

PROFESSIONAL ENGINEER (P.ENG.), DOCTOR OF PHILOSOPHY (PH.D.)

Montréal, Canada

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Work_

Halodi Robotics Montréal, Canada & Oslo, Norway

CTO 2021-

- · Spearheaded the development of a new humanoid robot design for security guarding.
- Successful Series A funding of \$10M with Valinor and ADT Commercial.
- Led company recruitment and growth to 50+ employees in 4 countries.
- Led pilot projects with enterprise customers leading to the single biggest contract ever for humanoid robots (140 robots to ADT Commercial).
- Led software development, team management, architecture design, and implementation of internal infrastructure.
- General manager of Halodi Robotics Canada Inc.

BRIDGR Montréal, Canada

ADVISOR 2020 -

- Expert advisor assisting with team growth, architecture, and special projects (e.g., robotics, Industry 4..0) and critical introductions.
- Mentor through the Techstars AI Montréal accelerator.

AON3D Montréal, Canada

Engineering Manager 2018 - 2021

- Head of engineering and executive team member through \$11.5M Series A with SineWave Ventures, AlleyCorp, and Y Combinator.
- Led engineering team management, software and hardware development, product direction, and certification to develop high-performance 3D printing and additive manufacturing systems.
- Responsible for Scientific Research and Experimental Development (SR&ED) Tax Incentive Program (\$300K+ in tax refunds).

Nicholas Nadeau Consulting

Montréal, Canada

FOUNDER

2017 -

· Start-up advising, specializing in R&D, team growth, and product development.

YPC Technologies Montréal, Canada

TECHNOLOGY ADVISOR TO THE CEO

2017 - 2018

- Advised CEO throughout FounderFuel startup accelerator, leading to a \$1.8M seed with Hike Ventures, Real Ventures, and Toyota Al Ventures.
- · Led a team of engineers and directed robotics and software design, development, and implementation for FounderFuel Demo Day.

Rogue Research Inc.

Montréal, Canada

R&D ENGINEER

2011 - 2018

- Led the development of a novel robotic veterinary neurosurgery system, including trajectory generation algorithms, computer vision, and hardware design.
- Developed biomedical devices and systems for transcranial magnetic stimulation (TMS), near-infrared spectroscopy (NIRS), deep brain stimulation (DBS), and image-based neuronavigation.

Education

École de technologie supérieure

Montréal, Canada

Ph.D. - Precision and Collaborative Robotics

2014 - 2019

- Thesis: Towards the Development of Safe, Collaborative Robotic Freehand Ultrasound
- Development of AI/ML models and algorithms for physical human-robot interaction, controller tuning, and robot calibration.
- Creator of *Pybotics*, a published open-source Python toolbox for robotics calibration, kinematics, ML/Al, and optimization.

McGill University Montréal, Canada

B.Eng. - Mechanical Engineering, Biomedical Engineering Minor 2010 - 2014

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Skills & Certifications

Certifications Associate Value Specialist (SAVE International), Open Water Diver (PADI), Professional Engineer (Ordre des ingénieurs du Québec)

Productivity Confluence, GitHub, GitLab, Jira

Hardware KiCAD, SOLIDWORKS

Software Balena, CMake, Docker, Flask, Gradle, gRPC, Linux, Make, PyTorch, REST API, ROS, TensorFlow, Yocto

Programming C/C++, Java, LaTeX, Node.js, Python

Languages English, French

Recent Publications

Improved Test Methods for Polymer AM Inter-Layer Weld Strength and Filament Mechanical Properties,

2020 Richard G. Cole, Kazem Fayazbakhsh, Abraham Avalos, Nicholas A. Nadeau. ASTM International Conference on Additive Manufacturing (ICAM).

Towards the development of safe, collaborative robotic freehand ultrasound, Nicholas A. Nadeau. École de technologie supérioure

2019 technologie supérieure.

Pybotics: Python Toolbox for Robotics, Nicholas A. Nadeau. The Journal of Open Source Software.

Impedance Control Self-Calibration of a Collaborative Robot Using Kinematic Coupling, Nicholas A. Nadeau,

2019 Ilian A. Bonev. MDPI Robotics.

Evolutionary Motion Control Optimization in Physical Human-Robot Interaction, Nicholas A. Nadeau, Ilian A.

2018 Bonev. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).

An Extrinsic Dexterity Approach to the IROS 2018 Fan Robotic Challenge Modality B, Jennifer Kwiatkowski,

Jean-Philippe Roberge, Nicholas A. Nadeau, Louis L'Écuyer-Lapierre, Vincent Duchaine. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).

Characterization of a robotic micro-surgical system for small-animal neurosurgery, Nicholas A. Nadeau,

Alexandru Ciobanu, Fred Lamer, Mathieu Coursolle, Sean McBride, Stephen Frey, Roch Comeau. Society for

Neuroscience.

Recent Talks_

2017

2022-01	Careers in	Robotics,	Dallas ISD	STEM Expo
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- 2021-10 Let's talk robotics with Dr. Nicholas Nadeau!, Let's Talk Robotics Podcast
- 2021-10 Pitch: Halodi Robotics, Déclic Techno: Rendez-vous des startups et industrie de l'électronique
- 2021-10 Safe and Capable Robots, IEEE-EMBS Robotics Webinar
- 2021-04 Hiring for Inclusive Robotics, Silicon Valley Robotics Society, Robots, and Us
- 2021-04 Hardware in the Loop: Training Robot Contact in an Unstructured Environment, Montréal-Python 85
- 2020-04 Making Materials Matter, Dyndrite Developer Conference 2020

Evolutionary Motion Control Optimization in Physical Human-Robot Interaction, 2018 IEEE/RSJ International

Conference on Intelligent Robots and Systems (IROS)

2017-11 Calibrating Robots with Python, PyCon Canada 2017

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Volunteer & Committees _____

2022	Startup Mentor, Next Al
2022	Startup Mentor, Creative Destruction Lab (CDL)
2021	Technical Committee ISO/TC 299 - Robotics, Standards Council of Canada Mirror Committee
2020	Mentor, Techstars Montréal AI Accelerator
2020	Mentor, FounderFuel Startup Accelerator
2020	Member of Technical Expert Panel & Mentor, Code Life Ventilator Challenge for COVID-19
2020	Reviewer, Sensors, MDPI
2019	Reviewer, Journal of Applied Mathematical Modelling
2019	Reviewer, International Journal of Advanced Robotic Systems (IJARS)
2018	Committee F42 on Additive Manufacturing Technologies, ASTM International
2018	Reviewer The Journal of Open Source Software (JOSS)

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