

Gerry Chen

412-956-3047

<https://gerry-chen.com>

gerry.chen2015@gmail.com

Education

Georgia Institute of Technology, Ph.D. & M.S.

08/2019 to 05/2024 (Expected)

School of Interactive Computing – Robotics – Prof. Frank Dellaert

- Thesis: Rendering, Replicating, and Adapting Human Motions on a Cable Robot for Artistic Painting
- 4.00/4.00 cumulative GPA

Duke University, B.S.E.

08/2015 to 05/2019

Pratt School of Engineering

- Electrical and Computer Engineering + Mechanical Engineering; Minors in Computer Science, Math
 - 3.87/4.00 cumulative GPA, Dean's List every semester
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Work History

PhD Research Assistant

08/2019 to Present

Georgia Institute of Technology - Prof. Frank Dellaert

- Graffiti robot system design (IEEE ICRA 2022) & Plant phenotyping robot (IEEE ICRA 2023)
- Factor Graphs, GTSAM, Simultaneous State Estimation and Optimal Control
- 4x 1st author publications, 3x 2nd author publication, 1x 3rd author publication
- Course Instructor for CS 3630: Intro to Perception & Robotics (Summer 2022)

Computer Vision Intern: Agricultural Robotics

05/2023 to 08/2023

Verdant Robotics - Dr. Frank Dellaert

- Implemented (CUDA/C++) KLT Pose tracker to improve localization accuracy and robustness
- Implemented field-scale offline mapping / 3D reconstruction for farmer analytics and visualization
- Prototyped passive camera auto-calibration to streamline manufacturing and improve accuracy

Software Engineer Intern: Autonomous Vehicle Perception

05/2021 to 08/2021

Zoox - Dr. Subhasis Das

- Developed smoothing-based tracker for improved object tracking using sensor fusion
- Achieved improvements in all tracking metrics for use in offline labeling (patent US-11782815-B2)

Integrated Control and Estimation Intern – Secret Security Clearance (Inactive)

06/2020 to 08/2020

Air Force Research Laboratory (Eglin AFB) - Dr. Adam Rutkowski

- Compute optimal collaborative trajectories to minimize navigation uncertainty using factor graphs

Controls Engineer Intern

05/2018 to 08/2018

Deka R&D - Dirk Van Der Merwe

- Developed novel 2-wheel balancing control scheme with constrained wheel displacement (patent pending)
- Created multi-system integration over CAN, EtherCAT, RS232 to create hybrid wheeled/legged robot

Robotics Intern: Motion Planning

01/2017 to 05/2018

Intelligent Motion Laboratory - Dr. Kris Hauser

- Co-first author on IEEE ICRA 2018 paper for robot actuation of human input devices (95.7% success rate)
 - Coded (Python, C++) and tested max. continuous range / min. manipulability arm configurations
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Skills

- Strong command of C++, Python, and Matlab
 - Proficiency in HTML/CSS/Javascript, L^AT_EX
 - Embedded Software Development
 - State Estimation, Sensor fusion, SLAM
 - Optimal Control, Cable-Driven Parallel Robots
 - Eagle, SPICE, Solidworks, Autodesk Fusion 360
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Activities

Co-President

08/2015 to 07/2019

Duke Electric Vehicles Team - 2x Guinness World Record holder

- President 2018-19, world record for most efficient electric vehicle at 27,482 MPGe
- Lead hydrogen fuel cell hybrid vehicle 2017-18, world record for most fuel efficient vehicle at 14,573 MPGe
- Increased fuel cell efficiency from 40% to 63% and designed super-cap array to increase vehicle eff. by 22%
- Built autonomous path-following car based on RTK GPS, internal sensors, and path planning algorithms