# licholas **Nadeau**

PROFESSIONAL ENGINEER (P.Eng.), DOCTOR OF PHILOSOPHY (Ph.D.)

Montréal, Canada

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#### Work

**Nadeau Innovations** Montréal, Canada

2017 -FOUNDER

- Offered fractional CTO services to advance Al/ML and robotics in startups and growth companies.
- Assisted executive teams with strategic planning and roadmaps.
- Coached managers and team leads on agile project execution and operations.

**Halodi Robotics** Montréal, Canada & Oslo, Norway

CTO

- Developed a new humanoid robot for security guarding and expanded the team to 50+ employees across 4 countries.
- Secured the largest contract ever for humanoid robots with ADT Commercial (140 robots), raised \$10M in Series A funding, and raised \$24M in Series A2 with OpenAI.
- · Managed software development, architecture design, and internal infrastructure implementation.

**BRIDGR** Montréal, Canada

**ADVISOR** 2020 -

- Provided expertise on team growth, architecture, and special projects in robotics and Industry 4.0.
- Mentored through the Techstars AI Montréal accelerator.
- Facilitated critical introductions for business development.

AON3D Montréal, Canada

**ENGINEERING MANAGER** 2018 - 2021

- Headed engineering and secured \$11.5M Series A funding for high-performance 3D printing systems.
- Directed software and hardware development, product strategy, and certification efforts.
- Managed SR&ED Tax Incentive Program, securing \$300K+ in tax refunds.

**YPC Technologies** Montréal, Canada

TECHNOLOGY ADVISOR TO THE CEO 2017 - 2018

- Advised CEO during startup accelerator, resulting in \$1.8M seed funding from top investors.
- Led engineering team for robotics and software design for FounderFuel Demo Day.
- Collaborated on strategy and execution with the CEO.

Rogue Research Inc. Montréal, Canada

**R&D ENGINEER** 

- · Developed a novel robotic veterinary neurosurgery system, including algorithms and hardware design.
- Created biomedical devices for TMS, NIRS, DBS, and image-based neuronavigation.
- · Contributed to advancements in computer vision and neuroscience.

#### Education \_

#### École de technologie supérieure

Montréal, Canada

Ph.D. - Precision and Collaborative Robotics

2014 - 2019

2011 - 2018

- Thesis: Towards the Development of Safe, Collaborative Robotic Freehand Ultrasound
- Development of AI/ML models and algorithms for physical human-robot interaction, controller tuning, and robot calibration.
- Creator of Pybotics, a published open-source Python toolbox for robotics calibration, kinematics, ML/AI, and optimization.

**McGill University** Montréal, Canada

B.Eng. - Mechanical Engineering, Biomedical Engineering Minor 2010 - 2014

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## **Skills & Certifications**

Certifications Associate Value Specialist (SAVE International), Open Water Diver (PADI), Professional Engineer (Ordre des ingénieurs du Québec)

**Engineering** Confluence, GitHub, GitLab, Jira, KiCAD, SOLIDWORKS

Software Balena, CMake, Docker, Flask, Gradle, gRPC, Linux, Make, PyTorch, REST API, ROS, TensorFlow, Yocto

**Programming** C/C++, Java, LaTeX, Node.js, Python

**Languages** English, French

#### **Recent Publications**

#### Improved Test Methods for Polymer AM Inter-Layer Weld Strength and Filament Mechanical Properties,

- 2020 Richard G. Cole, Kazem Fayazbakhsh, Abraham Avalos, Nicholas A. Nadeau. ASTM International Conference on Additive Manufacturing (ICAM).
- Towards the development of safe, collaborative robotic freehand ultrasound, Nicholas A. Nadeau. École de technologie supérieure.
- 2019 **Pybotics: Python Toolbox for Robotics**, Nicholas A. Nadeau. The Journal of Open Source Software.
- 2019 Impedance Control Self-Calibration of a Collaborative Robot Using Kinematic Coupling, Nicholas A. Nadeau, Ilian A. Bonev. MDPI Robotics.
- 2018 **Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**, Nicholas A. Nadeau, Ilian A. Bonev. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
  - An Extrinsic Dexterity Approach to the IROS 2018 Fan Robotic Challenge Modality B, Jennifer Kwiatkowski,
- Jean-Philippe Roberge, Nicholas A. Nadeau, Louis L'Écuyer-Lapierre, Vincent Duchaine. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
  - Characterization of a robotic micro-surgical system for small-animal neurosurgery, Nicholas A. Nadeau,
- 2017 Alexandru Ciobanu, Fred Lamer, Mathieu Coursolle, Sean McBride, Stephen Frey, Roch Comeau. Society for Neuroscience.

## Recent Talks

- 2022-10 The Applications of Pybotics, Seattle Robotics Society
- 2022-08 Applying Key Hardware Design Considerations, Design to Product Podcast
- 2022-01 Careers in Robotics, Dallas ISD STEM Expo
- 2021-10 Let's talk robotics with Dr. Nicholas Nadeau!, Let's Talk Robotics Podcast
- 2021-10 Safe and Capable Robots, IEEE-EMBS Robotics Webinar
- 2021-04 Hiring for Inclusive Robotics, Silicon Valley Robotics Society, Robots, and Us
- 2021-04 Hardware in the Loop: Training Robot Contact in an Unstructured Environment, Montréal-Python 85
- 2020-04 Making Materials Matter, Dyndrite Developer Conference 2020
- Evolutionary Motion Control Optimization in Physical Human-Robot Interaction, 2018 IEEE/RSJ International
- Conference on Intelligent Robots and Systems (IROS)
- 2017-11 Calibrating Robots with Python, PyCon Canada 2017

## Volunteer & Committees

- 2022 **Startup Mentor**, Next Al
- 2022 **Startup Mentor**, Creative Destruction Lab (CDL)
- 2021 **Technical Committee ISO/TC 299 Robotics**, Standards Council of Canada Mirror Committee
- 2020 **Mentor**, Techstars Montréal AI Accelerator
- 2020 **Mentor**, FounderFuel Startup Accelerator
- 2020 Member of Technical Expert Panel & Mentor, Code Life Ventilator Challenge for COVID-19
- 2020 **Reviewer**, Sensors, MDPI
- 2019 Reviewer, Journal of Applied Mathematical Modelling
- 2019 **Reviewer**, International Journal of Advanced Robotic Systems (IJARS)
- 2018 Committee F42 on Additive Manufacturing Technologies, ASTM International
- 2018 **Reviewer**, The Journal of Open Source Software (JOSS)

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