Nicholas **Nadeau**

PROFESSIONAL ENGINEER (P.ENG.), DOCTOR OF PHILOSOPHY (PH.D.)

Montréal, Canada

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Work

AON3D Montréal, Canada

ENGINEERING MANAGER 2019 -

- Head of software and hardware engineering, and member of executive team.
- Oversee the design, development, testing, and deployment of innovative solutions for challenging problems in the additive manufacturing domain.
- Ensure robust, scalable, reusable, efficient, production-quality software and hardware is being delivered to the organization.
- Usher and evangelize adoption of engineering best-practices and agile methodologies.
- Set the roadmap and budgets, drive detailed planning, and ensure execution of deliverables for a medium sized team.
- Manage the company-wide SR&ED program.
- Mentor and help bringing up of new team members, interviewing and hiring of new team members, ensure technical development of team.

AON3D Montréal, Canada

SENIOR R&D ENGINEER 2018 - 2019

- Responsible for innovation and technology development to drive 10x revenue.
- Introduced automated data collection framework to help drive business and engineering decisions.
- Engineering ScrumMaster, responsible for ensuring the team has everything they need to deliver value.

YPC Technologies Montréal, Canada

TECHNOLOGY ADVISOR TO THE CEO 2017 - 2018

- · Advised CEO throughout FounderFuel startup accelerator in order to go to market and raise seed capital.
- · Led a team of engineers and directed robotics and software design, development, and implementation.
- Recommended long-term approach to strategic suppliers and technologies with the aim of optimizing operations and delivering savings.

Rogue Research Inc.

Montréal, Canada

R&D Engineer 2011 - 2018

- · Led mechanical research, design, and development of brain imaging, cognitive neuroscience, and robotic products.
- Led the development of a novel robotic veterinary neurosurgery system, including trajectory generation algorithms, computer vision, and hardware design.
- Developed devices and systems for transcranial magnetic stimulation (TMS), near infrared spectroscopy (NIRS), deep brain stimulation (DBS), and image-based neuronavigation.

Education

École de technologie supérieure

Montréal, Canada

PhD - Precision and Collaborative Robotics

2014 - 2019

- Thesis: Towards the Development of Safe, Collaborative Robotic Freehand Ultrasound
- · Created machine learning models and genetic algorithms for physical human-robot interaction.
- Invented a novel, robust, low-cost robot calibration platform.

McGill University

Montréal, Canada

B.Eng. - Mechanical Engineering, Biomedical Engineering Minor

2010 - 2014

Certifications & Professional Affiliations

Professional Engineer (P.Eng.) Ordre des ingénieurs du Québec (OIQ)

Associate Value Specialist (AVS) SAVE International

Committee F42 on Additive Manufacturing Technologies ASTM International

Open Water Diver Professional Association of Diving Instructors (PADI)

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Publications

Improved Test Methods for Polymer AM Inter-Layer Weld Strength and Filament Mechanical Properties,

- 2020 Richard G. Cole, Kazem Fayazbakhsh, Abraham Avalos, Nicholas A. Nadeau. ASTM International Conference on Additive Manufacturing (ICAM).
- **Towards the development of safe, collaborative robotic freehand ultrasound,** Nicholas A. Nadeau. École de 2019 technologie supérieure.
- **Pybotics: Python Toolbox for Robotics,** Nicholas A. Nadeau. The Journal of Open Source Software.
 - Impedance Control Self-Calibration of a Collaborative Robot Using Kinematic Coupling, Nicholas A. Nadeau,
- 2019 Ilian A. Bonev. MDPI Robotics.
- **Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**, Nicholas A. Nadeau, Ilian A.
- 2018 Bonev. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
 - An Extrinsic Dexterity Approach to the IROS 2018 Fan Robotic Challenge Modality B, Jennifer Kwiatkowski,
- Jean-Philippe Roberge, Nicholas A. Nadeau, Louis L'Écuyer-Lapierre, Vincent Duchaine. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
 - Characterization of a robotic micro-surgical system for small-animal neurosurgery, Nicholas A. Nadeau,
- Alexandru Ciobanu, Fred Lamer, Mathieu Coursolle, Sean McBride, Stephen Frey, Roch Comeau. Society for Neuroscience.

Talks_

- 2020-04 **Speaker Making Materials Matter**, Dyndrite Developer Conference 2020
- Speaker Evolutionary Motion Control Optimization in Physical Human-Robot Interaction, 2018 IEEE/RSJ
- International Conference on Intelligent Robots and Systems (IROS)
- 2017-11 **Speaker Calibrating Robots with Python**, PyCon Canada 2017
- 2017-10 Speaker Calibrating Robots with Python, Montréal-Python 67
- 2016-12 Keynote Robotics and Neuroscience, Clearpoint Elementary Exhibition Summit
- 2015-06 **Speaker Medical Robotics**, McGill Faculty of Medicine Explore Camp

Professional Development _____

2020-03	Colombia Recruiting Mission, VanHack	Medellin, Colombia
2020-02	3nd ASTM Additive Manufacturing Center of Excellence Workshop, ASTM International	El Paso, USA
2019-11	Formnext 2019,	Frankfurt, Germany
2019-09	2nd ASTM Additive Manufacturing Center of Excellence Workshop, ASTM International	Senlis, France
2019-05	RAPID + TCT 2019, SME	Detroit, USA
2018-10	2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), IEEE	Madrid, Spain
2017-11	Neuroscience 2017, Society for Neuroscience	Washington, USA
2017-01	MUSE 1.0 Bedside Ultrasound Course for Primary Care Clinicians, McGill University Steinberg Centre for	Montréal, Canada
	Simulation and Interactive Learning	
2016-11	Neuroscience 2016, Society for Neuroscience	San Diego, USA
2016-05	Collaborative Robots Workshop, RIA International	Boston, USA

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Awards & Grants

- 2015 Alexander Graham Bell Canada Graduate Scholarship, NSERC
- 2014 Mitacs Accelerate Industrial Research Grant, Mitacs

Volunteer.

- 2020 **Mentor**, Techstars Montréal AI Accelerator
- 2020 Mentor, FounderFuel Startup Accelerator
- 2020 Member of Technical Expert Panel & Mentor, Code Life Ventilator Challenge for COVID-19
- 2020 Reviewer, Sensors
- 2019 **Reviewer**, Journal of Applied Mathematical Modelling
- 2019 **Reviewer**, International Journal of Advanced Robotic Systems (IJARS)
- 2018 **Reviewer**, The Journal of Open Source Software (JOSS)

Skills_

Languages English, French

Software Illustrator, Linux, MS Office, Photoshop, SolidWorks, Ubuntu, Windows

DevOps CircleCI, Docker, GitLab CI/CD, Travis CI, **Back-end** Flask, Protocol Buffers (protobuf), REST API

Front-end HTML5, Hugo, React

Programming C/C++, Java, JavaScript, LaTeX, Node.js, Python, TypeScript

Machine Learning Keras, OpenCV, scikit-learn, TensorFlow

Source Control Git, Subversion (SVN)

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