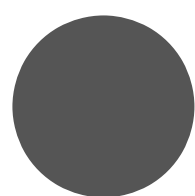


T_a



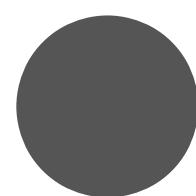
x_a

$-Q$



Q

T_b



x_b

x

