Nicholas **Nadeau**

PROFESSIONAL ENGINEER (P.Eng.), DOCTOR OF PHILOSOPHY (PH.D.)

Montréal, Canada

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Work.

Halodi Robotics Montréal, Canada & Oslo, Norway

CTO 2021 -

- Led the development of a new humanoid robot design for security guarding.
- Led company recruitment and growth to 50+ employees in 4 countries.
- Led pilot projects with enterprise customers leading to the single biggest contract ever for humanoid robots (140 robots to ADT Commercial).
- · Led software development, team management, architecture design, and implementation of internal infrastructure.
- Successful Series A funding of \$10M with Valinor and ADT Commercial.
- General manager of Halodi Robotics Canada Inc.

BRIDGR Montréal, Canada

ADVISOR 2020 -

- Expert advisor assisting with team growth, architecture, and special projects (e.g., robotics, Industry 4..0) and critical introductions.
- Mentor through the Techstars AI Montréal accelerator.

AON3D Montréal, Canada

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- Head of engineering and executive team member through \$11.5M Series A with SineWave Ventures, AlleyCorp, and Y Combinator.
- Led engineering team management, software and hardware development, product direction, and certification to develop high-performance 3D printing and additive manufacturing systems.
- · Responsible for Scientific Research and Experimental Development (SR&ED) Tax Incentive Program (\$300K+ in tax refunds).

Nadeau Innovations Montréal, Canada

FOUNDER 2017 -

Provide fractional CTO services, technical development, roadmap planning and strategy, and team building support.

YPC Technologies Montréal, Canada

TECHNOLOGY ADVISOR TO THE CEO

ENGINEERING MANAGER

• Advised CEO throughout FounderFuel startup accelerator, leading to a \$1.8M seed with Hike Ventures, Real Ventures, and Toyota Al Ventures.

· Led a team of engineers and directed robotics and software design, development, and implementation for FounderFuel Demo Day.

Rogue Research Inc.

Montréal, Canada

R&D ENGINEER

2011 - 2018

- Led the development of a novel robotic veterinary neurosurgery system, including trajectory generation algorithms, computer vision, and hardware design.
- Developed biomedical devices and systems for transcranial magnetic stimulation (TMS), near-infrared spectroscopy (NIRS), deep brain stimulation (DBS), and image-based neuronavigation.

Education

École de technologie supérieure

Montréal, Canada

Ph.D. - Precision and Collaborative Robotics

2014 - 2019

2010 - 2014

2018 - 2021

2017 - 2018

- Thesis: Towards the Development of Safe, Collaborative Robotic Freehand Ultrasound
- Development of AI/ML models and algorithms for physical human-robot interaction, controller tuning, and robot calibration.
- Creator of *Pybotics*, a published open-source Python toolbox for robotics calibration, kinematics, ML/AI, and optimization.

McGill University Montréal, Canada

B.Eng. - Mechanical Engineering, Biomedical Engineering Minor

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Skills & Certifications

Certifications Associate Value Specialist (SAVE International), Open Water Diver (PADI), Professional Engineer (Ordre des ingénieurs du Québec)

Engineering Confluence, GitHub, GitLab, Jira, KiCAD, SOLIDWORKS

Software Balena, CMake, Docker, Flask, Gradle, gRPC, Linux, Make, PyTorch, REST API, ROS, TensorFlow, Yocto

Programming C/C++, Java, LaTeX, Node.js, Python

Languages English, French

Recent Publications

Improved Test Methods for Polymer AM Inter-Layer Weld Strength and Filament Mechanical Properties,

- 2020 Richard G. Cole, Kazem Fayazbakhsh, Abraham Avalos, Nicholas A. Nadeau. ASTM International Conference on Additive Manufacturing (ICAM).
- Towards the development of safe, collaborative robotic freehand ultrasound, Nicholas A. Nadeau. École de technologie supérieure.
- 2019 **Pybotics: Python Toolbox for Robotics**, Nicholas A. Nadeau. The Journal of Open Source Software.
- 2019 Impedance Control Self-Calibration of a Collaborative Robot Using Kinematic Coupling, Nicholas A. Nadeau, Ilian A. Bonev. MDPI Robotics.
- 2018 **Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**, Nicholas A. Nadeau, Ilian A. Bonev. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
 - An Extrinsic Dexterity Approach to the IROS 2018 Fan Robotic Challenge Modality B, Jennifer Kwiatkowski,
- Jean-Philippe Roberge, Nicholas A. Nadeau, Louis L'Écuyer-Lapierre, Vincent Duchaine. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
 - Characterization of a robotic micro-surgical system for small-animal neurosurgery, Nicholas A. Nadeau,
- 2017 Alexandru Ciobanu, Fred Lamer, Mathieu Coursolle, Sean McBride, Stephen Frey, Roch Comeau. Society for Neuroscience.

Recent Talks

- 2022-08 Applying Key Hardware Design Considerations, Design to Product Podcast
- 2022-01 Careers in Robotics, Dallas ISD STEM Expo
- 2021-10 Let's talk robotics with Dr. Nicholas Nadeau!, Let's Talk Robotics Podcast
- 2021-10 Pitch: Halodi Robotics, Déclic Techno: Rendez-vous des startups et industrie de l'électronique
- 2021-10 Safe and Capable Robots, IEEE-EMBS Robotics Webinar
- 2021-04 Hiring for Inclusive Robotics, Silicon Valley Robotics Society, Robots, and Us
- 2021-04 Hardware in the Loop: Training Robot Contact in an Unstructured Environment, Montréal-Python 85
- 2020-04 Making Materials Matter, Dyndrite Developer Conference 2020
- Evolutionary Motion Control Optimization in Physical Human-Robot Interaction, 2018 IEEE/RSJ International
- Conference on Intelligent Robots and Systems (IROS)
- 2017-11 Calibrating Robots with Python, PyCon Canada 2017

Volunteer & Committees ____

- 2022 **Startup Mentor**, Next Al
- 2022 **Startup Mentor**, Creative Destruction Lab (CDL)
- 2021 **Technical Committee ISO/TC 299 Robotics**, Standards Council of Canada Mirror Committee
- 2020 **Mentor**, Techstars Montréal AI Accelerator
- 2020 **Mentor**, FounderFuel Startup Accelerator
- 2020 Member of Technical Expert Panel & Mentor, Code Life Ventilator Challenge for COVID-19
- 2020 **Reviewer**, Sensors, MDPI
- 2019 **Reviewer**, Journal of Applied Mathematical Modelling
- 2019 **Reviewer**, International Journal of Advanced Robotic Systems (IJARS)
- 2018 Committee F42 on Additive Manufacturing Technologies, ASTM International
- 2018 **Reviewer**, The Journal of Open Source Software (JOSS)

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