



Gerry Chen

Robotics Perception @ Zoox
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OVERVIEW

Autonomous driving perception engineer at Zoox.

Formerly PhD student at Georgia Institute of Technology studying generative embodied AI through a collaborative graffiti spray painting robot using diffusion models for robot action generation.

Keywords: robot art, human-robot collaboration, computer vision, robotics, optimal control

Primary Languages: C++, Python

EDUCATION

Georgia Institute of Technology, Ph.D. Robotics

08/2019 to 08/2024

School of Interactive Computing

Studying human-robot collaboration through generative art under Frank Dellaert and Seth Hutchinson

[Thesis](#): Rendering, Replicating, and Adapting Human Motions on a Cable Robot for Artistic Painting

3.96/4.00 cumulative GPA

Georgia Institute of Technology, M.S. Computer Science

08/2019 to 12/2022

College of Computing

3.96/4.00 cumulative GPA

Duke University, B.S.E. Electrical and Computer Engineering

08/2015 to 05/2019

Pratt School of Engineering

Electrical & Computer Engineering (major), Mechanical Engineering (major), CS (minor), Math (minor)

3.87/4.00 cumulative GPA, Magna Cum Laude

PUBLICATIONS

15. [G. Chen](#), S. K. Narayanan, T. G. Ottou, B. Missaoui, H. Muriki, C. Pradalier, and Y. Chen, “[Hyperspectral Neural Radiance Fields](#)”, *2025 Conference on Computer Vision and Pattern Recognition (CVPR) 2nd Workshop on Neural Fields Beyond Conventional Cameras*. p (2025). ★Spotlight★
14. [G. Chen](#), “[Rendering, Replicating, and Adapting Human Motions on a Cable Robot for Artistic Painting](#)”, *PhD Thesis, Georgia Institute of Technology*. p (2024).
13. [G. Chen](#), T. Al-Haddad, F. Dellaert, and S. Hutchinson, “[Architectural-Scale Artistic Brush Painting with a Hybrid Cable Robot](#)”, *IEEE International Conference on Intelligent Robots and Systems (IROS)*. p (2024).
12. [G. Chen](#), F. Dellaert, and S. Hutchinson, “[Dynamics-Aware Trajectory Generation for Artistic Painting using Diffusion](#)”, *IEEE Robotics Science and Systems (RSS)*. p (2024).

11. [G. Chen](#), F. Dellaert, and S. Hutchinson, “[Generalizing Trajectory Retiming to Quadratic Objective Functions](#)”, *IEEE International Conference on Robotics and Automation (ICRA)*. p (2024).
10. [G. Chen](#), H. Muriki, C. Pradalier, Y. Chen, and F. Dellaert, “[A Hybrid Cable-Driven Robot for Non-Destructive Leafy Plant Monitoring and Mass Estimation using Structure from Motion](#)”, *IEEE International Conference on Robotics and Automation (ICRA)*. p (2023).
9. Y. Zhang, F. Jiang, [G. Chen](#), V. Agrawal, A. Rutkowski, and F. Dellaert, “[Constraint Manifolds for Robotic Inference and Planning](#)”, *IEEE International Conference on Robotics and Automation (ICRA)*. p (2023).
8. [G. Chen](#), S. Hutchinson, F. Dellaert, “[Locally Optimal Estimation and Control of Cable Driven Parallel Robots using Time Varying Linear Quadratic Gaussian \(LQG\) Control](#)”, *2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. p (2022).
7. Y. Zhang, [G. Chen](#), A. Rutkowski, F. Dellaert, “[Efficient Range-Constrained Manifold Optimization with Application to Cooperative Navigation](#)”, *2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. p (2022).
6. [G. Chen](#), S. Baek, J. Florez, W. Qian, S. Leigh, S. Hutchinson, and F. Dellaert, “[GTGraffiti: Spray Painting Graffiti Art from Human Painting Motions with a Cable Driven Parallel Robot](#)”, *IEEE International Conference on Robotics and Automation (ICRA)*. p 3-19 (2022).
5. A. Cohen, [G. Chen](#), E. Berger, S. Warrier, G. Lan, E. Grubert, F. Dellaert, Y. Chen, “[Dynamically Controlled Environment Agriculture: Integrating Machine Learning and Mechanistic and Physiological Models for Sustainable Food Cultivation](#)”, *ACS ES&T Engineering*. p 3-19 (2022).
4. S. Yang*, [G. Chen](#)*, Y. Zhang, F. Dellaert, H. Choset, “[Equality Constrained Linear Optimal Control With Factor Graphs](#)”, *2021 International Conference on Robotics and Automation (ICRA)*. p 9717-9723 (2021).
3. Z. Li, A. Yang, [G. Chen](#), Z. Zeng, A. Peterchev, S. Goetz, “[A High-Frequency Pulsating DC-Link for Electric Vehicle Drives with Reduced Losses](#)”, *47th Annual Conference of the IEEE Industrial Electronics Society (IECON)*. p 1-6 (2021).
2. P. Grady, [G. Chen](#), S. Verma, A. Marellapudi, N. Hotz, “[A Study of Energy Losses in the World’s Most Fuel Efficient Vehicle](#)”, *IEEE Vehicle Power and Propulsion Conference (VPPC)*. p 1-6 (2019).
1. F. Wang*, [G. Chen](#)*, and K. Hauser, “[Robot Button Pressing in Human Environments](#)”, *2018 IEEE International Conference on Robotics and Automation (ICRA)*. p 7173-7180 (2018).

SKILLS

- Diffusion Models, Embodied AI, Imitation Learning
- NeRF, 3D Reconstruction, Computer Vision
- State Estimation, SLAM, Optimal Control
- Strong command of Python, C++, and Matlab

- Proficiency in CUDA, PyTorch, HTML/CSS/JS
- Full-Stack Robotist, Embedded, Hardware, ROS

HONORS AND AWARDS

Sigma Xi Honor Society	08/2020 to Present
Tau Beta Pi Honor Society – NC Gamma Chapter	05/2019 to Present
IEEE Eta Kappa Nu Honor Society – Delta Lambda Chapter	01/2018 to Present
Pi Tau Sigma Honor Society – Pi Iota Chapter	01/2017 to Present
GVU Foley Scholar	10/2022
<i>Finalist</i>	

[Foley Scholars](#) are the GVU Center's highest recognition for student research contributions to computing.

National Science Foundation Graduate Research Fellows Program	03/2020
<i>Honorable Mention</i>	

The NSF GRFP recognizes and supports outstanding graduate students in supported STEM disciplines.

Guinness World Records	06/2019
<i>Most Efficient Prototype Electric Vehicle</i>	

President of the Duke Electric Vehicles team that broke the record with 77.98Wh/100km.

Duke University Electrical and Computer Engineering Department	05/2019
<i>Graduation with Departmental Distinction</i>	

Presented for my distinguished research and academic record.

Guinness World Records	07/2018
<i>Most Fuel-Efficient Vehicle</i>	

Head of hydrogen fuel cell development for the record breaking fuel cell vehicle achieving 14,573MPGe.

RESEARCH EXPERIENCE

Robotics Estimation and Control	08/2019 to 08/2024
<i>Georgia Institute of Technology - Dr. Frank Dellaert</i>	

- Combined estimation and optimal control using factor graphs
- Cable driven parallel robot (CDPR) design and control

Robot Art	08/2019 to Present
<i>Georgia Institute of Technology - Dr. Frank Dellaert & Dr. Seth Hutchinson</i>	

- [Graffiti spray-painting robot](#) based on a cable driven parallel robot (CDPR) design.
- [Non-destructive plant analysis using structure-from-motion \(SfM\) and a cable-driven parallel robot.](#)

Power Electronics	08/2018 to 05/2019
<i>Duke University - Dr. Stefan Goetz and Dr. Angel Peterchev</i>	

- Implemented novel FOC motor controller using modular multilevel series-parallel converter to self-balance battery cells, reduce noise, increase voltage ratings, and minimize losses
- Thermal analysis of battery/converter modules for use in automotive setting
- Electrical losses analysis for MOSFET selection in converter modules
- Installation of novel motor controller in electric vehicle to test practical cell-balancing performance

Fuel Cell Hybrid Vehicle

08/2017 to 05/2018

Duke University - Dr. Josiah Knight and Dr. Nico Hotz

- Optimization of fuel cell operating parameters for use in hybrid vehicle to achieve 58.9% in-system efficiency (increase from baseline efficiency of 40%)
- Design and optimization of voltage converter for active supercapacitor load power leveling system resulting in 22% higher vehicle efficiency
- See Publication [2](#) – fuel cell vehicle system level design

Robotics Motion Planning

01/2017 to 05/2018

Intelligent Motion Laboratory - Dr. Kris Hauser

- Applied convolution-based image similarity metrics for database assisted vehicle path planning
- Fabricated silicon and polyurethane cornea models with <50um repeatability for use in surgical robot testing
- See Publication [1](#) – work funded by NSF Research Experiences for Undergraduates (REU) to implement a Precision Positioning Unit (PPU) on the Tele-Robotic Intelligent Nursing Assistant (TRINA)
- Redundancy resolution for minimum manipulability / maximum continuous range joint configurations
- Fabricated polyurethane “finger” tip with integrated tactile sensor and 95.7% actuation success rate

WORK HISTORY

Software Engineer

08/2024 to Present

Zoox - Dr. Francesco Papi

- 3D multi-object tracking (MOT) using sensor fusion, Extended Kalman Filters (EKF), occlusion modeling, auto-tuning, state estimation, dataset generation, data cleaning, machine learning, etc.

Computer Vision Intern

05/2023 to 08/2023

Verdant Robotics - Gabe Sibley

- Prototyped (Jax) and implemented (CUDA) KLT Pose tracker to improve vehicle localization accuracy and robustness
- Implemented field-scale offline mapping / 3D reconstruction for farmer analytics and visualization
- Prototyped (GTSAM) passive auto-calibration of camera intrinsics and extrinsics to streamline manufacturing and improve accuracy under changing environmental conditions

Instructor

05/2022 to 08/2022

Georgia Institute of Technology - Self

- **CS3630:** [Intro to Perception & Robotics](#)

Software Engineer Intern: Autonomous Vehicle Perception

05/2021 to 08/2021

Zoox - Dr. Subhasis Das

- Developed smoothing-based tracker for improved object tracking using sensor fusion
- My code achieved improvements in all tracking metrics for use in offline labeling, with 2 patents pending

Integrated Control and Estimation Intern

06/2020 to 08/2020

Air Force Research Laboratory (Eglin AFB) - Dr. Adam Rutkowski

- Refine collaborative vehicle control with imperfect multi-vehicle trajectory estimations
- Compute optimal sensor measurement timing and inter-vehicle communication
- Compute optimal collaborative trajectories to minimize navigation uncertainty using factor graphs

Controls Engineer Intern

05/2018 to 08/2018

Deka R&D - Dirk Van Der Merwe

- Developed novel 2-wheel balancing control scheme with constrained wheel displacement (patent pending)
- Created multi-system integration over CAN, EtherCAT, RS232 to create hybrid wheeled/legged robot
- Developed stability control of robot w/ powered casters + differential steering to test high speed dynamics

Robotics Motion Planning Intern

01/2017 to 05/2018

Intelligent Motion Laboratory - Dr. Kris Hauser

- Work on PPU for TRINA (see entry in Research Experience)
- Coded (Python, C++) and tested max. continuous range / min. manipulatability arm configurations

Teaching Assistant

08/2019 to 12/2019

Georgia Institute of Technology

- **CS3630:** Intro Perception & Robotics Fall 2019

Teaching Assistant

08/2016 to 05/2018

Duke University

- **EGR201:** Mechanics of Statics Fall 2017
- **ECE230:** Microelectronics Fall 2017
- **ECE230:** Microelectronics Summer 2017
- **EGR103:** Computational Methods in engineering Fall 2016
- **CS201:** Data structures and Algorithms Fall 2016

Tutor

05/2014 to 05/2019

Multiple Employers

- Duke Academic Resource Center - group instruction:
 - Multivariable Calculus 08/2016 to 05/2019
 - Linear Algebra 01/2017 to 01/2018
 - Differential Equations 01/2017 to 01/2018
- Duke Academic Resource Center - individual instruction:
 - Multivariable Calculus 08/2016 to 05/2017
 - Linear Algebra 08/2016 to 05/2017
 - Differential Equations 08/2016 to 05/2017
- America Reads America Counts at Duke
 - Durham Public Schools 08/2015 to 06/2016
 - Math + Reading
- Kumon Math and Reading Center of Fox Chapel 05/2014 to 08/2016
 - personalized curriculum generation for 40+ students
 - student performance evaluations

EXTRACURRICULAR ACTIVITIES

Co-President

08/2015 to 08/2019

Duke Electric Vehicles Team

- World Record (2019): World's most efficient electric vehicle - team president
- World Record (2018): World's most fuel efficient vehicle - head of hydrogen system
- Lead creation of a fully autonomous vehicle to allow the vehicle to follow a "total system energy" optimized path subject to physical control constraints
- Co-lead hydrogen fuel cell hybrid vehicle for 2018 to achieve 14,573 MPGe
- Design + Manufacture + Test the high power super-capacitor control board to increase vehicle efficiency by 22%
- Create an automated testing system resulting in fuel cell efficiency increase from 40% to 63%
- Design + Manufacture + Install the carbon fiber inserts to decrease weight and increase modularity
- 2018: 1st place H2, 1st place battery-electric (12,398 MPGe), Technical Innovation Award at the Shell Eco-Marathon Americas

CTO

08/2018 to 05/2019

Delta Band Inc. - deltatrainer.fit

- Designed all electrical systems of the strength training workout tracker watch based on machine learning
- Currently on 7th generation electrical boards (Dec 2018)
- Initiating small-scale (100 devices) manufacturing for beta-testing devices to be shipped Jan 2019

Project Lead

01/2016 to 01/2018

Solar Benches

- Lead technical, financial, and administrative aspects of augmenting existing campus benches with solar powered night-time task lighting and laptop/phone chargers to raise enthusiasm for clean energy
- Installed 2 test benches on campus after passing safety inspection on an off-site prototype bench

RELEVANT COURSEWORK

Georgia Institute of Technology

- CS7643 - Deep Learning
- CS8803 - Probabilistic Graphical Models in Machine Learning
- CS7476 - Advanced Computer Vision
- CS8803 - Mobile Manipulation
- CS6601 - Artificial Intelligence
- ECE6553 - Optimal Control

Duke University

- CS520/MATH565 - Numerical Analysis
- MATH577 - Mathematical Modeling
- MATH216 - Linear Algebra and Diff. Equations
- MATH353 - Ordinary and Partial Diff. Equations
- ECE382/ME344 - Control Systems