

# Nicholas Nadeau

PROFESSIONAL ENGINEER (P.ENG.), DOCTOR OF PHILOSOPHY (PH.D.)

Montréal, Canada

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## Education

### École de technologie supérieure

Montréal, Canada

PHD - PRECISION AND COLLABORATIVE ROBOTICS

2014 - 2019

- Thesis: Towards the Development of Safe, Collaborative Robotic Freehand Ultrasound
- Created machine learning models and genetic algorithms for physical human-robot interaction.
- Invented a novel, robust, low-cost robot calibration platform.

### McGill University

Montréal, Canada

B.ENG. - MECHANICAL ENGINEERING, BIOMEDICAL ENGINEERING MINOR

2010 - 2014

### Dawson College

Montréal, Canada

DEC - HONOURS HEALTH SCIENCE

2008 - 2010

## Work

### AON3D

Montréal, Canada

ENGINEERING MANAGER

2019 -

- Head of software and hardware engineering, and member of executive team.
- Oversee the design, development, testing, and deployment of innovative solutions for challenging problems in the additive manufacturing domain.
- Ensure robust, scalable, reusable, efficient, production-quality software and hardware is being delivered to the organization.
- Usher and evangelize adoption of engineering best-practices and agile methodologies.
- Set the roadmap and budgets, drive detailed planning, and ensure execution of deliverables for a medium sized team.
- Manage the company-wide SR&ED program.
- Mentor and help bringing up of new team members, interviewing and hiring of new team members, ensure technical development of team.

### AON3D

Montréal, Canada

SENIOR R&D ENGINEER

2018 - 2019

- Responsible for innovation and technology development to drive 10x revenue.
- Introduced automated data collection framework to help drive business and engineering decisions.
- Engineering ScrumMaster, responsible for ensuring the team has everything they need to deliver value.

### YPC Technologies

Montréal, Canada

TECHNOLOGY ADVISOR TO THE CEO

2017 - 2018

- Advised CEO throughout FounderFuel startup accelerator in order to go to market and raise seed capital.
- Led a team of engineers and directed robotics and software design, development, and implementation.
- Recommended long-term approach to strategic suppliers and technologies with the aim of optimizing operations and delivering savings.

### Rogue Research Inc.

Montréal, Canada

R&D ENGINEER

2011 - 2018

- Led mechanical research, design, and development of brain imaging, cognitive neuroscience, and robotic products.
- Led the development of a novel robotic veterinary neurosurgery system, including trajectory generation algorithms, computer vision, and hardware design.
- Developed devices and systems for transcranial magnetic stimulation (TMS), near infrared spectroscopy (NIRS), deep brain stimulation (DBS), and image-based neuronavigation.

## Certifications & Professional Affiliations

**Professional Engineer (P.Eng.)** Ordre des ingénieurs du Québec (OIQ)

**Associate Value Specialist (AVS)** SAVE International

**Committee F42 on Additive Manufacturing Technologies** ASTM International

**Open Water Diver** Professional Association of Diving Instructors (PADI)

## Publications

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### **Towards the development of safe, collaborative robotic freehand ultrasound**

NICHOLAS A. NADEAU. ÉCOLE DE TECHNOLOGIE SUPÉRIEURE.

2019

### **Pybotics: Python Toolbox for Robotics**

NICHOLAS A. NADEAU. THE JOURNAL OF OPEN SOURCE SOFTWARE.

2019

### **Impedance Control Self-Calibration of a Collaborative Robot Using Kinematic Coupling**

NICHOLAS A. NADEAU, ILIAN A. BONEV. MDPI ROBOTICS.

2019

### **Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**

NICHOLAS A. NADEAU, ILIAN A. BONEV. IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS (IROS).

2018

### **An Extrinsic Dexterity Approach to the IROS 2018 Fan Robotic Challenge Modality B**

JENNIFER KWIATKOWSKI, JEAN-PHILIPPE ROBERGE, NICHOLAS A. NADEAU, LOUIS L'ÉCUYER-LAPIERRE, VINCENT DUCHAINE. IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS (IROS).

2018

### **Characterization of a robotic micro-surgical system for small-animal neurosurgery**

NICHOLAS A. NADEAU, ALEXANDRU CIOBANU, FRED LAMER, MATHIEU COURSOLE, SEAN MCBRIDE, STEPHEN FREY, ROCH COMEAU. SOCIETY FOR NEUROSCIENCE.

2017

## Professional Development

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2020-03 **Colombia Recruiting Mission**, VanHack

Medellin, Colombia

2020-02 **3rd ASTM Additive Manufacturing Center of Excellence Workshop**, ASTM International

El Paso, USA

2019-11 **Formnext 2019**,

Frankfurt, Germany

2019-09 **2nd ASTM Additive Manufacturing Center of Excellence Workshop**, ASTM International

Senlis, France

2019-05 **RAPID + TCT 2019**, SME

Detroit, USA

2018-10 **2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)**, IEEE

Madrid, Spain

2017-11 **Neuroscience 2017**, Society for Neuroscience

Washington, USA

2017-01 **MUSE 1.0 Bedside Ultrasound Course for Primary Care Clinicians**, McGill University Steinberg Centre for Simulation and Interactive Learning

Montréal, Canada

2016-11 **Neuroscience 2016**, Society for Neuroscience

San Diego, USA

2016-05 **Collaborative Robots Workshop**, RIA International

Boston, USA

2013-06 **OHBM 2013**, Organization for Human Brain Mapping

Seattle, USA

## Volunteer

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2020 - **Mentor**, FounderFuel Startup Accelerator

2020 **Member of Technical Expert Panel & Mentor**, Code Life Ventilator Challenge for COVID-19

2020 - **Reviewer**, Sensors

2019 - **Reviewer**, Journal of Applied Mathematical Modelling

2019 - **Reviewer**, International Journal of Advanced Robotic Systems (IJARS)

2018 - **Reviewer**, The Journal of Open Source Software (JOSS)

2013 - 2014 **Communications Administrator**, Interaction du quartier Peter-McGill

2011 - 2014 **Discover McGill and Orientation Week Leader**, McGill University

2012 - 2013 **Treasurer and Communications Administrator**, Forum Jeunesse Centre-ville

2009 - 2011 **Volunteer Math and Science Teacher**, Innovation Jeunes

## Talks

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- 2020-04 **Speaker - Making Materials Matter**, Dyndrite Developer Conference 2020
- 2018-10 **Speaker - Evolutionary Motion Control Optimization in Physical Human-Robot Interaction**, 2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
- 2017-11 **Speaker - Calibrating Robots with Python**, PyCon Canada 2017
- 2017-10 **Speaker - Calibrating Robots with Python**, Montréal-Python 67
- 2016-12 **Keynote - Robotics and Neuroscience**, Clearpoint Elementary Exhibition Summit
- 2015-06 **Speaker - Medical Robotics**, McGill Faculty of Medicine Explore Camp
- 2014-05 **Keynote**, Riverdale High School Career Seminar
- 2014-02 **Keynote**, Riverdale High School Career Seminar
- 2013-05 **Keynote**, Lester B. Pearson School Board Science Showcase

## Awards

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- 2015 **Alexander Graham Bell Canada Graduate Scholarship**, NSERC
- 2014 **Mitacs Accelerate Industrial Research Grant**, Mitacs
- 2014 **Graduation Honours**, McGill University
- 2013 **Québec Iron Titanium Scholarship**, McGill University
- 2013 **Abe and Jennie Brock Award**, McGill University
- 2013 **Dean's Honour List**, McGill University
- 2013 **Industrial Undergraduate Research Award**, NSERC
- 2012 **Industrial Undergraduate Research Award**, NSERC
- 2011 **Industrial Undergraduate Research Award**, NSERC
- 2011 **Golden Key International Honour Society**, McGill University
- 2010 **First Class Graduation Honours**, Dawson College
- 2010 **Athletic Academic Achievement Award**, Dawson College

## Skills

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|-------------------------|---|
| <b>Languages</b>        | English, French   |
| <b>Software</b>         | Illustrator, Linux, MS Office, Photoshop, SolidWorks, Ubuntu, Windows |
| <b>DevOps</b>           | CircleCI, Docker, GitLab CI/CD, Travis CI,                            |
| <b>Back-end</b>         | Flask, Protocol Buffers (protobuf), REST API                          |
| <b>Front-end</b>        | HTML5, Hugo, React  |
| <b>Programming</b>      | C/C++, Java, JavaScript, LaTeX, Node.js, Python, TypeScript           |
| <b>Machine Learning</b> | Keras, OpenCV, scikit-learn, TensorFlow                               |
| <b>Source Control</b>   | Git, Subversion (SVN)   |