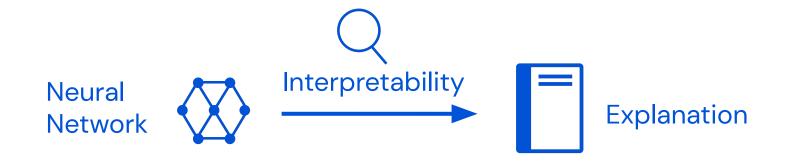
DeepMind

Compiled Transformers as a Laboratory for Interpretability

David Lindner, János Kramár, Matthew Rahtz, Tom McGrath, Vladimir Mikulik



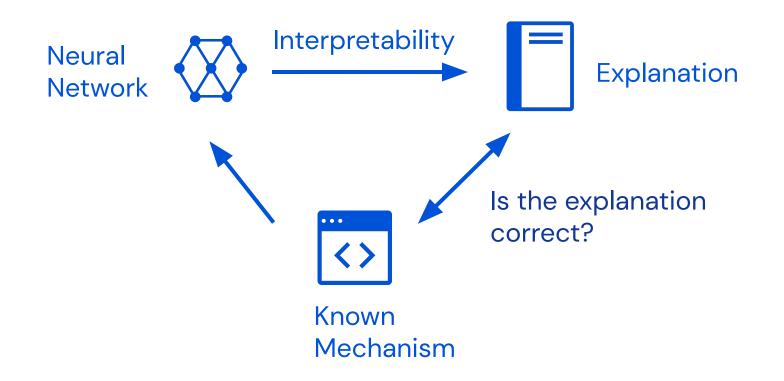
One reason interpretability is hard is that there is no ground truth information



Is the explanation correct?

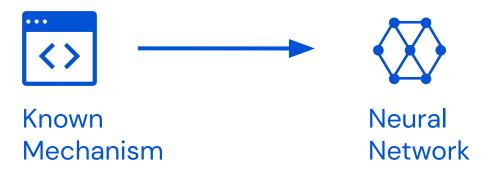


What if we could create situations where we do have a ground truth?





Introducing Tracr: A Transformer Compiler for RASP





Plan for today

1. Building a **compiler** for transformer models



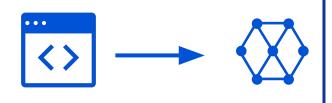
2. Studying **superposition** in compiled models





Plan for today

1. Building a **compiler** for transformer models



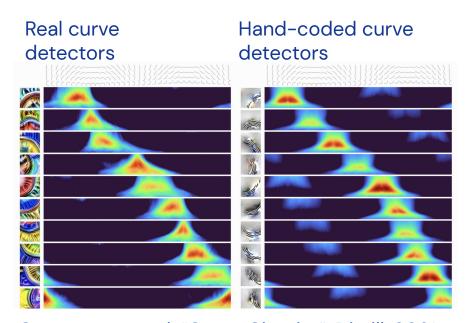
2. Studying superposition in compiled models





Hand-coding weights is useful but not scalable

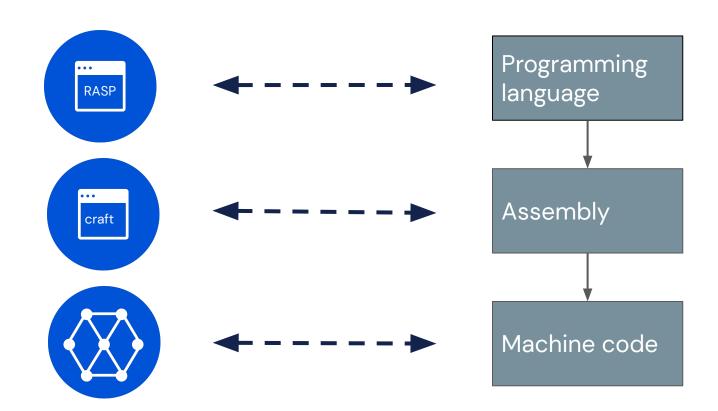
- We can hand-code weights to build ground truth models
- Very good measure of how good we understand a model
- Difficult to scale to more complex/bigger models
- This approach is like
 programming in byte-code



Cammarata et al. "Curve Circuits", Distill, 2021.



Tracr works analogously to how we would translate a programming language into executable code





Tracr translates human readable code into transformer model weights in three steps



Human readable code in domain-specific language

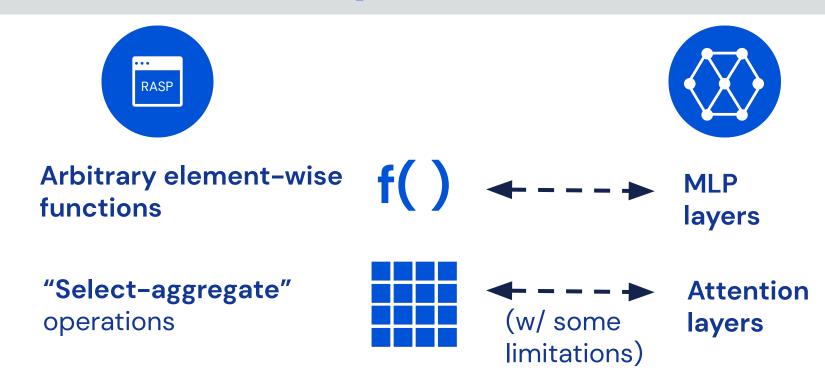


Basis independent representation of vector spaces and transformers





RASP is a symbolic programming language to describe transformer computations



RASP = "Restricted Access Sequence Programming"

Weiss, Gail, Yoav Goldberg, and Eran Yahav. "Thinking like transformers." ICML 2021.



An example RASP program



```
is_x = (tokens == "x")
prevs = select(indices, indices, <=)
frac_prev = aggregate(prevs, is_x)</pre>
```

```
seq := ["a", "x", "b", "x", "c"]
tokens(seq) = ["a", "x", "b", "x", "c"]
indices(seq) = [0, 1, 2, 3, 4]
is x(seq) = [0, 1, 0, 1, 0]
prevs(seq) = [[1, 0, 0, 0, 0],
              [1, 1, 0, 0, 0],
              [1, 1, 1, 0, 0],
              [1, 1, 1, 1, 0],
              [1, 1, 1, 1, 1]
frac_prev(seq) = [0, 1/2, 1/3, 2/4, 2/5]
```



Translating a RASP program into a craft transformer

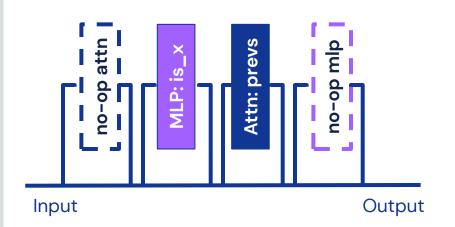
Step 1: Create computational graph

Step 2: Infer inputs/outputs

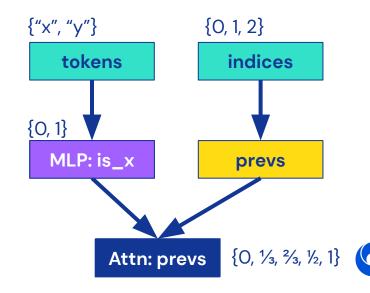
Step 3: Create model components

Step 4: Assign components to layers

Step 5: Assemble craft model

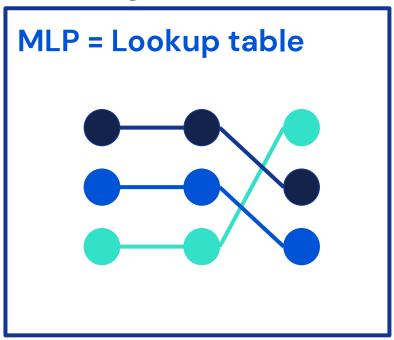


```
is_x = (tokens == "x")
prevs = select(indices, indices, <=)
frac_prev = aggregate(prevs, is_x)</pre>
```

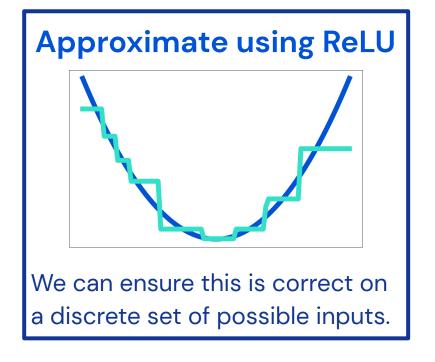


We implement MLP layers to approximate arbitrary pointwise functions

For categorical variables:



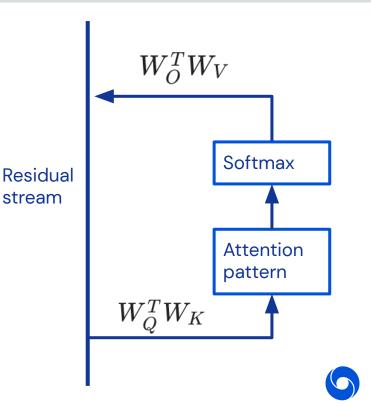
For numerical variables:



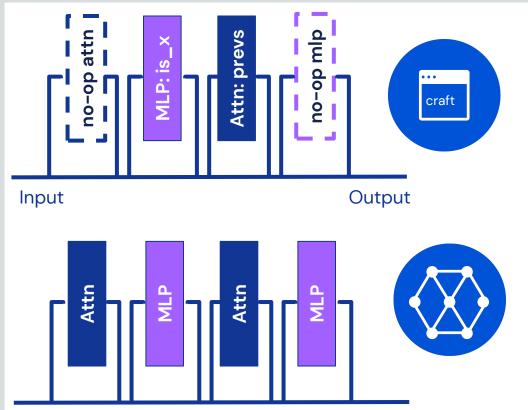


Attention heads can implement arbitrary selectors with categorical inputs

- We can use a low softmax temperature to make attention patterns binary
- But what if we don't want to attend to anything?
 - We add a beginning of sequence token that we can always attend to
 - Anecdotally, it seems like real transformers also do this!



A craft model can be directly mapped to any standard transformer architecture



Abstract representation of a transformer that makes it easier to reason about vector spaces

Can be mapped to any GPT-like transformer implementation.

We primarily support a standard haiku transformer implementation.



Tracr can compile a range of meaningful programs, but it is not fully general

We can implement programs to:

- Count tokens and compute histograms
- Detect all occurrences of a patterns
- Sort the input sequence
- Check balanced parentheses (Dyck-n)
- ...

Limitations of RASP

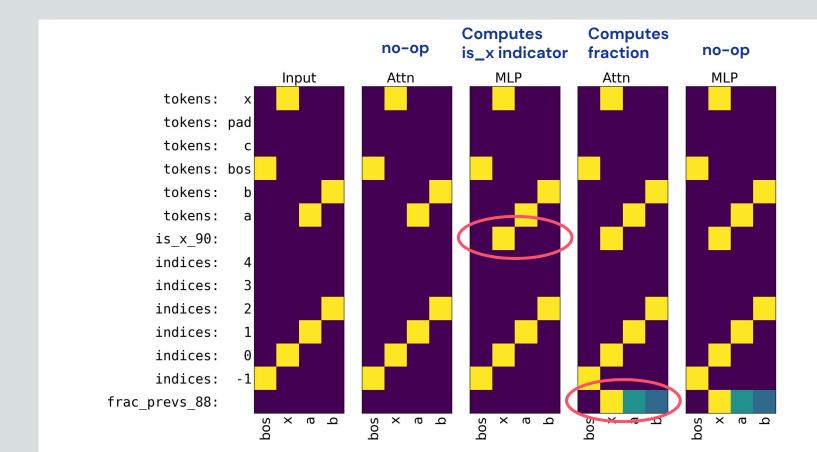
- Binary attention patterns
- Designed to model algorithmic tasks and not probabilistic tasks
- Programs still relatively close to transformer architecture

Limitations of Tracr

- Resulting models are large and inefficient
- Many possible optimization missing
- Some advanced RASP features not supported



We can now compile RASP programs!





Plan for today

1. Building a **compiler** for transformer models



2. Studying superposition in compiled models





Plan for today

1. Building a **compiler** for transformer models



2. Studying **superposition** in compiled models



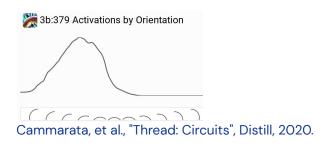


The superposition hypothesis

Observation 1: Sometimes neurons corresponds to clearly interpretable features.

Observation 2: Sometimes neurons seem to represent multiple interpretable features.

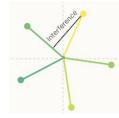
Observation 3: A linear representation can approximately embed exponentially more features than it has dimensions.







Simple Optimization Dataset examples
Olah, et al., "Feature Visualization", Distill, 2017.



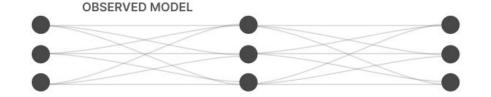


Elhage, et al., "Toy Models of Superposition", Transformer Circuits Thread, 2022.

The superposition hypothesis

Neural networks simulate larger networks with disentangled features

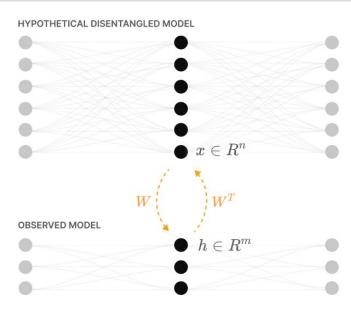
These hypothetical features are **projected** into the actual network using **superposition**



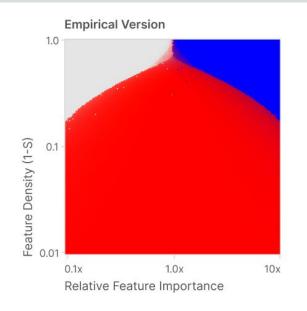
This results in **polysemanticity** when looking at single neurons.



Superposition occurs in toy models



$$egin{aligned} h &= Wx \ x' &= \mathrm{ReLU}(W^T h + b) \ x' &= \mathrm{ReLU}(W^T W x + b) \end{aligned} \qquad L = \sum_x \sum_i I_i (x_i - x_i')^2$$



Extra Feature is Not Represented

Extra Feature Gets Dedicated Dimension

Extra Feature is Stored In Superposition



We expect superposition to occur, if we "compress" Tracr models to be more efficient

In toy models we see superposition if

- 1. Features are **sparse**
- Some features are more important than others
- 3. The model has to use **fewer** dimensions than features

In Tracr models

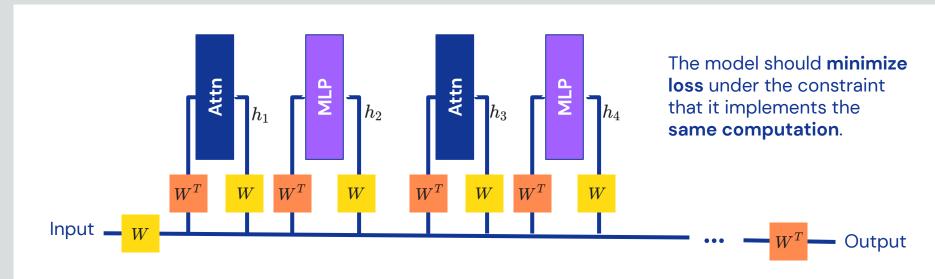
- 1. Features are **sparse**
- 2. Some features are more **important** for the computation
- 3. Can we "compress" the model to use **fewer dimensions**?

Motivation

- a. Learn something about superposition in more realistic models
- b. Make Tracr models more naturalistic



We linearly compress the model's residual stream



Train (only)
$$W \in \mathbb{R}^{D imes d}$$
 to minimize: $\mathcal{L}(W,x) = \mathcal{L}_{ ext{out}}(W,x) + \mathcal{L}_{ ext{layer}}(W,x)$

$$\mathcal{L}_{ ext{out}}(W,x) = \operatorname{loss}(f(x),\hat{f}_{|W}(x))$$
 minimize output loss

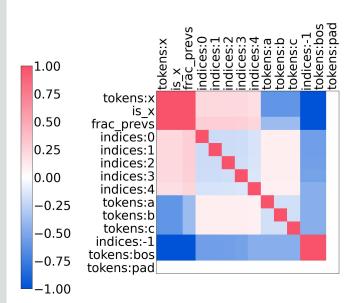
$$\mathcal{L}_{ ext{layer}}(W,x) = \sum_{ ext{layer}\,i} (h_i(x) - \hat{h}_{W,i}(x))^2$$

implement the same computation

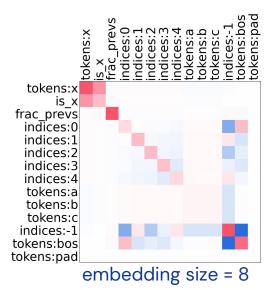


The embeddings show superposition that is qualitatively different from PCA embeddings

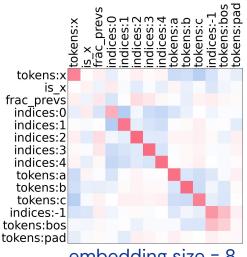
Correlation matrix



Superposition W^TW



PCA Solution



embedding size = 8



Which features will be stored in superposition?

Feature importance

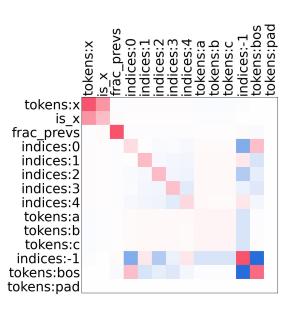


Feature

Density

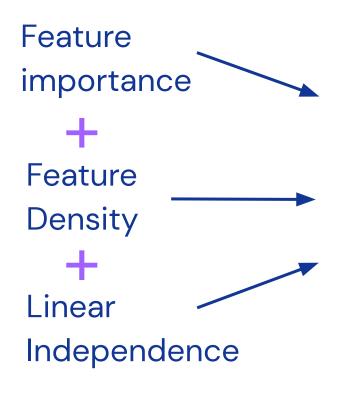


Linear Independence





Which features will be stored in superposition?



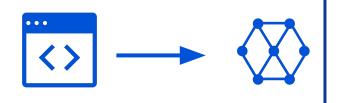
Open question:

Can we find a more predictive description of which features will be stored in superposition?



Plan for today

1. Building a **compiler** for transformer models



2. Studying **superposition** in compiled models





The future for Tracr and manual transformers

Make Tracr models more **naturalistic**

1. Can we use Tracr to create **evaluation benchmarks** for interpretability tools?

2. Can we **revert superposition** in Tracr models? (e.g., sparse coding, dictionary learning)

3. Can we use Tracr to **manually replace** model components that we (think we) understand?



Tracr is available open-source!



https://github.com/deepmind/tracr



https://arxiv.org/abs/2301.05062



