#### PROFESSIONAL ENGINEER (P.ENG.), DOCTOR OF PHILOSOPHY (PH.D.)

Montréal, Canada

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Work

**ADVISOR** 

**Halodi Robotics** Montréal, Canada

PROJECT DIRECTOR

· Director of special robotics projects across various domains, including security, retail, and manufacturing.

General manager of North American headquarters in Montréal.

**BRIDGR** Montréal, Canada

Expert advisor assisting with special projects and key introductions.

Mentor through the Techstars AI Montréal accelerator.

AON3D Montréal, Canada

**ENGINEERING MANAGER** 2018 - 2021

· Head of engineering and member of executive team through \$11.5M Series A.

- Responsible for Scientific Research and Experimental Development (SR&ED) Tax Incentive Program (\$300K+ in tax refunds).
- Led product compliance and certification for EMI/EMC, CE Machinery Directive, and CE Low Voltage Directive.
- Directed requirements definition, development process, and transfer to production of industrial additive manufacturing products.

#### **Nicholas Nadeau Consulting**

Montréal, Canada

2017 -

2017 - 2018

2020 -

**FOUNDER** 

· Start-up advising, specializing in R&D and product development.

**YPC Technologies** Montréal, Canada

**TECHNOLOGY ADVISOR TO THE CEO** 

Advised CEO throughout FounderFuel startup accelerator, leading to \$1.8M CAD seed round in 2020.

Led a team of engineers and directed robotics and software design, development, and implementation for FounderFuel Demo Day.

Rogue Research Inc. Montréal, Canada

**R&D ENGINEER** 

- · Led the development of a novel robotic veterinary neurosurgery system, including trajectory generation algorithms, computer vision, and hardware
- Developed devices and systems for transcranial magnetic stimulation (TMS), near infrared spectroscopy (NIRS), deep brain stimulation (DBS), and image-based neuronavigation.

## **Education**

#### École de technologie supérieure

Montréal, Canada

PhD - Precision and Collaborative Robotics

2014 - 2019

- Thesis: Towards the Development of Safe, Collaborative Robotic Freehand Ultrasound
- Created machine learning models and genetic algorithms for physical human-robot interaction.

**McGill University** Montréal, Canada

B.Eng. - Mechanical Engineering, Biomedical Engineering Minor

2010 - 2014

# Certifications & Professional Affiliations

Professional Engineer (P.Eng.) Ordre des ingénieurs du Québec (OIQ)

Associate Value Specialist (AVS) SAVE International

Committee F42 on Additive Manufacturing Technologies ASTM International

**Open Water Diver** Professional Association of Diving Instructors (PADI)

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### **Publications**

Improved Test Methods for Polymer AM Inter-Layer Weld Strength and Filament Mechanical Properties,

- 2020 Richard G. Cole, Kazem Fayazbakhsh, Abraham Avalos, Nicholas A. Nadeau. ASTM International Conference on Additive Manufacturing (ICAM).
- **Towards the development of safe, collaborative robotic freehand ultrasound,** Nicholas A. Nadeau. École de 2019 technologie supérieure.
- **Pybotics: Python Toolbox for Robotics,** Nicholas A. Nadeau. The Journal of Open Source Software.
  - Impedance Control Self-Calibration of a Collaborative Robot Using Kinematic Coupling, Nicholas A. Nadeau,
- 2019 Ilian A. Bonev. MDPI Robotics.
- **Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**, Nicholas A. Nadeau, Ilian A.
- 2018 Bonev. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
  - An Extrinsic Dexterity Approach to the IROS 2018 Fan Robotic Challenge Modality B, Jennifer Kwiatkowski,
- Jean-Philippe Roberge, Nicholas A. Nadeau, Louis L'Écuyer-Lapierre, Vincent Duchaine. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
  - Characterization of a robotic micro-surgical system for small-animal neurosurgery, Nicholas A. Nadeau,
- Alexandru Ciobanu, Fred Lamer, Mathieu Coursolle, Sean McBride, Stephen Frey, Roch Comeau. Society for Neuroscience.

#### Talks\_

- 2021-04 Speaker Hardware in the Loop: Training Robot Contact in an Unstructured Environment, Montréal-Python 85
- 2020-04 **Speaker Making Materials Matter**, Dyndrite Developer Conference 2020
- Speaker Evolutionary Motion Control Optimization in Physical Human-Robot Interaction, 2018 IEEE/RSJ
- International Conference on Intelligent Robots and Systems (IROS)
- 2017-11 Speaker Calibrating Robots with Python, PyCon Canada 2017
- 2017-10 **Speaker Calibrating Robots with Python**, Montréal-Python 67
- 2016-12 Keynote Robotics and Neuroscience, Clearpoint Elementary Exhibition Summit
- 2015-06 **Speaker Medical Robotics**, McGill Faculty of Medicine Explore Camp

# Professional Development \_\_\_\_\_

2020-03	Colombia Recruiting Mission, VanHack	Medellin, Colombia
2020-02	3nd ASTM Additive Manufacturing Center of Excellence Workshop, ASTM International	El Paso, USA
2019-11	Formnext 2019,	Frankfurt, Germany
2019-09	2nd ASTM Additive Manufacturing Center of Excellence Workshop, ASTM International	Senlis, France
2019-05	<b>RAPID + TCT 2019,</b> SME	Detroit, USA
2018-10	2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), IEEE	Madrid, Spain
2017-11	Neuroscience 2017, Society for Neuroscience	Washington, USA
2017-01	MUSE 1.0 Bedside Ultrasound Course for Primary Care Clinicians, McGill University Steinberg Centre for	Montréal, Canada
	Simulation and Interactive Learning	
2016-11	Neuroscience 2016, Society for Neuroscience	San Diego, USA
2016-05	Collaborative Robots Workshop, RIA International	Boston, USA

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## Volunteer.

- 2020 **Mentor**, Techstars Montréal AI Accelerator
- 2020 Mentor, FounderFuel Startup Accelerator
- 2020 Member of Technical Expert Panel & Mentor, Code Life Ventilator Challenge for COVID-19
- 2020 Reviewer, Sensors
- 2019 Reviewer, Journal of Applied Mathematical Modelling
- 2019 **Reviewer**, International Journal of Advanced Robotic Systems (IJARS)
- 2018 **Reviewer**, The Journal of Open Source Software (JOSS)

## Skills\_

Languages English, French

**Software** Illustrator, Linux, MS Office, Photoshop, SolidWorks, Ubuntu, Windows

**DevOps** CircleCI, Docker, GitLab CI/CD, Travis CI, **Back-end** Flask, Protocol Buffers (protobuf), REST API

**Front-end** HTML5, Hugo, React

**Programming** C/C++, Java, JavaScript, LaTeX, Node.js, Python, TypeScript

**Machine Learning** Keras, OpenCV, scikit-learn, TensorFlow

**Source Control** Git, Subversion (SVN)

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