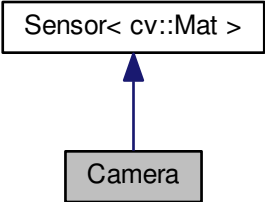


Sensor< cv::Mat >



```
graph BT; Camera[Camera] --> Sensor["Sensor< cv::Mat >"]
```

Camera