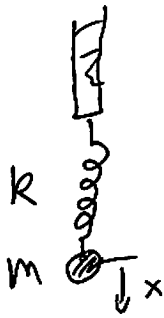


SPRING MOTION - CONTINUATION

4-vii-2020
STAGER

①



$$m \ddot{x} = -kx$$

$$\dot{x} = \frac{dx}{dt} = v$$

$$\dot{v} = \frac{dv}{dt} = a$$

$$a \equiv \ddot{x}$$

1)

$$t_0 = 0$$

$$x(0) \equiv x_0 = 1 \text{ m}$$

$$v(0) \equiv \dot{x}_0 = 0$$

$$m = 1 \text{ kg}$$

$$k = 20 \frac{\text{kg}}{\text{s}^2}$$

$$t_i = ih$$

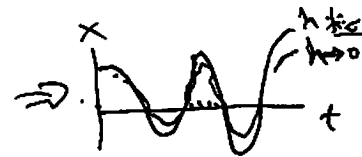
$$x_i = x_{i-1} + v_i h$$

$$i = 1, 2, \dots$$

$$t_i = t_{i-1} + h$$

$$v_i = v_{i-1} + a_i h$$

$$a_i = -\frac{k}{m} x_i$$



2)

~~More accurate integration~~
Conservation of energy

$$\dot{x}(t) \equiv \frac{dx}{dt} \approx \frac{\Delta x}{\Delta t}$$

$$\dot{x} (m \ddot{x}) = (-kx) \dot{x}$$

$$m (\ddot{x} \dot{x}) = -k (\dot{x} x) \quad (1)$$

$$\left(\frac{dx}{dt}\right) x = \dot{x} x \approx \frac{\Delta x}{\Delta t} x$$

	t	$t + \Delta t$
x	2	2.1
x^2	4	$(2.1)^2$

$$\Delta x = 2.1 - 2 = 0.1$$

$$\Delta(x^2) = (2.1)^2 - 4 = 0.41$$

$$(x + \Delta x)^2 = x^2 + 2x\Delta x + (\Delta x)^2$$

$$(x + \Delta x)^2 - x^2 = \underbrace{2x\Delta x}_{0.4} + \underbrace{(\Delta x)^2}_{0.01}$$

$$\approx 2x\Delta x$$

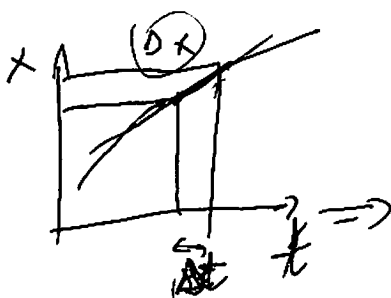
$$\Delta(x^2) \approx 2x\Delta x$$

$$\frac{\Delta(x^2)}{\Delta t} \approx 2x \frac{\Delta x}{\Delta t}$$

$$\Delta t \rightarrow 0$$

$$\frac{d(x^2)}{dt} = 2x \frac{dx}{dt} \quad (2)$$

~~c.g.
x = 2
Δx = 0.1
Δt = 0.1
x + Δx = 2.1
Δ(x^2) = (x + Δx)^2 - x^2~~



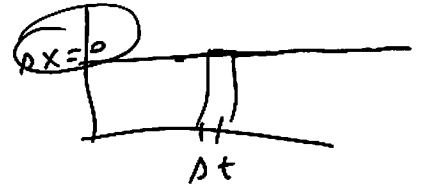
$$(1) \rightarrow L(x) \rightarrow m \frac{1}{2} \frac{d(\dot{x})^2}{dt} = -k \frac{1}{2} \frac{d(x^2)}{dt} \quad (2)$$

$$\dot{x} \equiv v \equiv \frac{dx}{dt}$$

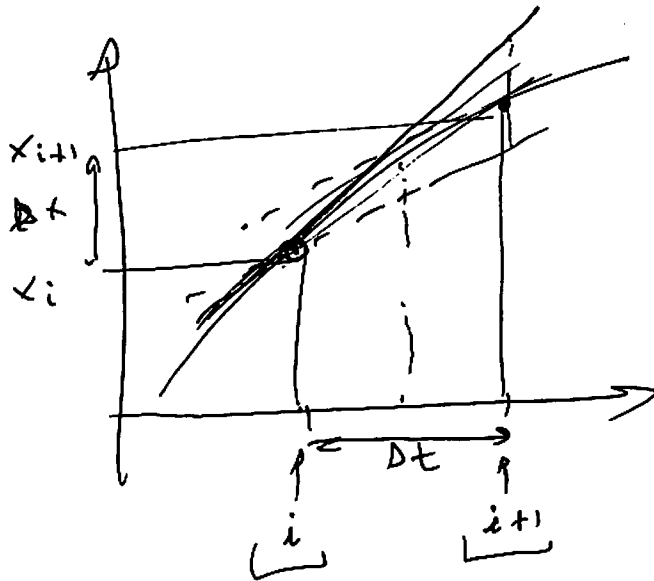
$$\frac{d}{dt} \left[\underbrace{\frac{1}{2} m \dot{x}^2 + \frac{k}{2} x^2}_{\equiv E} \right] = 0$$

$$\dot{x} x = \frac{1}{2} \frac{d x^2}{dt}$$

$$\ddot{x} \dot{x} = \frac{1}{2} \frac{d \dot{x}^2}{dt}$$



$$E = \underbrace{\frac{1}{2} m \dot{x}^2}_{\substack{\uparrow \\ \text{kinetic} \\ \text{energy}}} + \underbrace{\frac{k x^2}{2}}_{\substack{\uparrow \\ \text{potential} \\ \text{energy}}}$$



t_i → x_i, \dot{x}_i

(4) $x_{i+1} = x_i + v h$

(3) $\dot{x}_{i+1} = \dot{x}_i + a h$

$\ddot{x}_i = -\frac{k}{m} x_i$

$\ddot{x}_{i+1} = -\frac{k}{m} x_{i+1}$

$h = \Delta t$

$v = \frac{\dot{x}_i + \dot{x}_{i+1}}{2}$

$a = \frac{\ddot{x}_i + \ddot{x}_{i+1}}{2}$

$a = -\frac{k}{m} \frac{x_i + x_{i+1}}{2}$

(3)

$$(3) \rightarrow \dot{x}_{i+1} = \dot{x}_i + \left(\frac{-k}{m} \right) \frac{(x_i + x_{i+1})}{2} h$$

$$(4) \rightarrow x_{i+1} = x_i + \frac{\dot{x}_i + \dot{x}_{i+1}}{2} h$$

$$\dot{x}_{i+1} + \frac{kh}{2m} x_{i+1} = \dot{x}_i - \frac{kh}{2m} x_i \quad (5)$$

$$\frac{h}{2} \dot{x}_{i+1} + x_{i+1} = x_i + \frac{h}{2} \dot{x}_i \quad (6)$$

at time $t_{i+1} = t_i + h$ | at point i
at time t_i

$$\frac{h}{2} (5) + (6)$$

$$\hookrightarrow \left(1 + \frac{kh^2}{4m} \right) x_{i+1} = x_i \left(1 - \frac{kh^2}{4m} \right) + h \dot{x}_i$$

$$\hookrightarrow x_{i+1} = x_i \left(\frac{1 - \frac{kh^2}{4m}}{1 + \frac{kh^2}{4m}} \right) + \frac{h \dot{x}_i}{\left(1 + \frac{kh^2}{4m} \right)}$$

$$(5) + \left(\frac{-kh}{2m} \right) (6)$$

$$\hookrightarrow \left(1 + \frac{kh^2}{4m} \right) \dot{x}_{i+1} = -\frac{kh}{m} x_i + \left(1 - \frac{kh^2}{4m} \right) \dot{x}_i$$

$$\hookrightarrow \dot{x}_{i+1} = \frac{-\left(\frac{kh}{m} \right)}{\left(1 + \frac{kh^2}{4m} \right)} x_i + \left(\frac{1 - \frac{kh^2}{4m}}{1 + \frac{kh^2}{4m}} \right) \dot{x}_i$$

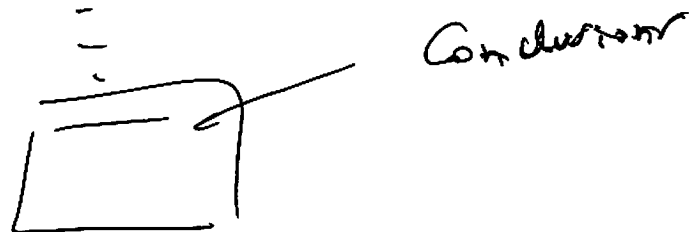
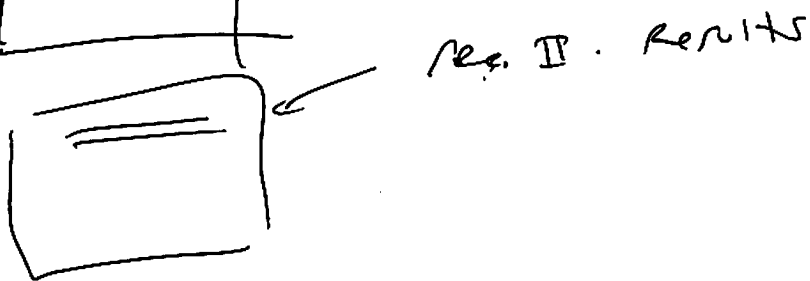
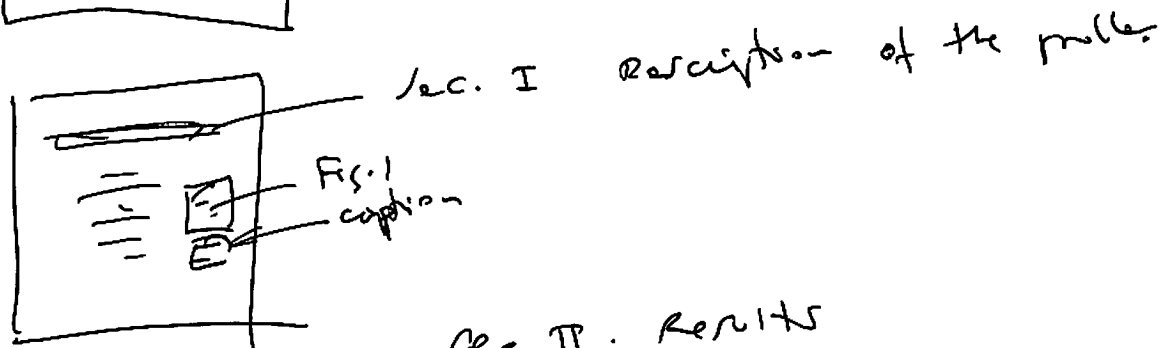
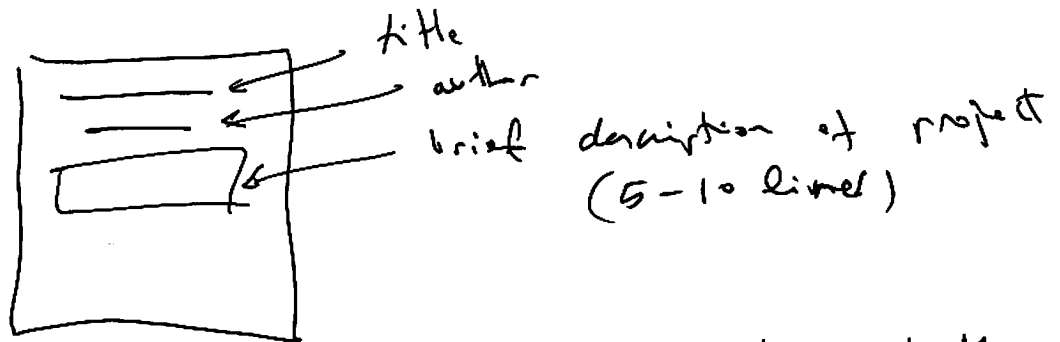
$$t_i \rightarrow x_i, \dot{x}_i = v_i \Rightarrow t_{i+1} = t_i + h$$

$$\left. \begin{array}{l} x_{i+1} \\ \dot{x}_{i+1} = v_{i+1} \end{array} \right\}$$

TASKS

④

1) start progress report



$$E_i = \frac{1}{2} m \dot{x}_i^2 + \frac{K}{2} x_i^2$$

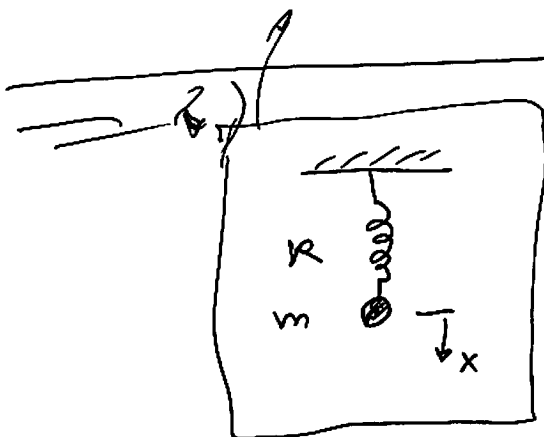
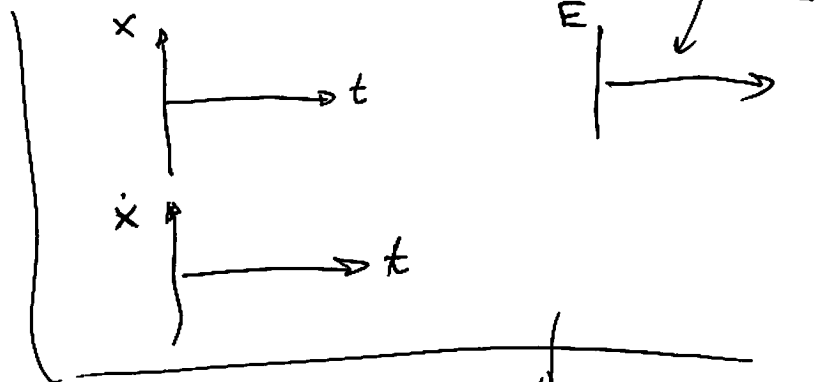


Fig. 1



method 1

method 2

3)

- limits
- derivatives

⑤

$$\lim_{x \rightarrow 0} f(x) =$$

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

$$\left(\frac{dx}{dt} \equiv \dot{x}\right)$$

$$(f(x)g(x))' = f'(x)g(x) + f(x)g'(x)$$

$$(f(x) + g(x))' = f'(x) + g'(x)$$

$$(a)' = 0$$

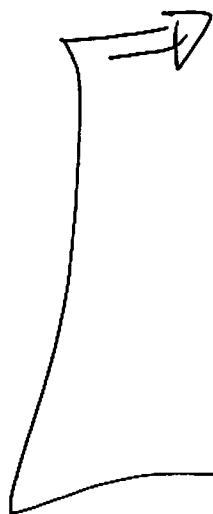
$$(x)' = 1$$

$$(x^n)' = n x^{n-1}$$

$$(\sin x)' = \cos x$$

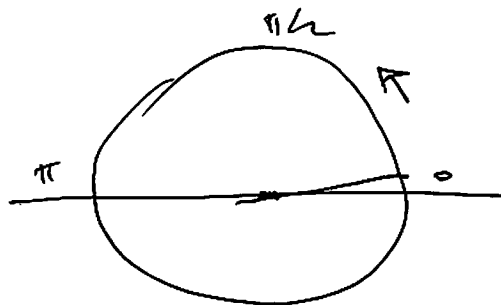
$$(\cos x)' = -\sin x$$

a = constant



$$\sin(a+b) = \sin a \cos b + \cos a \sin b$$

$$\cos(a+b) = \cos a \cos b - \sin a \sin b$$



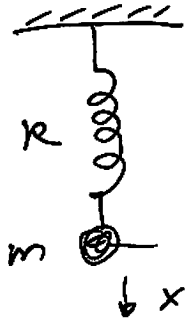
radian

$$\lim_{x \rightarrow 0} x \approx x$$

$$\cos x \approx 1$$

6

4)



$$m \ddot{x} = -kx - f \dot{x}$$