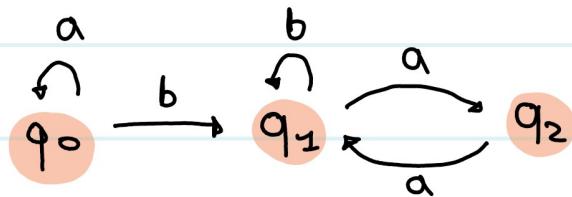


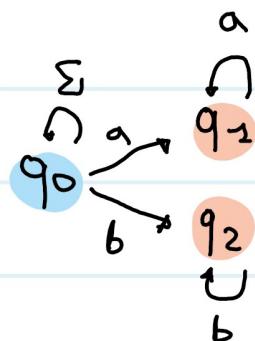
es. 1. 2013

$$\Sigma = \{a, b\}$$



es. 2. 2013

	a	b
→ q ₀	{q ₀ , q ₁ }	{q ₀ , q ₂ }
* q ₁	{q ₁ }	∅
* q ₂	{q ₂ }	∅



(i) il codominio di $\delta \in \mathcal{P}(\Omega)$.

$$\cdot \hat{\delta}(q_0, \varepsilon) = \{q_0\}$$

$$\cdot \hat{\delta}(q_0, a) = \delta(q_0, a) = \{q_0, q_1\}$$

$$\begin{aligned} \cdot \hat{\delta}(q_0, ab) &= \bigcup_{p \in \hat{\delta}(q_0, a)} \delta(p, b) = \delta(q_0, b) \cup \delta(q_1, b) = \\ &= \{q_0, q_2\} \cup \emptyset = \{q_0, q_2\} \end{aligned}$$

$$\begin{aligned} \cdot \hat{\delta}(q_0, aba) &= \delta(q_0, a) \cup \delta(q_2, a) = \\ &= \{q_0, q_1\} \cup \emptyset = \{q_0, q_1\} \end{aligned}$$

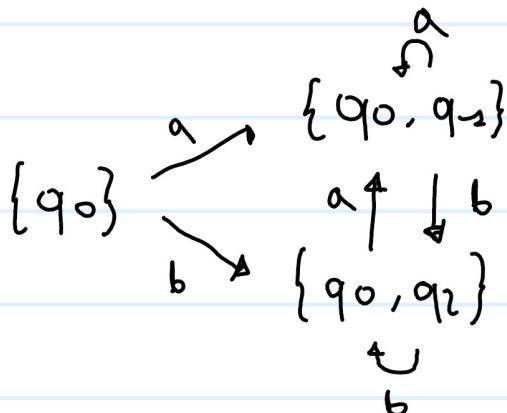
$$\begin{aligned} \cdot \hat{\delta}(q_0, abaa) &= \delta(q_0, a) \cup \delta(q_1, a) = \\ &= \{q_0, q_1\} \cup \emptyset = \{q_0, q_1\} \end{aligned}$$

$$\begin{aligned}\hat{\delta}(q_0, aba\alpha) &= \delta(q_0, a) \cup \delta(q_1, a) = \\ &= \{q_0, q_1\} \cup \emptyset = \{q_0, q_1\}\end{aligned}$$

$\hat{\delta}(q_0, aba\alpha) \cap F = \{q_2\} \neq \emptyset$, quindi
aba\alpha è accettata.

(iii)

	a	b
$\rightarrow \{q_0\}$	$\{q_0, q_1\}$	$\{q_0, q_2\}$
$\{q_1\}$	\emptyset	\emptyset
$\times \{q_2\}$	\emptyset	\emptyset
$\{q_0, q_1\}$	$\{q_0, q_2\}$	$\{q_0, q_2\}$
$\times \{q_0, q_2\}$	$\{q_0, q_1\}$	$\{q_0, q_2\}$



es. 3. 2013

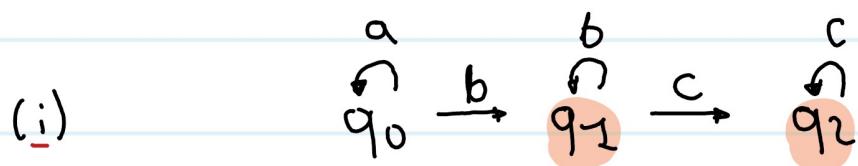
Stato iniziale: $\{ \text{dim} \rightsquigarrow K, c[0] \rightsquigarrow V_0, \dots \}$ con $K > 0$

Stato finale: $\{ \text{massimo} \rightsquigarrow \max \{V_i \mid 0 \leq i < K\},$
 $\text{minimo} \rightsquigarrow \min \{V_i \mid 0 \leq i < K\}, \text{coincidenti} \rightsquigarrow$

→ true se il valore di massimo e' uguale a quello di minimo, altrimenti: false }

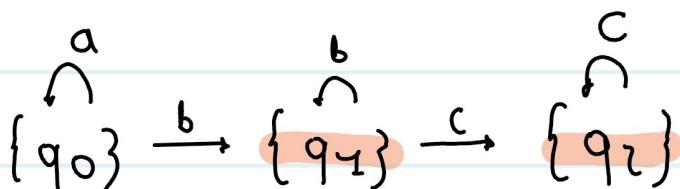
es. 1. 2014

$$L = \{a^n b^m c^k \mid n \geq 0, m > 0, k \geq 0\} \quad \Sigma = \{a, b, c\}$$



(ii)

	a	b	c
→ {q0}	{q0}	{q2}	∅
* {q1}	∅	{q1}	{q2}
* {q2}	∅	∅	{q2}



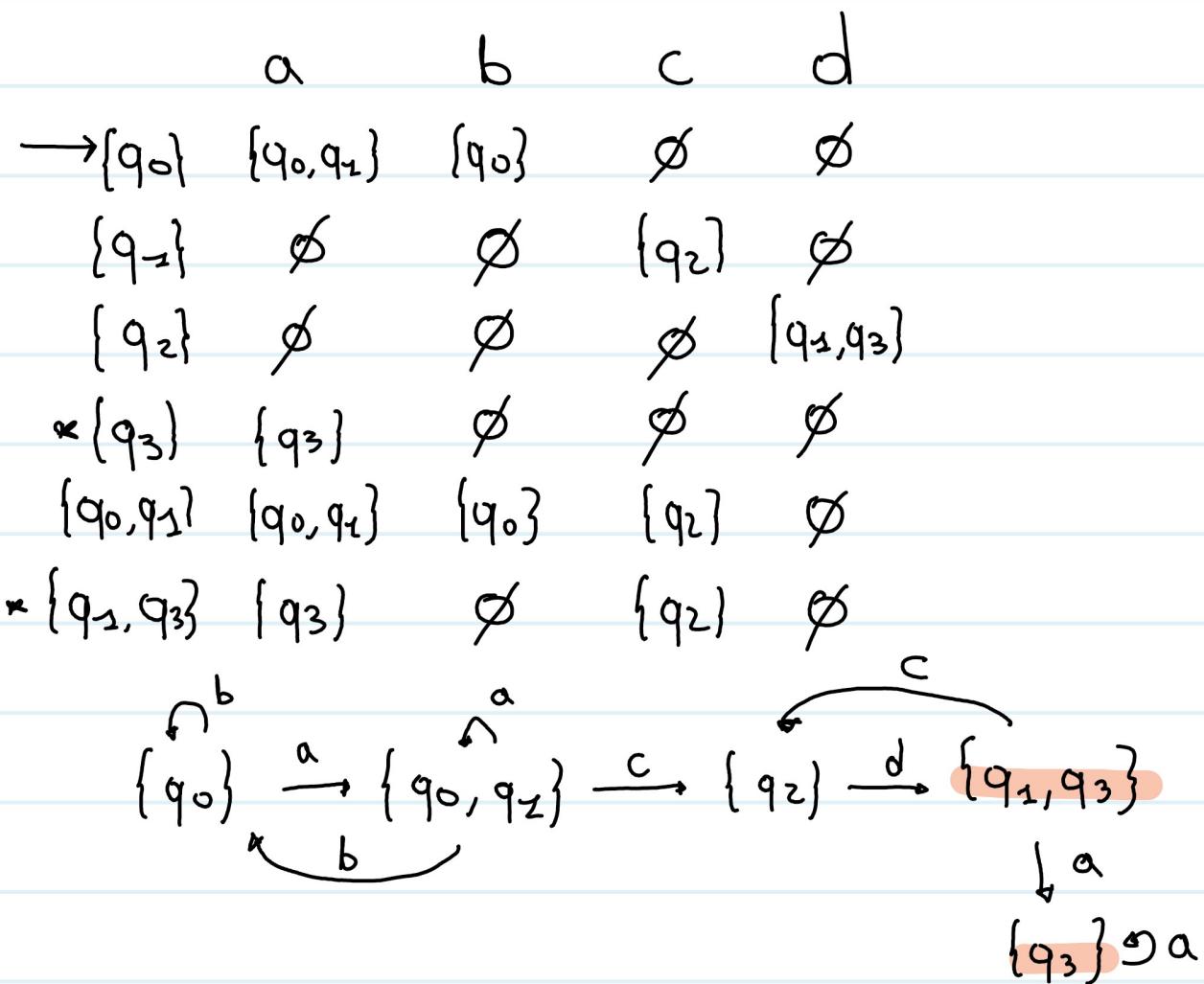
es. 4. 2014

STATI iniziali: {dim ~ K, C[0] ~ V0, ..., C[K-1] ~ VK-1, val ~ V}

Stati finali: $\{ \text{occDisp} \sim \# \{ 0 \leq i < k \mid V_i \equiv 1 \pmod{2} \},$
 check \rightarrow true se il valore d. occDisp è V , altrimenti:
 false }

es. 1.2015

$$\Sigma = \{a, b, c, d\}$$



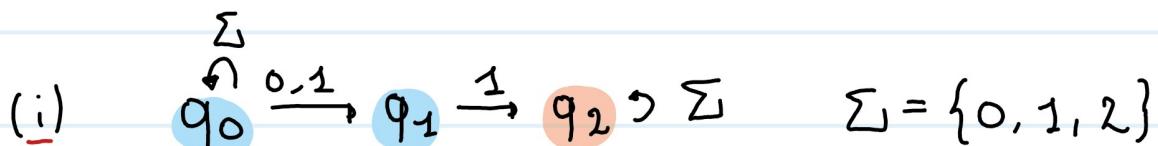
es. S. 2015

Stato iniziale: { dim $\rightsquigarrow K$, $c[0] \rightsquigarrow V_0, \dots, c[K-1] \rightsquigarrow V_{K-1}$ }

con $K > 0$

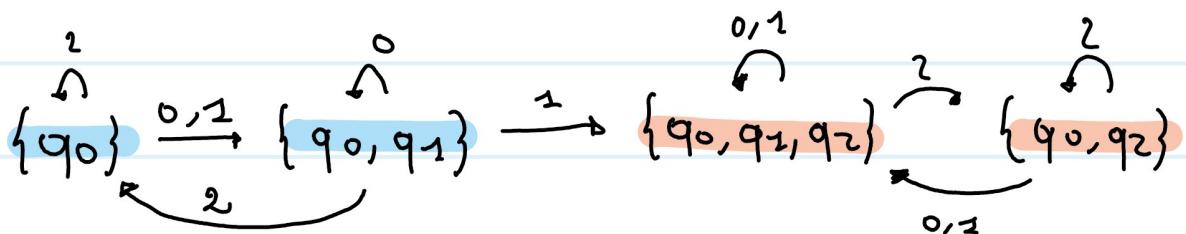
Stato finale: { count $\rightsquigarrow \#\{0 \leq i < K \mid V_i = 0\}$ (2),
check \rightsquigarrow true se K è il doppio del valore di
count, altrimenti false }

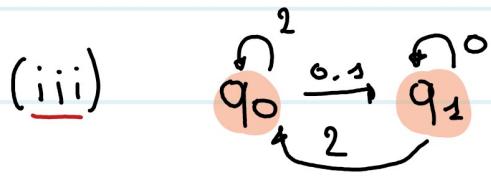
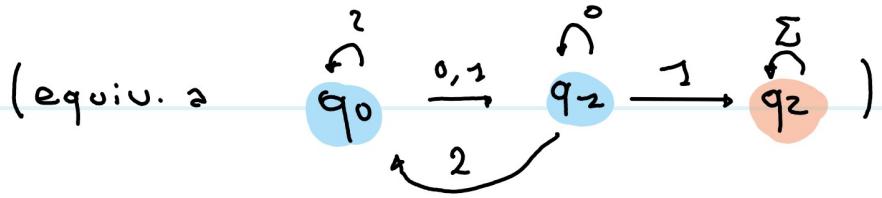
es. 1. 2018



(ii)

0	1	2
$\rightarrow \{q_0\}$	$\{q_0, q_2\}$	$\{q_0, q_1\}$
$\{q_1\}$	\emptyset	$\{q_2\}$
$\times \{q_2\}$	$\{q_2\}$	$\{q_2\}$
$\{q_0, q_1\}$	$\{q_0, q_2\}$	$\{q_0, q_1, q_2\}$
$\times \{q_0, q_1, q_2\}$	$\{q_0, q_1, q_2\}$	$\{q_0, q_2\}$
$\star \{q_0, q_2\}$	$\{q_0, q_1, q_2\}$	$\{q_0, q_1, q_2\}$





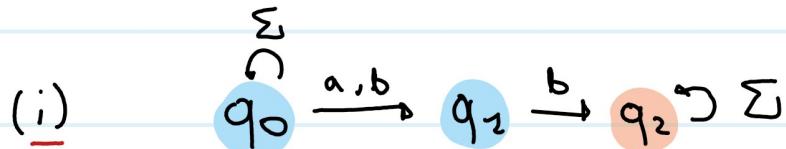
es. 5. 2018

$$\text{(i)} \quad \underbrace{\langle b_0, \sigma \rangle \rightarrow \text{true} \quad \langle b_1, \sigma \rangle \rightarrow \text{true}}_{\langle b_0 \wedge b_1, \sigma \rangle \rightarrow \text{true}}$$

$$\frac{\langle b_0, \sigma \rangle \rightarrow t_1 \quad \langle b_1, \sigma \rangle \rightarrow t_2}{\langle b_0 \wedge b_1, \sigma \rangle \rightarrow \text{false}} \quad \begin{matrix} \text{se almeno uno fra } t_1 \text{ e} \\ t_2 \text{ e' false} \end{matrix}$$

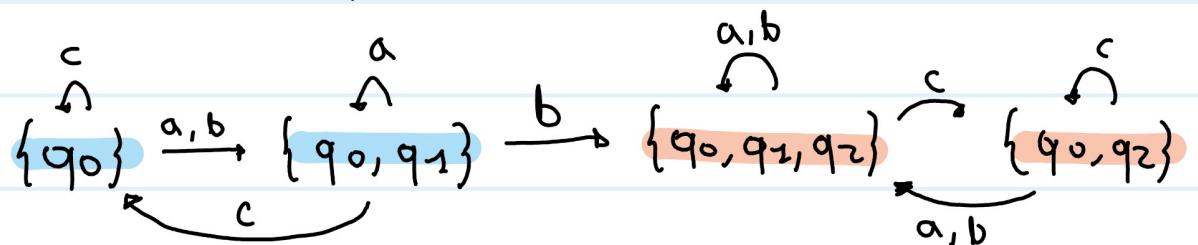
$$\text{(ii)} \quad \underbrace{\langle b_0, \sigma \rangle \rightarrow \text{false}}_{\langle b_0 \wedge b_1, \sigma \rangle \rightarrow \text{false}} \quad \underbrace{\langle b_0, \sigma \rangle \rightarrow \text{true} \quad \langle b_1, \sigma \rangle \rightarrow t_1}_{\langle b_0 \wedge b_1, \sigma \rangle \rightarrow t_1}$$

es. 1. 2019

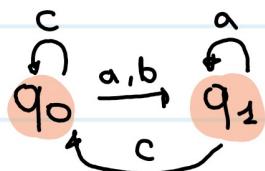


(ii)

	a	b	c
$\rightarrow \{q_0\}$	$\{q_0, q_2\}$	$\{q_0, q_1\}$	$\{q_0\}$
$\{q_1\}$	\emptyset	$\{q_2\}$	\emptyset
$\star \{q_2\}$	$\{q_2\}$	$\{q_2\}$	$\{q_2\}$
$\{q_0, q_1\}$	$\{q_0, q_1\}$	$\{q_0, q_1, q_2\}$	$\{q_0\}$
$\star \{q_0, q_1, q_2\}$	$\{q_0, q_1, q_2\}$	$\{q_0, q_1, q_2\}$	$\{q_0, q_2\}$
$\star \{q_0, q_2\}$	$\{q_0, q_2\}$	$\{q_0, q_1, q_2\}$	$\{q_0, q_2\}$



(iii)



es. 5.2019

(i)

$$\frac{\langle a_0, \sigma \rangle \rightarrow h_0 \quad \langle a_1, \sigma \rangle \rightarrow h_1}{\langle a_0 + a_1, \sigma \rangle \rightarrow h_0 + h_1}$$

(ii)

$$\frac{\begin{array}{l} \langle Y, \sigma_0 \rangle \rightarrow 1 \quad \langle 3, \sigma_0 \rangle \rightarrow 3 \\ \hline \langle Y+3, \sigma_0 \rangle \rightarrow 4 \end{array}}{\langle (Y+3) + (4+2), \sigma_0 \rangle \rightarrow 10} \quad \frac{\begin{array}{l} \langle 4, \sigma_0 \rangle \rightarrow 4 \quad \langle 2, \sigma_0 \rangle \rightarrow 2 \\ \hline \langle 4+2, \sigma_0 \rangle \rightarrow 6 \end{array}}{\langle (4+2) + (4+2), \sigma_0 \rangle \rightarrow 10}$$

es. 2. 2019

#include <stdio.h>

int read_seq() {

int n = 1;

int last; scanf("%d", &last);

int valid_seq = TRUE; int current;

while(valid_seq) {

scanf("%d", ¤t);

n++;

if (last == current + 1) {

valid_seq = FALSE;

}

last = current;

}

return n;

}

es. 3. 2019

```
int check_arr ( int a[], int dim) {  
    int valid = TRUE;  
    int i = 0;  
  
    while (valid && i < dim) {  
        if ( a[i+1] != 2 * a[i] || a[i+2] != 3 * a[i] ) {  
            valid = FALSE;  
        }  
        i += 3;  
    }  
    return valid;  
}
```