

APPLICATIONI LINEARI

$$\underline{v_1}, \dots, \underline{v_k} \in V, U = \text{Span}(\underline{v_1}, \dots, \underline{v_k})$$

Prop. $f(\underline{v_1}), \dots, f(\underline{v_k})$ lin. ind. $\Leftrightarrow \underline{v_1}, \dots, \underline{v_k}$ lin. ind. \wedge
(1) $U \cap \ker f = \{\underline{0}\}$
(2)

(2) \Rightarrow (1):

$$\begin{aligned} & \alpha_1 f(\underline{v_1}) + \dots + \alpha_k f(\underline{v_k}) = \underline{0} \Rightarrow \\ & \Rightarrow f(\underbrace{\alpha_1 \underline{v_1} + \dots + \alpha_k \underline{v_k}}_{\in U \cap \ker f}) = \underline{0} \Rightarrow \\ & \Rightarrow \alpha_1 \underline{v_1} + \dots + \alpha_k \underline{v_k} = \underline{0} \Rightarrow \alpha_1 = \dots = \alpha_k = 0 \Rightarrow \\ & \Rightarrow f(\underline{v_1}), \dots, f(\underline{v_k}) \text{ lin. ind.} \end{aligned}$$

(1) \Rightarrow (2):

$$\begin{aligned} & \alpha_1 \underline{v_1} + \dots + \alpha_k \underline{v_k} = \underline{0} \Rightarrow \\ & \Rightarrow \alpha_1 f(\underline{v_1}) + \dots + \alpha_k f(\underline{v_k}) = f(\underline{0}) = \underline{0} \Rightarrow \\ & \Rightarrow \alpha_1 = \dots = \alpha_k = 0 \quad (\underline{v_1}, \dots, \underline{v_k} \text{ lin. ind.}) \end{aligned}$$

$\underline{v} \in U \cap \text{Ker } f$

- $\underline{v} = \alpha_1 \underline{v_1} + \dots + \alpha_k \underline{v_k}$
- $f(\underline{v}) = \underline{0} \Rightarrow \alpha_1 f(\underline{v_1}) + \dots + \alpha_k f(\underline{v_k}) = \underline{0} \Rightarrow$
 $\Rightarrow \alpha_1 = \dots = \alpha_k = 0 \quad (\underline{v} = \underline{0}, U \cap \text{Ker } f = \{\underline{0}\}).$

□

Oss: $U \subset V$ ssp., $\dim U = k$, $\underline{v_1}, \dots, \underline{v_k}$ base di U

$$f(U) = \text{Span}(f(\underline{v_1}), \dots, f(\underline{v_k}))$$

se $U \cap \text{Ker } f = \{\underline{0}\}$:

- $\dim f(U) = k$

se f è iniettiva, $\text{Ker } f = \{\underline{0}\}$:

- $\dim f(U) = k$ (in realtà anche per il caso infinito)
- f manda vett. lin. ind. in vett. lin. ind.

Oss. 2 $\dim f(U) = \dim U - \dim \text{Ker } f|_U =$
 $= \dim U - \dim(U \cap \text{Ker } f).$

Oss. 3 $f: V \rightarrow W \wedge \dim W > \dim V \Rightarrow$

$\Rightarrow \dim W > \dim \text{Im } f \Rightarrow f \text{ NON pu' essere surgettiva}$

Oss. 4 $f: V \rightarrow W \wedge \dim V > \dim W \Rightarrow$

$\Rightarrow \dots$

Oss. 5 $f|_U: U \subset V \rightarrow W, u \mapsto f(u)$ e sempre

ben definita e lineare, se f e' lineare

$$\dim V = \dim \ker f|_U + \dim f|_U = (*)$$

- $\text{Im } f|_U = f(U)$
- $\ker f|_U = U \cap \ker f$

$$(*) = \dim(U \cap \ker f) + \dim f(U)$$

Oss. 6 f isomorfismo $\Rightarrow \dim V = \dim W$

- $\ker f = \{\underline{0}\}$ perché f iniettiva

- $\dim W = \dim \text{Im } f = \dim V - \underbrace{\dim \ker f}_{=0} = \dim V$

Matrici

$$A = (A^1) (A^2) \cdots (A^n) = \\ A\underline{x} = x_1 A^1 + \cdots + x_n A^n \in \mathbb{K}^m$$

$$f_A : \mathbb{K}^n \rightarrow \mathbb{K}^m, \underline{x} \mapsto A\underline{x}$$

f_A è lineare:

- $f_A(\underline{x} + \underline{y}) = A(\underline{x} + \underline{y}) = A\underline{x} + A\underline{y}$
- $f_A(\alpha \underline{x}) = A(\alpha \underline{x}) = \alpha(A\underline{x}) = \alpha f_A(\underline{x}).$

$$\ker f_A = \left\{ \underline{x} \in \mathbb{K}^n \mid f(\underline{x}) = \underline{0} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \in \mathbb{K}^m \right\},$$

oss.2 le soluzioni del sistema omogeneo

$$A\underline{x} = \underline{0}$$

Imm $f_A = \left\{ f(\underline{x}) \in \mathbb{K}^m \mid \underline{x} \in \mathbb{K}^n \right\}$, oss.2
 $\text{Span}(A^1, \dots, A^n)$, la cui dimensione è $\text{rg}(A)$.

Sapendo che un insieme di generatori di \mathbb{K}^n

genera \mathbb{K}^m perché f_A è un'app. lineare,

la base canonica di \mathbb{K}^n applicata genera \mathbb{K}^m .

es. $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$, $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} x - 2y - z \\ 3x - y + 3z \end{pmatrix} =$

$$= x \begin{pmatrix} 1 \\ 3 \end{pmatrix} + y \begin{pmatrix} -2 \\ -1 \end{pmatrix} + z \begin{pmatrix} -1 \\ 3 \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & -2 & -1 \\ 3 & -1 & 3 \end{pmatrix}}_A \underbrace{\begin{pmatrix} x \\ y \\ z \end{pmatrix}}_{\underline{x}}$$
, quindi:
 è app. lineare.

$$\text{Imm } f_A = \text{Span} \left(\begin{pmatrix} 1 \\ 3 \end{pmatrix}, \begin{pmatrix} -2 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 3 \end{pmatrix} \right) =$$

$$= \text{Span} \left(\underbrace{\begin{pmatrix} 1 \\ 3 \end{pmatrix}, \begin{pmatrix} -2 \\ -1 \end{pmatrix}}_{\text{lin. ind.}} \right) \Rightarrow$$

$\Rightarrow \dim \text{Imm } f_A = 2 = \dim \mathbb{R}^2 \rightarrow$
 $\Rightarrow \mathbb{R}^2 = \text{Imm } f_A \Rightarrow f$ è surgettiva (i.e.
 $A \underline{x} = \underline{b}$ ammette sempre soluzione).

$$\dim \ker f_A = \dim \mathbb{R}^3 - \dim \text{Imm } f_A =$$

$$= 1$$

Prop. $f: \mathbb{K}^n \rightarrow \mathbb{K}^m$ lineare $\Leftrightarrow \exists! A \in M(m, n, \mathbb{K})$

$$f = f_A$$

$$A = (\underbrace{f(\underline{e}_1)}_{A^1} | \underbrace{f(\underline{e}_2)}_{A^2} | \dots | \underbrace{f(\underline{e}_n)}_{A^n}) \in M(m, n, \mathbb{K})$$

$$x \in \mathbb{K}^n \quad \underline{x} = x_1 \underline{e}_1 + \dots + x_n \underline{e}_n \Rightarrow$$

$$\Rightarrow f(\underline{x}) = x_1 f(\underline{e}_1) + \dots + x_n f(\underline{e}_n) =$$

$$= A \underline{x} \quad \forall \underline{x} \in \mathbb{K}^n$$

E' únicamente determinada la A:

$$\cdot A^i = f(e_i) = B^i \Rightarrow A = B$$

es. $f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ lineare: $f\begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$

$$f\begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

$$\begin{cases} f(\underline{e}_1) - f(\underline{e}_2) = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} \\ 2f(\underline{e}_1) + f(\underline{e}_2) = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \end{cases} \Rightarrow$$

$$\Rightarrow \begin{cases} f(\underline{e}_1) = \frac{1}{3} \left(\begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \right) = \frac{1}{3} \begin{pmatrix} 4 \\ 2 \\ -1 \end{pmatrix} \\ 2f(\underline{e}_2) = -\begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} - f(\underline{e}_1) \end{cases} \Rightarrow$$

$$\Rightarrow \begin{cases} f(\underline{e}_1) = \frac{1}{3} \begin{pmatrix} 4 \\ 2 \\ -1 \end{pmatrix} \\ f(\underline{e}_2) = \frac{1}{3} \begin{pmatrix} -5 \\ -4 \\ -1 \end{pmatrix} \end{cases}$$

Quindi $A = \left(\begin{array}{c|c} f(\underline{e}_1) & f(\underline{e}_2) \end{array} \right) =$

$$= \frac{1}{3} \underbrace{\begin{pmatrix} 4 & -5 \\ 2 & -4 \\ -2 & -1 \end{pmatrix}}_{\text{lin. ind.}}. \quad \dim \text{Im } f_A = 2$$

$$\dim \text{Ker } f_A = 0 \Rightarrow \text{iniettiva}$$

es. $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3 \quad A = \begin{pmatrix} 2 & 0 & 0 \\ 1 & 1 & -1 \\ 1 & 1 & 1 \end{pmatrix}$

- $\exists! V \subset \mathbb{R}^3$ ssp. | $\dim V = 1$ con f invariante
(i.e. $f(V) \subset V$)
- $\exists! W \subset \mathbb{R}^3$ ssp. | $\dim W = 2$ con f invariante

$$\exists \frac{\underline{u}_0 \in \mathbb{R}^3}{\neq 0} \mid V = \underset{V}{\text{Span}}(\underline{u}_0)$$

$$\cdot f(\underline{u}) \subset \overbrace{\text{Span}(\underline{u}_0)} \iff f(\underline{u}_0) \subset \text{Span}(\underline{u}_0)$$

$$f(\underline{u}_0) = \begin{pmatrix} 2 & 0 & 0 \\ 1 & 1 & -1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 2a \\ a+b-c \\ a+b+c \end{pmatrix} = \lambda \begin{pmatrix} a \\ b \\ c \end{pmatrix} \rightarrow$$

$$\Rightarrow \begin{cases} 2a = \lambda a \\ a+b-c = \lambda b \\ a+b+c = \lambda c \end{cases} \Rightarrow \begin{cases} (2-\lambda)a = 0 \\ a + (1-\lambda)b - c = 0 \\ a + b + (1-\lambda)c = 0 \end{cases} \Rightarrow \text{(i)} \vee \text{(ii)}$$

$$\begin{aligned}
 \text{(i)} \implies a=0 & \quad \left\{ \begin{array}{l} (1-\lambda)b - c = 0 \Rightarrow c = (1-\lambda)b \\ b + (1-\lambda)c = 0 \Rightarrow b + (1-\lambda)^2b = 0 \Rightarrow \end{array} \right. \\
 & \quad \Rightarrow (1+(1-\lambda)^2) b = 0 \Rightarrow b=0 \Rightarrow c=0 \\
 \Rightarrow \underline{u}_0 = \underline{0} & \text{ imp.}
 \end{aligned}$$

$$\begin{aligned}
 \text{(ii)} \quad \lambda=2 & \quad \left\{ \begin{array}{l} 0=0 \\ a-b-c=0 \\ a+b-c=0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} b=0 \\ a=c \end{array} \right. \Rightarrow \underline{u}_1 = \begin{pmatrix} a \\ 0 \\ a \end{pmatrix} = \\
 & = a \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \Rightarrow \underline{u}_0 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, U = \text{Span}(\underline{u}_0)
 \end{aligned}$$

$$U = \ker \left(f_{A - \underbrace{2I}_{\lambda}} \right) \quad I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Riprendi le slide sull'imm. f -invariante