOR TO THE CEO 2017 - 2018

- · Advised CEO throughout FounderFuel startup accelerator in order to go to market and raise seed capital.
- · Led a team of engineers and directed robotics and software design, development, and implementation.
- Recommended long-term approach to strategic suppliers and technologies with the aim of optimizing operations and delivering savings.

Rogue Research Inc. Montréal, Canada

**R&D Engineer** 2011 - 2018

- · Led mechanical research, design, and development of brain imaging, cognitive neuroscience, and robotic products.
- Led the development of a novel robotic veterinary neurosurgery system, including trajectory generation algorithms, computer vision, and hardware design
- Developed devices and systems for transcranial magnetic stimulation (TMS), near infrared spectroscopy (NIRS), deep brain stimulation (DBS), and image-based neuronavigation.

# **Certifications & Professional Affiliations**

**Professional Engineer (P.Eng.)** Ordre des ingénieurs du Québec (OIQ) **Associate Value Specialist (AVS)** SAVE International

Committee F42 on Additive Manufacturing Technologies ASTM International

**Open Water Diver** Professional Association of Diving Instructors (PADI)

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## **Publications**

#### Towards the development of safe, collaborative robotic freehand ultrasound

Nicholas A. Nadeau. École de technologie supérieure.

#### **Pybotics: Python Toolbox for Robotics**

NICHOLAS A. NADEAU. THE JOURNAL OF OPEN SOURCE SOFTWARE.

#### Impedance Control Self-Calibration of a Collaborative Robot Using Kinematic Coupling

NICHOLAS A. NADEAU, ILIAN A. BONEV. MDPI ROBOTICS.

#### **Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**

NICHOLAS A. NADEAU, ILIAN A. BONEV. IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS (IROS).

#### An Extrinsic Dexterity Approach to the IROS 2018 Fan Robotic Challenge Modality B

JENNIFER KWIATKOWSKI, JEAN-PHILIPPE ROBERGE, NICHOLAS A. NADEAU, LOUIS L'ÉCUYER-LAPIERRE, VINCENT DUCHAINE. IEEE/RSJ

INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS (IROS).

#### Characterization of a robotic micro-surgical system for small-animal neurosurgery

NICHOLAS A. NADEAU, ALEXANDRU CIOBANU, FRED LAMER, MATHIEU COURSOLLE, SEAN MCBRIDE, STEPHEN FREY, ROCH COMEAU.

SOCIETY FOR NEUROSCIENCE.

# **Professional Development**

2020-03	Colombia Recruiting Mission, VanHack	Medellin, Colombia
2020-02	3nd ASTM Additive Manufacturing Center of Excellence Workshop, ASTM International	El Paso, USA
2019-11	Formnext 2019,	Frankfurt, Germany
2019-09	2nd ASTM Additive Manufacturing Center of Excellence Workshop, ASTM International	Senlis, France
2019-05	<b>RAPID + TCT 2019</b> , SME	Detroit, USA
2018-10	2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), IEEE	Madrid, Spain
2017-11	Neuroscience 2017, Society for Neuroscience	Washington, USA
2017-01	MUSE 1.0 Bedside Ultrasound Course for Primary Care Clinicians, McGill University Steinberg Centre for	Montráal Canada
	Simulation and Interactive Learning	Montréal, Canada
2016-11	Neuroscience 2016, Society for Neuroscience	San Diego, USA
2016-05	Collaborative Robots Workshop, RIA International	Boston, USA
2013-06	OHBM 2013, Organization for Human Brain Mapping	Seattle, USA

## Volunteer\_

2020 -	Mentor.	FounderFuel	Startup Accelerator

- 2020 Member of Technical Expert Panel & Mentor, Code Life Ventilator Challenge for COVID-19
- 2020 **Reviewer**, Sensors
- 2019 Reviewer, Journal of Applied Mathematical Modelling
- 2019 **Reviewer**, International Journal of Advanced Robotic Systems (IJARS)
- 2018 **Reviewer**, The Journal of Open Source Software (JOSS)
- 2013 2014 **Communications Administrator**, Interaction du quartier Peter-McGill
- 2011 2014 Discover McGill and Orientation Week Leader, McGill University
- 2012 2013 Treasurer and Communications Administrator, Forum Jeunesse Centre-ville
- 2009 2011 Volunteer Math and Science Teacher, Innovation Jeunes

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# Talks\_\_\_\_\_

2020-04	Speaker - Making Materials Matter, Dyndrite Developer Conference 2020
2018-10	Speaker-Evolutionary Motion Control Optimization in Physical Human-Robot Interaction, 2018~IEEE/RSJ
	International Conference on Intelligent Robots and Systems (IROS)
2017-11	Speaker - Calibrating Robots with Python, PyCon Canada 2017
2017-10	Speaker - Calibrating Robots with Python, Montréal-Python 67
2016-12	Keynote - Robotics and Neuroscience, Clearpoint Elementary Exhibition Summit
2015-06	Speaker - Medical Robotics, McGill Faculty of Medicine Explore Camp
2014-05	Keynote, Riverdale High School Career Seminar
2014-02	Keynote, Riverdale High School Career Seminar
2013-05	Keynote, Lester B. Pearson School Board Science Showcase

## Awards \_\_\_\_\_

2015	Alexander Graham Bell Canada Graduate Scholarship, NSERC
2014	Mitacs Accelerate Industrial Research Grant, Mitacs
2014	Graduation Honours, McGill University
2013	Québec Iron Titanium Scholarship, McGill University
2013	Abe and Jennie Brock Award, McGill University
2013	Dean's Honour List, McGill University
2013	Industrial Undergraduate Research Award, NSERC
2012	Industrial Undergraduate Research Award, NSERC
2011	Industrial Undergraduate Research Award, NSERC
2011	Golden Key International Honour Society, McGill University
2010	First Class Graduation Honours, Dawson College
2010	Athletic Academic Achievement Award, Dawson College

# Skills\_\_\_\_\_

Languages	English, French	
Software	re Illustrator, Linux, MS Office, Photoshop, SolidWorks, Ubuntu, Window	
DevOps	CircleCI, Docker, GitLab CI/CD, Travis CI,	
Back-end	Flask, Protocol Buffers (protobuf), REST API	
Front-end	HTML5, Hugo, React	
Programming	C/C++, Java, JavaScript, LaTeX, Node.js, Python, TypeScript	
<b>Machine Learning</b>	Keras, OpenCV, scikit-learn, TensorFlow	
<b>Source Control</b>	Git, Subversion (SVN)	

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