

Gerry Chen

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Education

Georgia Institute of Technology, Ph.D. & M.S.

08/2019 to 08/2024

School of Interactive Computing – Robotics – Prof. Frank Dellaert & Seth Hutchinson

- [Thesis](#): Rendering, Replicating, and Adapting Human Motions on a Cable Robot for Artistic Painting
- 3.96/4.00 cumulative GPA

Duke University, B.S.E.

08/2015 to 05/2019

Pratt School of Engineering

- Electrical and Computer Engineering + Mechanical Engineering; Minors in Computer Science, Math
 - 3.88/4.00 cumulative GPA, Dean's List every semester
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Work History

Software Engineer: Autonomous Vehicle Perception

08/2024 to Present

Zoox - Dr. Francesco Papi

- 3D multi-object tracking (MOT) w/ sensor fusion, Extended Kalman Filters (EKF), occlusion, auto-tuning

PhD Research Assistant: Factor Graphs

08/2019 to 08/2024

Georgia Institute of Technology - Prof. Frank Dellaert & Seth Hutchinson

- Designed novel estimation+control algorithms ([IROS 2022](#)) for custom Cable Driven Parallel Robot
- Maintain/develop the popular *GTSAM* factor graph library used in SLAM, sensor fusion, mapping, etc.
- 9x 1st author publications, 3x 2nd author publication, 1x 3rd author publication, course instructor [CS 3630](#)

Computer Vision Intern: Agricultural Robotics

05/2023 to 08/2023

Verdant Robotics - Dr. Frank Dellaert

- Implemented (CUDA/C++) KLT Pose tracker for real-time dense visual tracking
- Implemented passive camera auto-calibration and field-scale offline mapping / 3D reconstruction

Software Engineer Intern: Autonomous Vehicle Perception

05/2021 to 08/2021

Zoox - Dr. Subhasis Das

- Developed GTSAM-based 3D MOT for auto-labeling (patent [US-11782815-B2](#)) (still in prod as of 2025)

Integrated Control and Estimation Intern – Secret Security Clearance (Inactive)

06/2020 to 08/2020

Air Force Research Laboratory (Eglin AFB) - Dr. Adam Rutkowski

- Compute optimal collaborative trajectories to minimize navigation uncertainty using factor graphs

Controls Engineer Intern

05/2018 to 08/2018

Deka R&D - Dirk Van Der Merwe

- Developed novel 2-wheel balancing control scheme with constrained wheel displacement (patent pending)
- Created multi-system integration over CAN, EtherCAT, RS232 to create hybrid wheeled/legged robot

Robotics Intern: Motion Planning

01/2017 to 05/2018

Intelligent Motion Laboratory - Dr. Kris Hauser

- Co-first author on [IEEE ICRA 2018 paper](#) for robot actuation of human input devices (95.7% success rate)
 - Coded (Python, C++) and tested max continuous range / min manipulability arm configurations
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Skills

- State Estimation, SLAM, Optimal Control
 - Computer Vision, 3D Reconstruction, NeRF
 - Factor Graphs, GTSAM, Nonlinear Optimization
 - Strong command of Python, C++, and Matlab
 - Proficiency in CUDA, PyTorch, HTML/CSS/JS
 - Full-Stack Robotician, Embedded, Hardware, ROS
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Activities

Co-President

08/2015 to 07/2019

Duke Electric Vehicles Team - 2x [Guinness World Record](#) holder

- President 2018-19, world record for most efficient electric vehicle at 27,482 MPGe
- Lead hydrogen fuel cell hybrid vehicle 2017-18, world record for most fuel efficient vehicle at 14,573 MPGe
- Built autonomous path-following car based on RTK GPS, internal sensors, and path planning algorithms