# icholas **Nadeau**

PROFESSIONAL ENGINEER (P.Eng.), DOCTOR OF PHILOSOPHY (Ph.D.)

Montréal, Canada

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#### Work

**Halodi Robotics** Montréal, Canada & Oslo, Norway

CTO

- Led the development of a new humanoid robot design for security guarding.
- Led company recruitment and growth to 50+ employees in 4 countries.
- Led pilot projects with enterprise customers leading to the single biggest contract ever for humanoid robots (140 robots to ADT Commercial).
- Led software development, team management, architecture design, and implementation of internal infrastructure.
- Successful Series A funding of \$10M with Valinor and ADT Commercial.
- General manager of Halodi Robotics Canada Inc.

**BRIDGR** Montréal, Canada

ADVISOR 2020 -

- Expert advisor assisting with team growth, architecture, and special projects (e.g., robotics, Industry 4..0) and critical introductions.
- Mentor through the Techstars AI Montréal accelerator.

AON3D Montréal, Canada

**ENGINEERING MANAGER** 2018 - 2021

- Head of engineering and executive team member through \$11.5M Series A with SineWave Ventures, AlleyCorp, and Y Combinator.
- Led engineering team management, software and hardware development, product direction, and certification to develop high-performance 3D printing and additive manufacturing systems.
- Responsible for Scientific Research and Experimental Development (SR&ED) Tax Incentive Program (\$300K+ in tax refunds).

**Nadeau Innovations** Montréal, Canada

FOUNDER 2017 -

Provide fractional CTO services, technical development, roadmap planning and strategy, and team building support.

**YPC Technologies** Montréal, Canada

**TECHNOLOGY ADVISOR TO THE CEO** 

Advised CEO throughout FounderFuel startup accelerator, leading to a \$1.8M seed with Hike Ventures, Real Ventures, and Toyota Al Ventures.

· Led a team of engineers and directed robotics and software design, development, and implementation for FounderFuel Demo Day.

Rogue Research Inc. Montréal, Canada

**R&D ENGINEER** 

2011 - 2018

- · Led the development of a novel robotic veterinary neurosurgery system, including trajectory generation algorithms, computer vision, and hardware design.
- · Developed biomedical devices and systems for transcranial magnetic stimulation (TMS), near-infrared spectroscopy (NIRS), deep brain stimulation (DBS), and image-based neuronavigation.

#### **Education**

#### École de technologie supérieure

Montréal, Canada

Ph.D. - Precision and Collaborative Robotics

2014 - 2019

2017 - 2018

- Thesis: Towards the Development of Safe, Collaborative Robotic Freehand Ultrasound
- Development of AI/ML models and algorithms for physical human-robot interaction, controller tuning, and robot calibration.
- Creator of Pybotics, a published open-source Python toolbox for robotics calibration, kinematics, ML/AI, and optimization.

**McGill University** Montréal, Canada

B.Eng. - Mechanical Engineering, Biomedical Engineering Minor 2010 - 2014

OCTOBER 13, 2022

## **Skills & Certifications**

Certifications Associate Value Specialist (SAVE International), Open Water Diver (PADI), Professional Engineer (Ordre des ingénieurs du Québec)

**Engineering** Confluence, GitHub, GitLab, Jira, KiCAD, SOLIDWORKS

**Software** Balena, CMake, Docker, Flask, Gradle, gRPC, Linux, Make, PyTorch, REST API, ROS, TensorFlow, Yocto

**Programming** C/C++, Java, LaTeX, Node.js, Python

**Languages** English, French

#### **Recent Publications**

#### Improved Test Methods for Polymer AM Inter-Layer Weld Strength and Filament Mechanical Properties,

- 2020 Richard G. Cole, Kazem Fayazbakhsh, Abraham Avalos, Nicholas A. Nadeau. ASTM International Conference on Additive Manufacturing (ICAM).
- Towards the development of safe, collaborative robotic freehand ultrasound, Nicholas A. Nadeau. École de technologie supérieure.
- 2019 **Pybotics: Python Toolbox for Robotics**, Nicholas A. Nadeau. The Journal of Open Source Software.
- 2019 Impedance Control Self-Calibration of a Collaborative Robot Using Kinematic Coupling, Nicholas A. Nadeau, Ilian A. Bonev. MDPI Robotics.
- 2018 **Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**, Nicholas A. Nadeau, Ilian A. Bonev. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
  - An Extrinsic Dexterity Approach to the IROS 2018 Fan Robotic Challenge Modality B, Jennifer Kwiatkowski,
- Jean-Philippe Roberge, Nicholas A. Nadeau, Louis L'Écuyer-Lapierre, Vincent Duchaine. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
  - Characterization of a robotic micro-surgical system for small-animal neurosurgery, Nicholas A. Nadeau,
- 2017 Alexandru Ciobanu, Fred Lamer, Mathieu Coursolle, Sean McBride, Stephen Frey, Roch Comeau. Society for Neuroscience.

## Recent Talks

- 2022-10 The Applications of Pybotics, Seattle Robotics Society
- 2022-08 Applying Key Hardware Design Considerations, Design to Product Podcast
- 2022-01 Careers in Robotics, Dallas ISD STEM Expo
- 2021-10 Let's talk robotics with Dr. Nicholas Nadeau!, Let's Talk Robotics Podcast
- 2021-10 Safe and Capable Robots, IEEE-EMBS Robotics Webinar
- 2021-04 Hiring for Inclusive Robotics, Silicon Valley Robotics Society, Robots, and Us
- 2021-04 Hardware in the Loop: Training Robot Contact in an Unstructured Environment, Montréal-Python 85
- 2020-04 Making Materials Matter, Dyndrite Developer Conference 2020
- **Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**, 2018 IEEE/RSJ International
- Conference on Intelligent Robots and Systems (IROS)
- 2017-11 Calibrating Robots with Python, PyCon Canada 2017

## Volunteer & Committees \_\_\_\_

- 2022 **Startup Mentor**, Next Al
- 2022 **Startup Mentor**, Creative Destruction Lab (CDL)
- 2021 **Technical Committee ISO/TC 299 Robotics**, Standards Council of Canada Mirror Committee
- 2020 **Mentor**, Techstars Montréal AI Accelerator
- 2020 **Mentor**, FounderFuel Startup Accelerator
- 2020 Member of Technical Expert Panel & Mentor, Code Life Ventilator Challenge for COVID-19
- 2020 **Reviewer**, Sensors, MDPI
- 2019 **Reviewer**, Journal of Applied Mathematical Modelling
- 2019 **Reviewer**, International Journal of Advanced Robotic Systems (IJARS)
- 2018 Committee F42 on Additive Manufacturing Technologies, ASTM International
- 2018 **Reviewer**, The Journal of Open Source Software (JOSS)

OCTOBER 13, 2022